

LM3S2739 Microcontroller

DATA SHEET

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Luminary Micro, Inc. 108 Wild Basin, Suite 350 Austin, TX 78746 Main: +1-512-279-8800 Fax: +1-512-279-8879

http://www.luminarymicro.com







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About This Document

This data sheet provides reference information for the LM3S2739 microcontroller, describing the functional blocks of the system-on-chip (SoC) device designed around the ARM® Cortex™-M3 core.

Audience

This manual is intended for system software developers, hardware designers, and application developers.

About This Manual

This document is organized into sections that correspond to each major feature.

Related Documents

The following documents are referenced by the data sheet, and available on the documentation CD or from the Luminary Micro web site at www.luminarymicro.com:

- ARM® Cortex™-M3 Technical Reference Manual
- ARM® CoreSight Technical Reference Manual
- ARM® v7-M Architecture Application Level Reference Manual

The following related documents are also referenced:

IEEE Standard 1149.1-Test Access Port and Boundary-Scan Architecture

This documentation list was current as of publication date. Please check the Luminary Micro web site for additional documentation, including application notes and white papers.

Documentation Conventions

This document uses the conventions shown in Table 1 on page 21.

Table 1. Documentation Conventions

Notation	Meaning		
General Register Nota	General Register Notation		
REGISTER	APB registers are indicated in uppercase bold. For example, PBORCTL is the Power-On and Brown-Out Reset Control register. If a register name contains a lowercase n, it represents more than one register. For example, SRCRn represents any (or all) of the three Software Reset Control registers: SRCR0 , SRCR1 , and SRCR2 .		
bit	A single bit in a register.		
bit field	Two or more consecutive and related bits.		
offset 0xnnn	A hexadecimal increment to a register's address, relative to that module's base address as specified in "Memory Map" on page 43.		
Register N	Registers are numbered consecutively throughout the document to aid in referencing them. The register number has no meaning to software.		

Notation	Meaning
reserved	Register bits marked <i>reserved</i> are reserved for future use. In most cases, reserved bits are set to 0; however, user software should not rely on the value of a reserved bit. To provide software compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
уу:хх	The range of register bits inclusive from xx to yy. For example, 31:15 means bits 15 through 31 in that register.
Register Bit/Field Types	This value in the register bit diagram indicates whether software running on the controller can change the value of the bit field.
RC	Software can read this field. The bit or field is cleared by hardware after reading the bit/field.
RO	Software can read this field. Always write the chip reset value.
R/W	Software can read or write this field.
R/W1C	Software can read or write this field. A write of a 0 to a W1C bit does not affect the bit value in the register. A write of a 1 clears the value of the bit in the register; the remaining bits remain unchanged.
	This register type is primarily used for clearing interrupt status bits where the read operation provides the interrupt status and the write of the read value clears only the interrupts being reported at the time the register was read.
W1C	Software can write this field. A write of a 0 to a W1C bit does not affect the bit value in the register. A write of a 1 clears the value of the bit in the register; the remaining bits remain unchanged. A read of the register returns no meaningful data.
	This register is typically used to clear the corresponding bit in an interrupt register.
WO	Only a write by software is valid; a read of the register returns no meaningful data.
Register Bit/Field Reset Value	This value in the register bit diagram shows the bit/field value after any reset, unless noted.
0	Bit cleared to 0 on chip reset.
1	Bit set to 1 on chip reset.
-	Nondeterministic.
Pin/Signal Notation	
[]	Pin alternate function; a pin defaults to the signal without the brackets.
pin	Refers to the physical connection on the package.
signal	Refers to the electrical signal encoding of a pin.
assert a signal	Change the value of the signal from the logically False state to the logically True state. For active High signals, the asserted signal value is 1 (High); for active Low signals, the asserted signal value is 0 (Low). The active polarity (High or Low) is defined by the signal name (see SIGNAL and SIGNAL below).
deassert a signal	Change the value of the signal from the logically True state to the logically False state.
SIGNAL	Signal names are in uppercase and in the Courier font. An overbar on a signal name indicates that it is active Low. To assert SIGNAL is to drive it Low; to deassert SIGNAL is to drive it High.
SIGNAL	Signal names are in uppercase and in the Courier font. An active High signal has no overbar. To assert SIGNAL is to drive it High; to deassert SIGNAL is to drive it Low.
Numbers	-
X	An uppercase X indicates any of several values is allowed, where X can be any legal pattern. For example, a binary value of 0X00 can be either 0100 or 0000, a hex value of 0xX is 0x0 or 0x1, and so on.
0x	Hexadecimal numbers have a prefix of 0x. For example, 0x00FF is the hexadecimal number FF. Binary numbers are indicated with a b suffix, for example, 1011b. Decimal numbers are written without a prefix or suffix.

1 Architectural Overview

The Luminary Micro Stellaris[®] family of microcontrollers—the first ARM® Cortex[™]-M3 based controllers—brings high-performance 32-bit computing to cost-sensitive embedded microcontroller applications. These pioneering parts deliver customers 32-bit performance at a cost equivalent to legacy 8- and 16-bit devices, all in a package with a small footprint.

The Stellaris[®] family offers efficient performance and extensive integration, favorably positioning the device into cost-conscious applications requiring significant control-processing and connectivity capabilities. The Stellaris[®] LM3S2000 series, designed for Controller Area Network (CAN) applications, extends the Stellaris family with Bosch CAN networking technology, the golden standard in short-haul industrial networks. The Stellaris[®] LM3S2000 series also marks the first integration of CAN capabilities with the revolutionary Cortex-M3 core. The Stellaris[®] LM3S6000 series combines both a 10/100 Ethernet Media Access Control (MAC) and Physical (PHY) layer, marking the first time that integrated connectivity is available with an ARM Cortex-M3 MCU and the only integrated 10/100 Ethernet MAC and PHY available in an ARM architecture MCU.

The LM3S2739 microcontroller is targeted for industrial applications, including remote monitoring, electronic point-of-sale machines, test and measurement equipment, network appliances and switches, factory automation, HVAC and building control, gaming equipment, motion control, medical instrumentation, and fire and security.

For applications requiring extreme conservation of power, the LM3S2739 microcontroller features a Battery-backed Hibernation module to efficiently power down the LM3S2739 to a low-power state during extended periods of inactivity. With a power-up/power-down sequencer, a continuous time counter (RTC), a pair of match registers, an APB interface to the system bus, and dedicated non-volatile memory, the Hibernation module positions the LM3S2739 microcontroller perfectly for battery applications.

In addition, the LM3S2739 microcontroller offers the advantages of ARM's widely available development tools, System-on-Chip (SoC) infrastructure IP applications, and a large user community. Additionally, the microcontroller uses ARM's Thumb®-compatible Thumb-2 instruction set to reduce memory requirements and, thereby, cost. Finally, the LM3S2739 microcontroller is code-compatible to all members of the extensive Stellaris® family; providing flexibility to fit our customers' precise needs.

Luminary Micro offers a complete solution to get to market quickly, with evaluation and development boards, white papers and application notes, an easy-to-use peripheral driver library, and a strong support, sales, and distributor network.

1.1 Product Features

The LM3S2739 microcontroller includes the following product features:

- 32-Bit RISC Performance
 - 32-bit ARM® Cortex™-M3 v7M architecture optimized for small-footprint embedded applications
 - System timer (SysTick), providing a simple, 24-bit clear-on-write, decrementing, wrap-on-zero counter with a flexible control mechanism
 - Thumb®-compatible Thumb-2-only instruction set processor core for high code density
 - 50-MHz operation

- Hardware-division and single-cycle-multiplication
- Integrated Nested Vectored Interrupt Controller (NVIC) providing deterministic interrupt handling
- 33 interrupts with eight priority levels
- Memory protection unit (MPU), providing a privileged mode for protected operating system functionality
- Unaligned data access, enabling data to be efficiently packed into memory
- Atomic bit manipulation (bit-banding), delivering maximum memory utilization and streamlined peripheral control

Internal Memory

- 128 KB single-cycle flash
 - User-managed flash block protection on a 2-KB block basis
 - · User-managed flash data programming
 - User-defined and managed flash-protection block
- 64 KB single-cycle SRAM

General-Purpose Timers

- Three General-Purpose Timer Modules (GPTM), each of which provides two 16-bit timer/counters. Each GPTM can be configured to operate independently as timers or event counters (eight total): as a single 32-bit timer (four total), as one 32-bit Real-Time Clock (RTC) to event capture, for Pulse Width Modulation (PWM), or to trigger analog-to-digital conversions
- 32-bit Timer modes
 - Programmable one-shot timer
 - Programmable periodic timer
 - Real-Time Clock when using an external 32.768-KHz clock as the input
 - User-enabled stalling in periodic and one-shot mode when the controller asserts the CPU Halt flag during debug
 - ADC event trigger
- 16-bit Timer modes
 - General-purpose timer function with an 8-bit prescaler
 - Programmable one-shot timer
 - Programmable periodic timer
 - User-enabled stalling when the controller asserts CPU Halt flag during debug

- · ADC event trigger
- 16-bit Input Capture modes
 - · Input edge count capture
 - · Input edge time capture
- 16-bit PWM mode
 - Simple PWM mode with software-programmable output inversion of the PWM signal
- ARM FiRM-compliant Watchdog Timer
 - 32-bit down counter with a programmable load register
 - Separate watchdog clock with an enable
 - Programmable interrupt generation logic with interrupt masking
 - Lock register protection from runaway software
 - Reset generation logic with an enable/disable
 - User-enabled stalling when the controller asserts the CPU Halt flag during debug
- Controller Area Network (CAN)
 - Supports CAN protocol version 2.0 part A/B
 - Bit rates up to 1Mb/s
 - 32 message objects, each with its own identifier mask
 - Maskable interrupt
 - Disable automatic retransmission mode for TTCAN
 - Programmable loop-back mode for self-test operation
- Synchronous Serial Interface (SSI)
 - Master or slave operation
 - Programmable clock bit rate and prescale
 - Separate transmit and receive FIFOs, 16 bits wide, 8 locations deep
 - Programmable interface operation for Freescale SPI, MICROWIRE, or Texas Instruments synchronous serial interfaces
 - Programmable data frame size from 4 to 16 bits
 - Internal loopback test mode for diagnostic/debug testing
- UART

- Two fully programmable 16C550-type UARTs with IrDA support
- Separate 16x8 transmit (TX) and 16x12 receive (RX) FIFOs to reduce CPU interrupt service loading
- Programmable baud-rate generator with fractional divider
- Programmable FIFO length, including 1-byte deep operation providing conventional double-buffered interface
- FIFO trigger levels of 1/8, ½, ½, ¾, and 7/8
- Standard asynchronous communication bits for start, stop, and parity
- False-start-bit detection
- Line-break generation and detection

ADC

- Single- and differential-input configurations
- Four 10-bit channels (inputs) when used as single-ended inputs
- Sample rate of 500 thousand samples/second
- Flexible, configurable analog-to-digital conversion
- Four programmable sample conversion sequences from one to eight entries long, with corresponding conversion result FIFOs
- Each sequence triggered by software or internal event (timers, analog comparators, PWM or GPIO)
- On-chip temperature sensor

Analog Comparators

- One integrated analog comparator
- Configurable for output to: drive an output pin, generate an interrupt, or initiate an ADC sample sequence
- Compare external pin input to external pin input or to internal programmable voltage reference

I²C

- Master and slave receive and transmit operation with transmission speed up to 100 Kbps in Standard mode and 400 Kbps in Fast mode
- Interrupt generation
- Master with arbitration and clock synchronization, multimaster support, and 7-bit addressing mode

PWM

- Three PWM generator blocks, each with one 16-bit counter, two comparators, a PWM generator, and a dead-band generator
- One 16-bit counter
 - Runs in Down or Up/Down mode
 - Output frequency controlled by a 16-bit load value
 - Load value updates can be synchronized
 - · Produces output signals at zero and load value
- Two PWM comparators
 - Comparator value updates can be synchronized
 - · Produces output signals on match
- PWM generator
 - Output PWM signal is constructed based on actions taken as a result of the counter and PWM comparator output signals
 - · Produces two independent PWM signals
- Dead-band generator
 - Produces two PWM signals with programmable dead-band delays suitable for driving a half-H bridge
 - · Can be bypassed, leaving input PWM signals unmodified
- Flexible output control block with PWM output enable of each PWM signal
 - PWM output enable of each PWM signal
 - Optional output inversion of each PWM signal (polarity control)
 - Optional fault handling for each PWM signal
 - Synchronization of timers in the PWM generator blocks
 - · Synchronization of timer/comparator updates across the PWM generator blocks
 - Interrupt status summary of the PWM generator blocks
- Can initiate an ADC sample sequence

QEI

- Hardware position integrator tracks the encoder position
- Velocity capture using built-in timer
- Interrupt generation on index pulse, velocity-timer expiration, direction change, and quadrature error detection

GPIOs

- 18-56 GPIOs, depending on configuration
- 5-V-tolerant input/outputs
- Programmable interrupt generation as either edge-triggered or level-sensitive
- Bit masking in both read and write operations through address lines
- Can initiate an ADC sample sequence
- Programmable control for GPIO pad configuration:
 - Weak pull-up or pull-down resistors
 - · 2-mA, 4-mA, and 8-mA pad drive
 - Slew rate control for the 8-mA drive
 - · Open drain enables
 - · Digital input enables

Power

- On-chip Low Drop-Out (LDO) voltage regulator, with programmable output user-adjustable from 2.25 V to 2.75 V
- Hibernation module handles the power-up/down 3.3 V sequencing and control for the core digital logic and analog circuits
- Low-power options on controller: Sleep and Deep-sleep modes
- Low-power options for peripherals: software controls shutdown of individual peripherals
- User-enabled LDO unregulated voltage detection and automatic reset
- 3.3-V supply brown-out detection and reporting via interrupt or reset
- Flexible Reset Sources
 - Power-on reset (POR)
 - Reset pin assertion
 - Brown-out (BOR) detector alerts to system power drops
 - Software reset
 - Watchdog timer reset
 - Internal low drop-out (LDO) regulator output goes unregulated
- Additional Features
 - Six reset sources

- Programmable clock source control
- Clock gating to individual peripherals for power savings
- IEEE 1149.1-1990 compliant Test Access Port (TAP) controller
- Debug access via JTAG and Serial Wire interfaces
- Full JTAG boundary scan
- Industrial-range 100-pin RoHS-compliant LQFP package

1.2 Target Applications

- Remote monitoring
- Electronic point-of-sale (POS) machines
- Test and measurement equipment
- Network appliances and switches
- Factory automation
- HVAC and building control
- Gaming equipment
- Motion control
- Medical instrumentation
- Fire and security
- Power and energy
- Transportation

1.3 High-Level Block Diagram

Figure 1-1 on page 30 shows the features on the Stellaris® Fury-class family of devices.

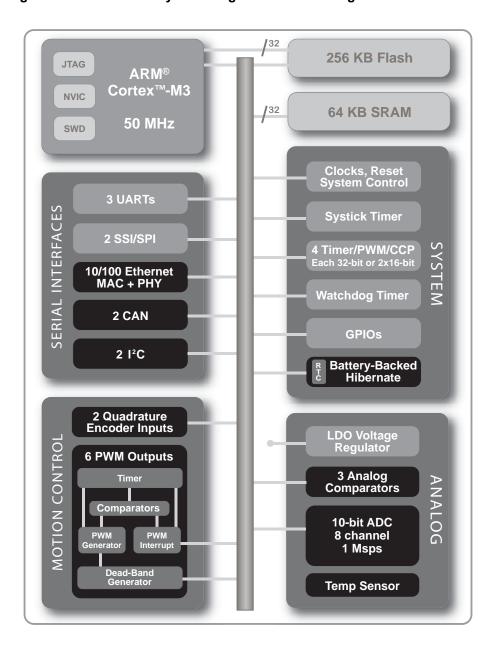


Figure 1-1. Stellaris® Fury-class High-Level Block Diagram

1.4 Functional Overview

The following sections provide an overview of the features of the LM3S2739 microcontroller. The page number in parenthesis indicates where that feature is discussed in detail. Ordering and support information can be found in "Ordering and Contact Information" on page 527.

1.4.1 ARM Cortex™-M3

1.4.1.1 Processor Core (see page 37)

All members of the Stellaris[®] product family, including the LM3S2739 microcontroller, are designed around an ARM Cortex[™]-M3 processor core. The ARM Cortex-M3 processor provides the core for a high-performance, low-cost platform that meets the needs of minimal memory implementation, reduced pin count, and low-power consumption, while delivering outstanding computational performance and exceptional system response to interrupts.

"ARM Cortex-M3 Processor Core" on page 37 provides an overview of the ARM core; the core is detailed in the ARM® Cortex™-M3 Technical Reference Manual.

1.4.1.2 System Timer (SysTick)

Cortex-M3 includes an integrated system timer, SysTick. SysTick provides a simple, 24-bit clear-on-write, decrementing, wrap-on-zero counter with a flexible control mechanism. The counter can be used in several different ways, for example:

- An RTOS tick timer which fires at a programmable rate (for example, 100 Hz) and invokes a SysTick routine.
- A high-speed alarm timer using the system clock.
- A variable rate alarm or signal timer—the duration is range-dependent on the reference clock used and the dynamic range of the counter.
- A simple counter. Software can use this to measure time to completion and time used.
- An internal clock source control based on missing/meeting durations. The COUNTFLAG bit-field in the control and status register can be used to determine if an action completed within a set duration, as part of a dynamic clock management control loop.

1.4.1.3 Nested Vectored Interrupt Controller (NVIC)

The LM3S2739 controller includes the ARM Nested Vectored Interrupt Controller (NVIC) on the ARM Cortex-M3 core. The NVIC and Cortex-M3 prioritize and handle all exceptions. All exceptions are handled in Handler Mode. The processor state is automatically stored to the stack on an exception, and automatically restored from the stack at the end of the Interrupt Service Routine (ISR). The vector is fetched in parallel to the state saving, which enables efficient interrupt entry. The processor supports tail-chaining, which enables back-to-back interrupts to be performed without the overhead of state saving and restoration. Software can set eight priority levels on 7 exceptions (system handlers) and 33 interrupts.

"Interrupts" on page 45 provides an overview of the NVIC controller and the interrupt map. Exceptions and interrupts are detailed in the *ARM*® *Cortex*™-*M3 Technical Reference Manual*.

1.4.2 Motor Control Peripherals

To enhance motor control, the LM3S2739 controller features Pulse Width Modulation (PWM) outputs and the Quadrature Encoder Interface (QEI).

1.4.2.1 PWM (see page 202)

Pulse width modulation (PWM) is a powerful technique for digitally encoding analog signal levels. High-resolution counters are used to generate a square wave, and the duty cycle of the square

wave is modulated to encode an analog signal. Typical applications include switching power supplies and motor control.

On the LM3S2739, PWM motion control functionality can be achieved through dedicated, flexible motion control hardware (the PWM pins) or through the motion control features of the general-purpose timers (using the CCP pins).

PWM Pins (see page 449)

The LM3S2739 PWM module consists of three PWM generator blocks and a control block. Each PWM generator block contains one timer (16-bit down or up/down counter), two comparators, a PWM signal generator, a dead-band generator, and an interrupt/ADC-trigger selector. The control block determines the polarity of the PWM signals, and which signals are passed through to the pins.

Each PWM generator block produces two PWM signals that can either be independent signals or a single pair of complementary signals with dead-band delays inserted. The output of the PWM generation blocks are managed by the output control block before being passed to the device pins.

CCP Pins (see page 202)

The General-Purpose Timer Module's CCP (Capture Compare PWM) pins are software programmable to support a simple PWM mode with a software-programmable output inversion of the PWM signal.

1.4.2.2 **QEI** (see page 480)

A quadrature encoder, also known as a 2-channel incremental encoder, converts linear displacement into a pulse signal. By monitoring both the number of pulses and the relative phase of the two signals, you can track the position, direction of rotation, and speed. In addition, a third channel, or index signal, can be used to reset the position counter.

The Stellaris quadrature encoder with index (QEI) module interprets the code produced by a quadrature encoder wheel to integrate position over time and determine direction of rotation. In addition, it can capture a running estimate of the velocity of the encoder wheel.

1.4.3 Serial Communications Peripherals

The LM3S2739 controller supports both asynchronous and synchronous serial communications with two fully programmable 16C550-type UARTs, one SSI module, one I²C module, and one CAN unit.

1.4.3.1 **UART** (see page 285)

A Universal Asynchronous Receiver/Transmitter (UART) is an integrated circuit used for RS-232C serial communications, containing a transmitter (parallel-to-serial converter) and a receiver (serial-to-parallel converter), each clocked separately.

The LM3S2739 controller includes two fully programmable 16C550-type UARTs that support data transfer speeds up to 460.8 Kbps. In addition, each UART is capable of supporting IrDA. (Although similar in functionality to a 16C550 UART, it is not register-compatible.)

Separate 16x8 transmit (TX) and 16x12 receive (RX) FIFOs reduce CPU interrupt service loading. The UART can generate individually masked interrupts from the RX, TX, modem status, and error conditions. The module provides a single combined interrupt when any of the interrupts are asserted and are unmasked.

1.4.3.2 SSI (see page 325)

Synchronous Serial Interface (SSI) is a four-wire bi-directional communications interface.

The LM3S2739 controller includes one SSI module that provides the functionality for synchronous serial communications with peripheral devices, and can be configured to use the Freescale SPI, MICROWIRE, or TI synchronous serial interface frame formats. The size of the data frame is also configurable, and can be set between 4 and 16 bits, inclusive.

The SSI module performs serial-to-parallel conversion on data received from a peripheral device, and parallel-to-serial conversion on data transmitted to a peripheral device. The TX and RX paths are buffered with internal FIFOs, allowing up to eight 16-bit values to be stored independently.

The SSI module can be configured as either a master or slave device. As a slave device, the SSI module can also be configured to disable its output, which allows a master device to be coupled with multiple slave devices.

The SSI module also includes a programmable bit rate clock divider and prescaler to generate the output serial clock derived from the SSI module's input clock. Bit rates are generated based on the input clock and the maximum bit rate is determined by the connected peripheral.

1.4.3.3 I²C(see page 359)

The Inter-Integrated Circuit (I²C) bus provides bi-directional data transfer through a two-wire design (a serial data line SDA and a serial clock line SCL).

The I²C bus interfaces to external I²C devices such as serial memory (RAMs and ROMs), networking devices, LCDs, tone generators, and so on. The I²C bus may also be used for system testing and diagnostic purposes in product development and manufacture.

The LM3S2739 controller includes one I²C module that provides the ability to communicate to other IC devices over an I²C bus. The I²C bus supports devices that can both transmit and receive (write and read) data.

Devices on the I²C bus can be designated as either a master or a slave. The I²C module supports both sending and receiving data as either a master or a slave, and also supports the simultaneous operation as both a master and a slave. The four I²C modes are: Master Transmit, Master Receive, Slave Transmit, and Slave Receive.

A Stellaris $^{\tiny{(8)}}$ I $^{\tiny{(2)}}$ C module can operate at two speeds: Standard (100 Kbps) and Fast (400 Kbps).

Both the I²C master and slave can generate interrupts. The I²C master generates interrupts when a transmit or receive operation completes (or aborts due to an error). The I²C slave generates interrupts when data has been sent or requested by a master.

1.4.3.4 Controller Area Network (see page 394)

Controller Area Network (CAN) is a multicast shared serial-bus standard for connecting electronic control units (ECUs). CAN was specifically designed to be robust in electromagnetically noisy environments and can utilize a differential balanced line like RS-485 or a more robust twisted-pair wire. Originally created for automotive purposes, now it is used in many embedded control applications (for example, industrial or medical). Bit rates up to 1Mb/s are possible at network lengths below 40 meters. Decreased bit rates allow longer network distances (for example, 125 Kb/s at 500m).

A transmitter sends a message to all CAN nodes (broadcasting). Each node decides on the basis of the identifier received whether it should process the message. The identifier also determines the priority that the message enjoys in competition for bus access. Each CAN message can transmit from 0 to 8 bytes of user information. The LM3S2739 includes three CAN units.

1.4.4 System Peripherals

1.4.4.1 Programmable GPIOs (see page 155)

General-purpose input/output (GPIO) pins offer flexibility for a variety of connections.

The Stellaris[®] GPIO module is composed of eight physical GPIO blocks, each corresponding to an individual GPIO port. The GPIO module is FiRM-compliant (compliant to the ARM Foundation IP for Real-Time Microcontrollers specification) and supports 18-56 programmable input/output pins. The number of GPIOs available depends on the peripherals being used (see "Signal Tables" on page 498 for the signals available to each GPIO pin).

The GPIO module features programmable interrupt generation as either edge-triggered or level-sensitive on all pins, programmable control for GPIO pad configuration, and bit masking in both read and write operations through address lines.

1.4.4.2 Three Programmable Timers (see page 196)

Programmable timers can be used to count or time external events that drive the Timer input pins.

The Stellaris[®] General-Purpose Timer Module (GPTM) contains three GPTM blocks. Each GPTM block provides two 16-bit timer/counters that can be configured to operate independently as timers or event counters, or configured to operate as one 32-bit timer or one 32-bit Real-Time Clock (RTC). Timers can also be used to trigger analog-to-digital (ADC) conversions.

When configured in 32-bit mode, a timer can run as a one-shot timer, periodic timer, or Real-Time Clock (RTC). When in 16-bit mode, a timer can run as a one-shot timer or periodic timer, and can extend its precision by using an 8-bit prescaler. A 16-bit timer can also be configured for event capture or Pulse Width Modulation (PWM) generation.

1.4.4.3 Watchdog Timer (see page 229)

A watchdog timer can generate nonmaskable interrupts (NMIs) or a reset when a time-out value is reached. The watchdog timer is used to regain control when a system has failed due to a software error or to the failure of an external device to respond in the expected way.

The Stellaris[®] Watchdog Timer module consists of a 32-bit down counter, a programmable load register, interrupt generation logic, and a locking register.

The Watchdog Timer can be configured to generate an interrupt to the controller on its first time-out, and to generate a reset signal on its second time-out. Once the Watchdog Timer has been configured, the lock register can be written to prevent the timer configuration from being inadvertently altered.

1.4.5 Memory Peripherals

The LM3S2739 controller offers both SRAM and Flash memory.

1.4.5.1 SRAM (see page 131)

The LM3S2739 static random access memory (SRAM) controller supports 64 KB SRAM. The internal SRAM of the Stellaris[®] devices is located at offset 0x0000.0000 of the device memory map. To reduce the number of time-consuming read-modify-write (RMW) operations, ARM has introduced *bit-banding* technology in the new Cortex-M3 processor. With a bit-band-enabled processor, certain regions in the memory map (SRAM and peripheral space) can use address aliases to access individual bits in a single, atomic operation.

1.4.5.2 Flash (see page 132)

The LM3S2739 Flash controller supports 128 KB of flash memory. The flash is organized as a set of 1-KB blocks that can be individually erased. Erasing a block causes the entire contents of the block to be reset to all 1s. These blocks are paired into a set of 2-KB blocks that can be individually protected. The blocks can be marked as read-only or execute-only, providing different levels of code protection. Read-only blocks cannot be erased or programmed, protecting the contents of those blocks from being modified. Execute-only blocks cannot be erased or programmed, and can only be read by the controller instruction fetch mechanism, protecting the contents of those blocks from being read by either the controller or by a debugger.

1.4.6 Additional Features

1.4.6.1 Memory Map (see page 43)

A memory map lists the location of instructions and data in memory. The memory map for the LM3S2739 controller can be found in "Memory Map" on page 43. Register addresses are given as a hexadecimal increment, relative to the module's base address as shown in the memory map.

The ARM® Cortex™-M3 Technical Reference Manual provides further information on the memory map.

1.4.6.2 JTAG TAP Controller (see page 48)

The Joint Test Action Group (JTAG) port provides a standardized serial interface for controlling the Test Access Port (TAP) and associated test logic. The TAP, JTAG instruction register, and JTAG data registers can be used to test the interconnects of assembled printed circuit boards, obtain manufacturing information on the components, and observe and/or control the inputs and outputs of the controller during normal operation. The JTAG port provides a high degree of testability and chip-level access at a low cost.

The JTAG port is comprised of the standard five pins: TRST, TCK, TMS, TDI, and TDO. Data is transmitted serially into the controller on TDI and out of the controller on TDO. The interpretation of this data is dependent on the current state of the TAP controller. For detailed information on the operation of the JTAG port and TAP controller, please refer to the *IEEE Standard 1149.1-Test Access Port and Boundary-Scan Architecture*.

The Luminary Micro JTAG controller works with the ARM JTAG controller built into the Cortex-M3 core. This is implemented by multiplexing the TDO outputs from both JTAG controllers. ARM JTAG instructions select the ARM TDO output while Luminary Micro JTAG instructions select the Luminary Micro TDO outputs. The multiplexer is controlled by the Luminary Micro JTAG controller, which has comprehensive programming for the ARM, Luminary Micro, and unimplemented JTAG instructions.

1.4.6.3 System Control and Clocks (see page 59)

System control determines the overall operation of the device. It provides information about the device, controls the clocking of the device and individual peripherals, and handles reset detection and reporting.

1.4.6.4 Hibernation Module (see page 113)

The Hibernation module provides logic to switch power off to the main processor and peripherals, and to wake on external or time-based events. The Hibernation module includes power-sequencing logic, a real-time clock with a pair of match registers, low-battery detection circuitry, and interrupt signalling to the processor. It also includes 64 32-bit words of non-volatile memory that can be used for saving state during hibernation.

1.4.7 Hardware Details

Details on the pins and package can be found in the following sections:

- "Pin Diagram" on page 497
- "Signal Tables" on page 498
- "Operating Characteristics" on page 512
- "Electrical Characteristics" on page 513
- "Package Information" on page 525

2 ARM Cortex-M3 Processor Core

The ARM Cortex-M3 processor provides the core for a high-performance, low-cost platform that meets the needs of minimal memory implementation, reduced pin count, and low power consumption, while delivering outstanding computational performance and exceptional system response to interrupts. Features include:

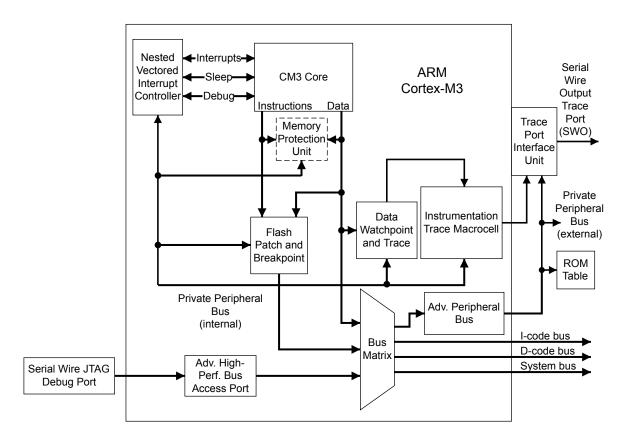
- Compact core.
- Thumb-2 instruction set, delivering the high-performance expected of an ARM core in the memory size usually associated with 8- and 16-bit devices; typically in the range of a few kilobytes of memory for microcontroller class applications.
- Speedy application execution through Harvard architecture characterized by separate buses for instruction and data.
- Exceptional interrupt handling, by implementing the register manipulations required for handling an interrupt in hardware.
- Memory protection unit (MPU) to provide a privileged mode of operation for complex applications.
- Migration from the ARM7(TM) processor family for better performance and power efficiency.
- Full-featured debug solution with a:
 - Serial Wire JTAG Debug Port (SWJ-DP)
 - Flash Patch and Breakpoint (FPB) unit for implementing breakpoints
 - Data Watchpoint and Trigger (DWT) unit for implementing watchpoints, trigger resources, and system profiling
 - Instrumentation Trace Macrocell (ITM) for support of printf style debugging
 - Trace Port Interface Unit (TPIU) for bridging to a Trace Port Analyzer

The Stellaris[®] family of microcontrollers builds on this core to bring high-performance 32-bit computing to cost-sensitive embedded microcontroller applications, such as factory automation and control, industrial control power devices, building and home automation, and stepper motors.

For more information on the ARM Cortex-M3 processor core, see the *ARM*® *Cortex*™-*M3 Technical Reference Manual*. For information on SWJ-DP, see the *ARM*® *CoreSight Technical Reference Manual*.

2.1 Block Diagram

Figure 2-1. CPU Block Diagram



2.2 Functional Description

Important: The ARM® Cortex™-M3 Technical Reference Manual describes all the features of an ARM Cortex-M3 in detail. However, these features differ based on the implementation. This section describes the Stellaris® implementation.

Luminary Micro has implemented the ARM Cortex-M3 core as shown in Figure 2-1 on page 38. As noted in the *ARM*® *Cortex*™-*M3 Technical Reference Manual*, several Cortex-M3 components are flexible in their implementation: SW/JTAG-DP, ETM, TPIU, the ROM table, the MPU, and the Nested Vectored Interrupt Controller (NVIC). Each of these is addressed in the sections that follow.

2.2.1 Serial Wire and JTAG Debug

Luminary Micro has replaced the ARM SW-DP and JTAG-DP with the ARM CoreSight™-compliant Serial Wire JTAG Debug Port (SWJ-DP) interface. This means Chapter 12, "Debug Port," of the *ARM*® *Cortex™-M3 Technical Reference Manual* does not apply to Stellaris[®] devices.

The SWJ-DP interface combines the SWD and JTAG debug ports into one module. See the CoreSight™ Design Kit Technical Reference Manual for details on SWJ-DP.

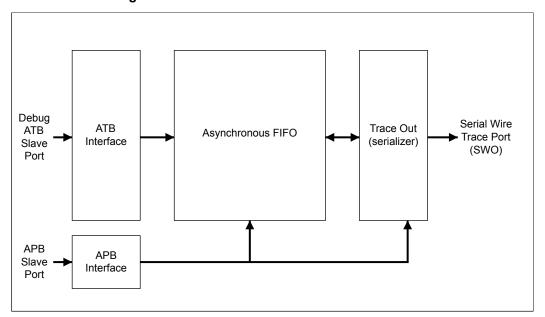
2.2.2 Embedded Trace Macrocell (ETM)

ETM was not implemented in the Stellaris[®] devices. This means Chapters 15 and 16 of the *ARM*® *Cortex*™-*M3 Technical Reference Manual* can be ignored.

2.2.3 Trace Port Interface Unit (TPIU)

The TPIU acts as a bridge between the Cortex-M3 trace data from the ITM, and an off-chip Trace Port Analyzer. The Stellaris[®] devices have implemented TPIU as shown in Figure 2-2 on page 39. This is similar to the non-ETM version described in the *ARM® Cortex™-M3 Technical Reference Manual*, however, SWJ-DP only provides SWV output for the TPIU.

Figure 2-2. TPIU Block Diagram



2.2.4 ROM Table

The default ROM table was implemented as described in the *ARM*® *Cortex*™-*M3 Technical Reference Manual*.

2.2.5 Memory Protection Unit (MPU)

The Memory Protection Unit (MPU) is included on the LM3S2739 controller and supports the standard ARMv7 Protected Memory System Architecture (PMSA) model. The MPU provides full support for protection regions, overlapping protection regions, access permissions, and exporting memory attributes to the system.

2.2.6 Nested Vectored Interrupt Controller (NVIC)

The Nested Vectored Interrupt Controller (NVIC):

Facilitates low-latency exception and interrupt handling

- Controls power management
- Implements system control registers

The NVIC supports up to 240 dynamically reprioritizable interrupts each with up to 256 levels of priority. The NVIC and the processor core interface are closely coupled, which enables low latency interrupt processing and efficient processing of late arriving interrupts. The NVIC maintains knowledge of the stacked (nested) interrupts to enable tail-chaining of interrupts.

You can only fully access the NVIC from privileged mode, but you can pend interrupts in user-mode if you enable the Configuration Control Register (see the ARM® Cortex™-M3 Technical Reference Manual). Any other user-mode access causes a bus fault.

All NVIC registers are accessible using byte, halfword, and word unless otherwise stated.

All NVIC registers and system debug registers are little endian regardless of the endianness state of the processor.

2.2.6.1 Interrupts

The ARM® Cortex™-M3 Technical Reference Manual describes the maximum number of interrupts and interrupt priorities. The LM3S2739 microcontroller supports 33 interrupts with eight priority levels.

2.2.6.2 System Timer (SysTick)

Cortex-M3 includes an integrated system timer, SysTick. SysTick provides a simple, 24-bit clear-on-write, decrementing, wrap-on-zero counter with a flexible control mechanism. The counter can be used in several different ways, for example:

- An RTOS tick timer which fires at a programmable rate (for example 100 Hz) and invokes a SysTick routine.
- A high-speed alarm timer using the system clock.
- A variable rate alarm or signal timer—the duration is range-dependent on the reference clock used and the dynamic range of the counter.
- A simple counter. Software can use this to measure time to completion and time used.
- An internal clock source control based on missing/meeting durations. The COUNTFLAG bit-field
 in the control and status register can be used to determine if an action completed within a set
 duration, as part of a dynamic clock management control loop.

Functional Description

The timer consists of three registers:

- A control and status counter to configure its clock, enable the counter, enable the SysTick interrupt, and determine counter status.
- The reload value for the counter, used to provide the counter's wrap value.
- The current value of the counter.

A fourth register, the SysTick Calibration Value Register, is not implemented in the Stellaris devices.

When enabled, the timer counts down from the reload value to zero, reloads (wraps) to the value in the SysTick Reload Value register on the next clock edge, then decrements on subsequent clocks. Writing a value of zero to the Reload Value register disables the counter on the next wrap. When the counter reaches zero, the COUNTFLAG status bit is set. The COUNTFLAG bit clears on reads.

Writing to the Current Value register clears the register and the COUNTFLAG status bit. The write does not trigger the SysTick exception logic. On a read, the current value is the value of the register at the time the register is accessed.

If the core is in debug state (halted), the counter will not decrement. The timer is clocked with respect to a reference clock. The reference clock can be the core clock or an external clock source.

SysTick Control and Status Register

Use the SysTick Control and Status Register to enable the SysTick features. The reset is 0x0000.0000.

Bit/Field	Name	Туре	Reset	Description	
31:17	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.	
16	COUNTFLAG	R/W	0	Returns 1 if timer counted to 0 since last time this was read. Clears on read by application. If read by the debugger using the DAP, this bit is cleared on read-only if the MasterType bit in the AHB-AP Control Register is set to 0. Otherwise, the COUNTFLAG bit is not changed by the debugger read.	
15:3	reserved	R/W	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.	
2	CLKSOURCE	R/W	0	0 = external reference clock. (Not implemented for Stellaris microcontrollers.) 1 = core clock. If no reference clock is provided, it is held at 1 and so gives the same time as the core clock. The core clock must be at least 2.5 times faster than the reference clock.	
1	TICKINT	R/W	0	If it is not, the count values are Unpredictable.	
	HORINI	17/1/1	0	1 = counting down to 0 pends the SysTick handler.0 = counting down to 0 does not pend the SysTick handler. Software can use the COUNTFLAG to determine if ever counted to 0.	
0	ENABLE	R/W	0	1 = counter operates in a multi-shot way. That is, counter loads with the Reload value and then begins counting down. On reaching 0, it sets the COUNTFLAG to 1 and optionally pends the SysTick handler, based on TICKINT. It then loads the Reload value again, and begins counting. 0 = counter disabled.	

SysTick Reload Value Register

Use the SysTick Reload Value Register to specify the start value to load into the current value register when the counter reaches 0. It can be any value between 1 and 0x00FFFFFF. A start value of 0 is possible, but has no effect because the SysTick interrupt and COUNTFLAG are activated when counting from 1 to 0.

Therefore, as a multi-shot timer, repeated over and over, it fires every N+1 clock pulse, where N is any value from 1 to 0x00FFFFFF. So, if the tick interrupt is required every 100 clock pulses, 99 must be written into the RELOAD. If a new value is written on each tick interrupt, so treated as single shot, then the actual count down must be written. For example, if a tick is next required after 400 clock pulses, 400 must be written into the RELOAD.

Bit/Field	Name	Type	Reset	Description
31:24	reserved	RO		Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
23:0	RELOAD	W1C	-	Value to load into the SysTick Current Value Register when the counter reaches 0.

SysTick Current Value Register

Use the SysTick Current Value Register to find the current value in the register.

Bit/Field	Name	Туре	Reset	Description
31:24	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
23:0	CURRENT	W1C		Current value at the time the register is accessed. No read-modify-write protection is provided, so change with care. This register is write-clear. Writing to it with any value clears the register to 0. Clearing this register also clears the COUNTFLAG bit of the SysTick Control and Status Register.

SysTick Calibration Value Register

The SysTick Calibration Value register is not implemented.

3 Memory Map

The memory map for the LM3S2739 controller is provided in Table 3-1 on page 43.

In this manual, register addresses are given as a hexadecimal increment, relative to the module's base address as shown in the memory map. See also Chapter 4, "Memory Map" in the *ARM*® *Cortex™-M3 Technical Reference Manual*.

Note: In Table 3-1 on page 43 addresses not listed are reserved.

Table 3-1. Memory Map^a

Start	End	Description	For details on registers, see page
Memory			
0x0000.0000	0x1FFF.FFFF	On-chip flash ^b	135
0x2000.0000	0x200F.FFFF	Bit-banded on-chip SRAM ^c	135
0x2010.0000	0x21FF.FFFF	Reserved non-bit-banded SRAM space	-
0x2200.0000	0x23FF.FFFF	Bit-band alias of 0x2000.0000 through 0x200F.FFFF	131
0x2400.0000	0x3FFF.FFFF	Reserved non-bit-banded SRAM space	-
FiRM Peripherals			
0x4000.0000	0x4000.0FFF	Watchdog timer	231
0x4000.1000	0x4000.3FFF	Reserved	-
0x4000.4000	0x4000.4FFF	GPIO Port A	161
0x4000.5000	0x4000.5FFF	GPIO Port B	161
0x4000.6000	0x4000.6FFF	GPIO Port C	161
0x4000.7000	0x4000.7FFF	GPIO Port D	161
0x4000.8000	0x4000.8FFF	SSI0	336
0x4000.A000	0x4000.BFFF	Reserved	-
0x4000.C000	0x4000.CFFF	UART0	292
0x4000.D000	0x4000.DFFF	UART1	292
0x4000.F000	0x4000.FFFF	Reserved	-
0x4001.0000	0x4001.FFFF	Reserved for future FiRM peripherals	-
Peripherals			
0x4002.0000	0x4002.07FF	I2C Master 0	372
0x4002.0800	0x4002.0FFF	I2C Slave 0	385
0x4002.2000	0x4002.3FFF	Reserved	-
0x4002.4000	0x4002.4FFF	GPIO Port E	161
0x4002.5000	0x4002.5FFF	GPIO Port F	161
0x4002.6000	0x4002.6FFF	GPIO Port G	161
0x4002.7000	0x4002.7FFF	GPIO Port H	161
0x4002.8000	0x4002.8FFF	PWM	455
0x4002.9000	0x4002.BFFF	Reserved	-
0x4002.C000	0x4002.CFFF	QEI0	484
0x4002.E000	0x4002.FFFF	Reserved	-

Start	End	Description	For details
			on
			registers, see page
0x4003.0000	0x4003.0FFF	Timer0	207
0x4003.1000	0x4003.1FFF	Timer1	207
0x4003.2000	0x4003.2FFF	Timer2	207
0x4003.4000	0x4003.7FFF	Reserved	-
0x4003.8000	0x4003.8FFF	ADC	258
0x4003.9000	0x4003.BFFF	Reserved	-
0x4003.C000	0x4003.CFFF	Analog Comparators	438
0x4003.D000	0x4003.FFFF	Reserved	-
0x4004.0000	0x4004.0FFF	CAN0 Controller	407
0x4004.3000	0x4004.7FFF	Reserved	-
0x4004.9000	0x4004.BFFF	Reserved	-
0x4004.C000	0x400F.BFFF	Reserved	-
0x400F.C000	0x400F.CFFF	Hibernation Module	118
0x400F.D000	0x400F.DFFF	Flash control	135
0x400F.E000	0x400F.EFFF	System control	66
0x400F.F000	0x400F.FFFF	Reserved	-
0x4011.1000	0x4011.1FFF	Reserved	-
0x4012.0000	0x41FF.FFFF	F Reserved for non bit-banded peripheral space	
0x4200.0000	0x43FF.FFFF	F.FFFF Bit-banded alias of 0x4000.0000 through 0x400F.FFFF	
0x4400.0000	0x5E32.FFFF	2.FFFF Reserved for non bit-banded peripheral space	
0x5E34.0000	0x5FFF.FFFF	Reserved	
0x6000.0000	0xDFFF.FFFF	Reserved for external devices	-
Private Peripheral Bus	1		
0xE000.0000	0xE000.0FFF	Instrumentation Trace Macrocell (ITM)	<i>ARM</i> ®
0xE000.1000	0xE000.1FFF	Data Watchpoint and Trace (DWT)	Cortex™-M3 Technical
0xE000.2000	0xE000.2FFF	Flash Patch and Breakpoint (FPB)	Reference
0xE000.3000	0xE000.DFFF	Reserved	Manual
0xE000.E000	0xE000.EFFF	Nested Vectored Interrupt Controller (NVIC)	
0xE000.F000	0xE003.FFFF	Reserved	
0xE004.0000	0xE004.0FFF	Trace Port Interface Unit (TPIU)	
0xE004.1000	0xE004.1FFF	Reserved	-
0xE004.2000	0xE00F.FFFF	Reserved	-
0xE010.0000	0xFFFF.FFFF	Reserved for vendor peripherals	-

a. All reserved space returns a bus fault when read or written.

b. The unavailable flash will bus fault throughout this range.

c. The unavailable SRAM will bus fault throughout this range.

4 Interrupts

The ARM Cortex-M3 processor and the Nested Vectored Interrupt Controller (NVIC) prioritize and handle all exceptions. All exceptions are handled in Handler Mode. The processor state is automatically stored to the stack on an exception, and automatically restored from the stack at the end of the Interrupt Service Routine (ISR). The vector is fetched in parallel to the state saving, which enables efficient interrupt entry. The processor supports tail-chaining, which enables back-to-back interrupts to be performed without the overhead of state saving and restoration.

Table 4-1 on page 45 lists all the exceptions. Software can set eight priority levels on seven of these exceptions (system handlers) as well as on 33 interrupts (listed in Table 4-2 on page 46).

Priorities on the system handlers are set with the NVIC System Handler Priority registers. Interrupts are enabled through the NVIC Interrupt Set Enable register and prioritized with the NVIC Interrupt Priority registers. You can also group priorities by splitting priority levels into pre-emption priorities and subpriorities. All the interrupt registers are described in Chapter 8, "Nested Vectored Interrupt Controller" in the *ARM® Cortex™-M3 Technical Reference Manual*.

Internally, the highest user-settable priority (0) is treated as fourth priority, after a Reset, NMI, and a Hard Fault. Note that 0 is the default priority for all the settable priorities.

If you assign the same priority level to two or more interrupts, their hardware priority (the lower the position number) determines the order in which the processor activates them. For example, if both GPIO Port A and GPIO Port B are priority level 1, then GPIO Port A has higher priority.

See Chapter 5, "Exceptions" and Chapter 8, "Nested Vectored Interrupt Controller" in the *ARM*® *Cortex*™-*M3 Technical Reference Manual* for more information on exceptions and interrupts.

Note: In Table 4-2 on page 46 interrupts not listed are reserved.

Table 4-1. Exception Types

Exception Type	Position	Priority ^a	Description
-	0	-	Stack top is loaded from first entry of vector table on reset.
Reset	1	-3 (highest) Invoked on power up and warm reset. On first instruction, drops to lo priority (and then is called the base level of activation). This is asynchronous.	
Non-Maskable Interrupt (NMI)	2	-2	Cannot be stopped or preempted by any exception but reset. This is asynchronous.
			An NMI is only producible by software, using the NVIC Interrupt Control State register.
Hard Fault	3	-1	All classes of Fault, when the fault cannot activate due to priority or the configurable fault handler has been disabled. This is synchronous.
Memory Management	4	settable	MPU mismatch, including access violation and no match. This is synchronous.
			The priority of this exception can be changed.
Bus Fault	5	settable Pre-fetch fault, memory access fault, and other address/memory faults. This is synchronous when precise and asynchronous whimprecise.	
			You can enable or disable this fault.
Usage Fault	6	settable Usage fault, such as undefined instruction executed or illegal state transition attempt. This is synchronous.	
-	7-10	-	Reserved.
SVCall	11	settable	System service call with SVC instruction. This is synchronous.

Exception Type	Position	Priority ^a	Description
Debug Monitor	12	settable	Debug monitor (when not halting). This is synchronous, but only active when enabled. It does not activate if lower priority than the current activation.
-	13	-	Reserved.
PendSV	14	settable Pendable request for system service. This is asynchronous and only pended by software.	
SysTick	15	settable	System tick timer has fired. This is asynchronous.
Interrupts	16 and above	settable	Asserted from outside the ARM Cortex-M3 core and fed through the NVIC (prioritized). These are all asynchronous. Table 4-2 on page 46 lists the interrupts on the LM3S2739 controller.

a. 0 is the default priority for all the settable priorities.

Table 4-2. Interrupts

Interrupt (Bit in Interrupt Registers)	Description
0	GPIO Port A
1	GPIO Port B
2	GPIO Port C
3	GPIO Port D
4	GPIO Port E
5	UARTO
6	UART1
7	SSI0
8	12C0
9	PWM Fault
10	PWM Generator 0
11	PWM Generator 1
12	PWM Generator 2
13	QEI0
14	ADC Sequence 0
15	ADC Sequence 1
16	ADC Sequence 2
17	ADC Sequence 3
18	Watchdog timer
19	Timer0 A
20	Timer0 B
21	Timer1 A
22	Timer1 B
23	Timer2 A
24	Timer2 B
25	Analog Comparator 0
28	System Control
29	Flash Control
30	GPIO Port F
31	GPIO Port G

Interrupt (Bit in Interrupt Registers)	Description
32	GPIO Port H
39	CAN0
43	Hibernation Module
44-47	Reserved

5 JTAG Interface

The Joint Test Action Group (JTAG) port is an IEEE standard that defines a Test Access Port and Boundary Scan Architecture for digital integrated circuits and provides a standardized serial interface for controlling the associated test logic. The TAP, Instruction Register (IR), and Data Registers (DR) can be used to test the interconnections of assembled printed circuit boards and obtain manufacturing information on the components. The JTAG Port also provides a means of accessing and controlling design-for-test features such as I/O pin observation and control, scan testing, and debugging.

The JTAG port is comprised of the standard five pins: TRST, TCK, TMS, TDI, and TDO. Data is transmitted serially into the controller on TDI and out of the controller on TDO. The interpretation of this data is dependent on the current state of the TAP controller. For detailed information on the operation of the JTAG port and TAP controller, please refer to the IEEE Standard 1149.1-Test Access Port and Boundary-Scan Architecture.

The Luminary Micro JTAG controller works with the ARM JTAG controller built into the Cortex-M3 core. This is implemented by multiplexing the TDO outputs from both JTAG controllers. ARM JTAG instructions select the ARM TDO output while Luminary Micro JTAG instructions select the Luminary Micro TDO outputs. The multiplexer is controlled by the Luminary Micro JTAG controller, which has comprehensive programming for the ARM, LMI, and unimplemented JTAG instructions.

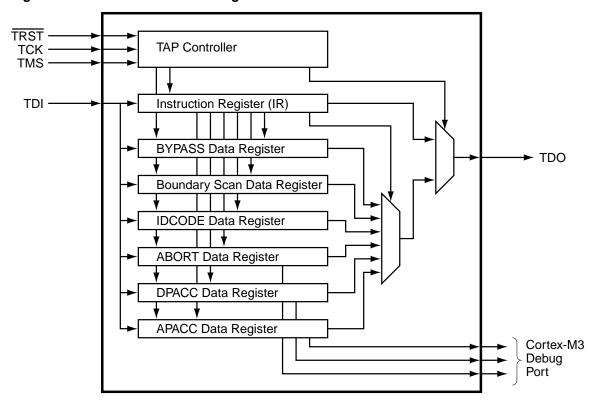
The JTAG module has the following features:

- IEEE 1149.1-1990 compatible Test Access Port (TAP) controller
- Four-bit Instruction Register (IR) chain for storing JTAG instructions
- IEEE standard instructions:
 - BYPASS instruction
 - IDCODE instruction
 - SAMPLE/PRELOAD instruction
 - EXTEST instruction
 - INTEST instruction
- ARM additional instructions:
 - APACC instruction
 - DPACC instruction
 - ABORT instruction
- Integrated ARM Serial Wire Debug (SWD)

See the *ARM*® *Cortex*™-*M3 Technical Reference Manual* for more information on the ARM JTAG controller.

5.1 Block Diagram

Figure 5-1. JTAG Module Block Diagram



5.2 Functional Description

A high-level conceptual drawing of the JTAG module is shown in Figure 5-1 on page 49. The JTAG module is composed of the Test Access Port (TAP) controller and serial shift chains with parallel update registers. The TAP controller is a simple state machine controlled by the TRST, TCK and TMS inputs. The current state of the TAP controller depends on the current value of TRST and the sequence of values captured on TMS at the rising edge of TCK. The TAP controller determines when the serial shift chains capture new data, shift data from TDI towards TDO, and update the parallel load registers. The current state of the TAP controller also determines whether the Instruction Register (IR) chain or one of the Data Register (DR) chains is being accessed.

The serial shift chains with parallel load registers are comprised of a single Instruction Register (IR) chain and multiple Data Register (DR) chains. The current instruction loaded in the parallel load register determines which DR chain is captured, shifted, or updated during the sequencing of the TAP controller.

Some instructions, like EXTEST and INTEST, operate on data currently in a DR chain and do not capture, shift, or update any of the chains. Instructions that are not implemented decode to the BYPASS instruction to ensure that the serial path between TDI and TDO is always connected (see Table 5-2 on page 55 for a list of implemented instructions).

See "JTAG and Boundary Scan" on page 521 for JTAG timing diagrams.

5.2.1 JTAG Interface Pins

The JTAG interface consists of five standard pins: TRST, TCK, TMS, TDI, and TDO. These pins and their associated reset state are given in Table 5-1 on page 50. Detailed information on each pin follows.

Table 5-1. JTAG Port Pins Reset State

Pin Name	Data Direction	Internal Pull-Up	Internal Pull-Down	Drive Strength	Drive Value
TRST	Input	Enabled	Disabled	N/A	N/A
TCK	Input	Enabled	Disabled	N/A	N/A
TMS	Input	Enabled	Disabled	N/A	N/A
TDI	Input	Enabled	Disabled	N/A	N/A
TDO	Output	Enabled	Disabled	2-mA driver	High-Z

5.2.1.1 Test Reset Input (TRST)

The TRST pin is an asynchronous active Low input signal for initializing and resetting the JTAG TAP controller and associated JTAG circuitry. When TRST is asserted, the TAP controller resets to the Test-Logic-Reset state and remains there while TRST is asserted. When the TAP controller enters the Test-Logic-Reset state, the JTAG Instruction Register (IR) resets to the default instruction, IDCODE.

By default, the internal pull-up resistor on the TRST pin is enabled after reset. Changes to the pull-up resistor settings on GPIO Port B should ensure that the internal pull-up resistor remains enabled on PB7/TRST; otherwise JTAG communication could be lost.

5.2.1.2 Test Clock Input (TCK)

The ${ t TCK}$ pin is the clock for the JTAG module. This clock is provided so the test logic can operate independently of any other system clocks. In addition, it ensures that multiple JTAG TAP controllers that are daisy-chained together can synchronously communicate serial test data between components. During normal operation, ${ t TCK}$ is driven by a free-running clock with a nominal 50% duty cycle. When necessary, ${ t TCK}$ can be stopped at 0 or 1 for extended periods of time. While ${ t TCK}$ is stopped at 0 or 1, the state of the TAP controller does not change and data in the JTAG Instruction and Data Registers is not lost.

By default, the internal pull-up resistor on the ${ t TCK}$ pin is enabled after reset. This assures that no clocking occurs if the pin is not driven from an external source. The internal pull-up and pull-down resistors can be turned off to save internal power as long as the ${ t TCK}$ pin is constantly being driven by an external source.

5.2.1.3 Test Mode Select (TMS)

The TMS pin selects the next state of the JTAG TAP controller. TMS is sampled on the rising edge of TCK. Depending on the current TAP state and the sampled value of TMS, the next state is entered. Because the TMS pin is sampled on the rising edge of TCK, the *IEEE Standard 1149.1* expects the value on TMS to change on the falling edge of TCK.

Holding TMS high for five consecutive TCK cycles drives the TAP controller state machine to the Test-Logic-Reset state. When the TAP controller enters the Test-Logic-Reset state, the JTAG Instruction Register (IR) resets to the default instruction, IDCODE. Therefore, this sequence can be used as a reset mechanism, similar to asserting TRST. The JTAG Test Access Port state machine can be seen in its entirety in Figure 5-2 on page 52.

By default, the internal pull-up resistor on the TMS pin is enabled after reset. Changes to the pull-up resistor settings on GPIO Port C should ensure that the internal pull-up resistor remains enabled on PC1/TMS; otherwise JTAG communication could be lost.

5.2.1.4 Test Data Input (TDI)

The TDI pin provides a stream of serial information to the IR chain and the DR chains. TDI is sampled on the rising edge of TCK and, depending on the current TAP state and the current instruction, presents this data to the proper shift register chain. Because the TDI pin is sampled on the rising edge of TCK, the *IEEE Standard 1149.1* expects the value on TDI to change on the falling edge of TCK.

By default, the internal pull-up resistor on the TDI pin is enabled after reset. Changes to the pull-up resistor settings on GPIO Port C should ensure that the internal pull-up resistor remains enabled on PC2/TDI: otherwise JTAG communication could be lost.

5.2.1.5 Test Data Output (TDO)

The TDO pin provides an output stream of serial information from the IR chain or the DR chains. The value of TDO depends on the current TAP state, the current instruction, and the data in the chain being accessed. In order to save power when the JTAG port is not being used, the TDO pin is placed in an inactive drive state when not actively shifting out data. Because TDO can be connected to the TDI of another controller in a daisy-chain configuration, the *IEEE Standard 1149.1* expects the value on TDO to change on the falling edge of TCK.

By default, the internal pull-up resistor on the <code>TDO</code> pin is enabled after reset. This assures that the pin remains at a constant logic level when the JTAG port is not being used. The internal pull-up and pull-down resistors can be turned off to save internal power if a High-Z output value is acceptable during certain TAP controller states.

5.2.2 JTAG TAP Controller

The JTAG TAP controller state machine is shown in Figure 5-2 on page 52. The TAP controller state machine is reset to the Test-Logic-Reset state on the assertion of a Power-On-Reset (POR) or the assertion of TRST. Asserting the correct sequence on the TMS pin allows the JTAG module to shift in new instructions, shift in data, or idle during extended testing sequences. For detailed information on the function of the TAP controller and the operations that occur in each state, please refer to *IEEE Standard 1149.1*.

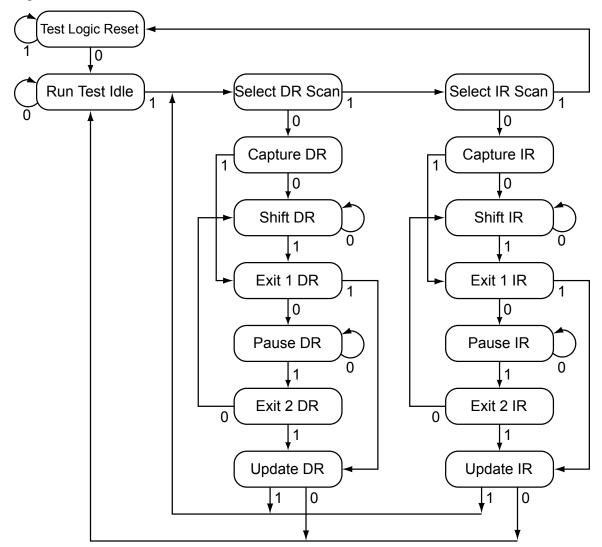


Figure 5-2. Test Access Port State Machine

5.2.3 Shift Registers

The Shift Registers consist of a serial shift register chain and a parallel load register. The serial shift register chain samples specific information during the TAP controller's CAPTURE states and allows this information to be shifted out of TDO during the TAP controller's SHIFT states. While the sampled data is being shifted out of the chain on TDO, new data is being shifted into the serial shift register on TDI. This new data is stored in the parallel load register during the TAP controller's UPDATE states. Each of the shift registers is discussed in detail in "Register Descriptions" on page 55.

5.2.4 Operational Considerations

There are certain operational considerations when using the JTAG module. Because the JTAG pins can be programmed to be GPIOs, board configuration and reset conditions on these pins must be considered. In addition, because the JTAG module has integrated ARM Serial Wire Debug, the method for switching between these two operational modes is described below.

5.2.4.1 GPIO Functionality

When the controller is reset with either a POR or RST, the JTAG/SWD port pins default to their JTAG/SWD configurations. The default configuration includes enabling digital functionality (setting **GPIODEN** to 1), enabling the pull-up resistors (setting **GPIOPUR** to 1), and enabling the alternate hardware function (setting **GPIOAFSEL** to 1) for the PB7 and PC[3:0] JTAG/SWD pins.

It is possible for software to configure these pins as GPIOs after reset by writing 0s to PB7 and PC[3:0] in the **GPIOAFSEL** register. If the user does not require the JTAG/SWD port for debugging or board-level testing, this provides five more GPIOs for use in the design.

Caution – If the JTAG pins are used as GPIOs in a design, PB7 and PC2 cannot have external pull-down resistors connected to both of them at the same time. If both pins are pulled Low during reset, the controller has unpredictable behavior. If this happens, remove one or both of the pull-down resistors, and apply $\overline{\text{RST}}$ or power-cycle the part.

In addition, it is possible to create a software sequence that prevents the debugger from connecting to the Stellaris® microcontroller. If the program code loaded into flash immediately changes the JTAG pins to their GPIO functionality, the debugger may not have enough time to connect and halt the controller before the JTAG pin functionality switches. This may lock the debugger out of the part. This can be avoided with a software routine that restores JTAG functionality based on an external or software trigger.

The commit control registers provide a layer of protection against accidental programming of critical hardware peripherals. Writes to protected bits of the **GPIO Alternate Function Select (GPIOAFSEL)** register (see page 171) are not committed to storage unless the **GPIO Lock (GPIOLOCK)** register (see page 181) has been unlocked and the appropriate bits of the **GPIO Commit (GPIOCR)** register (see page 182) have been set to 1.

Recovering a "Locked" Device

If software configures any of the JTAG/SWD pins as GPIO and loses the ability to communicate with the debugger, there is a debug sequence that can be used to recover the device. Performing a total of ten JTAG-to-SWD and SWD-to-JTAG switch sequences while holding the device in reset mass erases the flash memory. The sequence to recover the device is:

- 1. Assert and hold the RST signal.
- 2. Perform the JTAG-to-SWD switch sequence.
- Perform the SWD-to-JTAG switch sequence.
- Perform the JTAG-to-SWD switch sequence.
- 5. Perform the SWD-to-JTAG switch sequence.
- Perform the JTAG-to-SWD switch sequence.
- **7.** Perform the SWD-to-JTAG switch sequence.
- 8. Perform the JTAG-to-SWD switch sequence.
- Perform the SWD-to-JTAG switch sequence.
- 10. Perform the JTAG-to-SWD switch sequence.
- 11. Perform the SWD-to-JTAG switch sequence.

12. Release the RST signal.

The JTAG-to-SWD and SWD-to-JTAG switch sequences are described in "ARM Serial Wire Debug (SWD)" on page 54. When performing switch sequences for the purpose of recovering the debug capabilities of the device, only steps 1 and 2 of the switch sequence need to be performed.

5.2.4.2 ARM Serial Wire Debug (SWD)

In order to seamlessly integrate the ARM Serial Wire Debug (SWD) functionality, a serial-wire debugger must be able to connect to the Cortex-M3 core without having to perform, or have any knowledge of, JTAG cycles. This is accomplished with a SWD preamble that is issued before the SWD session begins.

The preamble used to enable the SWD interface of the SWJ-DP module starts with the TAP controller in the Test-Logic-Reset state. From here, the preamble sequences the TAP controller through the following states: Run Test Idle, Select DR, Select IR, Test Logic Reset, Test Logic Reset, Run Test Idle, Run Test Idle, Select DR, Select IR, Test Logic Reset, Test Logic Reset, Run Test Idle, Run Test Idle, Select DR, Select IR, and Test Logic Reset states.

Stepping through this sequences of the TAP state machine enables the SWD interface and disables the JTAG interface. For more information on this operation and the SWD interface, see the *ARM*® *Cortex*™-*M3 Technical Reference Manual* and the *ARM*® *CoreSight Technical Reference Manual*.

Because this sequence is a valid series of JTAG operations that could be issued, the ARM JTAG TAP controller is not fully compliant to the *IEEE Standard 1149.1*. This is the only instance where the ARM JTAG TAP controller does not meet full compliance with the specification. Due to the low probability of this sequence occurring during normal operation of the TAP controller, it should not affect normal performance of the JTAG interface.

JTAG-to-SWD Switching

To switch the operating mode of the Debug Access Port (DAP) from JTAG to SWD mode, the external debug hardware must send a switch sequence to the device. The 16-bit switch sequence for switching to SWD mode is defined as b1110011110011110, transmitted LSB first. This can also be represented as 16'hE79E when transmitted LSB first. The complete switch sequence should consist of the following transactions on the TCK/SWCLK and TMS/SWDIO signals:

- 1. Send at least 50 TCK/SWCLK cycles with TMS/SWDIO set to 1. This ensures that both JTAG and SWD are in their reset/idle states.
- 2. Send the 16-bit JTAG-to-SWD switch sequence, 16'hE79E.
- Send at least 50 TCK/SWCLK cycles with TMS/SWDIO set to 1. This ensures that if SWJ-DP was already in SWD mode, before sending the switch sequence, the SWD goes into the line reset state.

SWD-to-JTAG Switching

To switch the operating mode of the Debug Access Port (DAP) from SWD to JTAG mode, the external debug hardware must send a switch sequence to the device. The 16-bit switch sequence for switching to JTAG mode is defined as b1110011110011110, transmitted LSB first. This can also be represented as 16'hE73C when transmitted LSB first. The complete switch sequence should consist of the following transactions on the TCK/SWCLK and TMS/SWDIO signals:

1. Send at least 50 TCK/SWCLK cycles with TMS/SWDIO set to 1. This ensures that both JTAG and SWD are in their reset/idle states.

- 2. Send the 16-bit SWD-to-JTAG switch sequence, 16'hE73C.
- 3. Send at least 5 TCK/SWCLK cycles with TMS/SWDIO set to 1. This ensures that if SWJ-DP was already in JTAG mode, before sending the switch sequence, the JTAG goes into the Test Logic Reset state.

5.3 Initialization and Configuration

After a Power-On-Reset or an external reset (RST), the JTAG pins are automatically configured for JTAG communication. No user-defined initialization or configuration is needed. However, if the user application changes these pins to their GPIO function, they must be configured back to their JTAG functionality before JTAG communication can be restored. This is done by enabling the five JTAG pins (PB7 and PC[3:0]) for their alternate function using the **GPIOAFSEL** register.

5.4 Register Descriptions

There are no APB-accessible registers in the JTAG TAP Controller or Shift Register chains. The registers within the JTAG controller are all accessed serially through the TAP Controller. The registers can be broken down into two main categories: Instruction Registers and Data Registers.

5.4.1 Instruction Register (IR)

The JTAG TAP Instruction Register (IR) is a four-bit serial scan chain with a parallel load register connected between the JTAG TDI and TDO pins. When the TAP Controller is placed in the correct states, bits can be shifted into the Instruction Register. Once these bits have been shifted into the chain and updated, they are interpreted as the current instruction. The decode of the Instruction Register bits is shown in Table 5-2 on page 55. A detailed explanation of each instruction, along with its associated Data Register, follows.

Table 5-2. JTAG	Instruction	Register	Commands
-----------------	-------------	----------	----------

IR[3:0]	Instruction	Description
0000	EXTEST	Drives the values preloaded into the Boundary Scan Chain by the SAMPLE/PRELOAD instruction onto the pads.
0001	INTEST	Drives the values preloaded into the Boundary Scan Chain by the SAMPLE/PRELOAD instruction into the controller.
0010	SAMPLE / PRELOAD	Captures the current I/O values and shifts the sampled values out of the Boundary Scan Chain while new preload data is shifted in.
1000	ABORT	Shifts data into the ARM Debug Port Abort Register.
1010	DPACC	Shifts data into and out of the ARM DP Access Register.
1011	APACC	Shifts data into and out of the ARM AC Access Register.
1110	IDCODE	Loads manufacturing information defined by the <i>IEEE Standard 1149.1</i> into the IDCODE chain and shifts it out.
1111	BYPASS	Connects TDI to TDO through a single Shift Register chain.
All Others	Reserved	Defaults to the BYPASS instruction to ensure that TDI is always connected to TDO.

5.4.1.1 EXTEST Instruction

The EXTEST instruction does not have an associated Data Register chain. The EXTEST instruction uses the data that has been preloaded into the Boundary Scan Data Register using the SAMPLE/PRELOAD instruction. When the EXTEST instruction is present in the Instruction Register, the preloaded data in the Boundary Scan Data Register associated with the outputs and output enables are used to drive the GPIO pads rather than the signals coming from the core. This allows

tests to be developed that drive known values out of the controller, which can be used to verify connectivity.

5.4.1.2 INTEST Instruction

The INTEST instruction does not have an associated Data Register chain. The INTEST instruction uses the data that has been preloaded into the Boundary Scan Data Register using the SAMPLE/PRELOAD instruction. When the INTEST instruction is present in the Instruction Register, the preloaded data in the Boundary Scan Data Register associated with the inputs are used to drive the signals going into the core rather than the signals coming from the GPIO pads. This allows tests to be developed that drive known values into the controller, which can be used for testing. It is important to note that although the RST input pin is on the Boundary Scan Data Register chain, it is only observable.

5.4.1.3 SAMPLE/PRELOAD Instruction

The SAMPLE/PRELOAD instruction connects the Boundary Scan Data Register chain between TDI and TDO. This instruction samples the current state of the pad pins for observation and preloads new test data. Each GPIO pad has an associated input, output, and output enable signal. When the TAP controller enters the Capture DR state during this instruction, the input, output, and output-enable signals to each of the GPIO pads are captured. These samples are serially shifted out of TDO while the TAP controller is in the Shift DR state and can be used for observation or comparison in various tests.

While these samples of the inputs, outputs, and output enables are being shifted out of the Boundary Scan Data Register, new data is being shifted into the Boundary Scan Data Register from TDI. Once the new data has been shifted into the Boundary Scan Data Register, the data is saved in the parallel load registers when the TAP controller enters the Update DR state. This update of the parallel load register preloads data into the Boundary Scan Data Register that is associated with each input, output, and output enable. This preloaded data can be used with the EXTEST and INTEST instructions to drive data into or out of the controller. Please see "Boundary Scan Data Register" on page 58 for more information.

5.4.1.4 ABORT Instruction

The ABORT instruction connects the associated ABORT Data Register chain between TDI and TDO. This instruction provides read and write access to the ABORT Register of the ARM Debug Access Port (DAP). Shifting the proper data into this Data Register clears various error bits or initiates a DAP abort of a previous request. Please see the "ABORT Data Register" on page 58 for more information.

5.4.1.5 DPACC Instruction

The DPACC instruction connects the associated DPACC Data Register chain between TDI and TDO. This instruction provides read and write access to the DPACC Register of the ARM Debug Access Port (DAP). Shifting the proper data into this register and reading the data output from this register allows read and write access to the ARM debug and status registers. Please see "DPACC Data Register" on page 58 for more information.

5.4.1.6 APACC Instruction

The APACC instruction connects the associated APACC Data Register chain between <code>TDI</code> and <code>TDO</code>. This instruction provides read and write access to the APACC Register of the ARM Debug Access Port (DAP). Shifting the proper data into this register and reading the data output from this register allows read and write access to internal components and buses through the Debug Port. Please see "APACC Data Register" on page 58 for more information.

5.4.1.7 IDCODE Instruction

The IDCODE instruction connects the associated IDCODE Data Register chain between <code>TDI</code> and <code>TDO</code>. This instruction provides information on the manufacturer, part number, and version of the ARM core. This information can be used by testing equipment and debuggers to automatically configure their input and output data streams. IDCODE is the default instruction that is loaded into the JTAG Instruction Register when a power-on-reset (POR) is asserted, <code>TRST</code> is asserted, or the Test-Logic-Reset state is entered. Please see "IDCODE Data Register" on page 57 for more information.

5.4.1.8 BYPASS Instruction

The BYPASS instruction connects the associated BYPASS Data Register chain between TDI and TDO. This instruction is used to create a minimum length serial path between the TDI and TDO ports. The BYPASS Data Register is a single-bit shift register. This instruction improves test efficiency by allowing components that are not needed for a specific test to be bypassed in the JTAG scan chain by loading them with the BYPASS instruction. Please see "BYPASS Data Register" on page 57 for more information.

5.4.2 Data Registers

The JTAG module contains six Data Registers. These include: IDCODE, BYPASS, Boundary Scan, APACC, DPACC, and ABORT serial Data Register chains. Each of these Data Registers is discussed in the following sections.

5.4.2.1 IDCODE Data Register

The format for the 32-bit IDCODE Data Register defined by the *IEEE Standard 1149.1* is shown in Figure 5-3 on page 57. The standard requires that every JTAG-compliant device implement either the IDCODE instruction or the BYPASS instruction as the default instruction. The LSB of the IDCODE Data Register is defined to be a 1 to distinguish it from the BYPASS instruction, which has an LSB of 0. This allows auto configuration test tools to determine which instruction is the default instruction.

The major uses of the JTAG port are for manufacturer testing of component assembly, and program development and debug. To facilitate the use of auto-configuration debug tools, the IDCODE instruction outputs a value of 0x3BA00477. This value indicates an ARM Cortex-M3, Version 1 processor. This allows the debuggers to automatically configure themselves to work correctly with the Cortex-M3 during debug.

Figure 5-3. IDCODE Register Format



5.4.2.2 BYPASS Data Register

The format for the 1-bit BYPASS Data Register defined by the *IEEE Standard 1149.1* is shown in Figure 5-4 on page 58. The standard requires that every JTAG-compliant device implement either the BYPASS instruction or the IDCODE instruction as the default instruction. The LSB of the BYPASS Data Register is defined to be a 0 to distinguish it from the IDCODE instruction, which has an LSB of 1. This allows auto configuration test tools to determine which instruction is the default instruction.

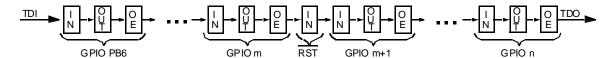
Figure 5-4. BYPASS Register Format

5.4.2.3 Boundary Scan Data Register

The format of the Boundary Scan Data Register is shown in Figure 5-5 on page 58. Each GPIO pin, in a counter-clockwise direction from the JTAG port pins, is included in the Boundary Scan Data Register. Each GPIO pin has three associated digital signals that are included in the chain. These signals are input, output, and output enable, and are arranged in that order as can be seen in the figure. In addition to the GPIO pins, the controller reset pin, $\overline{\text{RST}}$, is included in the chain. Because the reset pin is always an input, only the input signal is included in the Data Register chain.

When the Boundary Scan Data Register is accessed with the SAMPLE/PRELOAD instruction, the input, output, and output enable from each digital pad are sampled and then shifted out of the chain to be verified. The sampling of these values occurs on the rising edge of TCK in the Capture DR state of the TAP controller. While the sampled data is being shifted out of the Boundary Scan chain in the Shift DR state of the TAP controller, new data can be preloaded into the chain for use with the EXTEST and INTEST instructions. These instructions either force data out of the controller, with the EXTEST instruction, or into the controller, with the INTEST instruction.

Figure 5-5. Boundary Scan Register Format



For detailed information on the order of the input, output, and output enable bits for each of the GPIO ports, please refer to the Stellaris[®] Family Boundary Scan Description Language (BSDL) files, downloadable from www.luminarymicro.com.

5.4.2.4 APACC Data Register

The format for the 35-bit APACC Data Register defined by ARM is described in the *ARM*® *Cortex*™-*M3 Technical Reference Manual*.

5.4.2.5 DPACC Data Register

The format for the 35-bit DPACC Data Register defined by ARM is described in the *ARM*® Cortex™-M3 Technical Reference Manual.

5.4.2.6 ABORT Data Register

The format for the 35-bit ABORT Data Register defined by ARM is described in the *ARM*® *Cortex*™-*M3 Technical Reference Manual*.

6 System Control

System control determines the overall operation of the device. It provides information about the device, controls the clocking to the core and individual peripherals, and handles reset detection and reporting.

6.1 Functional Description

The System Control module provides the following capabilities:

- Device identification, see "Device Identification" on page 59
- Local control, such as reset (see "Reset Control" on page 59), power (see "Power Control" on page 62) and clock control (see "Clock Control" on page 62)
- System control (Run, Sleep, and Deep-Sleep modes), see "System Control" on page 64

6.1.1 Device Identification

Seven read-only registers provide software with information on the microcontroller, such as version, part number, SRAM size, flash size, and other features. See the **DID0**, **DID1**, and **DC0-DC4** registers.

6.1.2 Reset Control

This section discusses aspects of hardware functions during reset as well as system software requirements following the reset sequence.

6.1.2.1 CMODO and CMOD1 Test-Mode Control Pins

Two pins, CMOD0 and CMOD1, are defined for use by Luminary Micro for testing the devices during manufacture. They have no end-user function and should not be used. The CMOD pins should be connected to ground.

6.1.2.2 Reset Sources

The controller has five sources of reset:

- External reset input pin (RST) assertion, see "RST Pin Assertion" on page 59.
- 2. Power-on reset (POR), see "Power-On Reset (POR)" on page 60.
- 3. Internal brown-out (BOR) detector, see "Brown-Out Reset (BOR)" on page 60.
- 4. Software-initiated reset (with the software reset registers), see "Software Reset" on page 61.
- A watchdog timer reset condition violation, see "Watchdog Timer Reset" on page 61.

After a reset, the **Reset Cause (RESC)** register is set with the reset cause. The bits in this register are sticky and maintain their state across multiple reset sequences, except when an internal POR is the cause, and then all the other bits in the **RESC** register are cleared except for the POR indicator.

6.1.2.3 RST Pin Assertion

The external reset pin (\overline{RST}) resets the controller. This resets the core and all the peripherals except the JTAG TAP controller (see "JTAG Interface" on page 48). The external reset sequence is as follows:

- 1. The external reset pin (RST) is asserted and then de-asserted.
- 2. The internal reset is released and the core loads from memory the initial stack pointer, the initial program counter, the first instruction designated by the program counter, and begins execution. A few clocks cycles from RST de-assertion to the start of the reset sequence is necessary for synchronization.

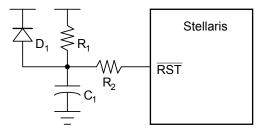
The external reset timing is shown in Figure 23-10 on page 523.

6.1.2.4 Power-On Reset (POR)

The Power-On Reset (POR) circuit monitors the power supply voltage (V_{DD}). The POR circuit generates a reset signal to the internal logic when the power supply ramp reaches a threshold value (V_{TH}). If the application only uses the POR circuit, the $\overline{\tt RST}$ input needs to be connected to the power supply (V_{DD}) through a pull-up resistor (1K to 10K Ω).

The device must be operating within the specified operating parameters at the point when the on-chip power-on reset pulse is complete. The 3.3-V power supply to the device must reach 3.0 V within 10 msec of it crossing 2.0 V to guarantee proper operation. For applications that require the use of an external reset to hold the device in reset longer than the internal POR, the RST input may be used with the circuit as shown in Figure 6-1 on page 60.

Figure 6-1. External Circuitry to Extend Reset



The R_1 and C_1 components define the power-on delay. The R_2 resistor mitigates any leakage from the \overline{RST} input. The diode (D₁) discharges C_1 rapidly when the power supply is turned off.

The Power-On Reset sequence is as follows:

- 1. The controller waits for the later of external reset (RST) or internal POR to go inactive.
- 2. The internal reset is released and the core loads from memory the initial stack pointer, the initial program counter, the first instruction designated by the program counter, and begins execution.

The internal POR is only active on the initial power-up of the controller. The Power-On Reset timing is shown in Figure 23-11 on page 524.

Note: The power-on reset also resets the JTAG controller. An external reset does not.

6.1.2.5 Brown-Out Reset (BOR)

A drop in the input voltage resulting in the assertion of the internal brown-out detector can be used to reset the controller. This is initially disabled and may be enabled by software.

The system provides a brown-out detection circuit that triggers if the power supply (V_{DD}) drops below a brown-out threshold voltage (V_{BTH}) . If a brown-out condition is detected, the system may generate a controller interrupt or a system reset.

Brown-out resets are controlled with the **Power-On and Brown-Out Reset Control (PBORCTL)** register. The BORIOR bit in the **PBORCTL** register must be set for a brown-out condition to trigger a reset.

The brown-out reset is equivelent to an assertion of the external $\overline{\mathtt{RST}}$ input and the reset is held active until the proper V_{DD} level is restored. The **RESC** register can be examined in the reset interrupt handler to determine if a Brown-Out condition was the cause of the reset, thus allowing software to determine what actions are required to recover.

The internal Brown-Out Reset timing is shown in Figure 23-12 on page 524.

6.1.2.6 Software Reset

Software can generate a reset to the entire system or may reset a specific peripheral.

Peripherals can be individually reset by software via three registers that control reset signals to each peripheral (see the **SRCRn** registers). If the bit position corresponding to a peripheral is set, the peripheral is reset. The encoding of the reset registers is consistent with the encoding of the clock gating control for peripherals and on-chip functions (see "System Control" on page 64). Writing a bit lane with a value of 1 initiates a reset of the corresponding unit. Note that all reset signals for all clocks of the specified unit are asserted as a result of a software-initiated reset.

The entire system can be reset by software by setting the SYSRESETREQ bit in the Cortex-M3 Application Interrupt and Reset Control register resets the entire system including the core. The software-initiated system reset sequence is as follows:

- 1. A software system reset is initiated by writing the SYSRESETREQ bit in the ARM Cortex-M3 Application Interrupt and Reset Control register.
- 2. An internal reset is asserted.
- 3. The internal reset is deasserted and the controller loads from memory the initial stack pointer, the initial program counter, and the first instruction designated by the program counter, and then begins execution.

The software-initiated system reset timing is shown in Figure 23-13 on page 524.

6.1.2.7 Watchdog Timer Reset

The watchdog timer module's function is to prevent system hangs. The watchdog timer can be configured to generate an interrupt to the controller on its first time-out, and to generate a reset signal on its second time-out.

After the first time-out event, the 32-bit counter is reloaded with the value of the **Watchdog Timer Load (WDTLOAD)** register, and the timer resumes counting down from that value. If the timer counts down to its zero state again before the first time-out interrupt is cleared, and the reset signal has been enabled, the watchdog timer asserts its reset signal to the system. The watchdog timer reset sequence is as follows:

- 1. The watchdog timer times out for the second time without being serviced.
- 2. An internal reset is asserted.
- The internal reset is released and the controller loads from memory the initial stack pointer, the initial program counter, the first instruction designated by the program counter, and begins execution.

The watchdog reset timing is shown in Figure 23-14 on page 524.

6.1.3 Power Control

The Stellaris microcontroller provides an integrated LDO regulator that may be used to provide power to the majority of the controller's internal logic. The LDO regulator provides software a mechanism to adjust the regulated value, in small increments (VSTEP), over the range of 2.25 V to 2.75 V (inclusive)—or 2.5 V \pm 10%. The adjustment is made by changing the value of the VADJ field in the **LDO Power Control (LDOPCTL)** register.

Note: The use of the LDO is optional. The internal logic may be supplied by the on-chip LDO or by an external regulator. If the LDO is used, the LDO output pin is connected to the VDD25 pins on the printed circuit board. The LDO requires decoupling capacitors on the printed circuit board. If an external regulator is used, it is strongly recommended that the external regulator supply the controller only and not be shared with other devices on the printed circuit board.

6.1.4 Clock Control

System control determines the control of clocks in this part.

6.1.4.1 Fundamental Clock Sources

There are four clock sources for use in the device:

- Internal Oscillator (IOSC): The internal oscillator is an on-chip clock source. It does not require the use of any external components. The frequency of the internal oscillator is 12 MHz ± 30%. Applications that do not depend on accurate clock sources may use this clock source to reduce system cost. The internal oscillator is the clock source the device uses during and following POR. If the main oscillator is required, software must enable the main oscillator following reset and allow the main oscillator to stabilize before changing the clock reference.
- Main Oscillator: The main oscillator provides a frequency-accurate clock source by one of two means: an external single-ended clock source is connected to the OSC0 input pin, or an external crystal is connected across the OSC0 input and OSC1 output pins. The crystal value allowed depends on whether the main oscillator is used as the clock reference source to the PLL. If so, the crystal must be one of the supported frequencies between 3.579545 MHz through 8.192 MHz (inclusive). If the PLL is not being used, the crystal may be any one of the supported frequencies between 1 MHz and 8.192 MHz. The single-ended clock source range is from DC through the specified speed of the device. The supported crystals are listed in Table 6-3 on page 78.
- Internal 30-kHz oscillator: The internal 30-kHz oscillator is similar to the internal oscillator, except that it provides an operational frequency of 30 kHz ± 30%. It is intended for use during Deep-Sleep power-saving modes. This power-savings mode benefits from reduced internal switching and also allows the main oscillator to be powered down.
- External real-time oscillator: The external real-time oscillator provides a low-frequency, accurate clock reference. It is intended to provide the system with a real-time clock source. The real-time oscillator is part of the Hibernation Module ("Hibernation Module" on page 113) and may also provide an accurate source of Deep-Sleep or Hibernate mode power savings.

The internal system clock (sysclk), is derived from any of the four sources plus two others: the output of the internal PLL, and the internal oscillator divided by four (3 MHz \pm 30%). The frequency of the PLL clock reference must be in the range of 3.579545 MHz to 8.192 MHz (inclusive).

The Run-Mode Clock Configuration (RCC) and Run-Mode Clock Configuration 2 (RCC2) registers provide control for the system clock. The RCC2 register is provided to extend fields that offer additional encodings over the RCC register. When used, the RCC2 register field values are used by the logic over the corresponding field in the RCC register. In particular, RCC2 provides for a larger assortment of clock configuration options.

6.1.4.2 Crystal Configuration for the Main Oscillator (MOSC)

The main oscillator supports the use of a select number of crystals in the range of 1 MHz through 8.192 MHz. This method allows Luminary Micro to provide the best possible PLL settings.

Table 6-3 on page 78 describes the available crystal choices and default programming values.

Software configures the **RCC** register XTAL field with the crystal number. If the PLL is used in the design, the XTAL field value is internally translated to the PLL settings.

6.1.4.3 PLL Frequency Configuration

The PLL is disabled by default during power-on reset and is enabled later by software if required. Software configures the PLL input reference clock source, specifies the output divisor to set the system clock frequency, and enables the PLL to drive the output.

If the main oscillator provides the clock reference to the PLL, the translation provided by hardware and used to program the PLL is available for software in the **XTAL to PLL Translation (PLLCFG)** register (see page 79). The internal translation provides a translation within \pm 1% of the targetted PLL VCO frequency.

Table 6-3 on page 78 describes the available crystal choices and default programming of the **PLLCFG** register. The crystal number is written into the XTAL field of the **Run-Mode Clock Configuration (RCC)** register. Any time the XTAL field changes, the new settings are translated and the internal PLL settings are updated.

6.1.4.4 PLL Modes

The PLL has two modes of operation: Normal and Power-Down

- Normal: The PLL multiplies the input clock reference and drives the output.
- Power-Down: Most of the PLL internal circuitry is disabled and the PLL does not drive the output.

The modes are programmed using the RCC/RCC2 register fields (see page 75 and page 80).

6.1.4.5 PLL Operation

If the PLL configuration is changed, the PLL output frequency is unstable until it reconverges (relocks) to the new setting. The time between the configuration change and relock is T_{READY} (see Table 23-6 on page 516). During this time, the PLL is not usable as a clock reference.

The PLL is changed by one of the following:

- Change to the XTAL value in the RCC register—writes of the same value do not cause a relock.
- Change in the PLL from Power-Down to Normal mode.

A counter is defined to measure the T_{READY} requirement. The counter is clocked by the main oscillator. The range of the main oscillator has been taken into account and the down counter is set to 0x1200 (that is, ~600 μ s at a 8.192 MHz external oscillator clock). Hardware is provided to keep the PLL from being used as a system clock until the T_{READY} condition is met after one of the two

changes above. It is the user's responsibility to have a stable clock source (like the main oscillator) before the **RCC/RCC2** register is switched to use the PLL.

6.1.5 System Control

For power-savings purposes, the **RCGCn**, **SCGCn**, and **DCGCn** registers control the clock gating logic for each peripheral or block in the system while the controller is in Run, Sleep, and Deep-Sleep mode, respectively.

In Run mode, the processor executes code. In Sleep mode, the clock frequency of the active peripherals is unchanged, but the processor is not clocked and therefore no longer executes code. In Deep-Sleep mode, the clock frequency of the active peripherals may change (depending on the Run mode clock configuration) in addition to the processor clock being stopped. An interrupt returns the device to Run mode from one of the sleep modes; the sleep modes are entered on request from the code. Each mode is described in more detail below.

There are four levels of operation for the device defined as:

- Run Mode. Run Mode provides normal operation of the processor and all of the peripherals that are currently enabled by the RCGCn registers. The system clock can be any of the available clock sources including the PLL.
- Sleep Mode. Sleep mode is entered by the Cortex-M3 core executing a WFI (Wait for Interrupt) instruction. Any properly configured interrupt event in the system will bring the processor back into Run mode. See the system control NVIC section of the ARM® Cortex™-M3 Technical Reference Manual for more details.
 - In Sleep Mode, the Cortex-M3 processor core and the memory subsystem are not clocked. Peripherals are clocked that are enabled in the **SCGCn** register when auto-clock gating is enabled (see the **RCC** register) or the **RCGCn** register when the auto-clock gating is disabled. The system clock has the same source and frequency as that during Run mode.
- Deep-Sleep Mode. Deep-Sleep mode is entered by first writing the Deep Sleep Enable bit in the ARM Cortex-M3 NVIC system control register and then executing a WFI instruction. Any properly configured interrupt event in the system will bring the processor back into Run mode. See the system control NVIC section of the ARM® Cortex™-M3 Technical Reference Manual for more details.
 - The Cortex-M3 processor core and the memory subsystem are not clocked. Peripherals are clocked that are enabled in the **DCGCn** register when auto-clock gating is enabled (see the **RCC** register) or the **RCGCn** register when auto-clock gating is disabled. The system clock source is the main oscillator by default or the internal oscillator specified in the **DSLPCLKCFG** register if one is enabled. When the **DSLPCLKCFG** register is used, the internal oscillator is powered up, if necessary, and the main oscillator is powered down. If the PLL is running at the time of the WFI instruction, hardware will power the PLL down and override the SYSDIV field of the active **RCC/RCC2** register to be /16 or /64, respectively. When the Deep-Sleep exit event occurs, hardware brings the system clock back to the source and frequency it had at the onset of Deep-Sleep mode before enabling the clocks that had been stopped during the Deep-Sleep duration.
- Hibernate Mode. In this mode, the power supplies are turned off to the main part of the device and only the Hibernation module's circuitry is active. An external wake event or RTC event is required to bring the device back to Run mode. The Cortex-M3 processor and peripherals outside of the Hibernation module see a normal "power on" sequence and the processor starts running

code. It can determine that it has been restarted from Hibernate mode by inspecting the Hibernation module registers.

6.2 Initialization and Configuration

The PLL is configured using direct register writes to the RCC/RCC2 register. If the RCC2 register is being used, the USERCC2 bit must be set and the appropriate RCC2 bit/field is used. The steps required to successfully change the PLL-based system clock are:

- 1. Bypass the PLL and system clock divider by setting the BYPASS bit and clearing the USESYS bit in the RCC register. This configures the system to run off a "raw" clock source (using the main oscillator or internal oscillator) and allows for the new PLL configuration to be validated before switching the system clock to the PLL.
- 2. Select the crystal value (XTAL) and oscillator source (OSCSRC), and clear the PWRDN bit in RCC/RCC2. Setting the XTAL field automatically pulls valid PLL configuration data for the appropriate crystal, and clearing the PWRDN bit powers and enables the PLL and its output.
- 3. Select the desired system divider (SYSDIV) in RCC/RCC2 and set the USESYS bit in RCC. The SYSDIV field determines the system frequency for the microcontroller.
- 4. Wait for the PLL to lock by polling the PLLLRIS bit in the **Raw Interrupt Status (RIS)** register.
- 5. Enable use of the PLL by clearing the BYPASS bit in RCC/RCC2.

6.3 Register Map

"Register Map" on page 65 lists the System Control registers, grouped by function. The offset listed is a hexadecimal increment to the register's address, relative to the System Control base address of 0x400F.E000.

Note: Spaces in the System Control register space that are not used are reserved for future or internal use by Luminary Micro, Inc. Software should not modify any reserved memory address.

Note: A BV in the Reset column indicates the reset value is a Build Value and part-specific. See the page number referenced for the reset value description.

Table 6-1. System Control Register Map

Offset	Name	Type	Reset	Description	See page
0x000	DID0	RO	-	Device Identification 0	67
0x004	DID1	RO	BV	Device Identification 1	83
0x008	DC0	RO	BV	Device Capabilities 0	85
0x010	DC1	RO	BV	Device Capabilities 1	86
0x014	DC2	RO	BV	Device Capabilities 2	88
0x018	DC3	RO	BV	Device Capabilities 3	89
0x01C	DC4	RO	BV	Device Capabilities 4	91
0x030	PBORCTL	R/W	0x0000.7FFD	Brown-Out Reset Control	69

Offset	Name	Type	Reset	Description	See page
0x034	LDOPCTL	R/W	0x0000.0000	LDO Power Control	70
0x040	SRCR0	R/W	0x00000000	Software Reset Control 0	110
0x044	SRCR1	R/W	0x00000000	Software Reset Control 1	111
0x048	SRCR2	R/W	0x00000000	Software Reset Control 2	112
0x050	RIS	RO	0x0000.0000	Raw Interrupt Status	71
0x054	IMC	R/W	0x0000.0000	Interrupt Mask Control	72
0x058	MISC	R/W1C	0x0000.0000	Masked Interrupt Status and Clear	73
0x05C	RESC	R/W	-	Reset Cause	74
0x060	RCC	R/W	0x07AE.3AD1	Run-Mode Clock Configuration	75
0x064	PLLCFG	RO	-	XTAL to PLL Translation	79
0x070	RCC2	R/W	0x0780.2800	Run-Mode Clock Configuration 2	80
0x100	RCGC0	R/W	0x00000040	Run Mode Clock Gating Control Register 0	92
0x104	RCGC1	R/W	0x00000000	Run Mode Clock Gating Control Register 1	98
0x108	RCGC2	R/W	0x00000000	Run Mode Clock Gating Control Register 2	104
0x110	SCGC0	R/W	0x00000040	Sleep Mode Clock Gating Control Register 0	94
0x114	SCGC1	R/W	0x00000000	Sleep Mode Clock Gating Control Register 1	100
0x118	SCGC2	R/W	0x00000000	Sleep Mode Clock Gating Control Register 2	106
0x120	DCGC0	R/W	0x00000040	Deep Sleep Mode Clock Gating Control Register 0	96
0x124	DCGC1	R/W	0x00000000	Deep Sleep Mode Clock Gating Control Register 1	102
0x128	DCGC2	R/W	0x00000000	Deep Sleep Mode Clock Gating Control Register 2	108
0x144	DSLPCLKCFG	R/W	0x0780.0000	Deep Sleep Clock Configuration	82

6.4 Register Descriptions

All addresses given are relative to the System Control base address of 0x400F.E000.

Register 1: Device Identification 0 (DID0), offset 0x000

Reset

1

This register identifies the version of the device.

Type

RO

Device Identification 0 (DID0)

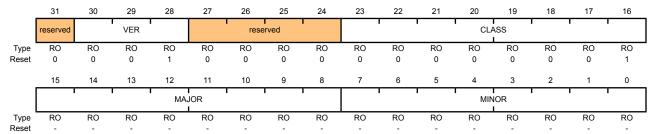
Name

CLASS

Base 0x400F.E000 Offset 0x000 Type RO, reset -

Bit/Field

23:16



31	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
30:28	VER	RO	1	This field defines the $\textbf{DID0}$ register format version. The version number is numeric. The value of the \mathtt{VER} field is encoded as follows:

Description

Value Description

 First revision of the **DID0** register format, for Stellaris® Fury-class devices.

27:24	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

The CLASS field value identifies the internal design from which all mask sets are generated for all devices in a particular product line. The CLASS field value is changed for new product lines, for changes in fab process (for example, a remap or shrink), or any case where the MAJOR OR MINOR fields require differentiation from prior devices. The value of the CLASS field is encoded as follows (all other encodings are reserved):

Value Description

- 0 Stellaris® Sandstorm-class devices.
- Stellaris® Fury-class devices.

Bit/Field	Name	Туре	Reset	Description
15:8	MAJOR	RO	-	This field specifies the major revision number of the device. The major revision reflects changes to base layers of the design. The major revision number is indicated in the part number as a letter (A for first revision, B for second, and so on). This field is encoded as follows:
				Value Description
				0 Revision A (initial device)
				1 Revision B (first base layer revision)
				2 Revision C (second base layer revision)
				and so on.
7:0	MINOR	RO	-	This field specifies the minor revision number of the device. The minor revision reflects changes to the metal layers of the design. The ${\tt MINOR}$ field value is reset when the ${\tt MAJOR}$ field is changed. This field is numeric and is encoded as follows:
				Value Description
				0 Initial device, or a major revision update.
				1 First metal layer change.
				2 Second metal layer change.
				and so on.

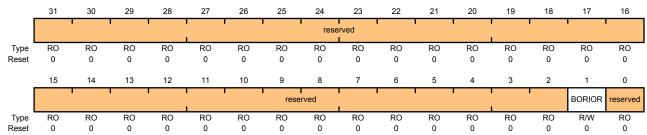
Register 2: Brown-Out Reset Control (PBORCTL), offset 0x030

This register is responsible for controlling reset conditions after initial power-on reset.

Brown-Out Reset Control (PBORCTL)

Base 0x400F.E000

Offset 0x030 Type R/W, reset 0x0000.7FFD



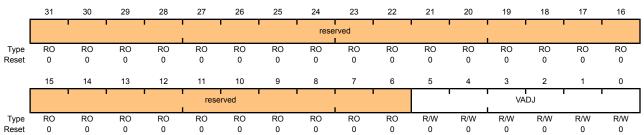
Bit/Field	Name	Туре	Reset	Description
31:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	BORIOR	R/W	0	BOR Interrupt or Reset
				This bit controls how a BOR event is signaled to the controller. If set, a reset is signaled. Otherwise, an interrupt is signaled.
0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

Register 3: LDO Power Control (LDOPCTL), offset 0x034

The \mathtt{VADJ} field in this register adjusts the on-chip output voltage ($\mathsf{V}_{\mathsf{OUT}}$).

LDO Power Control (LDOPCTL)

Base 0x400F.E000 Offset 0x034 Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:6	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
5:0	VADJ	R/W	0x0	This field sets the on-chip output voltage. The programming values for the VADJ field are provided in Table 6-2 on page 70.

Table 6-2. VADJ to VOUT

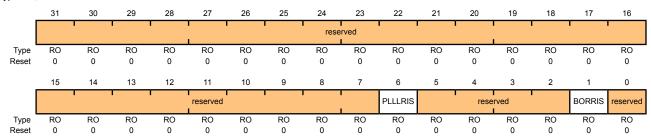
VADJ Value	$V_{OUT}\left(V\right)$	VADJ Value	$V_{OUT}\left(V\right)$	VADJ Value	V _{OUT} (V)
0x1B	2.75	0x1F	2.55	0x03	2.35
0x1C	2.70	0x00	2.50	0x04	2.30
0x1D	2.65	0x01	2.45	0x05	2.25
0x1E	2.60	0x02	2.40	0x06-0x3F	Reserved

Register 4: Raw Interrupt Status (RIS), offset 0x050

Central location for system control raw interrupts. These are set and cleared by hardware.

Raw Interrupt Status (RIS)

Base 0x400F.E000 Offset 0x050 Type RO, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:7	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
6	PLLLRIS	RO	0	PLL Lock Raw Interrupt Status
				This bit is set when the PLL $\mathrm{T}_{\mathrm{READY}}$ Timer asserts.
5:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	BORRIS	RO	0	Brown-Out Reset Raw Interrupt Status
				This bit is the raw interrupt status for any brown-out conditions. If set, a brown-out condition is currently active. This is an unregistered signal from the brown-out detection circuit. An interrupt is reported if the BORIM bit in the IMC register is set and the BORIOR bit in the PBORCTL register is cleared.
0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

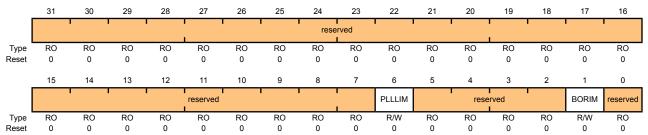
Register 5: Interrupt Mask Control (IMC), offset 0x054

Central location for system control interrupt masks.

Interrupt Mask Control (IMC)

Base 0x400F.E000

Offset 0x054 Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:7	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
6	PLLLIM	R/W	0	PLL Lock Interrupt Mask
				This bit specifies whether a current limit detection is promoted to a controller interrupt. If set, an interrupt is generated if PLLLRIS in RIS is set; otherwise, an interrupt is not generated.
5:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	BORIM	R/W	0	Brown-Out Reset Interrupt Mask
				This bit specifies whether a brown-out condition is promoted to a controller interrupt. If set, an interrupt is generated if BORRIS is set; otherwise, an interrupt is not generated.
0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

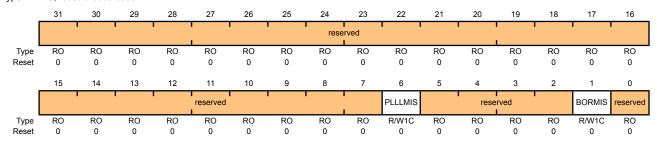
Register 6: Masked Interrupt Status and Clear (MISC), offset 0x058

Central location for system control result of RIS AND IMC to generate an interrupt to the controller. All of the bits are R/W1C and this action also clears the corresponding raw interrupt bit in the **RIS** register (see page 71).

Masked Interrupt Status and Clear (MISC)

Base 0x400F.E000

Offset 0x058
Type R/W1C, reset 0x0000.0000



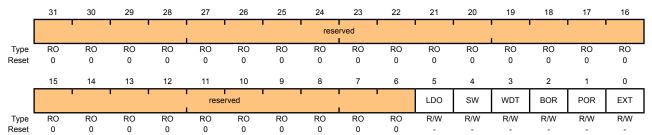
Bit/Field	Name	Туре	Reset	Description
31:7	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
6	PLLLMIS	R/W1C	0	PLL Lock Masked Interrupt Status
				This bit is set when the PLL T_{READY} timer asserts. The interrupt is cleared by writing a 1 to this bit.
5:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	BORMIS	R/W1C	0	The BORMIS is simply the BORRIS ANDed with the mask value, BORIM.
0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

Register 7: Reset Cause (RESC), offset 0x05C

This register is set with the reset cause after reset. The bits in this register are sticky and maintain their state across multiple reset sequences, except when an external reset is the cause, and then all the other bits in the **RESC** register are cleared.

Reset Cause (RESC)

Base 0x400F.E000 Offset 0x05C Type R/W, reset -



Bit/Field	Name	Туре	Reset	Description
31:6	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
5	LDO	R/W	-	When set, indicates the LDO circuit has lost regulation and has generated a reset event.
4	SW	R/W	-	When set, indicates a software reset is the cause of the reset event.
3	WDT	R/W	-	When set, indicates a watchdog reset is the cause of the reset event.
2	BOR	R/W	-	When set, indicates a brown-out reset is the cause of the reset event.
1	POR	R/W	-	When set, indicates a power-on reset is the cause of the reset event.
0	EXT	R/W	-	When set, indicates an external reset ($\overline{\tt RST}$ assertion) is the cause of the reset event.

Register 8: Run-Mode Clock Configuration (RCC), offset 0x060

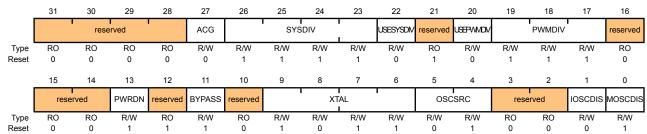
This register is defined to provide source control and frequency speed.

Run-Mode Clock Configuration (RCC)

Base 0x400F.E000 Offset 0x060

27

Type R/W, reset 0x07AE.3AD1



Bit/Field	Name	Туре	Reset	Description
31:28	reserved	RO	0x0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

R/W

0

ACG

Auto Clock Gating

This bit specifies whether the system uses the Sleep-Mode Clock Gating Control (SCGCn) registers and Deep-Sleep-Mode Clock Gating Control (DCGCn) registers if the controller enters a Sleep or Deep-Sleep mode (respectively). If set, the SCGCn or DCGCn registers are used to control the clocks distributed to the peripherals when the controller is in a sleep mode. Otherwise, the Run-Mode Clock Gating Control (RCGCn) registers are used when the controller enters a sleep mode.

The **RCGCn** registers are always used to control the clocks in Run mode.

This allows peripherals to consume less power when the controller is in a sleep mode and the peripheral is unused.

Bit/Field	Name	Туре	Reset	Description					
26:23	SYSDIV	R/W	0xF	System Clock Divisor					
				Specifies which divisor is used to generate the system clock from PLL output.					
				The PLL VCO frequency is 400 MHz.					
				Binary Value	Divisor (BYPASS=1)	Frequency (BYPASS=0)			
				0000-0010	reserved	reserved			
				0011	/8	50 MHz			
				0100	/10	40 MHz			
				0101	/12	33.33 MHz			
				0110	/14	28.57 MHz			
				0111	/16	25 MHz			
				1000	/18	22.22 MHz			
				1001	/20	20 MHz			
				1010	/22	18.18 MHz			
				1011	/24	16.67 MHz			
				1100	/26	15.38 MHz			
				1101	/28	14.29 MHz			
				1110	/30	13.33 MHz			
				1111	/32	12.5 MHz (default)			
				page 75), the requested and	When reading the Run-Mode Clock Configuration (RCC) register (see page 75), the SYSDIV value is MINSYSDIV if a lower divider was requested and the PLL is being used. This lower value is allowed to divide a non-PLL source.				
22	USESYSDIV	R/W	0			source for the system clock. The sed when the PLL is selected as			
21	reserved	RO	1	compatibility w		of a reserved bit. To provide value of a reserved bit should be operation.			
20	USEPWMDIV	R/W	0	Use the PWM	clock divider as the so	urce for the PWM clock.			

Bit/Field	Name	Туре	Reset	Description
19:17	PWMDIV	R/W	0x7	PWM Unit Clock Divisor
				This field specifies the binary divisor used to predivide the system clock down for use as the timing reference for the PWM module. This clock is only power 2 divide and rising edge is synchronous without phase shift from the system clock.
				Binary Value Divisor
				000 /2
				001 /4
				010 /8
				011 /16
				100 /32
				101 /64
				110 /64
				111 /64 (default)
16:14	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
13	PWRDN	R/W	1	PLL Power Down
				This bit connects to the PLL PWRDN input. The reset value of 1 powers down the PLL.
12	reserved	RO	1	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
11	BYPASS	R/W	1	PLL Bypass
				Chooses whether the system clock is derived from the PLL output or the OSC source. If set, the clock that drives the system is the OSC source. Otherwise, the clock that drives the system is the PLL output clock divided by the system divider.
				Note: The ADC must be clocked from the PLL or directly from a 14-MHz to 18-MHz clock source to operate properly. While the ADC works in a 14-18 MHz range, to maintain a 1 M sample/second rate, the ADC must be provided a 16-MHz clock source.
10	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
9:6	XTAL	R/W	0xB	This field specifies the crystal value attached to the main oscillator. The encoding for this field is provided in Table 6-3 on page 78.

Bit/Field	Name	Туре	Reset	Description
5:4	OSCSRC	R/W	0x1	Picks among the four input sources for the OSC. The values are:
				Value Input Source
				00 Main oscillator (default)
				01 Internal oscillator (default)
				10 Internal oscillator / 4 (this is necessary if used as input to PLL)
				11 reserved
3:2	reserved	RO	0x0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	IOSCDIS	R/W	0	Internal Oscillator (IOSC) Disable
				0: Internal oscillator is enabled.
				1: Internal oscillator is disabled.
0	MOSCDIS	R/W	1	Main Oscillator Disable
				0: Main oscillator is enabled.

Table 6-3. Default Crystal Field Values and PLL Programming

Crystal Number (XTAL Binary Value)	Crystal Frequency (MHz) Not Using the PLL	Crystal Frequency (MHz) Using the PLL					
0000	1.000	reserved					
0001	1.8432	reserved					
0010	2.000	reserved					
0011	2.4576	reserved					
0100	3.5795	45 MHz					
0101	3.686	4 MHz					
0110	4 MHz						
0111	4.096 MHz						
1000	4.915	2 MHz					
1001	51	MHz					
1010	5.12	! MHz					
1011	6 MHz (re	eset value)					
1100	6.14	4 MHz					
1101	7.372	8 MHz					
1110	18	ИНz					
1111	8.19	2 MHz					

1: Main oscillator is disabled (default).

Register 9: XTAL to PLL Translation (PLLCFG), offset 0x064

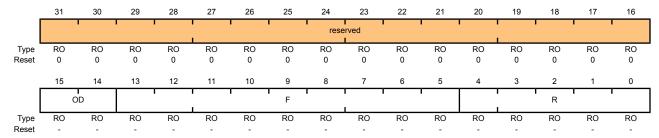
This register provides a means of translating external crystal frequencies into the appropriate PLL settings. This register is initialized during the reset sequence and updated anytime that the XTAL field changes in the **Run-Mode Clock Configuration (RCC)** register (see page 75).

The PLL frequency is calculated using the PLLCFG field values, as follows:

PLLFreq = OSCFreq * F / (R + 1)

XTAL to PLL Translation (PLLCFG)

Base 0x400F.E000 Offset 0x064 Type RO, reset -



Bit/Field	Name	Type	Reset	Description
31:16	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15:14	OD	RO	-	This field specifies the value supplied to the PLL's OD input.
13:5	F	RO	-	This field specifies the value supplied to the PLL's F input.
4:0	R	RO	-	This field specifies the value supplied to the PLL's R input.

Register 10: Run-Mode Clock Configuration 2 (RCC2), offset 0x070

This register overrides the RCC equivalent register fields when the USERCC2 bit is set. This allows RCC2 to be used to extend the capabilities, while also providing a means to be backward-compatible to previous parts. The fields within the RCC2 register occupy the same bit positions as they do within the RCC register as LSB-justified.

The SYSDIV2 field is wider so that additional larger divisors are possible. This allows a lower system clock frequency for improved Deep Sleep power consumption.

Run-Mode Clock Configuration 2 (RCC2)

Base 0x400F.E000 Offset 0x070 Type R/W, reset 0x0780.2800

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16		
	USERCC2	rese	erved			SYS	SDIV2	•	! !		reserved							
Type Reset	R/W 0	RO 0	RO 0	R/W 0	R/W 0	R/W 1	R/W 1	R/W 1	R/W 1	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0		
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0		
	reser	ved	PWRDN2	reserved	BYPASS2		rese	erved			OSCSRC2	!	ı	rese	rved			
Type Reset	RO 0	RO 0	R/W 1	RO 0	R/W 1	RO 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0	RO 0	RO 0	RO 0	RO 0		
reset	U	U	'	U	'	O	U	U	Ü	O	U	O	U	U	U	U		
Bit/F	ield		Name		Type	ı	Reset		Description									
31	I	ι	JSERCC	2	R/W	R/W 0		When set, overrides the RCC register fields.										
30:2	29		reserved		RO	RO 0			Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.									
28:2	23	,	SYSDIV2	2	R/W		0x0F	Syste	m Clock	Divisor	(6-bit)							
								Speci PLL o		h diviso	r is used	I to gene	erate the	system	clock fro	m the		
								The P	LL VCO	frequer	ncy is 40	0 MHz.						
								addition much the R 0	onal divisional divisi	sor value equencie eter syst	es. This es during DIV enc	permits Deep Soding of	r SYSDIV the syste Gleep mod 111 prov provides	em clock de. For d rides /16	to be ruexample	in at , where		
22:	14		reserved		RO		0	compa	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.									
13	3	F	PWRDN2	2	R/W		1	When	set, pov	vers dov	vn the P	LL.						
12	2		reserved		RO		0	compa	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.									
11		E	BYPASS2	2	R/W		1	When	set, byp	asses t	he PLL f	or the cl	ock sour	ce.				
10:	7		reserved		RO		0	compa	atibility v	vith futur	e produ	cts, the v	of a rese alue of a	a reserv				

Bit/Field	Name	Туре	Reset	Description					
6:4	OSCSRC2	R/W	0	System Clock Source					
				Name Value Description					
				MOSC 0 Main oscillator					
				IOSC 1 Internal oscillator					
				IOSC/4 2 Internal oscillator / 4					
				30kHz 3 30 kHz internal oscillator					
				32kHz 7 32 kHz external oscillator					
3:0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.					

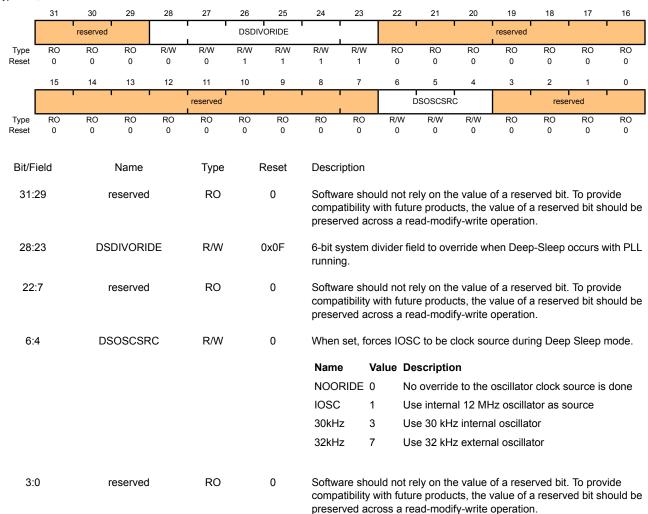
Register 11: Deep Sleep Clock Configuration (DSLPCLKCFG), offset 0x144

This register provides configuration information for the hardware control of Deep Sleep Mode.

Deep Sleep Clock Configuration (DSLPCLKCFG)

Base 0x400F.E000 Offset 0x144

Type R/W, reset 0x0780.0000



Register 12: Device Identification 1 (DID1), offset 0x004

This register identifies the device family, part number, temperature range, pin count, and package type.

Device Identification 1 (DID1)

Base 0x400F.E000 Offset 0x004 Type RO

•	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	
		VE	ER	1	'	FAM			PARTNO								
Type Reset	RO 0	RO 0	RO 0	RO 1	RO 0	RO 0	RO 0	RO 0	RO 0	RO 1	RO 0	RO 1	RO 0	RO 0	RO 1	RO 0	
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
		PINCOUNT	Ī		' '	reserved	•	'		TEMP		Pł	(G	ROHS	QU	AL	
Type Reset	RO 0	RO 1	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 1	RO 0	RO 1	RO 1	RO -	RO -	
Bit/Fi	eld	d Name			Туре	F	Reset	Description									
31:2	8 VER				RO		0x1	is nun	neric. Th		of the v			sion. The ded as fol			
								Value	Desci	iption							
								0x1		evision o nnnn de\		D1 regis	ter form	at, indica	ting a Si	tellaris	
27:2	27:24 FAM		RO	RO 0x0			Family										
								This field provides the family identification of the device within the Luminary Micro product portfolio. The value is encoded as follows (all other encodings are reserved):									
								Value Description									
								0x0		ris family al part n				is, all de 13S.	vices wit	th	
23:	16	F	PARTNO)	RO		0x52	Part N	lumber								
								This field provides the part number of the device within the family. The value is encoded as follows (all other encodings are reserved):									
								Value Description									
								0x52	LM3S	2739							
15:1	13	PI	NCOUN	Т	RO		0x2	Packa	ige Pin (Count							
									This field specifies the number of pins on the device package. The value is encoded as follows (all other encodings are reserved):								
								Value	Desci	iption							

0x2 100-pin package

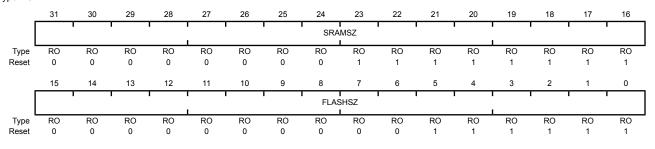
Bit/Field	Name	Туре	Reset	Description
12:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:5	TEMP	RO	0x1	Temperature Range
				This field specifies the temperature rating of the device. The value is encoded as follows (all other encodings are reserved):
				Value Description
				0x1 Industrial temperature range (-40C to 85C)
4:3	PKG	RO	0x1	Package Type
				This field specifies the package type. The value is encoded as follows (all other encodings are reserved):
				Value Description
				0x1 LQFP package
2	ROHS	RO	1	RoHS-Compliance
				This bit specifies whether the device is RoHS-compliant. A 1 indicates the part is RoHS-compliant.
1:0	QUAL	RO	-	Qualification Status
				This field specifies the qualification status of the device. The value is encoded as follows (all other encodings are reserved):
				Value Description
				0x0 Engineering Sample (unqualified)
				0x1 Pilot Production (unqualified)
				0x2 Fully Qualified

Register 13: Device Capabilities 0 (DC0), offset 0x008

This register is predefined by the part and can be used to verify features.

Device Capabilities 0 (DC0)

Base 0x400F.E000 Offset 0x008 Type RO



Bit/Field	Name	Туре	Reset	Description
31:16	SRAMSZ	RO	0x00FF	SRAM Size

Indicates the size of the on-chip SRAM memory.

Value Description

0x00FF 64 KB of SRAM

15:0 FLASHSZ RO 0x003F Flash Size

Indicates the size of the on-chip flash memory.

Value Description
0x003F 128 KB of Flash

Register 14: Device Capabilities 1 (DC1), offset 0x010

This register is predefined by the part and can be used to verify features. The PWM, SARADCO, MAXADCSPD, WDT, SWO, SWD, and JTAG bits mask the RCGCO, SCGCO, and DCGCO registers. Other bits are passed as 0. MAXADCSPD is clipped to the maximum value specified in DC1.

Device Capabilities 1 (DC1)

Base 0x400F.E000 Offset 0x010 Type RO

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	
		•	•	reserved			•	CAN0		reserved		PWM		reserved		SARADC0	
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 1	RO 0	RO 0	RO 0	RO 1	RO 0	RO 0	RO 0	RO 1	
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
		SYS	SDIV		ı	MAXA	DCSPD	ı	MPU	HIB	TEMPSNS	PLL	WDT	swo	SWD	JTAG	
Type Reset	RO 0	RO 0	RO 1	RO 1	RO 0	RO 0	RO 1	RO 0	RO 1	RO 1	RO 1	RO 1	RO 1	RO 1	RO 1	RO 1	
Bit/F	ield		Name		Туре	F	Reset	Descr	iption								
31:	25	I	reserved		RO		0	compa	atibility v		e produc	cts, the v	alue of	erved bit. a reserve n.			
24	1		CAN0		RO		1	When	set, ind	icates th	at CAN ı	unit 0 is	present	-			
23:2	21	I	reserved		RO		0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should preserved across a read-modify-write operation.									
20)		PWM		RO		1	When set, indicates that the PWM module is present.									
19:	17	I	reserved		RO		0	compa	atibility v		e produc	cts, the v	alue of	erved bit. a reserve n.			
16	3	S	ARADC	0	RO		1	When	set, ind	icates th	at gener	al SAR	ADC 0 is	s presen	t.		
15:	12		SYSDIV		RO		0x3	hardw	are-dep		See the	RCC re	gister fo	The rese			
								Value	Descr	iption							
								0x3	Specif	ies a 50-	-MHz CF	PU clock	with a F	PLL divid	er of 4.		
11:	8	MA	XADCS	PD	RO		0x2	This field indicates the maximum rate at which the ADC samples data									
								Value Description									
								0x2 500K samples/second									
7			MPU		RO		1	modul	e is pres		the ARM			ry Protec hnical Re		` ,	
6			HIB		RO		1	When set, indicates that the Hibernation module is present.									

Bit/Field	Name	Type	Reset	Description
5	TEMPSNS	RO	1	When set, indicates that the on-chip temperature sensor is present.
4	PLL	RO	1	When set, indicates that the on-chip Phase Locked Loop (PLL) is present.
3	WDT	RO	1	When set, indicates that a watchdog timer is present.
2	SWO	RO	1	When set, indicates that the Serial Wire Output (SWO) trace port is present.
1	SWD	RO	1	When set, indicates that the Serial Wire Debugger (SWD) is present.
0	JTAG	RO	1	When set, indicates that the JTAG debugger interface is present.

Register 15: Device Capabilities 2 (DC2), offset 0x014

This register is predefined by the part and can be used to verify features.

Device Capabilities 2 (DC2)

Base 0x400F.E000 Offset 0x014 Type RO

,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,																
Г	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
L				reserved				COMP0			reserved			TIMER2	TIMER1	TIMER0
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 1	RO 0	RO 0	RO 0	RO 0	RO 0	RO 1	RO 1	RO 1
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		reserved		12C0		reserved	•	QEI0		reserved	'	SSI0	rese	erved	UART1	UART0
Type Reset	RO 0	RO 0	RO 0	RO 1	RO 0	RO 0	RO 0	RO 1	RO 0	RO 0	RO 0	RO 1	RO 0	RO 0	RO 1	RO 1
110001	Ü	Ü	Ü	•	Ü	Ü	Ü	·	Ü	Ü	Ü	•	Ü	Ü		·
Bit/Fi	eld		Name		Туре	F	Reset	Descr	iption							
31:2	25	re	eserved	I	RO		0	compa	atibility v	uld not re with futur ross a re	e produc	ts, the v	alue of	a reserv		
24	ŀ	(COMP0		RO		1	When	set, inc	licates th	at analo	g compa	arator 0	is preser	nt.	
23:1	19	re	eserved	I	RO		0	compa	atibility v	uld not re with futur ross a re	e produc	ts, the v	alue of	a reserv		
18	3	Т	IMER2		RO		1	When	set, inc	dicates th	at Genei	ral-Purp	ose Tim	er modu	le 2 is p	resent.
17	•	Т	IMER1		RO		1	When	set, inc	dicates th	at Genei	ral-Purp	ose Tim	er modu	le 1 is p	resent.
16	i	Т	IMER0		RO		1	When	set, inc	dicates th	at Genei	ral-Purp	ose Tim	er modu	le 0 is p	resent.
15:1	13	re	eserveo	I	RO		0	compa	atibility v	uld not re with futur ross a re	e produc	ts, the v	alue of	a reserv		
12	!		I2C0		RO		1	When	set, inc	dicates th	at I2C m	odule 0	is prese	ent.		
11:	9	re	eserved	I	RO		0	compa	atibility v	uld not re with futur ross a re	e produc	ts, the v	alue of	a reserv		
8			QEI0		RO		1	When	set, inc	dicates th	at QEI m	nodule 0	is pres	ent.		
7:5	5	re	eserved	I	RO		0	compa	atibility v	uld not re with futur ross a re	e produc	cts, the v	alue of	a reserv		
4			SSI0		RO		1	When	set, inc	dicates th	at SSI m	odule 0	is prese	ent.		
3:2	2	re	eserved	I	RO		0	compa	atibility v	uld not re with futur ross a re	e produc	ts, the v	alue of	a reserv		
1		l	JART1		RO		1	When	set, inc	licates th	at UART	module	1 is pre	esent.		
0		ı	JART0		RO		1	When	set, inc	dicates th	at UART	module	e 0 is pre	esent.		

Register 16: Device Capabilities 3 (DC3), offset 0x018

This register is predefined by the part and can be used to verify features.

Device Capabilities 3 (DC3)

Base 0x400F.E000 Offset 0x018 Type RO

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	
	reser	ved	CCP5	CCP4	CCP3	CCP2	CCP1	CCP0		resei	rved		ADC3	ADC2	ADC1	ADC0	
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	
Reset	0	0	1	1	1	1	1	1	0	0	0	0	1	1	1	1	
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
	PWMFAULT		•	rese	rved I			C00	C0PLUS	COMINUS	PWM5	PWM4	PWM3	PWM2	PWM1	PWM0	
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	
Reset	1	0	0	0	0	0	0	1	1	1	1	1	1	1	1	1	

Bit/Field	Name	Туре	Reset	Description
31:30	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
29	CCP5	RO	1	When set, indicates that Capture/Compare/PWM pin 5 is present.
28	CCP4	RO	1	When set, indicates that Capture/Compare/PWM pin 4 is present.
27	CCP3	RO	1	When set, indicates that Capture/Compare/PWM pin 3 is present.
26	CCP2	RO	1	When set, indicates that Capture/Compare/PWM pin 2 is present.
25	CCP1	RO	1	When set, indicates that Capture/Compare/PWM pin 1 is present.
24	CCP0	RO	1	When set, indicates that Capture/Compare/PWM pin 0 is present.
23:20	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
19	ADC3	RO	1	When set, indicates that ADC pin 3 is present.
18	ADC2	RO	1	When set, indicates that ADC pin 2 is present.
17	ADC1	RO	1	When set, indicates that ADC pin 1 is present.
16	ADC0	RO	1	When set, indicates that ADC pin 0 is present.
15	PWMFAULT	RO	1	When set, indicates that the PWM Fault pin is present.
14:9	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
8	COO	RO	1	When set, indicates that the analog comparator 0 output pin is present.
7	C0PLUS	RO	1	When set, indicates that the analog comparator 0 (+) input pin is present.
6	COMINUS	RO	1	When set, indicates that the analog comparator 0 (-) input pin is present.
5	PWM5	RO	1	When set, indicates that the PWM pin 5 is present.

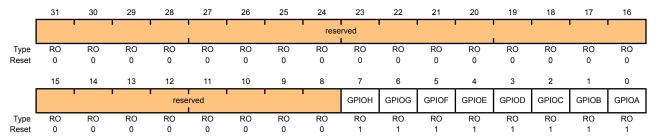
Bit/Field	Name	Туре	Reset	Description
4	PWM4	RO	1	When set, indicates that the PWM pin 4 is present.
3	PWM3	RO	1	When set, indicates that the PWM pin 3 is present.
2	PWM2	RO	1	When set, indicates that the PWM pin 2 is present.
1	PWM1	RO	1	When set, indicates that the PWM pin 1 is present.
0	PWM0	RO	1	When set, indicates that the PWM pin 0 is present.

Register 17: Device Capabilities 4 (DC4), offset 0x01C

This register is predefined by the part and can be used to verify features.

Device Capabilities 4 (DC4)

Base 0x400F.E000 Offset 0x01C Type RO



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7	GPIOH	RO	1	When set, indicates that GPIO Port H is present.
6	GPIOG	RO	1	When set, indicates that GPIO Port G is present.
5	GPIOF	RO	1	When set, indicates that GPIO Port F is present.
4	GPIOE	RO	1	When set, indicates that GPIO Port E is present.
3	GPIOD	RO	1	When set, indicates that GPIO Port D is present.
2	GPIOC	RO	1	When set, indicates that GPIO Port C is present.
1	GPIOB	RO	1	When set, indicates that GPIO Port B is present.
0	GPIOA	RO	1	When set, indicates that GPIO Port A is present.

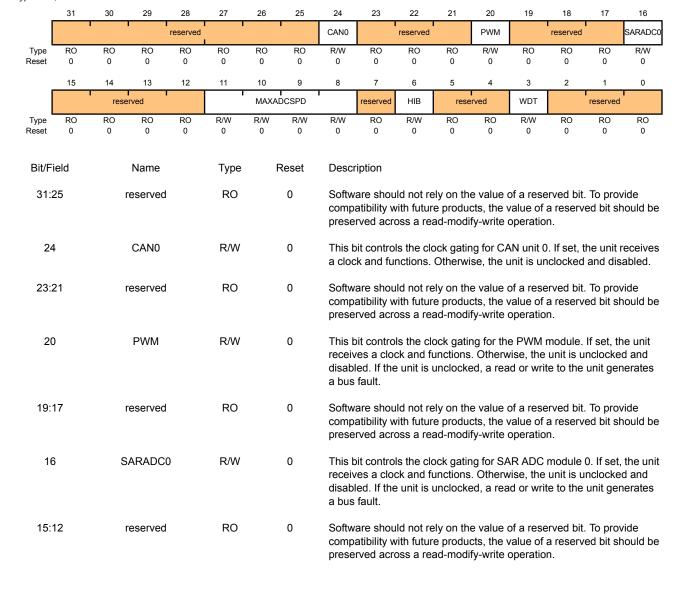
Register 18: Run Mode Clock Gating Control Register 0 (RCGC0), offset 0x100

This register controls the clock gating logic. Each bit controls a clock enable for a given interface, function, or unit. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled (saving power). If the unit is unclocked, reads or writes to the unit will generate a bus fault. The reset state of these bits is 0 (unclocked) unless otherwise noted, so that all functional units are disabled. It is the responsibility of software to enable the ports necessary for the application. Note that these registers may contain more bits than there are interfaces, functions, or units to control. This is to assure reasonable code compatibility with other family and future parts. **RCGC0** is the clock configuration register for running operation, **SCGC0** for Sleep operation, and **DCGC0** for Deep-Sleep operation. Setting the ACG bit in the **Run-Mode Clock Configuration (RCC)** register specifies that the system uses sleep modes.

Run Mode Clock Gating Control Register 0 (RCGC0)

Base 0x400F.E000 Offset 0x100

Type R/W, reset 0x00000040



Bit/Field	Name	Туре	Reset	Description
11:8	MAXADCSPD	R/W	0	This field sets the rate at which the ADC samples data. You cannot set the rate higher than the maximum rate. You can set the sample rate by setting the MAXADCSPD bit as follows:
				Value Description
				0x2 500K samples/second
				0x1 250K samples/second
				0x0 125K samples/second
7	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
6	HIB	R/W	0	This bit controls the clock gating for the Hibernation module. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled.
5:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	WDT	R/W	0	This bit controls the clock gating for the WDT module. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, a read or write to the unit generates a bus fault.
2:0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

Register 19: Sleep Mode Clock Gating Control Register 0 (SCGC0), offset 0x110

This register controls the clock gating logic. Each bit controls a clock enable for a given interface, function, or unit. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled (saving power). If the unit is unclocked, reads or writes to the unit will generate a bus fault. The reset state of these bits is 0 (unclocked) unless otherwise noted, so that all functional units are disabled. It is the responsibility of software to enable the ports necessary for the application. Note that these registers may contain more bits than there are interfaces, functions, or units to control. This is to assure reasonable code compatibility with other family and future parts. **RCGC0** is the clock configuration register for running operation, **SCGC0** for Sleep operation, and **DCGC0** for Deep-Sleep operation. Setting the ACG bit in the **Run-Mode Clock Configuration (RCC)** register specifies that the system uses sleep modes. bit was changed to

Sleep Mode Clock Gating Control Register 0 (SCGC0)

Base 0x400F.E000 Offset 0x110

Type R/W, reset 0x00000040

				reserved	'			CAN0		reserved		PWM		reserved		SARADC0	
Туре	RO	RO	RO	RO	RO	RO	RO	R/W	RO	RO	RO	R/W	RO	RO	RO	R/W	
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
		rese	rved	'	I	MAXA	DCSPD		reserved	HIB	rese	rved	WDT		reserved	ı	
Type Reset	RO 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0	R/W 0	RO 0	R/W 0	RO 0	RO 0	R/W 0	RO 0	RO 0	RO 0	
Bit/F	ield		Name		Туре	F	Reset	Descr	iption								
31:2	25	r	eserved		RO		0			ıld not re							
								compatibility with future products, the value of a reserved bit should preserved across a read-modify-write operation.									
24	1		CAN0		R/W		0	This bit controls the clock gating for CAN unit 0. If set, the unit receive									
								a clock and functions. Otherwise, the unit is unclocked and disabled.									
23:2	21	r	eserved		RO		0			ıld not re	•						
										vith future oss a rea					ed bit sh	ould be	
20)		PWM		R/W		0			ls the clo							
									ed. If the	ck and fu e unit is ι			,				
															_		
19:	17	r	eserved		RO		0	compa	atibility w	ıld not re vith future	e produ	cts, the v	alue of	a reserv			
								prese	rved acr	oss a rea	ad-modi [.]	fy-write	operatio	n.			
16	3	S	ARADC	0	R/W		0			ls the clo							
									sabled. I	f the unit				,			
15:	12	r	eserved		RO		0	Softwa	are shou	ıld not re	ly on the	e value o	of a rese	erved bit.	To prov	ride	
									•	vith future oss a rea	•				ed bit sh	ould be	

Bit/Field	Name	Туре	Reset	Description
11:8	MAXADCSPD	R/W	0	This field sets the rate at which the ADC samples data. You cannot set the rate higher than the maximum rate. You can set the sample rate by setting the MAXADCSPD bit as follows:
				Value Description
				0x2 500K samples/second
				0x1 250K samples/second
				0x0 125K samples/second
7	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be
				preserved across a read-modify-write operation.
6	HIB	R/W	0	This bit controls the clock gating for the Hibernation module. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled.
5:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	WDT	R/W	0	This bit controls the clock gating for the WDT module. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, a read or write to the unit generates a bus fault.
2:0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

Register 20: Deep Sleep Mode Clock Gating Control Register 0 (DCGC0), offset 0x120

This register controls the clock gating logic. Each bit controls a clock enable for a given interface, function, or unit. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled (saving power). If the unit is unclocked, reads or writes to the unit will generate a bus fault. The reset state of these bits is 0 (unclocked) unless otherwise noted, so that all functional units are disabled. It is the responsibility of software to enable the ports necessary for the application. Note that these registers may contain more bits than there are interfaces, functions, or units to control. This is to assure reasonable code compatibility with other family and future parts. **RCGC0** is the clock configuration register for running operation, **SCGC0** for Sleep operation, and **DCGC0** for Deep-Sleep operation. Setting the ACG bit in the **Run-Mode Clock Configuration (RCC)** register specifies that the system uses sleep modes. bit was changed to

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Deep Sleep Mode Clock Gating Control Register 0 (DCGC0)

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Base 0x400F.E000 Offset 0x120

Type R/W, reset 0x00000040

30

		•		reserved			'	CAN0	'' 	reserved		PWM		reserved		SARADC0
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	R/W 0	RO 0	RO 0	RO 0	R/W 0	RO 0	RO 0	RO 0	R/W 0
Reset			-													
Г	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Į			rved				DCSPD		reserved	HIB		rved	WDT		reserved	
Type Reset	RO 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0	R/W 0	RO 0	R/W 0	RO 0	RO 0	R/W 0	RO 0	RO 0	RO 0
Bit/Fi	eld		Name		Туре	ſ	Reset	Descr	ription							
31:2	25	r	reserved		RO		0	Software should not rely on the value of a reserved bit. To compatibility with future products, the value of a reserved b preserved across a read-modify-write operation.								
24	ļ		CAN0		R/W		0	This bit controls the clock gating for CAN unit 0. If set, the unit rea clock and functions. Otherwise, the unit is unclocked and disal								
23:2	21	r	reserved		RO		0	Software should not rely on the value of a reserved bit. To procompatibility with future products, the value of a reserved bit s preserved across a read-modify-write operation.								
20)		PWM		R/W		0	receiv	oit contro res a cloo led. If the fault.	ck and fu	unctions	. Otherw	ise, the	unit is u	nclocke	d and
19:1	17	r	reserved		RO		0	comp	are shou atibility w rved acre	ith futur	e produ	cts, the v	alue of	a reserv		
16	3	S	ARADC	0	R/W		0	the ur	oit contro nit receive sabled. I fault.	es a cloc	k and fu	nctions.	Otherwi	se, the ι	ınit is un	clocked
15:1	12	r	reserved		RO		0	comp	are shou atibility w	ith futur	e produ	cts, the v	alue of	a reserv		

Bit/Field	Name	Туре	Reset	Description
11:8	MAXADCSPD	R/W	0	This field sets the rate at which the ADC samples data. You cannot set the rate higher than the maximum rate. You can set the sample rate by setting the MAXADCSPD bit as follows:
				Value Description
				0x2 500K samples/second
				0x1 250K samples/second
				0x0 125K samples/second
7	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
6	HIB	R/W	0	This bit controls the clock gating for the Hibernation module. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled.
5:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	WDT	R/W	0	This bit controls the clock gating for the WDT module. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, a read or write to the unit generates a bus fault.
2:0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

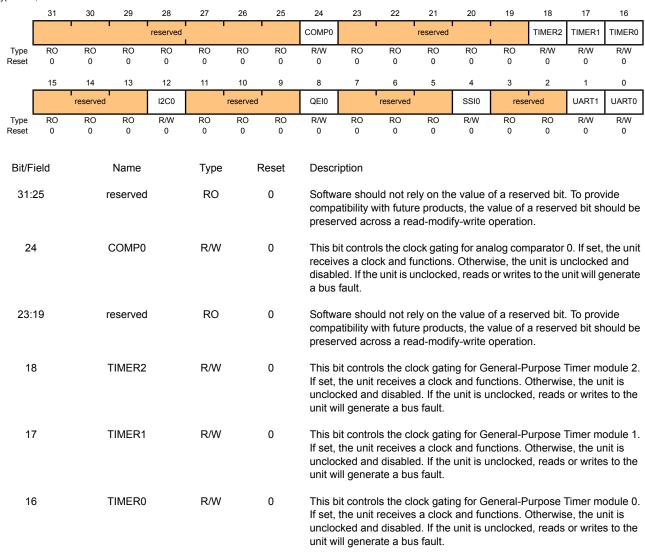
Register 21: Run Mode Clock Gating Control Register 1 (RCGC1), offset 0x104

This register controls the clock gating logic. Each bit controls a clock enable for a given interface, function, or unit. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled (saving power). If the unit is unclocked, reads or writes to the unit will generate a bus fault. The reset state of these bits is 0 (unclocked) unless otherwise noted, so that all functional units are disabled. It is the responsibility of software to enable the ports necessary for the application. Note that these registers may contain more bits than there are interfaces, functions, or units to control. This is to assure reasonable code compatibility with other family and future parts. **RCGC1** is the clock configuration register for running operation, **SCGC1** for Sleep operation, and **DCGC1** for Deep-Sleep operation. Setting the ACG bit in the **Run-Mode Clock Configuration (RCC)** register specifies that the system uses sleep modes.

Run Mode Clock Gating Control Register 1 (RCGC1)

Base 0x400F.E000 Offset 0x104

Type R/W, reset 0x00000000



Bit/Field	Name	Туре	Reset	Description
15:13	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
12	I2C0	R/W	0	This bit controls the clock gating for I2C module 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
11:9	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
8	QEI0	R/W	0	This bit controls the clock gating for QEI module 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
7:5	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
4	SSI0	R/W	0	This bit controls the clock gating for SSI module 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
3:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	UART1	R/W	0	This bit controls the clock gating for UART module 1. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
0	UART0	R/W	0	This bit controls the clock gating for UART module 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.

Register 22: Sleep Mode Clock Gating Control Register 1 (SCGC1), offset 0x114

This register controls the clock gating logic. Each bit controls a clock enable for a given interface, function, or unit. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled (saving power). If the unit is unclocked, reads or writes to the unit will generate a bus fault. The reset state of these bits is 0 (unclocked) unless otherwise noted, so that all functional units are disabled. It is the responsibility of software to enable the ports necessary for the application. Note that these registers may contain more bits than there are interfaces, functions, or units to control. This is to assure reasonable code compatibility with other family and future parts. RCGC1 is the clock configuration register for running operation, SCGC1 for Sleep operation, and DCGC1 for Deep-Sleep operation. Setting the ACG bit in the Run-Mode Clock Configuration (RCC) register specifies that the system uses sleep modes.

Sleep Mode Clock Gating Control Register 1 (SCGC1)

Base 0x400F.E000 Offset 0x114 Type R/W, reset 0x00000000

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
				reserved				COMP0		'	reserved			TIMER2	TIMER1	TIMER0
Туре	RO	RO	RO	RO	RO	RO	RO	R/W	RO	RO	RO	RO	RO	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		reserved		I2C0		reserved		QEI0		reserved		SSI0	rese	rved	UART1	UART0
Туре	RO	RO	RO	R/W	RO	RO	RO	R/W	RO	RO	RO	R/W	RO	RO	R/W	R/W
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Bit/Field	Name	Type	Reset	Description
31:25	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
24	COMP0	R/W	0	This bit controls the clock gating for analog comparator 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
23:19	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
18	TIMER2	R/W	0	This bit controls the clock gating for General-Purpose Timer module 2. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
17	TIMER1	R/W	0	This bit controls the clock gating for General-Purpose Timer module 1. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
16	TIMER0	R/W	0	This bit controls the clock gating for General-Purpose Timer module 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.

Bit/Field	Name	Туре	Reset	Description
15:13	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
12	I2C0	R/W	0	This bit controls the clock gating for I2C module 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
11:9	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
8	QEI0	R/W	0	This bit controls the clock gating for QEI module 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
7:5	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
4	SSI0	R/W	0	This bit controls the clock gating for SSI module 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
3:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	UART1	R/W	0	This bit controls the clock gating for UART module 1. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
0	UART0	R/W	0	This bit controls the clock gating for UART module 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.

Register 23: Deep Sleep Mode Clock Gating Control Register 1 (DCGC1), offset 0x124

This register controls the clock gating logic. Each bit controls a clock enable for a given interface, function, or unit. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled (saving power). If the unit is unclocked, reads or writes to the unit will generate a bus fault. The reset state of these bits is 0 (unclocked) unless otherwise noted, so that all functional units are disabled. It is the responsibility of software to enable the ports necessary for the application. Note that these registers may contain more bits than there are interfaces, functions, or units to control. This is to assure reasonable code compatibility with other family and future parts. **RCGC1** is the clock configuration register for running operation, **SCGC1** for Sleep operation, and **DCGC1** for Deep-Sleep operation. Setting the ACG bit in the **Run-Mode Clock Configuration (RCC)** register specifies that the system uses sleep modes.

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Deep Sleep Mode Clock Gating Control Register 1 (DCGC1)

Base 0x400F.E000 Offset 0x124

Type R/W, reset 0x00000000

_	31	30	29	28	21		25		23		21		19	18	17	16		
		' '		reserved				COMP0			reserved		1	TIMER2	TIMER1	TIMER0		
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	R/W 0	RO 0	RO 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0		
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0		
		reserved		I2C0		reserved		QEI0		reserved		SSI0	rese	rved	UART1	UART0		
Type Reset	RO 0	RO 0	RO 0	R/W 0	RO 0	RO 0	RO 0	R/W 0	RO 0	RO 0	RO 0	R/W 0	RO 0	RO 0	R/W 0	R/W 0		
	-	-			•	•				-	•							
Bit/Fi	eld		Name		Туре	F	Reset	Descri	ption									
31:2	25	r	eserved	i	RO		0	Softwa	are shou	uld not re	ely on the	e value d	of a rese	erved bit.	To prov	ide		
									•	vith futur oss a rea	•	-			ed bit sh	ould be		
24		,	COMP0		R/W		0	·							O If oot	tha unit		
24	•	,	JOIVIPU		K/VV		U	receiv	This bit controls the clock gating for analog comparator 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate									
								disable a bus		e unit is u	ınclocke	d, reads	or writes	s to the u	ınit will g	enerate		
23:1	19	n	eserved	İ	RO		0	Softwa	Software should not rely on the value of a reserved bit. To provide									
20.			000,700	•	110		Ü	compa	compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.									
								·										
18	}	٦	ΓIMER2		R/W		0			ols the clo receives								
								uncloc	ked and	d disable ate a bu	d. If the							
	-	_			D.444				•					_				
17			ΓIMER1		R/W		0			ols the clo receives								
								unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.										
16	i.	٦	ΓIMER0		R/W		0		Ü	ols the clo		na for Ga	aneral D	urnose -	Timer m	ndule 0		
10		'	IIIVILINO		17///		U	If set,	the unit	receives	a clock	and fun	ctions. (Otherwis	e, the ur	nit is		
										d disable ate a bu		unit is u	nclocke	d, reads	or writes	s to the		

Bit/Field	Name	Туре	Reset	Description
15:13	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
12	I2C0	R/W	0	This bit controls the clock gating for I2C module 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
11:9	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
8	QEI0	R/W	0	This bit controls the clock gating for QEI module 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
7:5	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
4	SSI0	R/W	0	This bit controls the clock gating for SSI module 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
3:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	UART1	R/W	0	This bit controls the clock gating for UART module 1. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
0	UART0	R/W	0	This bit controls the clock gating for UART module 0. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.

Register 24: Run Mode Clock Gating Control Register 2 (RCGC2), offset 0x108

This register controls the clock gating logic. Each bit controls a clock enable for a given interface, function, or unit. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled (saving power). If the unit is unclocked, reads or writes to the unit will generate a bus fault. The reset state of these bits is 0 (unclocked) unless otherwise noted, so that all functional units are disabled. It is the responsibility of software to enable the ports necessary for the application. Note that these registers may contain more bits than there are interfaces, functions, or units to control. This is to assure reasonable code compatibility with other family and future parts. RCGC2 is the clock configuration register for running operation, SCGC2 for Sleep operation, and DCGC2 for Deep-Sleep operation. Setting the ACG bit in the Run-Mode Clock Configuration (RCC) register specifies that the system uses sleep modes.

Run Mode Clock Gating Control Register 2 (RCGC2)

Base 0x400F.E000 Offset 0x108

Type R/W	l, reset (0x000000	000															
	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16		
		'	'		,		•	rese	rved									
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0		
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0		
		1	i i	rese	rved		•	i	GPIOH	GPIOG	GPIOF	GPIOE	GPIOD	GPIOC	GPIOB	GPIOA		
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0		
Bit/F	ield		Name		Туре		Reset	Descr	ription									
31:	:8		reserved		RO		0	comp	atibility v	vith futur	cts, the v	of a reserved bit. To provide value of a reserved bit should be operation.						
7			GPIOH		R/W		0	This bit controls the clock gating for Port H. If set, the u clock and functions. Otherwise, the unit is unclocked ar the unit is unclocked, reads or writes to the unit will gene								and disabled. If		
6			GPIOG		R/W		0	clock	and fund	ols the clootions. O	therwise	e, the un	it is uncl	ocked a	nd disab	led. If		
5			GPIOF		R/W		0	clock	and fund	ols the clo ctions. O ocked, r	therwise	e, the un	it is uncl	ocked a	nd disab	led. If		
4			GPIOE		R/W		0	clock	and fund	ols the clo ctions. O ocked, re	therwise	e, the un	it is uncl	ocked a	nd disab	led. If		
3			GPIOD		R/W		0	clock	and fund	ols the clo ctions. O ocked, re	therwise	e, the un	it is uncl	ocked a	nd disab	led. If		
2			GPIOC		R/W		0	clock	and fund	ols the clo ctions. O ocked, re	therwise	e, the un	it is uncl	ocked a	nd disab	led. If		

Bit/Field	Name	Type	Reset	Description
1	GPIOB	R/W	0	This bit controls the clock gating for Port B. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
0	GPIOA	R/W	0	This bit controls the clock gating for Port A. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.

Register 25: Sleep Mode Clock Gating Control Register 2 (SCGC2), offset 0x118

This register controls the clock gating logic. Each bit controls a clock enable for a given interface, function, or unit. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled (saving power). If the unit is unclocked, reads or writes to the unit will generate a bus fault. The reset state of these bits is 0 (unclocked) unless otherwise noted, so that all functional units are disabled. It is the responsibility of software to enable the ports necessary for the application. Note that these registers may contain more bits than there are interfaces, functions, or units to control. This is to assure reasonable code compatibility with other family and future parts. RCGC2 is the clock configuration register for running operation, SCGC2 for Sleep operation, and DCGC2 for Deep-Sleep operation. Setting the ACG bit in the Run-Mode Clock Configuration (RCC) register specifies that the system uses sleep modes.

reserved

Sleep Mode Clock Gating Control Register 2 (SCGC2)

Base 0x400F.E000 Offset 0x118

Type R/W, reset 0x00000000

								1636	I I							
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
			1	rese	rved		1	1	GPIOH	GPIOG	GPIOF	GPIOE	GPIOD	GPIOC	GPIOB	GPIOA
Type L	RO	RO	RO	RO	RO	RO	RO	RO	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Bit/Fi	ield		Name		Type		Reset	Descr	rintion							
Divi i	icia		Hame		Турс		110001	DCGG	iption							
31:	8	1	reserved		RO		0	comp	are shou atibility v rved acr	vith futur	e produ	cts, the v	alue of	a reserv		
7		GPIOH R/W 0 This bit controls the cloc clock and functions. Oth the unit is unclocked, rea									therwise	e, the un	it is uncl	ocked a	nd disab	led. If
6			GPIOG		R/W		0	clock	oit contro and fund hit is uncl	ctions. O	therwise	e, the un	it is uncl	ocked a	nd disab	led. If
5			GPIOF		R/W		0	clock	and fund	ctions. O	therwise	ating for Port F. If set, the unit received vise, the unit is unclocked and disabled or writes to the unit will generate a bus				
4			GPIOE		R/W		0	This bit controls the clock gating for Port E. If set, the unit receive clock and functions. Otherwise, the unit is unclocked and disable the unit is unclocked, reads or writes to the unit will generate a bus								
3			GPIOD		R/W		0	This bit controls the clock gating for Port D. If set, the unit receives clock and functions. Otherwise, the unit is unclocked and disabled the unit is unclocked, reads or writes to the unit will generate a bus fa								
2			GPIOC		R/W		0	clock	oit contro and fund hit is uncl	ctions. O	therwise	e, the un	it is uncl	ocked a	nd disab	led. If

Bit/Field	Name	Type	Reset	Description
1	GPIOB	R/W	0	This bit controls the clock gating for Port B. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
0	GPIOA	R/W	0	This bit controls the clock gating for Port A. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.

Register 26: Deep Sleep Mode Clock Gating Control Register 2 (DCGC2), offset 0x128

This register controls the clock gating logic. Each bit controls a clock enable for a given interface, function, or unit. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled (saving power). If the unit is unclocked, reads or writes to the unit will generate a bus fault. The reset state of these bits is 0 (unclocked) unless otherwise noted, so that all functional units are disabled. It is the responsibility of software to enable the ports necessary for the application. Note that these registers may contain more bits than there are interfaces, functions, or units to control. This is to assure reasonable code compatibility with other family and future parts. RCGC2 is the clock configuration register for running operation, SCGC2 for Sleep operation, and DCGC2 for Deep-Sleep operation. Setting the ACG bit in the Run-Mode Clock Configuration (RCC) register specifies that the system uses sleep modes.

Deep Sleep Mode Clock Gating Control Register 2 (DCGC2)

Base 0x400F.E000 Offset 0x128

Type R/W, reset 0x00000000

		reserved																
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO		
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0		
		•	' '	rese	rved		1	'	GPIOH	GPIOG	GPIOF	GPIOE	GPIOD	GPIOC	GPIOB	GPIOA		
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0		
Neset	U	U	O	U	O	U	O	U	U	U	U	U	U	U	U	O		
Bit/F	ield		Name		Туре		Reset	Descr	ription									
31:	:8		reserved		RO		0	comp	are shou atibility v	vith futur	e produ	cts, the v	alue of	a reserv				
7		clock the u							This bit controls the clock gating for Port H. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.									
6			GPIOG		R/W		0	clock	oit contro and fund nit is uncl	ctions. O	therwise	e, the un	it is uncl	ocked a	nd disab	led. If		
5			GPIOF		R/W		0	clock	oit contro and fund nit is uncl	ctions. O	therwise	e, the un	it is uncl	ocked a	nd disab	led. If		
4			GPIOE		R/W		0	clock	oit contro and fund nit is uncl	ctions. O	therwise	e, the un	it is uncl	ocked a	nd disab	led. If		
3			GPIOD		R/W		0	This bit controls the clock gating for Port D. If set, the unit receives clock and functions. Otherwise, the unit is unclocked and disabled. the unit is unclocked, reads or writes to the unit will generate a bus fa										
2		GPIOC R/W 0						clock	oit contro and fund nit is uncl	ctions. O	therwise	e, the un	it is uncl	ocked a	nd disab	led. If		

Bit/Field	Name	Type	Reset	Description
1	GPIOB	R/W	0	This bit controls the clock gating for Port B. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.
0	GPIOA	R/W	0	This bit controls the clock gating for Port A. If set, the unit receives a clock and functions. Otherwise, the unit is unclocked and disabled. If the unit is unclocked, reads or writes to the unit will generate a bus fault.

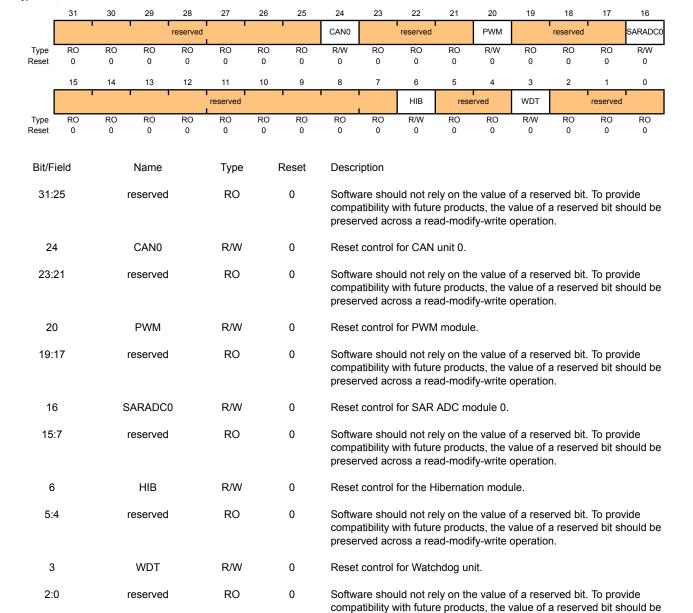
Register 27: Software Reset Control 0 (SRCR0), offset 0x040

Writes to this register are masked by the bits in the **Device Capabilities 1 (DC1)** register.

Software Reset Control 0 (SRCR0)

Base 0x400F.E000 Offset 0x040

Type R/W, reset 0x00000000



preserved across a read-modify-write operation.

Register 28: Software Reset Control 1 (SRCR1), offset 0x044

Writes to this register are masked by the bits in the **Device Capabilities 2 (DC2)** register.

Software Reset Control 1 (SRCR1)

Base 0x400F.E000

Offset 0x044
Type R/W, reset 0x00000000

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
				reserved				COMP0			reserved			TIMER2	TIMER1	TIMER0
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	R/W 0	RO 0	RO 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
[reserved		I2C0		reserved		QEI0		reserved		SSI0	rese	erved	UART1	UART0
Type Reset	RO 0	RO 0	RO 0	R/W 0	RO 0	RO 0	RO 0	R/W 0	RO 0	RO 0	RO 0	R/W 0	RO 0	RO 0	R/W 0	R/W 0
Neset	Ü	U	U	O	O	Ü	O	O	O	U	U	U	Ü	O	U	U
Bit/Fi	eld		Name		Туре	F	Reset	Descr	iption							
31:2	25	r	eserved		RO		0			uld not re with futur						
										oss a rea					cu bit sii	ould be
24		(COMP0		R/W		0	Reset	control	for analo	og comp	arator 0.				
23:1	19	ŗ	eserved		RO		0			uld not re						
									-	with futur oss a rea	•				ea bit sii	ould be
18	3		ΓIMER2		R/W		0	Reset	control	for Gene	eral-Purp	ose Tim	er modi	ule 2.		
17	•		TIMER1		R/W		0	Reset	control	for Gene	eral-Purp	ose Tim	er modi	ule 1.		
16	i	7	TIMER0		R/W		0	Reset	control	for Gene	eral-Purp	ose Tim	er mod	ule 0.		
15:1	13	r	eserved		RO		0			uld not re with futur						
										oss a rea					cu bit sii	ould be
12	!		I2C0		R/W		0	Reset	control	for I2C u	ınit 0.					
11:	9	ŗ	eserved		RO		0			uld not re with futur						
										oss a rea					cu bit sii	odia be
8			QEI0		R/W		0	Reset	control	for QEI ι	unit 0.					
7:5	5	r	eserved		RO		0			uld not re with futur						
										oss a rea					ou bit on	odia bo
4			SSI0		R/W		0	Reset	control	for SSI u	ınit 0.					
3:2	2	r	eserved		RO		0	compa	atibility v	uld not re with futur oss a rea	e produ	cts, the v	alue of	a reserv		
1			UART1		R/W		0	Reset	control	for UAR	T unit 1.					
0			UART0		R/W		0	Reset	control	for UAR	T unit 0.					

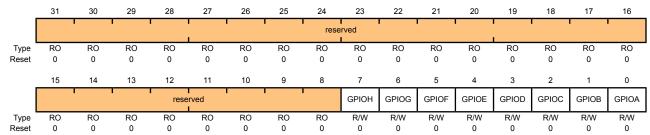
Register 29: Software Reset Control 2 (SRCR2), offset 0x048

Writes to this register are masked by the bits in the **Device Capabilities 4 (DC4)** register.

Software Reset Control 2 (SRCR2)

Base 0x400F.E000

Offset 0x048
Type R/W, reset 0x00000000



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7	GPIOH	R/W	0	Reset control for GPIO Port H.
6	GPIOG	R/W	0	Reset control for GPIO Port G.
5	GPIOF	R/W	0	Reset control for GPIO Port F.
4	GPIOE	R/W	0	Reset control for GPIO Port E.
3	GPIOD	R/W	0	Reset control for GPIO Port D.
2	GPIOC	R/W	0	Reset control for GPIO Port C.
1	GPIOB	R/W	0	Reset control for GPIO Port B.
0	GPIOA	R/W	0	Reset control for GPIO Port A.

7 Hibernation Module

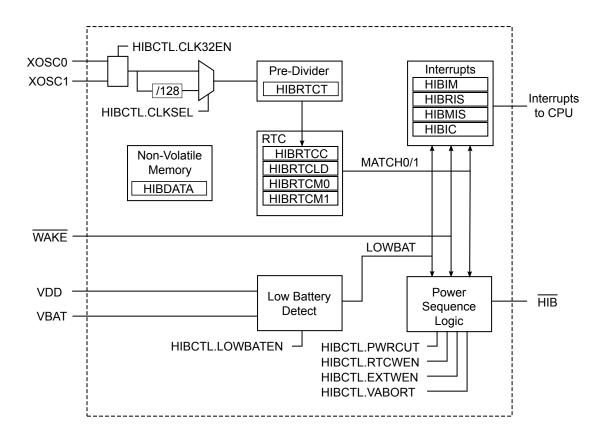
The Hibernation Module manages removal and restoration of power to the rest of the microcontroller to provide a means for reducing power consumption. When the processor and peripherals are idle, power can be completely removed with only the Hibernation Module remaining powered. Power can be restored based on an external signal, or at a certain time using the built-in real-time clock (RTC). The Hibernation module can be independently supplied from a battery or an auxillary power supply.

The Hibernation module has the following features:

- Power-switching logic to discrete external regulator
- Dedicated pin for waking from an external signal
- Low-battery detection, signalling, and interrupt generation
- 32-bit real-time counter (RTC)
- Two 32-bit RTC match registers for timed wake-up and interrupt generation
- Clock source from a 32.768-kHz external oscillator or a 4.194304-MHz crystal
- RTC trim predivider for making fine adjustments to the clock rate
- 64 32-bit words of non-volatile memory
- Programmable interrupts for RTC match, external wake, and low battery events

7.1 Block Diagram

Figure 7-1. Hibernation Module Block Diagram



7.2 Functional Description

The Hibernation module controls the power to the processor with an enable signal ($\overline{\texttt{HIB}}$) that signals an external voltage regulator to turn off. The Hibernation module itself is powered from a separate supply such as a battery or auxillary supply. It also has a separate clock source to maintain a real-time clock (RTC). Once in hibernation, the module signals an external voltage regulator to turn back on the power when an external pin ($\overline{\texttt{WAKE}}$) is asserted, or when the internal RTC reaches a certain value. The Hibernation module can also detect when the battery voltage is low, and optionally prevent hibernation when this occurs.

Power-up from a power cut to code execution is defined as the regulator turn-on time (specifed at $250 \mu s$ maximum) plus the normal chip POR (see Figure 23-11 on page 524).

7.2.1 Register Access Timing

Because the Hibernation module has an independent clocking domain, certain registers must be written only with a timing gap between accesses. The delay time is $t_{\rm HIB_REG_WRITE}$, therefore software must guarantee that a delay of $t_{\rm HIB_REG_WRITE}$ is inserted between back-to-back writes to certain Hibernation registers, or between a write followed by a read to those same registers. There is no restriction on timing for back-to-back reads from the Hibernation module. Refer to "Register Descriptions" on page 118 for details about which registers are subject to this timing restriction.

7.2.2 Clock Source

The Hibernation module must be clocked by an external source, even if the RTC feature will not be used. An external oscillator or crystal can be used for this purpose. To use a crystal, a 4.194304-MHz crystal is connected to the XOSCO and XOSCO pins. This clock signal will be divided by 128 internally to produce the 32.768-kHz clock reference. To use a more precise clock source, a 32.768-kHz oscillator can be connected to the XOSCO pin.

The clock source is enabled by setting the CLK32EN bit of the **HIBCTL** register. The type of clock source is selected by setting the CLKSEL bit to 0 for a 4.194304-MHz clock source, and to 1 for a 32.768-kHz clock source. If the bit is set to 0, the input clock is divided by 128, resulting in a 32.768-kHz clock source. If a crystal is used for the clock source, the software must leave a delay of $t_{\rm XOSC_SETTLE}$ after setting the CLK32EN bit and before any other accesses to the Hibernation module registers. The delay allows the crystal to power up and stabilize. If an oscillator is used for the clock source, no delay is needed.

7.2.3 Battery Management

The Hibernation module can be independently powered by a battery or an auxiliary power source. The module can monitor the voltage level of the battery and detect when the voltage becomes too low. When this happens, an interrupt can be generated. The module can also be configured so that it will not go into Hibernate mode if the battery voltage is too low.

Note that the Hibernation module draws power from whichever source (VBAT or VDD) has the higher voltage. Therefore, it is important to design the circuit to ensure that VDD is higher that VBAT under nominal conditions or else the Hibernation module draws power from the battery even when VDD is available.

The Hibernation module can be configured to detect a low battery condition by setting the LOWBATEN bit of the **HIBCTL** register. In this configuration, the LOWBAT bit of the **HIBRIS** register will be set when the battery level is low. If the VABORT bit is also set, then the module is prevented from entering Hibernation mode when a low battery is detected. The module can also be configured to generate an interrupt for the low-battery condition (see "Interrupts and Status" on page 116).

7.2.4 Real-Time Clock

The Hibernation module includes a 32-bit counter that increments once per second with a proper clock source and configuration (see "Clock Source" on page 115). The 32.768-kHz clock signal is fed into a trim predivider which counts down from a nominal value of 0x7FFF to achieve a once per second clock rate for the RTC. The trim predivider register can be adjusted up or down to compensate for inaccuracies in the clock source. The trim predivider should be adjusted up from 0x7FFF in order to slow down the RTC rate, and down from 0x7FFF in order to speed up the RTC rate.

The Hibernation module includes two 32-bit match registers that are compared to the value of the RTC counter. The match registers can be used to wake the processor from hibernation mode, or to generate an interrupt to the processor if it is not in hibernation.

The RTC must be enabled with the RTCEN bit of the **HIBCTL** register. The value of the RTC can be set at any time by writing to the **HIBRTCLD** register. The trim predivider can be adjusted by reading and writing the **HIBRTCT** register. The predivider is updated once every 64 seconds from this register. The two match registers can be set by writing to the **HIBRTCM0** and **HIBRTCM1** registers. The RTC can be configured to generate interrupts by using the interrupt registers (see "Interrupts and Status" on page 116).

7.2.5 Non-Volatile Memory

The Hibernation module contains 64 32-bit words of memory which are retained during hibernation. This memory is powered from the battery or auxillary power supply during hibernation. The processor software can save state information in this memory prior to hibernation, and can then recover the state upon waking. The non-volatile memory can be accessed through the **HIBDATA** registers.

7.2.6 Power Control

The Hibernation module controls power to the processor through the use of the $\overline{{\tt HIB}}$ pin, which is intended to be connected to the enable signal of the external regulator(s) providing 3.3 V and/or 2.5 V to the microcontroller. When the $\overline{{\tt HIB}}$ signal is asserted by the Hibernation module, the external regulator is turned off and no longer powers the microcontroller. The Hibernation module remains powered from the VBAT supply, which could be a battery or an auxillary power source. Hibernation mode is initiated by the microcontroller setting the HIBREQ bit of the **HIBCTL** register. Prior to doing this, a wake-up condition must be configured, either from the external $\overline{{\tt WAKE}}$ pin, or by using an RTC match.

The Hibernation module is configured to wake from the external WAKE pin by setting the PINWEN bit of the **HIBCTL** register. It is configured to wake from RTC match by setting the RTCWEN bit. Either one or both of these bits can be set prior to going into hibernation.

When the Hibernation module wakes, the microcontroller will see a normal power-on reset. It can detect that the power-on was due to a wake from hibernation by examining the raw interrupt status register (see "Interrupts and Status" on page 116) and by looking for state data in the non-volatile memory (see "Non-Volatile Memory" on page 116).

7.2.7 Interrupts and Status

The Hibernation module can generate interrupts when the following conditions occur:

- Assertion of WAKE pin
- RTC match
- Low battery detected

All of the interrupts are ORed together before being sent to the interrupt controller, so the Hibernate module can only generate a single interrupt request to the controller at any given time. The software interrupt handler can service multiple interrupt events by reading the **HIBMIS** register. Software can also read the status of the Hibernation module at any time by reading the **HIBRIS** register which shows all of the pending events. This register can be used at power-on to see if a wake condition is pending, which indicates to the software that a hibernation wake occurred.

The events that can trigger an interrupt are configured by setting the appropriate bits in the **HIBIM** register. Pending interrupts can be cleared by writing the corresponding bit in the **HIBIC** register.

7.3 Initialization and Configuration

The Hibernation module can be configured in several different combinations. The following sections show the recommended programming sequence for various scenarios. The examples below assume that a 32.768-kHz oscillator is used, and thus always show bit 2 (CLKSEL) of the **HIBCTL** register set to 1. If a 4.194304-MHz crystal is used instead, then the CLKSEL bit remains cleared. Because the Hibernation module runs at 32 kHz and is asynchronous to the rest of the system, software must allow a delay of $t_{\rm HIB-REG-WRITE}$ after writes to certain registers (see "Register Access

Timing" on page 114). The registers that require a delay are denoted with a footnote in "Register Map" on page 118.

7.3.1 Initialization

The clock source must be enabled first, even if the RTC will not be used. If a 4.194304-MHz crystal is used, perform the following steps:

- 1. Write 0x40 to the **HIBCTL** register at offset 0x10 to enable the crystal and select the divide-by-128 input path.
- 2. Wait for a time of $t_{\text{XOSC_SETTLE}}$ for the crystal to power up and stabilize before performing any other operations with the Hibernation module.

If a 32.678-kHz oscillator is used, then perform the following steps:

- 1. Write 0x44 to the **HIBCTL** register at offset 0x10 to enable the oscillator input.
- No delay is necessary.

The above is only necessary when the entire system is initialized for the first time. If the processor is powered due to a wake from hibernation, then the Hibernation module has already been powered up and the above steps are not necessary. The software can detect that the Hibernation module and clock are already powered by examining the CLK32EN bit of the **HIBCTL** register.

7.3.2 RTC Match Functionality (No Hibernation)

The following steps are needed to use the RTC match functionality of the Hibernation module:

- 1. Write the required RTC match value to one of the **HIBRTCMn** registers at offset 0x004 or 0x008.
- 2. Write the required RTC load value to the **HIBRTCLD** register at offset 0x00C.
- 3. Set the required RTC match interrupt mask in the RTCALT0 and RTCALT1 bits (bits 1:0) in the HIBIM register at offset 0x014.
- 4. Write 0x0000.0041 to the **HIBCTL** register at offset 0x010 to enable the RTC to begin counting.

7.3.3 RTC Match/Wake-Up from Hibernation

The following steps are needed to use the RTC match and wake-up functionality of the Hibernation module:

- Write the required RTC match value to the RTCMn registers at offset 0x004 or 0x008.
- 2. Write the required RTC load value to the **HIBRTCLD** register at offset 0x00C.
- 3. Write any data to be retained during power cut to the **HIBDATA** register at offsets 0x030-0x130.
- 4. Set the RTC Match Wake-Up and start the hibernation sequence by writing 0x0000.004F to the **HIBCTL** register at offset 0x010.

7.3.4 External Wake-Up from Hibernation

The following steps are needed to use the Hibernation module with the external \overline{WAKE} pin as the wake-up source for the microcontroller:

- 1. Write any data to be retained during power cut to the **HIBDATA** register at offsets 0x030-0x130.
- 2. Enable the external wake and start the hibernation sequence by writing 0x0000.0056 to the **HIBCTL** register at offset 0x010.

7.3.5 RTC/External Wake-Up from Hibernation

- 1. Write the required RTC match value to the **RTCMn** registers at offset 0x004 or 0x008.
- 2. Write the required RTC load value to the **HIBRTCLD** register at offset 0x00C.
- 3. Write any data to be retained during power cut to the **HIBDATA** register at offsets 0x030-0x130.
- 4. Set the RTC Match/External Wake-Up and start the hibernation sequence by writing 0x0000.005F to the **HIBCTL** register at offset 0x010.

7.4 Register Map

Note: HIBRTCC, HIBRTCM0, HIBRTCM1, HIBRTCLD, HIBRTCT, and HIBDATA are internal BAPI module registers on the VBAPI voltage domain and the 32-kHz clock domain.

Table 7-1. Hibernation Module Register Map

Offset	Name	Type	Reset	Description	See page
0x000	HIBRTCC	RO	0x0000.0000	Hibernation RTC Counter	119
0x004	HIBRTCM0	R/W	0xFFFF.FFFF	Hibernation RTC Match 0	120
0x008	HIBRTCM1	R/W	0xFFFF.FFFF	Hibernation RTC Match 1	121
0x00C	HIBRTCLD	R/W	0xFFFF.FFFF	Hibernation RTC Load	122
0x010	HIBCTL	R/W	0x0000.0000	Hibernation Control	123
0x014	HIBIM	R/W	0x0000.0000	Hibernation Interrupt Mask	125
0x018	HIBRIS	RO	0x0000.0000	Hibernation Raw Interrupt Status	126
0x01C	HIBMIS	RO	0x0000.0000	Hibernation Masked Interrupt Status	127
0x020	HIBIC	W1C	0x0000.0000	Hibernation Interrupt Clear	128
0x024	HIBRTCT	R/W	0x0000.0000	Hibernation RTC Trim	129
0x030- 0x12C	HIBDATA	R/W	0x0000.0000	Hibernation Data	130

7.5 Register Descriptions

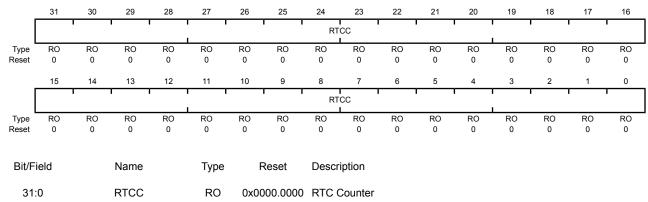
All addresses given are relative to the Hibernation module Base Address at 0x400F.C000.

Register 1: Hibernation RTC Counter (HIBRTCC), offset 0x000

This register is the current 32-bit value of the RTC counter.

Hibernation RTC Counter (HIBRTCC)

Offset 0x000 Type RO, reset 0x0000.0000



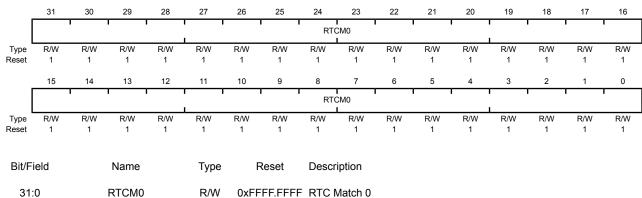
A read returns the 32-bit counter value. This register is read-only. To change the value, use the HIBRTCLD register.

Register 2: Hibernation RTC Match 0 (HIBRTCM0), offset 0x004

This register is the 32-bit match 0 register for the RTC counter.

Hibernation RTC Match 0 (HIBRTCM0)

Offset 0x004 Type R/W, reset 0xFFFF.FFF



A write loads the value into the RTC match register.

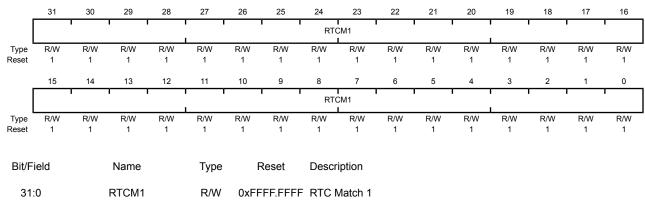
A read returns the current match value.

Register 3: Hibernation RTC Match 1 (HIBRTCM1), offset 0x008

This register is the 32-bit match 1 register for the RTC counter.

Hibernation RTC Match 1 (HIBRTCM1)

Offset 0x008 Type R/W, reset 0xFFFF.FFF



A write loads the value into the RTC match register.

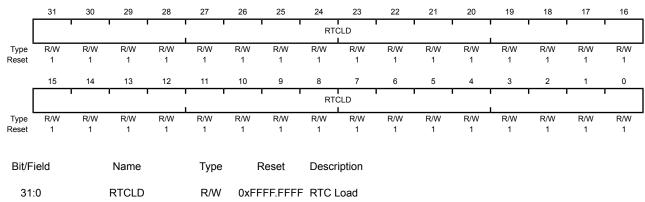
A read returns the current match value.

Register 4: Hibernation RTC Load (HIBRTCLD), offset 0x00C

This register is the 32-bit value loaded into the RTC counter.

Hibernation RTC Load (HIBRTCLD)

Offset 0x00C Type R/W, reset 0xFFFF.FFF



A writes load the current value into the RTC counter (RTCC).

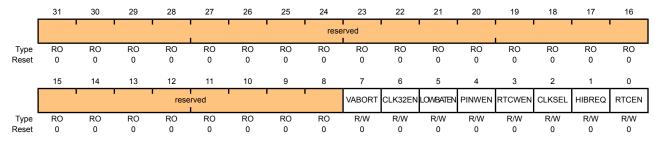
A read returns the 32-bit load value.

Register 5: Hibernation Control (HIBCTL), offset 0x010

This register is the control register for the Hibernation module.

Hibernation Control (HIBCTL)

Offset 0x010 Type R/W, reset 0x0000.0000



D		_	.	5
Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0x00	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7	VABORT	R/W	0	Power Cut Abort Enable
				0: Power Cut occurs during a low-battery alert
				1: Power Cut is aborted
6	CLK32EN	R/W	0	32-kHz Oscillator Enable
				0: Disabled
				1: Enabled
				This bit must be enabled to use the Hibernation module. If a crystal is used, then software should wait 20 ms after setting this bit to allow the crystal to power up and stabilize.
5	LOWBATEN	R/W	0	LOW BAT Monitoring Enable
				0: Disabled
				1: Enabled
				When set, low battery voltage detection is enabled.
4	PINWEN	R/W	0	External WAKE Pin Enable
				0: Disabled
				1: Enabled
				When set, an external event on the $\overline{\mathtt{WAKE}}$ pin will re-power the device.
3	RTCWEN	R/W	0	RTC Wake-up Enable
				0: Disabled
				1: Enabled

When set, an RTC match event (RTC0 or RTC1) will re-power the device based on the RTC counter value matching the corresponding match register 0 or 1.

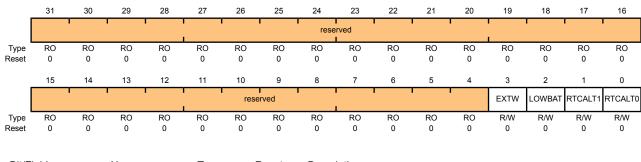
Bit/Field	Name	Туре	Reset	Description
2	CLKSEL	R/W	0	Hibernation Module Clock Select
				0: Use Divide by 128 output. Use this value for a 4-MHz crystal.
				1: Use raw output. Use this value for a 32-kHz oscillator.
1	HIBREQ	R/W	0	Hibernation Request
				0: Disabled
				1: Hibernation initiated
				After a wake-up event, this bit is cleared by hardware.
0	RTCEN	R/W	0	RTC Timer Enable
				0: Disabled
				1: Enabled

Register 6: Hibernation Interrupt Mask (HIBIM), offset 0x014

This register is the interrupt mask register for the Hibernation module interrupt sources.

Hibernation Interrupt Mask (HIBIM)

Offset 0x014
Type R/W, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:4	reserved	RO	0x000.0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	EXTW	R/W	0	External Wake-Up Interrupt Mask 0: Masked 1: Unmasked
2	LOWBAT	R/W	0	Low Battery Voltage Interrupt Mask 0: Masked 1: Unmasked
1	RTCALT1	R/W	0	RTC Alert1 Interrupt Mask 0: Masked 1: Unmasked
0	RTCALT0	R/W	0	RTC Alert0 Interrupt Mask 0: Masked

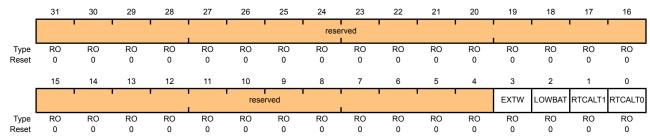
1: Unmasked

Register 7: Hibernation Raw Interrupt Status (HIBRIS), offset 0x018

This register is the raw interrupt status for the Hibernation module interrupt sources.

Hibernation Raw Interrupt Status (HIBRIS)

Offset 0x018 Type RO, reset 0x0000.0000



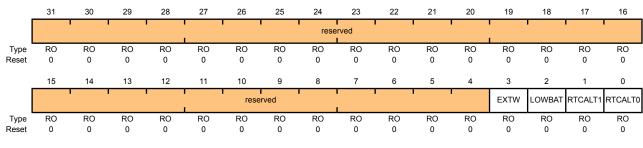
Bit/Field	Name	Type	Reset	Description
31:4	reserved	RO	0x000.0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	EXTW	RO	0	External Wake-Up Raw Interrupt Status
2	LOWBAT	RO	0	Low Battery Voltage Raw Interrupt Status
1	RTCALT1	RO	0	RTC Alert1 Raw Interrupt Status
0	RTCALT0	RO	0	RTC Alert0 Raw Interrupt Status

Register 8: Hibernation Masked Interrupt Status (HIBMIS), offset 0x01C

This register is the masked interrupt status for the Hibernation module interrupt sources.

Hibernation Masked Interrupt Status (HIBMIS)

Offset 0x01C Type RO, reset 0x0000.0000



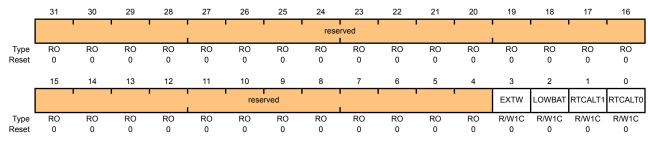
Bit/Field	Name	Type	Reset	Description
31:4	reserved	RO	0x000.0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	EXTW	RO	0	External Wake-Up Masked Interrupt Status
2	LOWBAT	RO	0	Low Battery Voltage Masked Interrupt Status
1	RTCALT1	RO	0	RTC Alert1 Masked Interrupt Status
0	RTCALT0	RO	0	RTC Alert0 Masked Interrupt Status

Register 9: Hibernation Interrupt Clear (HIBIC), offset 0x020

This register is the interrupt write-one-to-clear register for the Hibernation module interrupt sources.

Hibernation Interrupt Clear (HIBIC)

Offset 0x020 Type W1C, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:4	reserved	RO	0x000.0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	EXTW	R/W1C	0	External Wake-Up Masked Interrupt Clear Reads return an indeterminate value.
2	LOWBAT	R/W1C	0	Low Battery Voltage Masked Interrupt Clear Reads return an indeterminate value.
1	RTCALT1	R/W1C	0	RTC Alert1 Masked Interrupt Clear Reads return an indeterminate value.
0	RTCALT0	R/W1C	0	RTC Alert0 Masked Interrupt Clear Reads, return an indeterminate value.

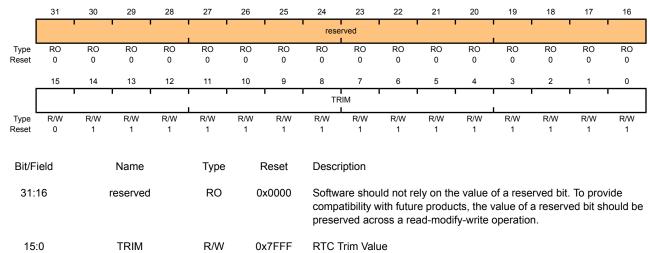
Register 10: Hibernation RTC Trim (HIBRTCT), offset 0x024

This register contains the value that is used to trim the RTC clock predivider. It represents the computed underflow value that is used during the trim cycle. It is represented as $0x7FFF \pm N$ clock cycles.

Hibernation RTC Trim (HIBRTCT)

Offset 0x024

Type R/W, reset 0x0000.0000



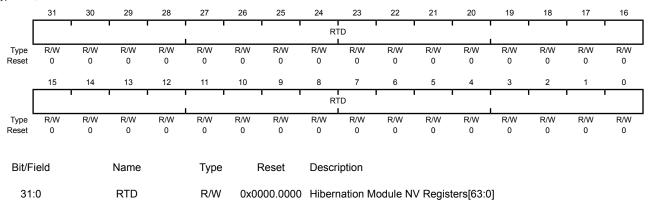
This value is loaded into the RTC predivider every 64 seconds. It is used to adjust the RTC rate to account for drift and inaccuracy in the clock source. The compensation is made by software by adjusting the default value of 0x7FFF up or down.

Register 11: Hibernation Data (HIBDATA), offset 0x030-0x12C

This address space is implemented as a 64x32-bit memory (256 bytes). It can be loaded by the system processor in order to store any non-volatile state data and will not lose power during a power cut operation.

Hibernation Data (HIBDATA)

Offset 0x030-0x12C Type R/W, reset 0x0000.0000

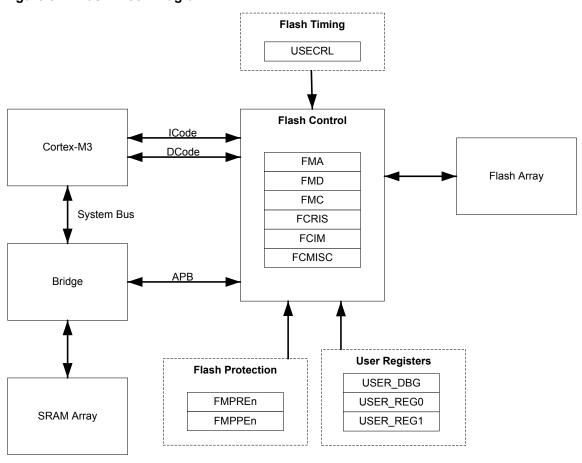


8 Internal Memory

The LM3S2739 microcontroller comes with 64 KB of bit-banded SRAM and 128 KB of flash memory. The flash controller provides a user-friendly interface, making flash programming a simple task. Flash protection can be applied to the flash memory on a 2-KB block basis.

8.1 Block Diagram

Figure 8-1. Flash Block Diagram



8.2 Functional Description

This section describes the functionality of both the flash and SRAM memories.

8.2.1 SRAM Memory

The internal SRAM of the Stellaris[®] devices is located at address 0x2000.0000 of the device memory map. To reduce the number of time consuming read-modify-write (RMW) operations, ARM has introduced *bit-banding* technology in the Cortex-M3 processor. With a bit-band-enabled processor, certain regions in the memory map (SRAM and peripheral space) can use address aliases to access individual bits in a single, atomic operation.

The bit-band alias is calculated by using the formula:

```
bit-band alias = bit-band base + (byte offset * 32) + (bit number * 4)
```

For example, if bit 3 at address 0x2000.1000 is to be modified, the bit-band alias is calculated as:

```
0x2200.0000 + (0x1000 * 32) + (3 * 4) = 0x2202.000C
```

With the alias address calculated, an instruction performing a read/write to address 0x2202.000C allows direct access to only bit 3 of the byte at address 0x2000.1000.

For details about bit-banding, please refer to Chapter 4, "Memory Map" in the *ARM*® *Cortex*™-*M3 Technical Reference Manual.*

8.2.2 Flash Memory

The flash is organized as a set of 1-KB blocks that can be individually erased. Erasing a block causes the entire contents of the block to be reset to all 1s. An individual 32-bit word can be programmed to change bits that are currently 1 to a 0. These blocks are paired into a set of 2-KB blocks that can be individually protected. The protection allows blocks to be marked as read-only or execute-only, providing different levels of code protection. Read-only blocks cannot be erased or programmed, protecting the contents of those blocks from being modified. Execute-only blocks cannot be erased or programmed, and can only be read by the controller instruction fetch mechanism, protecting the contents of those blocks from being read by either the controller or by a debugger.

8.2.2.1 Flash Memory Timing

The timing for the flash is automatically handled by the flash controller. However, in order to do so, it must know the clock rate of the system in order to time its internal signals properly. The number of clock cycles per microsecond must be provided to the flash controller for it to accomplish this timing. It is software's responsibility to keep the flash controller updated with this information via the **USec Reload (USECRL)** register.

On reset, the **USECRL** register is loaded with a value that configures the flash timing so that it works with the maximum clock rate of the part. If software changes the system operating frequency, the new operating frequency minus 1 (in MHz) must be loaded into **USECRL** before any flash modifications are attempted. For example, if the device is operating at a speed of 20 MHz, a value of 0x13 (20-1) must be written to the **USECRL** register.

8.2.2.2 Flash Memory Protection

The user is provided two forms of flash protection per 2-KB flash blocks intwo pairs of 32-bit wide registers. The protection policy for each form is controlled by individual bits (per policy per block) in the **FMPPEn** and **FMPREn** registers.

- Flash Memory Protection Program Enable (FMPPEn): If set, the block may be programmed (written) or erased. If cleared, the block may not be changed.
- Flash Memory Protection Read Enable (FMPREn): If set, the block may be executed or read by software or debuggers. If cleared, the block may only be executed. The contents of the memory block are prohibited from being accessed as data and traversing the DCode bus.

The policies may be combined as shown in Table 8-1 on page 133.

Table 8-1. Flash Protection Policy Combinations

FMPPEn	FMPREn	Protection
0		Execute-only protection. The block may only be executed and may not be written or erased. This mode is used to protect code.
1	0	The block may be written, erased or executed, but not read. This combination is unlikely to be used.
0		Read-only protection. The block may be read or executed but may not be written or erased. This mode is used to lock the block from further modification while allowing any read or execute access.
1	1	No protection. The block may be written, erased, executed or read.

An access that attempts to program or erase a PE-protected block is prohibited. A controller interrupt may be optionally generated (by setting the AMASK bit in the **FIM** register) to alert software developers of poorly behaving software during the development and debug phases.

An access that attempts to read an RE-protected block is prohibited. Such accesses return data filled with all 0s. A controller interrupt may be optionally generated to alert software developers of poorly behaving software during the development and debug phases.

The factory settings for the **FMPREn** and **FMPPEn** registers are a value of 1 for all implemented banks. This implements a policy of open access and programmability. The register bits may be changed by writing the specific register bit. The changes are not permanent until the register is committed (saved), at which point the bit change is permanent. If a bit is changed from a 1 to a 0 and not committed, it may be restored by executing a power-on reset sequence. Details on programming these bits are discussed in "Nonvolatile Register Programming" on page 134.

8.3 Flash Memory Initialization and Configuration

8.3.1 Flash Programming

The Stellaris[®] devices provide a user-friendly interface for flash programming. All erase/program operations are handled via three registers: **FMA**, **FMD**, and **FMC**.

8.3.1.1 To program a 32-bit word:

- Write source data to the FMD register.
- Write the target address to the FMA register.
- Write the flash write key and the WRITE bit (a value of 0xA442.0001) to the FMC register.
- 4. Poll the **FMC** register until the WRITE bit is cleared.

8.3.1.2 To perform an erase of a 1-KB page:

- 1. Write the page address to the **FMA** register.
- 2. Write the flash write key and the ERASE bit (a value of 0xA442.0002) to the **FMC** register.
- 3. Poll the FMC register until the ERASE bit is cleared.

8.3.1.3 To perform a mass erase of the flash:

- 1. Write the flash write key and the MERASE bit (a value of 0xA442.0004) to the FMC register.
- 2. Poll the FMC register until the MERASE bit is cleared.

8.3.2 Nonvolatile Register Programming

This section discusses how to update registers that are resident within the flash memory itself. These registers exist in a separate space from the main flash array and are not affected by an ERASE or MASS ERASE operation. These nonvolatile registers are updated by using the COMT bit in the **FMC** register to activate a write operation. For the **USER_DBG** register, the data to be written must be loaded into the **FMD** register before it is "committed". All other registers are R/W and can have their operation tried before committing them to nonvolatile memory.

Important: These register can only have bits changed from 1 to 0 by the user and there is no mechanism for the user to erase them back to a 1 value.

In addition, the **USER_REG0**, **USER_REG1**, and **USER_DBG** use bit 31 (NOTWRITTEN) of their respective registers to indicate that they are available for user write. These three registers can only be written once whereas the flash protection registers may be written multiple times. Table 8-2 on page 134 provides the FMA address required for commitment of each of the registers and the source of the data to be written when the COMT bit of the **FMC** register is written with a value of 0xA442.0008. After writing the COMT bit, the user may poll the **FMC** register to wait for the commit operation to complete.

Table 8-2. Flash Resident Registers^a

Register to be Committed	FMA Value	Data Source
FMPRE0	0x0000.0000	FMPRE0
FMPRE1	0x0000.0002	FMPRE1
FMPRE2	0x0000.0004	FMPRE2
FMPRE3	0x0000.0008	FMPRE3
FMPPE0	0x0000.0001	FMPPE0
FMPPE1	0x0000.0003	FMPPE1
FMPPE2	0x0000.0005	FMPPE2
FMPPE3	0x0000.0007	FMPPE3
USER_REG0	0x8000.0000	USER_REG0
USER_REG1	0x8000.0001	USER_REG1
USER_DBG	0x7510.0000	FMD

a. Which **FMPREn** and **FMPPEn** registers are available depend on the flash size of your particular Stellaris[®] device.

8.4 Register Map

"Register Map" on page 134 lists the Flash memory and control registers. The offset listed is a hexadecimal increment to the register's address. The **FMA**, **FMD**, **FMC**, **FCRIS**, **FCIM**, and **FCMISC** registers are relative to the Flash control base address of 0x400F.D000. The **FMPPEn**, **USECRL**, **USER_DBG**, and **USER_REGn** registers are relative to the System Control base address of 0x400F.E000.

Note: A BV in the Reset column indicates the reset is a Build Value and part-specific. See the page number referenced for the reset value description.

Table 8-3. Internal Memory Register Map

Offse	t Name	Туре	Reset	Description	See page
0x000) FMA	R/W	0x0000.0000	Flash Memory Address	136

Offset	Name	Туре	Reset	Description	See page
0x004	FMD	R/W	0x0000.0000	Flash Memory Data	137
0x008	FMC	R/W	0x0000.0000	Flash Memory Control	138
0x00C	FCRIS	RO	0x0000.0000	Flash Controller Raw Interrupt Status	140
0x010	FCIM	R/W	0x0000.0000	Flash Controller Interrupt Mask	141
0x014	FCMISC	R/W1C	0x0000.0000	Flash Controller Masked Interrupt Status and Clear	142
0x130	FMPRE0	R/W	BV	Flash Memory Protection Read Enable 0	144
0x200	FMPRE0	R/W	BV	Flash Memory Protection Read Enable 0	144
0x134	FMPPE0	R/W	BV	Flash Memory Protection Program Enable 0	145
0x400	FMPPE0	R/W	BV	Flash Memory Protection Program Enable 0	145
0x140	USECRL	R/W	0x31	USec Reload	143
0x1D0	USER_DBG	R/W	BV	User Debug	146
0x1E0	USER_REG0	R/W	BV	User Register 0	147
0x1E4	USER_REG1	R/W	BV	User Register 1	148
0x204	FMPRE1	R/W	BV	Flash Memory Protection Read Enable 1	149
0x208	FMPRE2	R/W	BV	Flash Memory Protection Read Enable 2	150
0x20C	FMPRE3	R/W	BV	Flash Memory Protection Read Enable 3	151
0x404	FMPPE1	R/W	BV	Flash Memory Protection Program Enable 1	152
0x408	FMPPE2	R/W	BV	Flash Memory Protection Program Enable 2	153
0x40C	FMPPE3	R/W	BV	Flash Memory Protection Program Enable 3	154

8.5 Flash Register Descriptions

The remainder of this section lists and describes the Flash Memory registers, in numerical order by address offset.

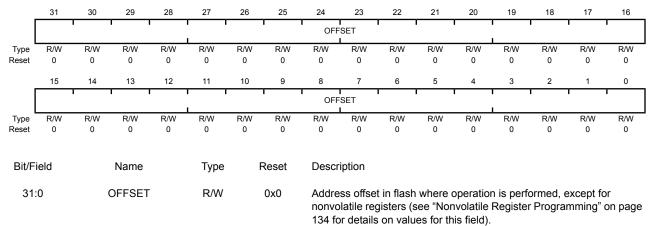
Register 1: Flash Memory Address (FMA), offset 0x000

During a write operation, this register contains a 4-byte-aligned address and specifies where the data is written. During erase operations, this register contains a 1 KB-aligned address and specifies which page is erased. Note that the alignment requirements must be met by software or the results of the operation are unpredictable.

Flash Memory Address (FMA)

Base 0x400F.D000

Offset 0x000 Type R/W, reset 0x0000.0000



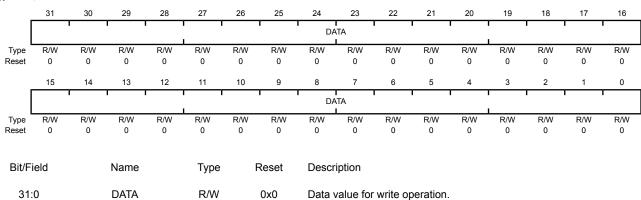
Register 2: Flash Memory Data (FMD), offset 0x004

This register contains the data to be written during the programming cycle or read during the read cycle. Note that the contents of this register are undefined for a read access of an execute-only block. This register is not used during the erase cycles.

Flash Memory Data (FMD)

Base 0x400F.D000

Offset 0x004 Type R/W, reset 0x0000.0000



Register 3: Flash Memory Control (FMC), offset 0x008

When this register is written, the flash controller initiates the appropriate access cycle for the location specified by the Flash Memory Address (FMA) register (see page 136). If the access is a write access, the data contained in the Flash Memory Data (FMD) register (see page 137) is written.

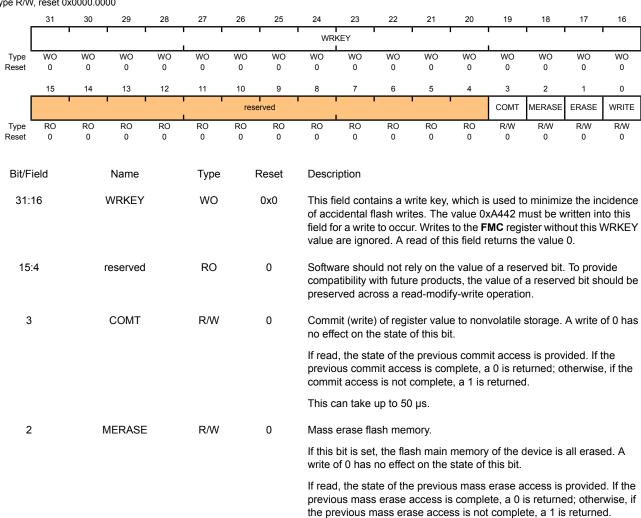
This is the final register written and initiates the memory operation. There are four control bits in the lower byte of this register that, when set, initiate the memory operation. The most used of these register bits are the ERASE and WRITE bits.

It is a programming error to write multiple control bits and the results of such an operation are unpredictable.

Flash Memory Control (FMC)

Base 0x400F.D000 Offset 0x008

Type R/W, reset 0x0000.0000



This can take up to 250 ms.

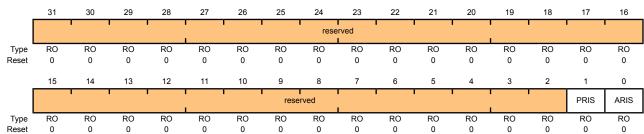
Bit/Field	Name	Type	Reset	Description
1	ERASE	R/W	0	Erase a page of flash memory.
				If this bit is set, the page of flash main memory as specified by the contents of FMA is erased. A write of 0 has no effect on the state of this bit.
				If read, the state of the previous erase access is provided. If the previous erase access is complete, a 0 is returned; otherwise, if the previous erase access is not complete, a 1 is returned.
				This can take up to 25 ms.
0	WRITE	R/W	0	Write a word into flash memory.
				If this bit is set, the data stored in FMD is written into the location as specified by the contents of FMA . A write of 0 has no effect on the state of this bit.
				If read, the state of the previous write update is provided. If the previous write access is complete, a 0 is returned; otherwise, if the write access is not complete, a 1 is returned.
				This can take up to 50 μs.

Register 4: Flash Controller Raw Interrupt Status (FCRIS), offset 0x00C

This register indicates that the flash controller has an interrupt condition. An interrupt is only signaled if the corresponding **FCIM** register bit is set.

Flash Controller Raw Interrupt Status (FCRIS)

Base 0x400F.D000 Offset 0x00C Type RO, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	PRIS	RO	0	Programming Raw Interrupt Status
				This bit indicates the current state of the programming cycle. If set, the programming cycle completed; if cleared, the programming cycle has not completed. Programming cycles are either write or erase actions generated through the Flash Memory Control (FMC) register bits (see page 138).
0	ARIS	RO	0	Access Raw Interrupt Status

This bit indicates if the flash was improperly accessed. If set, the program tried to access the flash counter to the policy as set in the Flash Memory Protection Read Enable (FMPREn) and Flash Memory Protection Program Enable (FMPPEn) registers. Otherwise, no access has tried to improperly access the flash.

Register 5: Flash Controller Interrupt Mask (FCIM), offset 0x010

This register controls whether the flash controller generates interrupts to the controller.

Flash Controller Interrupt Mask (FCIM)

Name

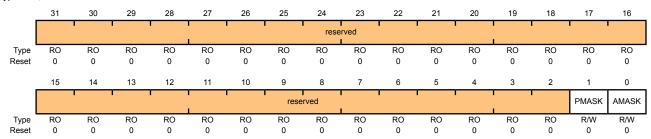
Type

Reset

Base 0x400F.D000 Offset 0x010

Bit/Field

Type R/W, reset 0x0000.0000



31:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	PMASK	R/W	0	Programming Interrupt Mask
				This bit controls the reporting of the programming raw interrupt status to the controller. If set, a programming-generated interrupt is promoted to the controller. Otherwise, interrupts are recorded but suppressed from the controller.
0	AMASK	R/W	0	Access Interrupt Mask

Description

This bit controls the reporting of the access raw interrupt status to the controller. If set, an access-generated interrupt is promoted to the controller. Otherwise, interrupts are recorded but suppressed from the controller.

Register 6: Flash Controller Masked Interrupt Status and Clear (FCMISC), offset 0x014

This register provides two functions. First, it reports the cause of an interrupt by indicating which interrupt source or sources are signalling the interrupt. Second, it serves as the method to clear the interrupt reporting.

Flash Controller Masked Interrupt Status and Clear (FCMISC)

Name

AMISC

Type

R/W1C

Reset

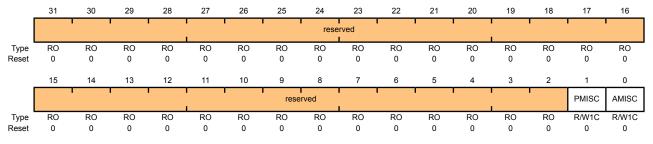
0

Base 0x400F.D000

Bit/Field

0

Offset 0x014
Type R/W1C, reset 0x0000.0000



31:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	PMISC	R/W1C	0	Programming Masked Interrupt Status and Clear
				This bit indicates whether an interrupt was signaled because a programming cycle completed and was not masked. This bit is cleared by writing a 1. The PRIS bit in the FCRIS register (see page 140) is also cleared when the PMISC bit is cleared.

Description

This bit indicates whether an interrupt was signaled because an improper access was attempted and was not masked. This bit is cleared by writing a 1. The \mathtt{ARIS} bit in the FCRIS register is also cleared when the \mathtt{AMISC} bit is cleared.

Access Masked Interrupt Status and Clear

Register 7: USec Reload (USECRL), offset 0x140

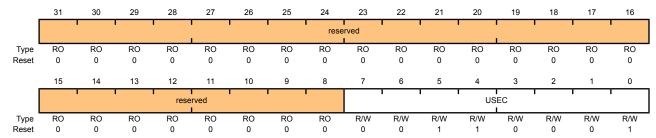
Note: Offset is relative to System Control base address of 0x400F.E000

This register is provided as a means of creating a 1-µs tick divider reload value for the flash controller. The internal flash has specific minimum and maximum requirements on the length of time the high voltage write pulse can be applied. It is required that this register contain the operating frequency (in MHz -1) whenever the flash is being erased or programmed. The user is required to change this value if the clocking conditions are changed for a flash erase/program operation.

USec Reload (USECRL)

Base 0x400F.E000 Offset 0x140 Type R/W, reset 0x31

D:4/E: -1-4



Bit/Field	Name	туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	USEC	R/W	0x31	MHz -1 of the controller clock when the flash is being erased or

programmed. ${\tt USEC\ should\ be\ set\ to\ 0x31\ (50\ MHz)\ whenever\ the\ flash\ is\ being\ erased}$

or programmed.

Register 8: Flash Memory Protection Read Enable 0 (FMPRE0), offset 0x130 and 0x200

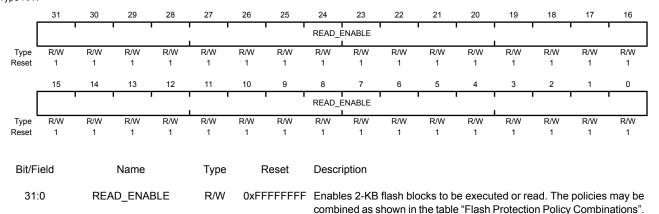
Note: This register is aliased for backwards compatability.

Note: Offset is relative to System Control base address of 0x400FE000.

This register stores the read-only protection bits for each 2-KB flash block (**FMPPEn** stores the execute-only bits). This register is loaded during the power-on reset sequence. The factory settings for the **FMPREn** and **FMPPEn** registers are a value of 1 for all implemented banks. This achieves a policy of open access and programmability. The register bits may be changed by writing the specific register bit. However, this register is R/W0; the user can only change the protection bit from a 1 to a 0 (and may NOT change a 0 to a 1). The changes are not permanent until the register is committed (saved), at which point the bit change is permanent. If a bit is changed from a 1 to a 0 and not committed, it may be restored by executing a power-on reset sequence. For additional information, see the "Flash Memory Protection" section.

Flash Memory Protection Read Enable 0 (FMPRE0)

Base 0x400F.D000 Offset 0x130 and 0x200 Type R/W



Value Description

0xFFFFFFFF Enables 128 KB of flash.

Register 9: Flash Memory Protection Program Enable 0 (FMPPE0), offset 0x134 and 0x400

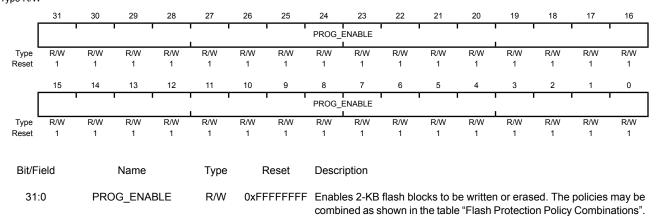
Note: This register is aliased for backwards compatability.

Note: Offset is relative to System Control base address of 0x400FE000.

This register stores the execute-only protection bits for each 2-KB flash block (**FMPREn** stores the execute-only bits). This register is loaded during the power-on reset sequence. The factory settings for the **FMPREn** and **FMPPEn** registers are a value of 1 for all implemented banks. This achieves a policy of open access and programmability. The register bits may be changed by writing the specific register bit. However, this register is R/W0; the user can only change the protection bit from a 1 to a 0 (and may NOT change a 0 to a 1). The changes are not permanent until the register is committed (saved), at which point the bit change is permanent. If a bit is changed from a 1 to a 0 and not committed, it may be restored by executing a power-on reset sequence. For additional information, see the "Flash Memory Protection" section.

Flash Memory Protection Program Enable 0 (FMPPE0)

Base 0x400F.D000 Offset 0x134 and 0x400 Type R/W



Value Description

0xFFFFFFFF Enables 128 KB of flash.

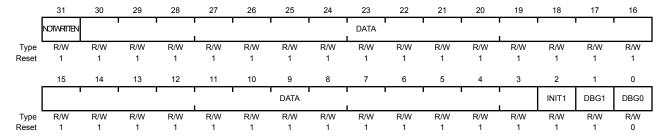
Register 10: User Debug (USER_DBG), offset 0x1D0

Note: Offset is relative to System Control base address of 0x400FE000.

This register provides a write-once mechanism to disable external debugger access to the device in addition to 27 additional bits of user-defined data. The DBG0 bit (bit 0) is set to 0 from the factory and the DBG1 bit (bit 1) is set to 1, which enables external debuggers. Changing the DBG1 bit to 0 disables any external debugger access to the device permanently, starting with the next power-up cycle of the device. The NOTWRITTEN bit (bit 31) indicates that the register is available to be written and is controlled through hardware to ensure that the register is only written once.

User Debug (USER DBG)

Base 0x400F.E000 Offset 0x1D0 Type R/W



Bit/Field	Name	Type	Reset	Description
31	NOTWRITTEN	R/W	1	Specifies that this 32-bit dword has not been written.
30:3	DATA	R/W	0xFFFFFFF	Contains the user data value. This field is initialized to all 1s and can only be written once.
2	INIT1	R/W	1	User data initialized to 1.
1	DBG1	R/W	1	The $\mathtt{DBG1}$ bit must be 1 and $\mathtt{DBG0}$ must be 0 for debug to be available.
0	DBG0	R/W	0	The DBG1 bit must be 1 and DBG0 must be 0 for debug to be available.

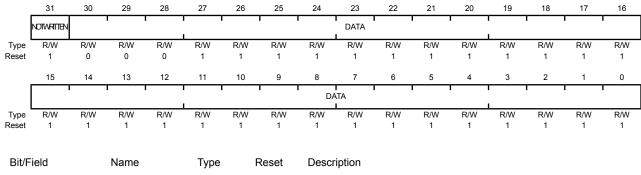
Register 11: User Register 0 (USER_REG0), offset 0x1E0

Note: Offset is relative to System Control base address of 0x400FE000.

This register provides 31 bits of user-defined data that is non-volatile and can only be written once. Bit 31 indicates that the register is available to be written and is controlled through hardware to ensure that the register is only written once. The write-once characteristics of this register are useful for keeping static information like communication addresses that need to be unique per part and would otherwise require an external EEPROM or other non-volatile device.

User Register 0 (USER_REG0)

Base 0x400F.E000 Offset 0x1E0 Type R/W



		• •		·
31	NOTWRITTEN	R/W	1	Specifies that this 32-bit dword has not been written.
30:0	DATA	R/W	0xFFFFFFF	Contains the user data value. This field is initialized to all 1s and can only be written once.

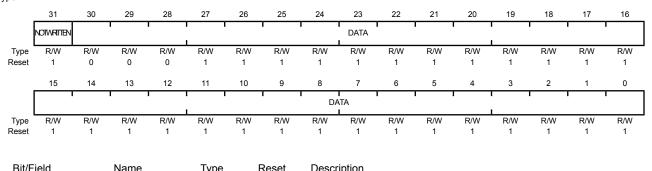
Register 12: User Register 1 (USER_REG1), offset 0x1E4

Note: Offset is relative to System Control base address of 0x400FE000.

This register provides 31 bits of user-defined data that is non-volatile and can only be written once. Bit 31 indicates that the register is available to be written and is controlled through hardware to ensure that the register is only written once. The write-once characteristics of this register are useful for keeping static information like communication addresses that need to be unique per part and would otherwise require an external EEPROM or other non-volatile device.

User Register 1 (USER_REG1)

Base 0x400F.E000 Offset 0x1E4 Type R/W



Didi icia	Name	Турс	110001	Beschiption
31	NOTWRITTEN	R/W	1	Specifies that this 32-bit dword has not been written.
30:0	DATA	R/W	0xFFFFFF	Contains the user data value. This field is initialized to all 1s and can only be written once.

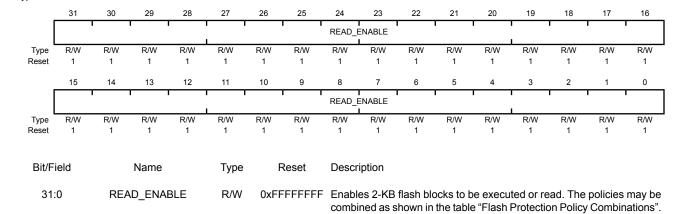
Register 13: Flash Memory Protection Read Enable 1 (FMPRE1), offset 0x204

Note: Offset is relative to System Control base address of 0x400FE000.

This register stores the read-only protection bits for each 2-KB flash block (**FMPPEn** stores the execute-only bits). This register is loaded during the power-on reset sequence. The factory settings for the **FMPREn** and **FMPPEn** registers are a value of 1 for all implemented banks. This achieves a policy of open access and programmability. The register bits may be changed by writing the specific register bit. However, this register is R/W0; the user can only change the protection bit from a 1 to a 0 (and may NOT change a 0 to a 1). The changes are not permanent until the register is committed (saved), at which point the bit change is permanent. If a bit is changed from a 1 to a 0 and not committed, it may be restored by executing a power-on reset sequence. For additional information, see the "Flash Memory Protection" section.



Type R/W



Value Description

0xFFFFFFF Enables 128 KB of flash.

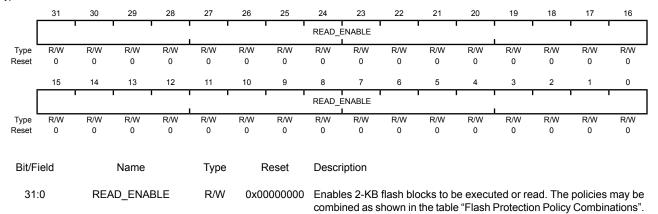
Register 14: Flash Memory Protection Read Enable 2 (FMPRE2), offset 0x208

Note: Offset is relative to System Control base address of 0x400FE000.

This register stores the read-only protection bits for each 2-KB flash block (**FMPPEn** stores the execute-only bits). This register is loaded during the power-on reset sequence. The factory settings for the **FMPREn** and **FMPPEn** registers are a value of 1 for all implemented banks. This achieves a policy of open access and programmability. The register bits may be changed by writing the specific register bit. However, this register is R/W0; the user can only change the protection bit from a 1 to a 0 (and may NOT change a 0 to a 1). The changes are not permanent until the register is committed (saved), at which point the bit change is permanent. If a bit is changed from a 1 to a 0 and not committed, it may be restored by executing a power-on reset sequence. For additional information, see the "Flash Memory Protection" section.

Flash Memory Protection Read Enable 2 (FMPRE2)

Base 0x400F.E000 Offset 0x208 Type R/W



Value Description

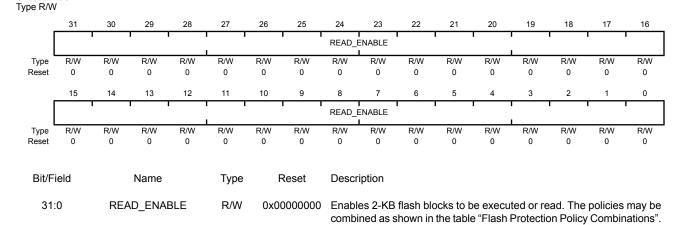
0x00000000 Enables 128 KB of flash.

Register 15: Flash Memory Protection Read Enable 3 (FMPRE3), offset 0x20C

Note: Offset is relative to System Control base address of 0x400FE000.

This register stores the read-only protection bits for each 2-KB flash block (**FMPPEn** stores the execute-only bits). This register is loaded during the power-on reset sequence. The factory settings for the **FMPREn** and **FMPPEn** registers are a value of 1 for all implemented banks. This achieves a policy of open access and programmability. The register bits may be changed by writing the specific register bit. However, this register is R/W0; the user can only change the protection bit from a 1 to a 0 (and may NOT change a 0 to a 1). The changes are not permanent until the register is committed (saved), at which point the bit change is permanent. If a bit is changed from a 1 to a 0 and not committed, it may be restored by executing a power-on reset sequence. For additional information, see the "Flash Memory Protection" section.

Flash Memory Protection Read Enable 3 (FMPRE3)
Base 0x400F.E000
Offset 0x20C



Value Description

0x00000000 Enables 128 KB of flash.

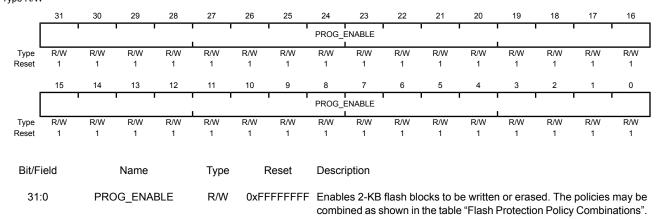
Register 16: Flash Memory Protection Program Enable 1 (FMPPE1), offset 0x404

Note: Offset is relative to System Control base address of 0x400FE000.

This register stores the execute-only protection bits for each 2-KB flash block (**FMPREn** stores the execute-only bits). This register is loaded during the power-on reset sequence. The factory settings for the **FMPREn** and **FMPPEn** registers are a value of 1 for all implemented banks. This achieves a policy of open access and programmability. The register bits may be changed by writing the specific register bit. However, this register is R/W0; the user can only change the protection bit from a 1 to a 0 (and may NOT change a 0 to a 1). The changes are not permanent until the register is committed (saved), at which point the bit change is permanent. If a bit is changed from a 1 to a 0 and not committed, it may be restored by executing a power-on reset sequence. For additional information, see the "Flash Memory Protection" section.

Flash Memory Protection Program Enable 1 (FMPPE1)

Base 0x400F.E000 Offset 0x404 Type R/W



Value Description

0xFFFFFFF Enables 128 KB of flash.

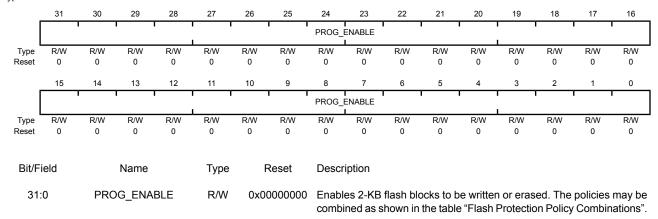
Register 17: Flash Memory Protection Program Enable 2 (FMPPE2), offset 0x408

Note: Offset is relative to System Control base address of 0x400FE000.

This register stores the execute-only protection bits for each 2-KB flash block (**FMPREn** stores the execute-only bits). This register is loaded during the power-on reset sequence. The factory settings for the **FMPREn** and **FMPPEn** registers are a value of 1 for all implemented banks. This achieves a policy of open access and programmability. The register bits may be changed by writing the specific register bit. However, this register is R/W0; the user can only change the protection bit from a 1 to a 0 (and may NOT change a 0 to a 1). The changes are not permanent until the register is committed (saved), at which point the bit change is permanent. If a bit is changed from a 1 to a 0 and not committed, it may be restored by executing a power-on reset sequence. For additional information, see the "Flash Memory Protection" section.

Flash Memory Protection Program Enable 2 (FMPPE2)

Base 0x400F.E000 Offset 0x408 Type R/W



Value Description

0x00000000 Enables 128 KB of flash.

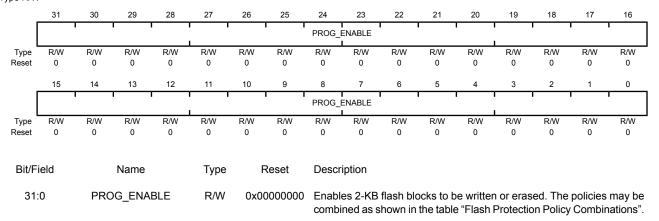
Register 18: Flash Memory Protection Program Enable 3 (FMPPE3), offset 0x40C

Note: Offset is relative to System Control base address of 0x400FE000.

This register stores the execute-only protection bits for each 2-KB flash block (**FMPREn** stores the execute-only bits). This register is loaded during the power-on reset sequence. The factory settings for the **FMPREn** and **FMPPEn** registers are a value of 1 for all implemented banks. This achieves a policy of open access and programmability. The register bits may be changed by writing the specific register bit. However, this register is R/W0; the user can only change the protection bit from a 1 to a 0 (and may NOT change a 0 to a 1). The changes are not permanent until the register is committed (saved), at which point the bit change is permanent. If a bit is changed from a 1 to a 0 and not committed, it may be restored by executing a power-on reset sequence. For additional information, see the "Flash Memory Protection" section.

Flash Memory Protection Program Enable 3 (FMPPE3)

Base 0x400F.E000 Offset 0x40C Type R/W



Value Description
0x00000000 Enables 128 KB of flash.

9 General-Purpose Input/Outputs (GPIOs)

The GPIO module is composed of eight physical GPIO blocks, each corresponding to an individual GPIO port (Port A, Port B, Port C, Port D, Port E, Port F, Port G, and Port H). The GPIO module is FiRM-compliant and supports 18-56 programmable input/output pins, depending on the peripherals being used.

The GPIO module has the following features:

- Programmable control for GPIO interrupts
 - Interrupt generation masking
 - Edge-triggered on rising, falling, or both
 - Level-sensitive on High or Low values
- 5-V-tolerant input/outputs
- Bit masking in both read and write operations through address lines
- Programmable control for GPIO pad configuration
 - Weak pull-up or pull-down resistors
 - 2-mA, 4-mA, and 8-mA pad drive
 - Slew rate control for the 8-mA drive
 - Open drain enables
 - Digital input enables

9.1 Function Description

Important: All GPIO pins are tri-stated by default (GPIOAFSEL=0, GPIODEN=0, GPIOPDR=0, and GPIOPUR=0), with the exception of the five JTAG/SWD pins (PB7 and PC[3:0]). The JTAG/SWD pins default to their JTAG/SWD functionality (GPIOAFSEL=1, GPIODEN=1 and GPIOPUR=1). A Power-On-Reset (POR) or asserting RST puts both groups of pins back to their default state.

Each GPIO port is a separate hardware instantiation of the same physical block. The LM3S2739 microcontroller contains eight ports and thus eight of these physical GPIO blocks.

9.1.1 Data Control

The data control registers allow software to configure the operational modes of the GPIOs. The data direction register configures the GPIO as an input or an output while the data register either captures incoming data or drives it out to the pads.

9.1.1.1 Data Direction Operation

The **GPIO Direction (GPIODIR)** register (see page 163) is used to configure each individual pin as an input or output. When the data direction bit is set to 0, the GPIO is configured as an input and the corresponding data register bit will capture and store the value on the GPIO port. When the data

direction bit is set to 1, the GPIO is configured as an output and the corresponding data register bit will be driven out on the GPIO port.

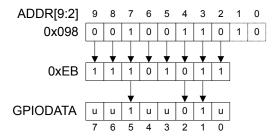
9.1.1.2 Data Register Operation

To aid in the efficiency of software, the GPIO ports allow for the modification of individual bits in the **GPIO Data (GPIODATA)** register (see page 162) by using bits [9:2] of the address bus as a mask. This allows software drivers to modify individual GPIO pins in a single instruction, without affecting the state of the other pins. This is in contrast to the "typical" method of doing a read-modify-write operation to set or clear an individual GPIO pin. To accommodate this feature, the **GPIODATA** register covers 256 locations in the memory map.

During a write, if the address bit associated with that data bit is set to 1, the value of the **GPIODATA** register is altered. If it is cleared to 0, it is left unchanged.

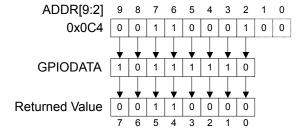
For example, writing a value of 0xEB to the address GPIODATA + 0x098 would yield as shown in Figure 9-1 on page 156, where u is data unchanged by the write.

Figure 9-1. GPIODATA Write Example



During a read, if the address bit associated with the data bit is set to 1, the value is read. If the address bit associated with the data bit is set to 0, it is read as a zero, regardless of its actual value. For example, reading address GPIODATA + 0x0C4 yields as shown in Figure 9-2 on page 156.

Figure 9-2. GPIODATA Read Example



9.1.2 Interrupt Control

The interrupt capabilities of each GPIO port are controlled by a set of seven registers. With these registers, it is possible to select the source of the interrupt, its polarity, and the edge properties. When one or more GPIO inputs cause an interrupt, a single interrupt output is sent to the interrupt controller for the entire GPIO port. For edge-triggered interrupts, software must clear the interrupt to enable any further interrupts. For a level-sensitive interrupt, it is assumed that the external source holds the level constant for the interrupt to be recognized by the controller.

Three registers are required to define the edge or sense that causes interrupts:

- GPIO Interrupt Sense (GPIOIS) register (see page 164)
- GPIO Interrupt Both Edges (GPIOIBE) register (see page 165)
- GPIO Interrupt Event (GPIOIEV) register (see page 166)

Interrupts are enabled/disabled via the GPIO Interrupt Mask (GPIOIM) register (see page 167).

When an interrupt condition occurs, the state of the interrupt signal can be viewed in two locations: the **GPIO Raw Interrupt Status (GPIORIS)** and **GPIO Masked Interrupt Status (GPIOMIS)** registers (see page 168 and page 169). As the name implies, the **GPIOMIS** register only shows interrupt conditions that are allowed to be passed to the controller. The **GPIORIS** register indicates that a GPIO pin meets the conditions for an interrupt, but has not necessarily been sent to the controller.

In addition to providing GPIO functionality, PB4 can also be used as an external trigger for the ADC. If PB4 is configured as a non-masked interrupt pin (GPIOIM is set to 1), not only is an interrupt for PortB generated, but an external trigger signal is sent to the ADC. If the **ADC Event Multiplexer Select (ADCEMUX)** register is configured to use the external trigger, an ADC conversion is initiated.

If no other PortB pins are being used to generate interrupts, the ARM Integrated Nested Vectored Interrupt Controller (NVIC) Interrupt Set Enable (SETNA) register can disable the PortB interrupts and the ADC interrupt can be used to read back the converted data. Otherwise, the PortB interrupt handler needs to ignore and clear interrupts on B4, and wait for the ADC interrupt or the ADC interrupt needs to be disabled in the SETNA register and the PortB interrupt handler polls the ADC registers until the conversion is completed.

Interrupts are cleared by writing a 1 to the GPIO Interrupt Clear (GPIOICR) register (see page 170).

When programming the following interrupt control registers, the interrupts should be masked (**GPIOIM** set to 0). Writing any value to an interrupt control register (**GPIOIS**, **GPIOIBE**, or **GPIOIEV**) can generate a spurious interrupt if the corresponding bits are enabled.

9.1.3 Mode Control

The GPIO pins can be controlled by either hardware or software. When hardware control is enabled via the **GPIO Alternate Function Select (GPIOAFSEL)** register (see page 171), the pin state is controlled by its alternate function (that is, the peripheral). Software control corresponds to GPIO mode, where the **GPIODATA** register is used to read/write the corresponding pins.

9.1.4 Commit Control

The commit control registers provide a layer of protection against accidental programming of critical hardware peripherals. Writes to protected bits of the **GPIO Alternate Function Select (GPIOAFSEL)** register (see page 171) are not committed to storage unless the **GPIO Lock (GPIOLOCK)** register (see page 181) has been unlocked and the appropriate bits of the **GPIO Commit (GPIOCR)** register (see page 182) have been set to 1.

9.1.5 Pad Control

The pad control registers allow for GPIO pad configuration by software based on the application requirements. The pad control registers include the GPIODR2R, GPIODR4R, GPIODR8R, GPIODDR, GPIOPDR, GPIOPDR, GPIOPDR, and GPIODEN registers.

9.1.6 Identification

The identification registers configured at reset allow software to detect and identify the module as a GPIO block. The identification registers include the **GPIOPeriphID0-GPIOPeriphID7** registers as well as the **GPIOPCeIIID0-GPIOPCeIIID3** registers.

9.2 Initialization and Configuration

To use the GPIO, the peripheral clock must be enabled by setting the appropriate GPIO Port bit field (GPIOn) in the **RCGC2** register.

On reset, all GPIO pins (except for the five JTAG pins) are configured out of reset to be undriven (tristate): **GPIOAFSEL**=0, **GPIODEN**=0, **GPIOPDR**=0, and **GPIOPUR**=0. Table 9-1 on page 158 shows all possible configurations of the GPIO pads and the control register settings required to achieve them. Table 9-2 on page 159 shows how a rising edge interrupt would be configured for pin 2 of a GPIO port.

Table 9-1. GPIO Pad Configuration Examples

Configuration	GPIO Register Bit Value ^a												
	AFSEL	DIR	ODR	DEN	PUR	PDR	DR2R	DR4R	DR8R	SLR			
Digital Input (GPIO)	0	0	0	1	?	?	Х	Х	Х	Х			
Digital Output (GPIO)	0	1	0	1	?	?	?	?	?	?			
Open Drain Input (GPIO)	0	0	1	1	Х	Х	Х	Х	Х	Х			
Open Drain Output (GPIO)	0	1	1	1	Х	Х	?	?	?	?			
Open Drain Input/Output (I ² C)	1	Х	1	1	Х	Х	?	?	?	?			
Digital Input (Timer CCP)	1	Х	0	1	?	?	Х	Х	Х	Х			
Digital Input (QEI)	1	Х	0	1	?	?	Х	Х	Х	Х			
Digital Output (PWM)	1	Х	0	1	?	?	?	?	?	?			
Digital Output (Timer PWM)	1	Х	0	1	?	?	?	?	?	?			
Digital Input/Output (SSI)	1	Х	0	1	?	?	?	?	?	?			
Digital Input/Output (UART)	1	Х	0	1	?	?	?	?	?	?			
Analog Input (Comparator)	0	0	0	0	0	0	Х	Х	Х	Х			
Digital Output (Comparator)	1	Х	0	1	?	?	?	?	?	?			

a. X=Ignored (don't care bit)

^{?=}Can be either 0 or 1, depending on the configuration

Table 9-2. GPIO Interrupt Configuration Example

Register	Desired	Pin 2 Bit Value ^a										
	Interrupt Event Trigger	7	6	5	4	3	2	1	0			
GPIOIS	0=edge 1=level	Х	Х	Х	Х	Х	0	Х	Х			
GPIOIBE	0=single edge	Х	Х	Х	Х	X	0	X	Х			
	1=both edges											
GPIOIEV	0=Low level, or negative edge	X	X	X	X	X	1	X	X			
	1=High level, or positive edge											
GPIOIM	0=masked 1=not masked	0	0	0	0	0	1	0	0			

a. X=Ignored (don't care bit)

9.3 Register Map

"Register Map" on page 160 lists the GPIO registers. The offset listed is a hexadecimal increment to the register's address, relative to that GPIO port's base address:

GPIO Port A: 0x4000.4000

GPIO Port B: 0x4000.5000

GPIO Port C: 0x4000.6000

GPIO Port D: 0x4000.7000

GPIO Port E: 0x4002.4000

GPIO Port F: 0x4002.5000

GPIO Port G: 0x4002.6000

GPIO Port H: 0x4002.7000

Important: The GPIO registers in this chapter are duplicated in each GPIO block, however, depending on the block, all eight bits may not be connected to a GPIO pad. In those cases, writing to those unconnected bits has no effect and reading those unconnected bits returns no meaningful data.

Note: The default reset value for the **GPIOAFSEL**, **GPIOPUR**, and **GPIODEN** registers are 0x0000.0000 for all GPIO pins, with the exception of the five JTAG/SWD pins (PB7 and PC[3:0]). These five pins default to JTAG/SWD functionality. Because of this, the default reset value of these registers for GPIO Port B is 0x0000.0080 while the default reset value for Port C is 0x0000.000F.

The default register type for the **GPIOCR** register is RO for all GPIO pins, with the exception of the five JTAG/SWD pins (PB7 and PC[3:0]). These five pins are currently the only GPIOs that are protected by the **GPIOCR** register. Because of this, the register type for GPIO Port B7 and GPIO Port C[3:0] is R/W.

The default reset value for the **GPIOCR** register is 0x0000.00FF for all GPIO pins, with the exception of the five JTAG/SWD pins (PB7 and PC[3:0]). To ensure that the JTAG port is not accidentally programmed as a GPIO, these five pins default to non-commitable. Because of this, the default reset value of **GPIOCR** for GPIO Port B is 0x0000.007F while the default reset value of **GPIOCR** for Port C is 0x0000.00F0.

Table 9-3. GPIO Register Map

Offset	Name	Туре	Reset	Description	See page
0x000	GPIODATA	R/W	0x0000.0000	GPIO Data	162
0x400	GPIODIR	R/W	0x0000.0000	GPIO Direction	163
0x404	GPIOIS	R/W	0x0000.0000	GPIO Interrupt Sense	164
0x408	GPIOIBE	R/W	0x0000.0000	GPIO Interrupt Both Edges	165
0x40C	GPIOIEV	R/W	0x0000.0000	GPIO Interrupt Event	166
0x410	GPIOIM	R/W	0x0000.0000	GPIO Interrupt Mask	167
0x414	GPIORIS	RO	0x0000.0000	GPIO Raw Interrupt Status	168
0x418	GPIOMIS	RO	0x0000.0000	GPIO Masked Interrupt Status	169
0x41C	GPIOICR	W1C	0x0000.0000	GPIO Interrupt Clear	170
0x420	GPIOAFSEL	R/W	-	GPIO Alternate Function Select	171
0x500	GPIODR2R	R/W	0x0000.00FF	GPIO 2-mA Drive Select	173
0x504	GPIODR4R	R/W	0x0000.0000	GPIO 4-mA Drive Select	174
0x508	GPIODR8R	R/W	0x0000.0000	GPIO 8-mA Drive Select	175
0x50C	GPIOODR	R/W	0x0000.0000	GPIO Open Drain Select	176
0x510	GPIOPUR	R/W	-	GPIO Pull-Up Select	177
0x514	GPIOPDR	R/W	0x0000.0000	GPIO Pull-Down Select	178
0x518	GPIOSLR	R/W	0x0000.0000	GPIO Slew Rate Control Select	179
0x51C	GPIODEN	R/W	-	GPIO Digital Enable	180
0x520	GPIOLOCK	R/W	0x0000.0001	GPIO Lock	181
0x524	GPIOCR	-	-	GPIO Commit	182
0xFD0	GPIOPeriphID4	RO	0x0x0000.0000	GPIO Peripheral Identification 4	184
0xFD4	GPIOPeriphID5	RO	0x0x0000.0000	GPIO Peripheral Identification 5	185
0xFD8	GPIOPeriphID6	RO	0x0x0000.0000	GPIO Peripheral Identification 6	186
0xFDC	GPIOPeriphID7	RO	0x0x0000.0000	GPIO Peripheral Identification 7	187
0xFE0	GPIOPeriphID0	RO	0x0x0000.0061	GPIO Peripheral Identification 0	188

Offset	Name	Туре	Reset	Description	See page
0xFE4	GPIOPeriphID1	RO	0x0x0000.0000	GPIO Peripheral Identification 1	189
0xFE8	GPIOPeriphID2	RO	0x0x0000.0018	GPIO Peripheral Identification 2	190
0xFEC	GPIOPeriphID3	RO	0x0x0000.0001	GPIO Peripheral Identification 3	191
0xFF0	GPIOPCellID0	RO	0x0x0000.000D	GPIO PrimeCell Identification 0	192
0xFF4	GPIOPCellID1	RO	0x0x0000.00F0	GPIO PrimeCell Identification 1	193
0xFF8	GPIOPCellID2	RO	0x0x0000.0005	GPIO PrimeCell Identification 2	194
0xFFC	GPIOPCellID3	RO	0x0x0000.00B1	GPIO PrimeCell Identification 3	195

9.4 Register Descriptions

The remainder of this section lists and describes the GPIO registers, in numerical order by address offset.

Register 1: GPIO Data (GPIODATA), offset 0x000

The **GPIODATA** register is the data register. In software control mode, values written in the **GPIODATA** register are transferred onto the GPIO port pins if the respective pins have been configured as outputs through the **GPIO Direction (GPIODIR)** register (see page 163).

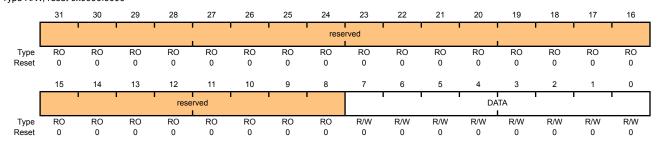
In order to write to **GPIODATA**, the corresponding bits in the mask, resulting from the address bus bits [9:2], must be High. Otherwise, the bit values remain unchanged by the write.

Similarly, the values read from this register are determined for each bit by the mask bit derived from the address used to access the data register, bits [9:2]. Bits that are 1 in the address mask cause the corresponding bits in **GPIODATA** to be read, and bits that are 0 in the address mask cause the corresponding bits in **GPIODATA** to be read as 0, regardless of their value.

A read from **GPIODATA** returns the last bit value written if the respective pins are configured as outputs, or it returns the value on the corresponding input pin when these are configured as inputs. All bits are cleared by a reset.

GPIO Data (GPIODATA)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.7000 GPIO Port H base: 0x4002.7000 GFISE 0x0000 Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	DATA	R/W	0	GPIO Data

This register is virtually mapped to 256 locations in the address space. To facilitate the reading and writing of data to these registers by independent drivers, the data read from and the data written to the registers are masked by the eight address lines <code>ipaddr[9:2]</code>. Reads from this register return its current state. Writes to this register only affect bits that are not masked by <code>ipaddr[9:2]</code> and are configured as outputs. See "Data Register Operation" on page 156 for examples of reads and writes.

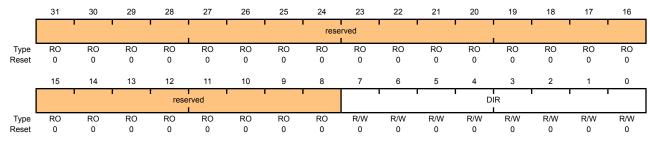
Register 2: GPIO Direction (GPIODIR), offset 0x400

The **GPIODIR** register is the data direction register. Bits set to 1 in the **GPIODIR** register configure the corresponding pin to be an output, while bits set to 0 configure the pins to be inputs. All bits are cleared by a reset, meaning all GPIO pins are inputs by default.

GPIO Direction (GPIODIR)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x400

Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	DIR	R/W	0x00	GPIO Data Direction

0: Pins are inputs.

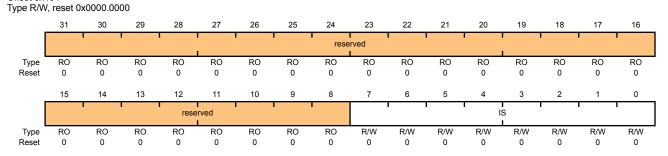
^{1:} Pins are outputs.

Register 3: GPIO Interrupt Sense (GPIOIS), offset 0x404

The **GPIOIS** register is the interrupt sense register. Bits set to 1 in **GPIOIS** configure the corresponding pins to detect levels, while bits set to 0 configure the pins to detect edges. All bits are cleared by a reset.

GPIO Interrupt Sense (GPIOIS)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x40404



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	IS	R/W	0x00	GPIO Interrupt Sense

0: Edge on corresponding pin is detected (edge-sensitive).

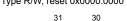
1: Level on corresponding pin is detected (level-sensitive).

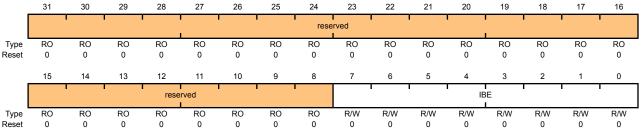
Register 4: GPIO Interrupt Both Edges (GPIOIBE), offset 0x408

The **GPIOIBE** register is the interrupt both-edges register. When the corresponding bit in the **GPIO Interrupt Sense (GPIOIS)** register (see page 164) is set to detect edges, bits set to High in **GPIOIBE** configure the corresponding pin to detect both rising and falling edges, regardless of the corresponding bit in the **GPIO Interrupt Event (GPIOIEV)** register (see page 166). Clearing a bit configures the pin to be controlled by **GPIOIEV**. All bits are cleared by a reset.

GPIO Interrupt Both Edges (GPIOIBE)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.7000 GPIO Port H base: 0x4002.7000 GPIO Port H base: 0x4002.7000 GPIO Port H base: 0x4002.7000





Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	IRE	R/M	0×00	GPIO Interrunt Both Edges

0: Interrupt generation is controlled by the **GPIO Interrupt Event** (**GPIOIEV**)register (see page 142).

Note: Single edge is determined by the corresponding bit in **GPIOIEV**.

^{1:} Both edges on the corresponding pin trigger an interrupt.

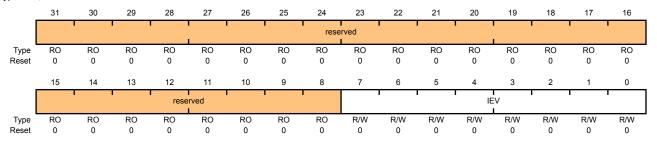
Register 5: GPIO Interrupt Event (GPIOIEV), offset 0x40C

The **GPIOIEV** register is the interrupt event register. Bits set to High in **GPIOIEV** configure the corresponding pin to detect rising edges or high levels, depending on the corresponding bit value in the **GPIO Interrupt Sense (GPIOIS)** register (see page 164). Clearing a bit configures the pin to detect falling edges or low levels, depending on the corresponding bit value in **GPIOIS**. All bits are cleared by a reset.

GPIO Interrupt Event (GPIOIEV)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x40C

Type R/W, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	IFV	R/W	0x00	GPIO Interrunt Event

0: Falling edge or Low levels on corresponding pins trigger interrupts.

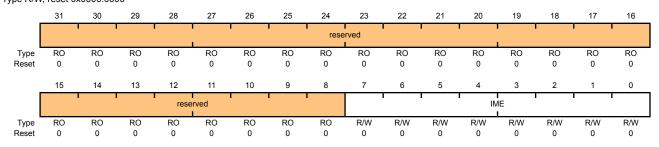
^{1:} Rising edge or High levels on corresponding pins trigger interrupts.

Register 6: GPIO Interrupt Mask (GPIOIM), offset 0x410

The **GPIOIM** register is the interrupt mask register. Bits set to High in **GPIOIM** allow the corresponding pins to trigger their individual interrupts and the combined GPIOINTR line. Clearing a bit disables interrupt triggering on that pin. All bits are cleared by a reset.

GPIO Interrupt Mask (GPIOIM)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x410 Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	IME	R/W	0x00	GPIO Interrupt Mask Enable

0: Corresponding pin interrupt is masked.

^{1:} Corresponding pin interrupt is not masked.

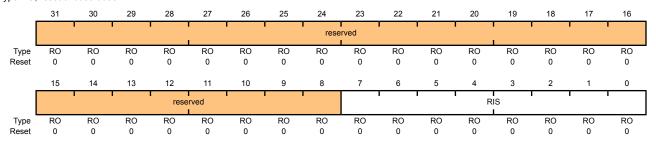
Register 7: GPIO Raw Interrupt Status (GPIORIS), offset 0x414

The GPIORIS register is the raw interrupt status register. Bits read High in GPIORIS reflect the status of interrupt trigger conditions detected (raw, prior to masking), indicating that all the requirements have been met, before they are finally allowed to trigger by the GPIO Interrupt Mask (GPIOIM) register (see page 167). Bits read as zero indicate that corresponding input pins have not initiated an interrupt. All bits are cleared by a reset.

GPIO Raw Interrupt Status (GPIORIS)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x414

Type RO, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	RIS	RO	0x00	GPIO Interrupt Raw Status

Reflect the status of interrupt trigger condition detection on pins (raw, prior to masking).

- 0: Corresponding pin interrupt requirements not met.
- 1: Corresponding pin interrupt has met requirements.

Register 8: GPIO Masked Interrupt Status (GPIOMIS), offset 0x418

The **GPIOMIS** register is the masked interrupt status register. Bits read High in **GPIOMIS** reflect the status of input lines triggering an interrupt. Bits read as Low indicate that either no interrupt has been generated, or the interrupt is masked.

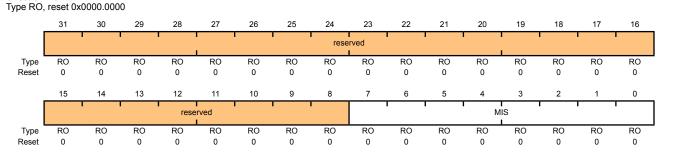
In addition to providing GPIO functionality, PB4 can also be used as an external trigger for the ADC. If PB4 is configured as a non-masked interrupt pin (GPIOIM is set to 1), not only is an interrupt for PortB generated, but an external trigger signal is sent to the ADC. If the **ADC Event Multiplexer Select (ADCEMUX)** register is configured to use the external trigger, an ADC conversion is initiated.

If no other PortB pins are being used to generate interrupts, the ARM Integrated Nested Vectored Interrupt Controller (NVIC) Interrupt Set Enable (SETNA) register can disable the PortB interrupts and the ADC interrupt can be used to read back the converted data. Otherwise, the PortB interrupt handler needs to ignore and clear interrupts on B4, and wait for the ADC interrupt or the ADC interrupt needs to be disabled in the SETNA register and the PortB interrupt handler polls the ADC registers until the conversion is completed.

GPIOMIS is the state of the interrupt after masking.

GPIO Masked Interrupt Status (GPIOMIS)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x418



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	MIS	RO	0x00	GPIO Masked Interrupt Status

Masked value of interrupt due to corresponding pin.

0: Corresponding GPIO line interrupt not active.

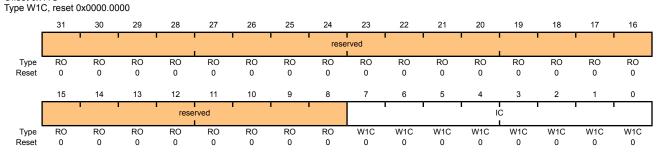
1: Corresponding GPIO line asserting interrupt.

Register 9: GPIO Interrupt Clear (GPIOICR), offset 0x41C

The **GPIOICR** register is the interrupt clear register. Writing a 1 to a bit in this register clears the corresponding interrupt edge detection logic register. Writing a 0 has no effect.

GPIO Interrupt Clear (GPIOICR)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x41C



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	IC	W1C	0x00	GPIO Interrupt Clear

^{0:} Corresponding interrupt is unaffected.

^{1:} Corresponding interrupt is cleared.

Register 10: GPIO Alternate Function Select (GPIOAFSEL), offset 0x420

The GPIOAFSEL register is the mode control select register. Writing a 1 to any bit in this register selects the hardware control for the corresponding GPIO line. All bits are cleared by a reset, therefore no GPIO line is set to hardware control by default.

The commit control registers provide a layer of protection against accidental programming of critical hardware peripherals. Writes to protected bits of the GPIO Alternate Function Select (GPIOAFSEL) register (see page 171) are not committed to storage unless the GPIO Lock (GPIOLOCK) register (see page 181) has been unlocked and the appropriate bits of the GPIO Commit (GPIOCR) register (see page 182) have been set to 1.

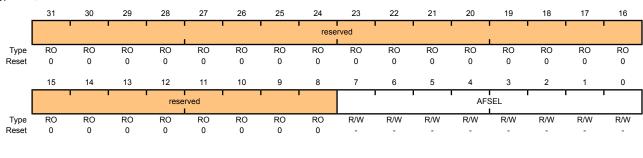
Important: All GPIO pins are tri-stated by default (GPIOAFSEL=0, GPIODEN=0, GPIOPDR=0, and GPIOPUR=0), with the exception of the five JTAG/SWD pins (PB7 and PC[3:0]). The JTAG/SWD pins default to their JTAG/SWD functionality (GPIOAFSEL=1. GPIODEN=1 and GPIOPUR=1). A Power-On-Reset (FOR) or asserting RST puts both groups of pins back to their default state.

Caution – If the JTAG pins are used as GPIOs in a design, PB7 and PC2 cannot have external pull-down resistors connected to both of them at the same time. If both pins are pulled Low during reset, the controller has unpredictable behavior. If this happens, remove one or both of the pull-down resistors, and apply RST or power-cycle the part.

In addition, it is possible to create a software sequence that prevents the debugger from connecting to the Stellaris® microcontroller. If the program code loaded into flash immediately changes the JTAG pins to their GPIO functionality, the debugger may not have enough time to connect and halt the controller before the JTAG pin functionality switches. This may lock the debugger out of the part. This can be avoided with a software routine that restores JTAG functionality based on an external or software trigger.

GPIO Alternate Function Select (GPIOAFSEL)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x420 Type R/W, reset



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

Bit/Field	Name	Туре	Reset	Description
7:0	AFSFI	R/W	_	GPIO Alternate Function Select

0: Software control of corresponding GPIO line (GPIO mode).

1: Hardware control of corresponding GPIO line (alternate hardware function).

Note:

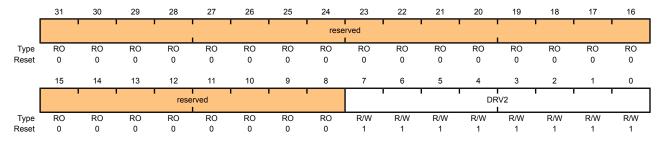
The default reset value for the $\ensuremath{\mathbf{GPIOAFSEL}}, \ensuremath{\mathbf{GPIOPUR}}, \ensuremath{\mathbf{and}}$ GPIODEN registers are 0x0000.0000 for all GPIO pins, with the exception of the five JTAG/SWD pins (PB7 and PC[3:0]). These five pins default to JTAG/SWD functionality. Because of this, the default reset value of these registers for GPIO Port B is 0x0000.0080 while the default reset value for Port C is 0x0000.000F.

Register 11: GPIO 2-mA Drive Select (GPIODR2R), offset 0x500

The **GPIODR2R** register is the 2-mA drive control register. It allows for each GPIO signal in the port to be individually configured without affecting the other pads. When writing a DRV2 bit for a GPIO signal, the corresponding DRV4 bit in the **GPIODR4R** register and the DRV8 bit in the **GPIODR8R** register are automatically cleared by hardware.

GPIO 2-mA Drive Select (GPIODR2R)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x500 Type RW, reset 0x0000.00FF



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	DRV2	R/W	0xFF	Output Pad 2-mA Drive Enable

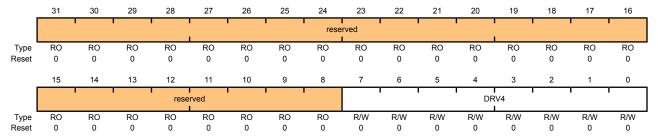
A write of 1 to either **GPIODR4[n]** or **GPIODR8[n]**clears the corresponding 2-mA enable bit. The change is effective on the second clock cycle after the write.

Register 12: GPIO 4-mA Drive Select (GPIODR4R), offset 0x504

The **GPIODR4R** register is the 4-mA drive control register. It allows for each GPIO signal in the port to be individually configured without affecting the other pads. When writing the DRV4 bit for a GPIO signal, the corresponding DRV2 bit in the **GPIODR2R** register and the DRV8 bit in the **GPIODR8R** register are automatically cleared by hardware.

GPIO 4-mA Drive Select (GPIODR4R)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x504 Type R/W, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	DRV4	R/W	0x00	Output Pad 4-mA Drive Enable

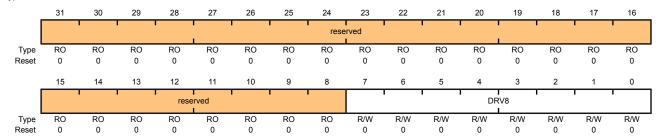
A write of 1 to either **GPIODR2[n]** or **GPIODR8[n]**clears the corresponding 4-mA enable bit. The change is effective on the second clock cycle after the write.

Register 13: GPIO 8-mA Drive Select (GPIODR8R), offset 0x508

The **GPIODR8R** register is the 8-mA drive control register. It allows for each GPIO signal in the port to be individually configured without affecting the other pads. When writing the DRV8 bit for a GPIO signal, the corresponding DRV2 bit in the **GPIODR2R** register and the DRV4 bit in the **GPIODR4R** register are automatically cleared by hardware.

GPIO 8-mA Drive Select (GPIODR8R)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x508 Type R/W, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	DRV8	R/W	0x00	Output Pad 8-mA Drive Enable

A write of 1 to either **GPIODR2[n]** or **GPIODR4[n]**clears the corresponding 8-mA enable bit. The change is effective on the second clock cycle after the write.

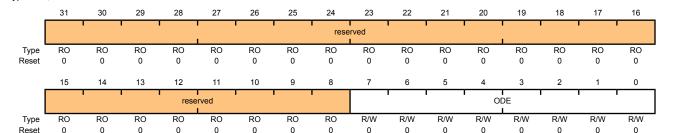
Register 14: GPIO Open Drain Select (GPIOODR), offset 0x50C

The **GPIOODR** register is the open drain control register. Setting a bit in this register enables the open drain configuration of the corresponding GPIO pad. When open drain mode is enabled, the corresponding bit should also be set in the **GPIO Digital Input Enable (GPIODEN)** register (see page 180). Corresponding bits in the drive strength registers (**GPIODR2R**, **GPIODR4R**, **GPIODR8R**, and **GPIOSLR**) can be set to achieve the desired rise and fall times. The GPIO acts as an open drain input if the corresponding bit in the **GPIODIR** register is set to 0; and as an open drain output when set to 1.

When using the I²C module, the **GPIO Alternate Function Select (GPIOAFSEL)** register bit for PB2 and PB3 should be set to 1 (see examples in "Initialization and Configuration" on page 158).

GPIO Open Drain Select (GPIOODR)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x50C Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	ODE	R/W	0x00	Output Pad Open Drain Enable

0: Open drain configuration is disabled.

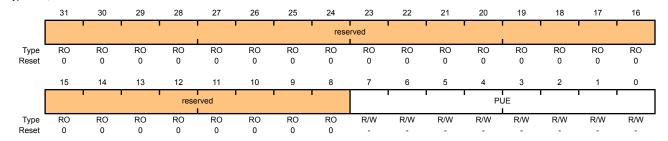
1: Open drain configuration is enabled.

Register 15: GPIO Pull-Up Select (GPIOPUR), offset 0x510

The **GPIOPUR** register is the pull-up control register. When a bit is set to 1, it enables a weak pull-up resistor on the corresponding GPIO signal. Setting a bit in **GPIOPUR** automatically clears the corresponding bit in the **GPIO Pull-Down Select (GPIOPDR)** register (see page 178).

GPIO Pull-Up Select (GPIOPUR)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x510 Type R/W, reset -



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PUE	R/W	_	Pad Weak Pull-Up Enable

A write of 1 to **GPIOPDR**[n]clears the corresponding **GPIOPUR**[n]enables. The change is effective on the second clock cycle after the write.

Note:

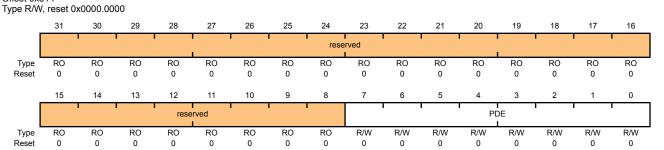
The default reset value for the **GPIOAFSEL**, **GPIOPUR**, and **GPIODEN** registers are 0x0000.0000 for all GPIO pins, with the exception of the five JTAG/SWD pins (PB7 and PC[3:0]). These five pins default to JTAG/SWD functionality. Because of this, the default reset value of these registers for GPIO Port B is 0x0000.0080 while the default reset value for Port C is 0x0000.000F.

Register 16: GPIO Pull-Down Select (GPIOPDR), offset 0x514

The **GPIOPDR** register is the pull-down control register. When a bit is set to 1, it enables a weak pull-down resistor on the corresponding GPIO signal. Setting a bit in **GPIOPDR** automatically clears the corresponding bit in the **GPIO Pull-Up Select (GPIOPUR)** register (see page 177).

GPIO Pull-Down Select (GPIOPDR)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x514



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PDE	R/W	0x00	Pad Weak Pull-Down Enable

A write of 1 to **GPIOPUR[n]**clears the corresponding **GPIOPDR[n]**enables. The change is effective on the second clock cycle after the write.

Register 17: GPIO Slew Rate Control Select (GPIOSLR), offset 0x518

The **GPIOSLR** register is the slew rate control register. Slew rate control is only available when using the 8-mA drive strength option via the **GPIO 8-mA Drive Select (GPIODR8R)** register (see page 175).

GPIO Slew Rate Control Select (GPIOSLR)

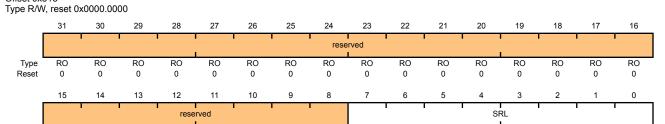
GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x518

Type

Reset

RO

0



RO

R/W

0

Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	SRL	R/W	0	Slew Rate Limit Enable (8-mA drive only)

0: Slew rate control disabled.

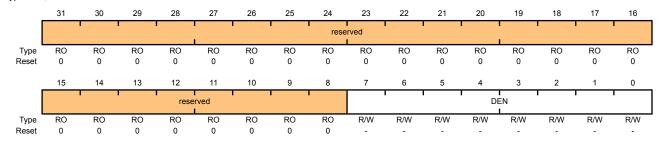
1: Slew rate control enabled.

Register 18: GPIO Digital Enable (GPIODEN), offset 0x51C

The **GPIODEN** register is the digital enable register. By default, with the exception of the GPIO signals used for JTAG/SWD function, all other GPIO signals are configured out of reset to be undriven (tristate). Their digital function is disabled; they do not drive a logic value on the pin and they do not allow the pin voltage into the GPIO receiver. To use the pin in a digital function (either GPIO or alternate function), the corresponding GPIODEN bit must be set.

GPIO Digital Enable (GPIODEN)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0x51C Type RW, reset -



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	DEN	R/W	-	Digital Enable

0: Digital functions disabled.

Note:

The default reset value for the **GPIOAFSEL**, **GPIOPUR**, and **GPIODEN** registers are 0x0000.0000 for all GPIO pins, with the exception of the five JTAG/SWD pins (PB7 and PC[3:0]). These five pins default to JTAG/SWD functionality. Because of this, the default reset value of these registers for GPIO Port B is 0x0000.0080 while the default reset value for Port C is 0x0000.000F.

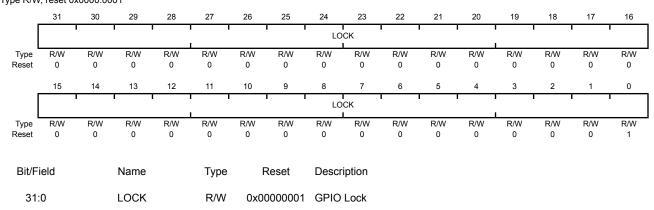
^{1:} Digital functions enabled.

Register 19: GPIO Lock (GPIOLOCK), offset 0x520

The **GPIOLOCK** register enables write access to the **GPIOCR** register (see page 182). Writing 0x1ACCE551 to the **GPIOLOCK** register will unlock the **GPIOCR** register. Writing any other value to the **GPIOLOCK** register re-enables the locked state. Reading the **GPIOLOCK** register returns the lock status rather than the 32-bit value that was previously written. Therefore, when write accesses are disabled, or locked, reading the **GPIOLOCK** register returns 0x00000001. When write accesses are enabled, or unlocked, reading the **GPIOLOCK** register returns 0x000000000.

GPIO Lock (GPIOLOCK)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.5000 GPIO Port H base: 0x4002.7000 Offset 0x520 Type R/W, reset 0x0000.0001



A write of the value 0x1ACCE551 unlocks the GPIO Commit register for write access. A write of any other value reapplies the lock, preventing any register updates. A read of this register returns the following values:

locked: 0x00000001 unlocked: 0x00000000

Register 20: GPIO Commit (GPIOCR), offset 0x524

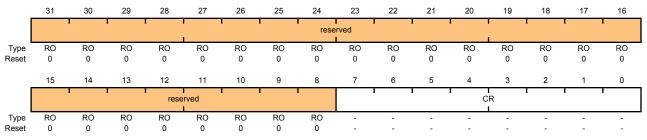
The **GPIOCR** register is the commit register. The value of the **GPIOCR** register determines which bits of the **GPIOAFSEL** register will be committed when a write to the **GPIOAFSEL** register is performed. If a bit in the **GPIOCR** register is a zero, the data being written to the corresponding bit in the **GPIOAFSEL** register will not be committed and will retain its previous value. If a bit in the **GPIOCR** register is a one, the data being written to the corresponding bit of the **GPIOAFSEL** register will be committed to the register and will reflect the new value.

The contents of the **GPIOCR** register can only be modified if the **GPIOLOCK** register is unlocked. Writes to the GPIOCR register will be ignored if the **GPIOLOCK** register is locked.

Important: This register is designed to prevent accidental programming of the GPIOAFSEL registers that control connectivity to the JTAG/SWD debug hardware. By initializing the bits of the GPIOCR register to 0 for PB7 and PC[3:0], the JTAG/SWD debug port can only be converted to GPIOs through a deliberate set of writes to the GPIOLOCK, GPIOCR, and GPIOAFSEL registers.

Because this protection is currently only implemented on the JTAG/SWD pins on PB7 and PC[3:0], all of the other bits in the **GPIOCR** registers cannot be written with 0x0. These bits are hardwired to 0x1, ensuring that it is always possible to commit new values to the **GPIOAFSEL** register bits of these other pins.

GPIO Commit (GPIOCR) GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.7000 GPIO Port H base: 0x4002.7000 GPIO Port H base: 0x4002.7000 GPIO Port F base: 0x4002.7000 GPIO Port F base: 0x4002.7000



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

Bit/Field	Name	Type	Reset	Description
7:0	CR	_	_	GPIO Commit

On a bit-wise basis, any bit set allows the corresponding ${\tt GPIOAFSEL}$ bit to be set to its alternate function.

Note:

The default register type for the **GPIOCR** register is RO for all GPIO pins, with the exception of the five JTAG/SWD pins (PB7 and PC[3:0]). These five pins are currently the only GPIOs that are protected by the **GPIOCR** register. Because of this, the register type for GPIO Port B7 and GPIO Port C[3:0] is R/W.

The default reset value for the **GPIOCR** register is 0x0000.00FF for all GPIO pins, with the exception of the five JTAG/SWD pins (PB7 and PC[3:0]). To ensure that the JTAG port is not accidentally programmed as a GPIO, these five pins default to non-commitable. Because of this, the default reset value of **GPIOCR** for GPIO Port B is 0x0000.007F while the default reset value of **GPIOCR** for Port C is 0x0000.00FO.

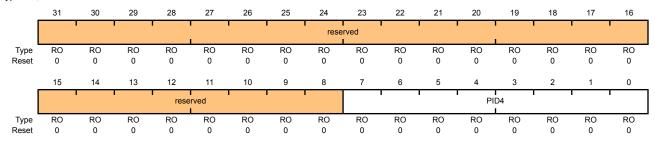
Register 21: GPIO Peripheral Identification 4 (GPIOPeriphID4), offset 0xFD0

The **GPIOPeriphID4**, **GPIOPeriphID5**, **GPIOPeriphID6**, and **GPIOPeriphID7** registers can conceptually be treated as one 32-bit register; each register contains eight bits of the 32-bit register, used by software to identify the peripheral.

GPIO Peripheral Identification 4 (GPIOPeriphID4)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0xFD0

Type RO, reset 0x0x0000.0000



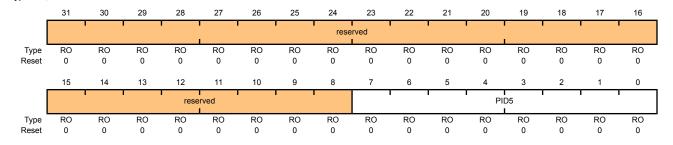
Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID4	RO	0x00	GPIO Peripheral ID Register[7:0]

Register 22: GPIO Peripheral Identification 5 (GPIOPeriphID5), offset 0xFD4

The **GPIOPeriphID4**, **GPIOPeriphID5**, **GPIOPeriphID6**, and **GPIOPeriphID7** registers can conceptually be treated as one 32-bit register; each register contains eight bits of the 32-bit register, used by software to identify the peripheral.

GPIO Peripheral Identification 5 (GPIOPeriphID5)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0xFD4 Type RO, reset 0x0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID5	RO	0x00	GPIO Peripheral ID Register[15:8]

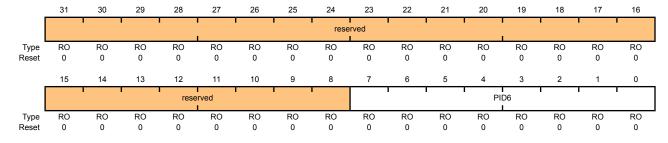
Register 23: GPIO Peripheral Identification 6 (GPIOPeriphID6), offset 0xFD8

The **GPIOPeriphID4**, **GPIOPeriphID5**, **GPIOPeriphID6**, and **GPIOPeriphID7** registers can conceptually be treated as one 32-bit register; each register contains eight bits of the 32-bit register, used by software to identify the peripheral.

GPIO Peripheral Identification 6 (GPIOPeriphID6)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000

Offset 0xFD8 Type RO, reset 0x0x0000.0000



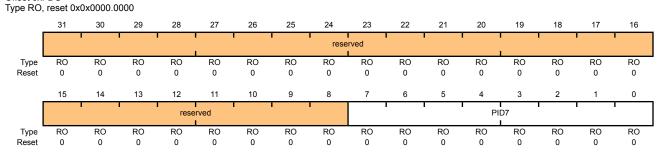
Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID6	RO	0x00	GPIO Peripheral ID Register[23:16]

Register 24: GPIO Peripheral Identification 7 (GPIOPeriphID7), offset 0xFDC

The **GPIOPeriphID4**, **GPIOPeriphID5**, **GPIOPeriphID6**, and **GPIOPeriphID7** registers can conceptually be treated as one 32-bit register; each register contains eight bits of the 32-bit register, used by software to identify the peripheral.

GPIO Peripheral Identification 7 (GPIOPeriphID7)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0xFDC



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID7	RO	0x00	GPIO Peripheral ID Register[31:24]

Register 25: GPIO Peripheral Identification 0 (GPIOPeriphID0), offset 0xFE0

The **GPIOPeriphID0**, **GPIOPeriphID1**, **GPIOPeriphID2**, and **GPIOPeriphID3** registers can conceptually be treated as one 32-bit register; each register contains eight bits of the 32-bit register, used by software to identify the peripheral.

GPIO Peripheral Identification 0 (GPIOPeriphID0)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0xFEO

Reset

0

0

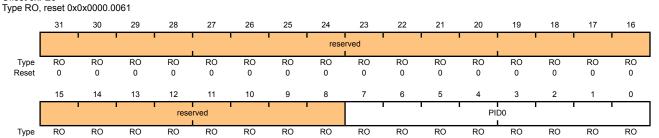
0

0

0

0

0



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID0	RO	0x61	GPIO Peripheral ID Register[7:0]

0

Can be used by software to identify the presence of this peripheral.

0

0

0

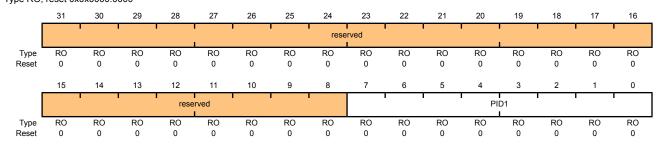
0

Register 26: GPIO Peripheral Identification 1(GPIOPeriphID1), offset 0xFE4

The **GPIOPeriphID0**, **GPIOPeriphID1**, **GPIOPeriphID2**, and **GPIOPeriphID3** registers can conceptually be treated as one 32-bit register; each register contains eight bits of the 32-bit register, used by software to identify the peripheral.

GPIO Peripheral Identification 1 (GPIOPeriphID1)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0xFE4 Type RO, reset 0x0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID1	RO	0x00	GPIO Peripheral ID Register[15:8]

Can be used by software to identify the presence of this peripheral.

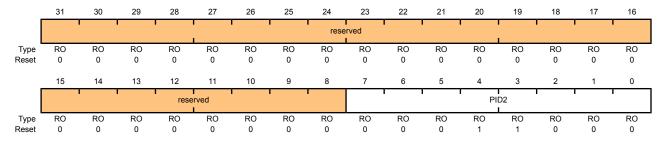
Register 27: GPIO Peripheral Identification 2 (GPIOPeriphID2), offset 0xFE8

The **GPIOPeriphID0**, **GPIOPeriphID1**, **GPIOPeriphID2**, and **GPIOPeriphID3** registers can conceptually be treated as one 32-bit register; each register contains eight bits of the 32-bit register, used by software to identify the peripheral.

GPIO Peripheral Identification 2 (GPIOPeriphID2)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0xFE8

Type RO, reset 0x0x0000.0018



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID2	RO	0x18	GPIO Peripheral ID Register[23:16]

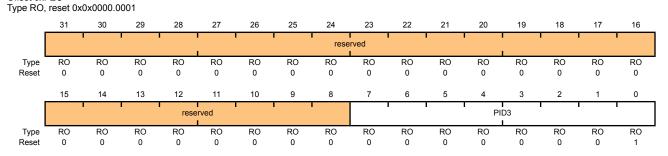
Can be used by software to identify the presence of this peripheral.

Register 28: GPIO Peripheral Identification 3 (GPIOPeriphID3), offset 0xFEC

The **GPIOPeriphID0**, **GPIOPeriphID1**, **GPIOPeriphID2**, and **GPIOPeriphID3** registers can conceptually be treated as one 32-bit register; each register contains eight bits of the 32-bit register, used by software to identify the peripheral.

GPIO Peripheral Identification 3 (GPIOPeriphID3)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0xFEC



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID3	RO	0x01	GPIO Peripheral ID Register[31:24]

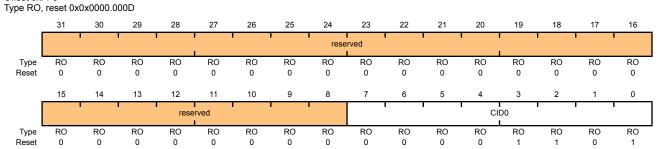
Can be used by software to identify the presence of this peripheral.

Register 29: GPIO PrimeCell Identification 0 (GPIOPCellID0), offset 0xFF0

The **GPIOPCeIIID1**, **GPIOPCeIIID1**, and **GPIOPCeIIID3** registers are four 8-bit wide registers, that can conceptually be treated as one 32-bit register. The register is used as a standard cross-peripheral identification system.

GPIO PrimeCell Identification 0 (GPIOPCellID0)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0xFF0



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CID0	RO	0x0D	GPIO PrimeCell ID Register[7:0]

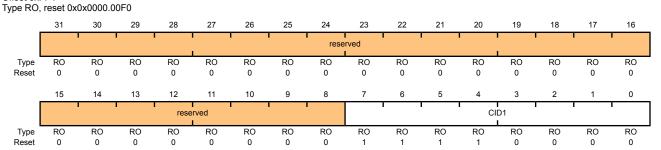
 $\label{provides} \mbox{Provides software a standard cross-peripheral identification system.}$

Register 30: GPIO PrimeCell Identification 1 (GPIOPCellID1), offset 0xFF4

The **GPIOPCeIIID1**, **GPIOPCeIIID1**, and **GPIOPCeIIID3** registers are four 8-bit wide registers, that can conceptually be treated as one 32-bit register. The register is used as a standard cross-peripheral identification system.

GPIO PrimeCell Identification 1 (GPIOPCellID1)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0xFF4



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CID1	RO	0xF0	GPIO PrimeCell ID Register[15:8]

Provides software a standard cross-peripheral identification system.

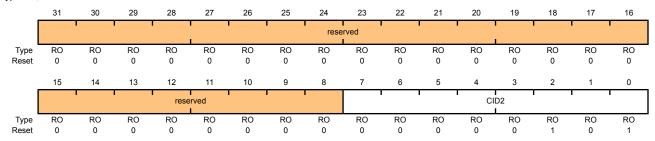
Register 31: GPIO PrimeCell Identification 2 (GPIOPCellID2), offset 0xFF8

The **GPIOPCeIIID1**, **GPIOPCeIIID1**, and **GPIOPCeIIID3** registers are four 8-bit wide registers, that can conceptually be treated as one 32-bit register. The register is used as a standard cross-peripheral identification system.

GPIO PrimeCell Identification 2 (GPIOPCellID2)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0xFF8

Type RO, reset 0x0x0000.0005



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CID2	RO	0x05	GPIO PrimeCell ID Register[23:16]

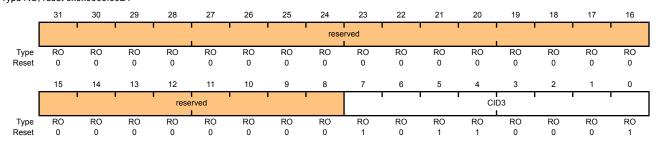
 $\label{provides} \mbox{Provides software a standard cross-peripheral identification system.}$

Register 32: GPIO PrimeCell Identification 3 (GPIOPCellID3), offset 0xFFC

The **GPIOPCeIIID1**, **GPIOPCeIIID1**, and **GPIOPCeIIID3** registers are four 8-bit wide registers, that can conceptually be treated as one 32-bit register. The register is used as a standard cross-peripheral identification system.

GPIO PrimeCell Identification 3 (GPIOPCellID3)

GPIO Port A base: 0x4000.4000 GPIO Port B base: 0x4000.5000 GPIO Port C base: 0x4000.6000 GPIO Port D base: 0x4000.7000 GPIO Port E base: 0x4002.4000 GPIO Port F base: 0x4002.5000 GPIO Port G base: 0x4002.6000 GPIO Port H base: 0x4002.7000 Offset 0xFFC Type RO, reset 0x0x0000.00B1



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CID3	RO	0xB1	GPIO PrimeCell ID Register[31:24]

Provides software a standard cross-peripheral identification system.

10 General-Purpose Timers

Programmable timers can be used to count or time external events that drive the Timer input pins.

The Stellaris® General-Purpose Timer Module (GPTM) contains three GPTM blocks (Timer0, Timer1, and Timer 2). Each GPTM block provides two 16-bit timer/counters (referred to as TimerA and TimerB) that can be configured to operate independently as timers or event counters, or configured to operate as one 32-bit timer or one 32-bit Real-Time Clock (RTC). Timers can also be used to trigger analog-to-digital (ADC) conversions. The trigger signals from all of the general-purpose timers are ORed together before reaching the ADC module, so only one timer should be used to trigger ADC events.

Note: Timer2 is an internal timer and can only be used to generate internal interrupts or trigger ADC events.

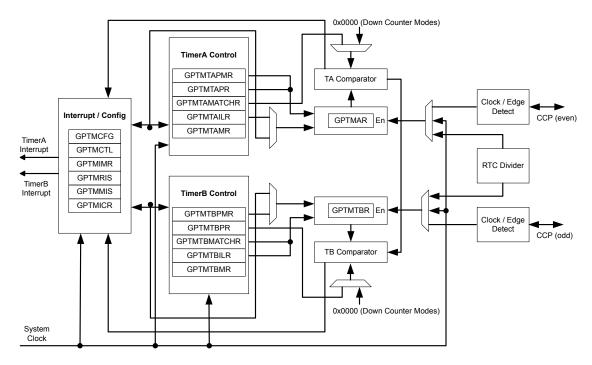
The General-Purpose Timer Module is one timing resource available on the Stellaris[®] microcontrollers. Other timer resources include the System Timer (SysTick) (see "System Timer (SysTick)" on page 40) and the PWM timer in the PWM module (see "PWM Timer" on page 449).

The following modes are supported:

- 32-bit Timer modes
 - Programmable one-shot timer
 - Programmable periodic timer
 - Real-Time Clock using 32.768-KHz input clock
 - Software-controlled event stalling (excluding RTC mode)
- 16-bit Timer modes
 - General-purpose timer function with an 8-bit prescaler (for one-shot and periodic modes only)
 - Programmable one-shot timer
 - Programmable periodic timer
 - Software-controlled event stalling
- 16-bit Input Capture modes
 - Input edge count capture
 - Input edge time capture
- 16-bit PWM mode
 - Simple PWM mode with software-programmable output inversion of the PWM signal

10.1 Block Diagram

Figure 10-1. GPTM Module Block Diagram



10.2 Functional Description

The main components of each GPTM block are two free-running 16-bit up/down counters (referred to as TimerA and TimerB), two 16-bit match registers, two prescaler match registers, and two 16-bit load/initialization registers and their associated control functions. The exact functionality of each GPTM is controlled by software and configured through the register interface.

Software configures the GPTM using the **GPTM Configuration (GPTMCFG)** register (see page 208), the **GPTM TimerA Mode (GPTMTAMR)** register (see page 209), and the **GPTM TimerB Mode (GPTMTBMR)** register (see page 210). When in one of the 32-bit modes, the timer can only act as a 32-bit timer. However, when configured in 16-bit mode, the GPTM can have its two 16-bit timers configured in any combination of the 16-bit modes.

10.2.1 GPTM Reset Conditions

After reset has been applied to the GPTM module, the module is in an inactive state, and all control registers are cleared and in their default states. Counters TimerA and TimerB are initialized to 0xFFFF, along with their corresponding load registers: the GPTM TimerA Interval Load (GPTMTAILR) register (see page 219) and the GPTM TimerB Interval Load (GPTMTBILR) register (see page 220). The prescale counters are initialized to 0x00: the GPTM TimerA Prescale (GPTMTAPR) register (see page 223) and the GPTM TimerB Prescale (GPTMTBPR) register (see page 224).

10.2.2 32-Bit Timer Operating Modes

Note: Both the odd- and even-numbered CCP pins are used for 16-bit mode. Only the even-numbered CCP pins are used for 32-bit mode.

This section describes the three GPTM 32-bit timer modes (One-Shot, Periodic, and RTC) and their configuration.

The GPTM is placed into 32-bit mode by writing a 0 (One-Shot/Periodic 32-bit timer mode) or a 1 (RTC mode) to the **GPTM Configuration (GPTMCFG)** register. In both configurations, certain GPTM registers are concatenated to form pseudo 32-bit registers. These registers include:

- GPTM TimerA Interval Load (GPTMTAILR) register [15:0], see page 219
- GPTM TimerB Interval Load (GPTMTBILR) register [15:0], see page 220
- GPTM TimerA (GPTMTAR) register [15:0], see page 227
- **GPTM TimerB (GPTMTBR)** register [15:0], see page 228

In the 32-bit modes, the GPTM translates a 32-bit write access to **GPTMTAILR** into a write access to both **GPTMTAILR** and **GPTMTBILR**. The resulting word ordering for such a write operation is:

```
GPTMTBILR[15:0]:GPTMTAILR[15:0]
```

Likewise, a read access to **GPTMTAR** returns the value:

```
GPTMTBR[15:0]:GPTMTAR[15:0]
```

10.2.2.1 32-Bit One-Shot/Periodic Timer Mode

In 32-bit one-shot and periodic timer modes, the concatenated versions of the TimerA and TimerB registers are configured as a 32-bit down-counter. The selection of one-shot or periodic mode is determined by the value written to the TAMR field of the **GPTM TimerA Mode (GPTMTAMR)** register (see page 209), and there is no need to write to the GPTM TimerB Mode (GPTMTBMR) register.

When software writes the TAEN bit in the **GPTM Control (GPTMCTL)** register (see page 211), the timer begins counting down from its preloaded value. Once the 0x0000.0000 state is reached, the timer reloads its start value from the concatenated **GPTMTAILR** on the next cycle. If configured to be a one-shot timer, the timer stops counting and clears the TAEN bit in the **GPTMCTL** register. If configured as a periodic timer, it continues counting.

In addition to reloading the count value, the GPTM generates interrupts and output triggers when it reaches the 0x0000000 state. The GPTM sets the TATORIS bit in the GPTM Raw Interrupt Status (GPTMRIS) register (see page 215), and holds it until it is cleared by writing the GPTM Interrupt Clear (GPTMICR) register (see page 217). If the time-out interrupt is enabled in the GPTM Interrupt Mask (GPTIMR) register (see page 213), the GPTM also sets the TATOMIS bit in the GPTM Masked Interrupt Status (GPTMMIS) register (see page 216).

The output trigger is a one-clock-cycle pulse that is asserted when the counter hits the 0x0000.0000 state, and deasserted on the following clock cycle. It is enabled by setting the TAOTE bit in **GPTMCTL**, and can trigger SoC-level events such as ADC conversions.

If software reloads the **GPTMTAILR** register while the counter is running, the counter loads the new value on the next clock cycle and continues counting from the new value.

If the TASTALL bit in the **GPTMCTL** register is asserted, the timer freezes counting until the signal is deasserted.

10.2.2.2 32-Bit Real-Time Clock Timer Mode

In Real-Time Clock (RTC) mode, the concatenated versions of the TimerA and TimerB registers are configured as a 32-bit up-counter. When RTC mode is selected for the first time, the counter is

loaded with a value of 0x0000.0001. All subsequent load values must be written to the **GPTM TimerA Match (GPTMTAMATCHR)** register (see page 221) by the controller.

The input clock on the CCP0, CCP2 or CCP4 pins is required to be 32.768 KHz in RTC mode. The clock signal is then divided down to a 1 Hz rate and is passed along to the input of the 32-bit counter.

When software writes the TAEN bit inthe **GPTMCTL** register, the counter starts counting up from its preloaded value of 0x0000.0001. When the current count value matches the preloaded value in the **GPTMTAMATCHR** register, it rolls over to a value of 0x0000.0000 and continues counting until either a hardware reset, or it is disabled by software (clearing the TAEN bit). When a match occurs, the GPTM asserts the RTCRIS bit in **GPTMRIS**. If the RTC interrupt is enabled in **GPTIMR**, the GPTM also sets the RTCMIS bit in **GPTMISR** and generates a controller interrupt. The status flags are cleared by writing the RTCCINT bit in **GPTMICR**.

If the TASTALL and/or TBSTALL bits in the **GPTMCTL** register are set, the timer does not freeze if the RTCEN bit is set in **GPTMCTL**.

10.2.3 16-Bit Timer Operating Modes

The GPTM is placed into global 16-bit mode by writing a value of 0x4 to the **GPTM Configuration** (**GPTMCFG**) register (see page 208). This section describes each of the GPTM 16-bit modes of operation. TimerA and TimerB have identical modes, so a single description is given using an *n* to reference both.

10.2.3.1 16-Bit One-Shot/Periodic Timer Mode

In 16-bit one-shot and periodic timer modes, the timer is configured as a 16-bit down-counter with an optional 8-bit prescaler that effectively extends the counting range of the timer to 24 bits. The selection of one-shot or periodic mode is determined by the value written to the TnMR field of the **GPTMTnMR** register. The optional prescaler is loaded into the **GPTM Timern Prescale (GPTMTnPR)** register.

When software writes the TnEN bit in the **GPTMCTL** register, the timer begins counting down from its preloaded value. Once the 0x0000 state is reached, the timer reloads its start value from **GPTMTnILR** and **GPTMTnPR** on the next cycle. If configured to be a one-shot timer, the timer stops counting and clears the TnEN bit in the **GPTMCTL** register. If configured as a periodic timer, it continues counting.

In addition to reloading the count value, the timer generates interrupts and output triggers when it reaches the 0x0000 state. The GPTM sets the TnTORIS bit in the **GPTMRIS** register, and holds it until it is cleared by writing the **GPTMICR** register. If the time-out interrupt is enabled in **GPTIMR**, the GPTM also sets the TnTOMIS bit in **GPTMISR** and generates a controller interrupt.

The output trigger is a one-clock-cycle pulse that is asserted when the counter hits the 0x0000 state, and deasserted on the following clock cycle. It is enabled by setting the ThOTE bit in the **GPTMCTL** register, and can trigger SoC-level events such as ADC conversions.

If software reloads the **GPTMTAILR** register while the counter is running, the counter loads the new value on the next clock cycle and continues counting from the new value.

If the TnSTALL bit in the **GPTMCTL** register is enabled, the timer freezes counting until the signal is deasserted.

The following example shows a variety of configurations for a 16-bit free running timer while using the prescaler. All values assume a 50-MHz clock with Tc=20 ns (clock period).

Table 10-1. 16-Bit Timer With Prescaler Configurations

Prescale	#Clock (T c) ^a	Max Time	Units
00000000	1	1.3107	mS
00000001	2	2.6214	mS
00000010	3	23.9321	mS
11111100	254	332.9229	mS
11111110	255	334.2336	mS
11111111	256	335.5443	mS

a. Tc is the clock period.

10.2.3.2 16-Bit Input Edge Count Mode

In Edge Count mode, the timer is configured as a down-counter capable of capturing three types of events: rising edge, falling edge, or both. To place the timer in Edge Count mode, the TnCMR bit of the GPTMTnMR register must be set to 0. The type of edge that the timer counts is determined by the TnEVENT fields of the GPTMCTL register. During initialization, the GPTM Timern Match (GPTMTnMATCHR) register is configured so that the difference between the value in the GPTMTnILR register and the GPTMTnMATCHR register equals the number of edge events that must be counted.

When software writes the TnEN bit in the **GPTM Control (GPTMCTL)** register, the timer is enabled for event capture. Each input event on the CCP pin decrements the counter by 1 until the event count matches **GPTMTnMATCHR**. When the counts match, the GPTM asserts the CnMRIS bit in the **GPTMRIS** register (and the CnMMIS bit, if the interrupt is not masked). The counter is then reloaded using the value in **GPTMTnILR**, and stopped since the GPTM automatically clears the TnEN bit in the **GPTMCTL** register. Once the event count has been reached, all further events are ignored until TnEN is re-enabled by software.

Figure 10-2 on page 201 shows how input edge count mode works. In this case, the timer start value is set to **GPTMnILR** =0x000A and the match value is set to **GPTMnMATCHR** =0x0006 so that four edge events are counted. The counter is configured to detect both edges of the input signal.

Note that the last two edges are not counted since the timer automatically clears the TnEN bit after the current count matches the value in the **GPTMnMR** register.

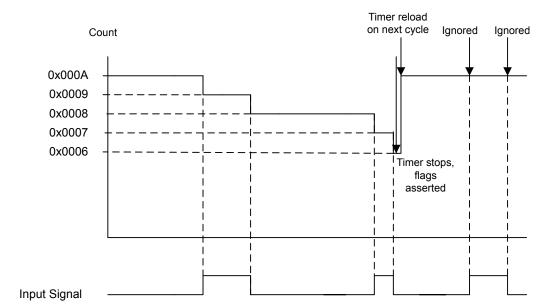


Figure 10-2. 16-Bit Input Edge Count Mode Example

10.2.3.3 16-Bit Input Edge Time Mode

Note: The prescaler is not available in 16-Bit Input Edge Time mode.

In Edge Time mode, the timer is configured as a free-running down-counter initialized to the value loaded in the **GPTMTnILR** register (or 0xFFFF at reset). This mode allows for event capture of both rising and falling edges. The timer is placed into Edge Time mode by setting the TnCMR bit in the **GPTMTnMR** register, and the type of event that the timer captures is determined by the TnEVENT fields of the **GPTMCnTL** register.

When software writes the TnEN bit in the **GPTMCTL** register, the timer is enabled for event capture. When the selected input event is detected, the current **Tn** counter value is captured in the **GPTMTnR** register and is available to be read by the controller. The GPTM then asserts the CnERIS bit (and the CnEMIS bit, if the interrupt is not masked).

After an event has been captured, the timer does not stop counting. It continues to count until the ${\tt TnEN}$ bit is cleared. When the timer reaches the 0x0000 state, it is reloaded with the value from the **GPTMnILR** register.

Figure 10-3 on page 202 shows how input edge timing mode works. In the diagram, it is assumed that the start value of the timer is the default value of 0xFFFF, and the timer is configured to capture rising edge events.

Each time a rising edge event is detected, the current count value is loaded into the **GPTMTnR** register, and is held there until another rising edge is detected (at which point the new count value is loaded into **GPTMTnR**).

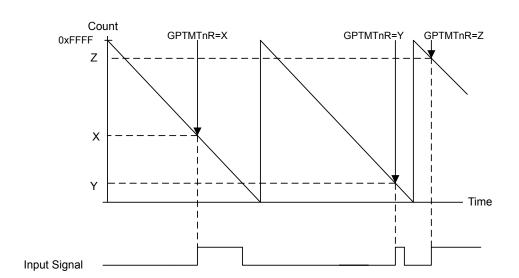


Figure 10-3. 16-Bit Input Edge Time Mode Example

10.2.3.4 16-Bit PWM Mode

The GPTM supports a simple PWM generation mode. In PWM mode, the timer is configured as a down-counter with a start value (and thus period) defined by **GPTMTnILR**. PWM mode is enabled with the **GPTMTnMR** register by setting the TnAMS bit to 0x1, the TnCMR bit to 0x0, and the TnMR field to 0x2.

When software writes the \mathtt{TnEN} bit in the **GPTMCTL** register, the counter begins counting down until it reaches the 0x0000 state. On the next counter cycle, the counter reloads its start value from **GPTMTnILR** (and **GPTMTnPR** if using a prescaler) and continues counting until disabled by software clearing the \mathtt{TnEN} bit in the **GPTMCTL** register. No interrupts or status bits are asserted in PWM mode.

The output PWM signal asserts when the counter is at the value of the **GPTMTnILR** register (its start state), and is deasserted when the counter value equals the value in the **GPTM Timern Match Register (GPTMnMATCHR)**. Software has the capability of inverting the output PWM signal by setting the TnPWML bit in the **GPTMCTL** register.

Figure 10-4 on page 203 shows how to generate an output PWM with a 1-ms period and a 66% duty cycle assuming a 50-MHz input clock and **TnPWML** =0 (duty cycle would be 33% for the **TnPWML** =1 configuration). For this example, the start value is **GPTMnIRL**=0xC350 and the match value is **GPTMnMR**=0x411A.

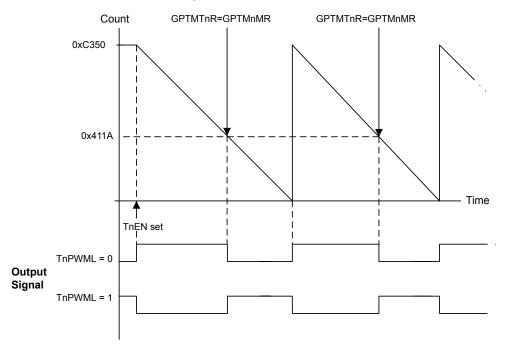


Figure 10-4. 16-Bit PWM Mode Example

10.3 Initialization and Configuration

To use the general purpose timers, the peripheral clock must be enabled by setting the GPTM0, GPTM1, and GPTM2 bits in the RCGC1 register.

This section shows module initialization and configuration examples for each of the supported timer modes.

10.3.1 32-Bit One-Shot/Periodic Timer Mode

The GPTM is configured for 32-bit One-Shot and Periodic modes by the following sequence:

- 1. Ensure the timer is disabled (the TAEN bit in the **GPTMCTL** register is cleared) before making any changes.
- 2. Write the **GPTM Configuration Register (GPTMCFG)** with a value of 0x0.
- 3. Set the TAMR field in the GPTM TimerA Mode Register (GPTMTAMR):
 - a. Write a value of 0x1 for One-Shot mode.
 - b. Write a value of 0x2 for Periodic mode.
- 4. Load the start value into the GPTM TimerA Interval Load Register (GPTMTAILR).
- If interrupts are required, set the TATOIM bit in the GPTM Interrupt Mask Register (GPTMIMR).
- 6. Set the TAEN bit in the **GPTMCTL** register to enable the timer and start counting.

7. Poll the TATORIS bit in the GPTMRIS register or wait for the interrupt to be generated (if enabled). In both cases, the status flags are cleared by writing a 1 to the TATOCINT bit of the GPTM Interrupt Clear Register (GPTMICR).

In One-Shot mode, the timer stops counting after 7 on page 204. To re-enable the timer, repeat the sequence. A timer configured in Periodic mode does not stop counting after it times out.

10.3.2 32-Bit Real-Time Clock (RTC) Mode

To use the RTC mode, the timer must have a 32.768-KHz input signal on its CCP0, CCP2 or CCP4 pins. To enable the RTC feature, follow these steps:

- Ensure the timer is disabled (the TAEN bit is cleared) before making any changes.
- 2. Write the GPTM Configuration Register (GPTMCFG) with a value of 0x1.
- Write the desired match value to the GPTM TimerA Match Register (GPTMTAMATCHR).
- 4. Set/clear the RTCEN bit in the GPTM Control Register (GPTMCTL) as desired.
- If interrupts are required, set the RTCIM bit in the GPTM Interrupt Mask Register (GPTMIMR).
- Set the TAEN bit in the GPTMCTL register to enable the timer and start counting.

When the timer count equals the value in the **GPTMTAMATCHR** register, the counter is re-loaded with 0x0000.0000 and begins counting. If an interrupt is enabled, it does not have to be cleared.

10.3.3 16-Bit One-Shot/Periodic Timer Mode

A timer is configured for 16-bit One-Shot and Periodic modes by the following sequence:

- Ensure the timer is disabled (the TnEN bit is cleared) before making any changes.
- 2. Write the GPTM Configuration Register (GPTMCFG) with a value of 0x4.
- 3. Set the TnMR field in the **GPTM Timer Mode (GPTMTnMR)** register:
 - a. Write a value of 0x1 for One-Shot mode.
 - b. Write a value of 0x2 for Periodic mode.
- If a prescaler is to be used, write the prescale value to the GPTM Timern Prescale Register (GPTMTnPR).
- Load the start value into the GPTM Timer Interval Load Register (GPTMTnILR).
- If interrupts are required, set the Thtolm bit in the GPTM Interrupt Mask Register (GPTMIMR).
- Set the TnEN bit in the GPTM Control Register (GPTMCTL) to enable the timer and start counting.
- 8. Poll the TnTORIS bit in the GPTMRIS register or wait for the interrupt to be generated (if enabled). In both cases, the status flags are cleared by writing a 1 to the TnTOCINT bit of the GPTM Interrupt Clear Register (GPTMICR).

In One-Shot mode, the timer stops counting after 8 on page 204. To re-enable the timer, repeat the sequence. A timer configured in Periodic mode does not stop counting after it times out.

10.3.4 16-Bit Input Edge Count Mode

A timer is configured to Input Edge Count mode by the following sequence:

- Ensure the timer is disabled (the TNEN bit is cleared) before making any changes.
- 2. Write the **GPTM Configuration (GPTMCFG)** register with a value of 0x4.
- 3. In the **GPTM Timer Mode (GPTMTnMR)** register, write the TnCMR field to 0x0 and the TnMR field to 0x3.
- Configure the type of event(s) that the timer captures by writing the Tnevent field of the GPTM Control (GPTMCTL) register.
- Load the timer start value into the GPTM Timern Interval Load (GPTMTnILR) register.
- Load the desired event count into the GPTM Timern Match (GPTMTnMATCHR) register.
- 7. If interrupts are required, set the CnMIM bit in the GPTM Interrupt Mask (GPTMIMR) register.
- 8. Set the TnEN bit in the **GPTMCTL** register to enable the timer and begin waiting for edge events.
- 9. Poll the CnMRIS bit in the GPTMRIS register or wait for the interrupt to be generated (if enabled). In both cases, the status flags are cleared by writing a 1 to the CnMCINT bit of the GPTM Interrupt Clear (GPTMICR) register.

In Input Edge Count Mode, the timer stops after the desired number of edge events has been detected. To re-enable the timer, ensure that the TnEN bit is cleared and repeat steps 4 on page 205-9 on page 205.

10.3.5 16-Bit Input Edge Timing Mode

A timer is configured to Input Edge Timing mode by the following sequence:

- 1. Ensure the timer is disabled (the TnEN bit is cleared) before making any changes.
- 2. Write the **GPTM Configuration (GPTMCFG)** register with a value of 0x4.
- In the GPTM Timer Mode (GPTMTnMR) register, write the TnCMR field to 0x1 and the TnMR field to 0x3.
- 4. Configure the type of event that the timer captures by writing the Tnevent field of the **GPTM** Control (GPTMCTL) register.
- 5. Load the timer start value into the GPTM Timern Interval Load (GPTMTnILR) register.
- 6. If interrupts are required, set the Cneim bit in the GPTM Interrupt Mask (GPTMIMR) register.
- 7. Set the Then bit in the GPTM Control (GPTMCTL) register to enable the timer and start counting.
- 8. Poll the Cners bit in the **GPTMRIS** register or wait for the interrupt to be generated (if enabled). In both cases, the status flags are cleared by writing a 1 to the Cnecint bit of the **GPTM**

Interrupt Clear (GPTMICR) register. The time at which the event happened can be obtained by reading the **GPTM Timern (GPTMTnR)** register.

In Input Edge Timing mode, the timer continues running after an edge event has been detected, but the timer interval can be changed at any time by writing the **GPTMTnILR** register. The change takes effect at the next cycle after the write.

10.3.6 16-Bit PWM Mode

A timer is configured to PWM mode using the following sequence:

- 1. Ensure the timer is disabled (the TnEN bit is cleared) before making any changes.
- 2. Write the **GPTM Configuration (GPTMCFG)** register with a value of 0x4.
- 3. In the **GPTM Timer Mode (GPTMTnMR)** register, set the TnAMS bit to 0x1, the TnCMR bit to 0x0, and the TnMR field to 0x2.
- 4. Configure the output state of the PWM signal (whether or not it is inverted) in the TREVENT field of the GPTM Control (GPTMCTL) register.
- Load the timer start value into the GPTM Timern Interval Load (GPTMTnILR) register.
- 6. Load the GPTM Timern Match (GPTMTnMATCHR) register with the desired value.
- 7. Set the TnEN bit in the **GPTM Control (GPTMCTL)** register to enable the timer and begin generation of the output PWM signal.

In PWM Timing mode, the timer continues running after the PWM signal has been generated. The PWM period can be adjusted at any time by writing the **GPTMTnILR** register, and the change takes effect at the next cycle after the write.

10.4 Register Map

"Register Map" on page 206 lists the GPTM registers. The offset listed is a hexadecimal increment to the register's address, relative to that timer's base address:

Timer0: 0x4003.0000 0x4003.0000

Timer1: 0x4003.1000 0x4003.1000

Timer2: 0x4003.2000 0x4003.2000

Table 10-2. Timers Register Map

Offset	Name	Туре	Reset	Description	See page
0x000	GPTMCFG	R/W	0x0x0000.0000	GPTM Configuration	208
0x004	GPTMTAMR	R/W	0x0x0000.0000	GPTM TimerA Mode	209
0x008	GPTMTBMR	R/W	0x0x0000.0000	GPTM TimerB Mode	210
0x00C	GPTMCTL	R/W	0x0x0000.0000	GPTM Control	211
0x018	GPTMIMR	R/W	0x0x0000.0000	GPTM Interrupt Mask	213

Offset	Name	Туре	Reset	Description	See page
0x01C	GPTMRIS	RO	0x0x0000.0000	GPTM Raw Interrupt Status	215
0x020	GPTMMIS	RO	0x0x0000.0000	GPTM Masked Interrupt Status	216
0x024	GPTMICR	W1C	0x0x0000.0000	GPTM Interrupt Clear	217
0x028	GPTMTAILR	R/W	0x0000.FFFF (16-bit mode) 0xFFFF.FFFF (32-bit mode)	GPTM TimerA Interval Load	219
0x02C	GPTMTBILR	R/W	0x0000.FFFF	GPTM TimerB Interval Load	220
0x030	GPTMTAMATCHR	R/W	0x0000.FFFF (16-bit mode) 0xFFFF.FFF (32-bit mode)	GPTM TimerA Match	221
0x034	GPTMTBMATCHR	R/W	0x0000.FFFF	GPTM TimerB Match	222
0x038	GPTMTAPR	R/W	0x0000.0000	GPTM TimerA Prescale	223
0x03C	GPTMTBPR	R/W	0x0000.0000	GPTM TimerB Prescale	224
0x040	GPTMTAPMR	R/W	0x0000.0000	GPTM TimerA Prescale Match	225
0x044	GPTMTBPMR	R/W	0x0000.0000	GPTM TimerB Prescale Match	226
0x048	GPTMTAR	RO	0x0000.FFFF (16-bit mode) 0xFFFF.FFF (32-bit mode)	GPTM TimerA	227
0x04C	GPTMTBR	RO	0x0000.FFFF	GPTM TimerB	228

10.5 Register Descriptions

The remainder of this section lists and describes the GPTM registers, in numerical order by address offset.

Register 1: GPTM Configuration (GPTMCFG), offset 0x000

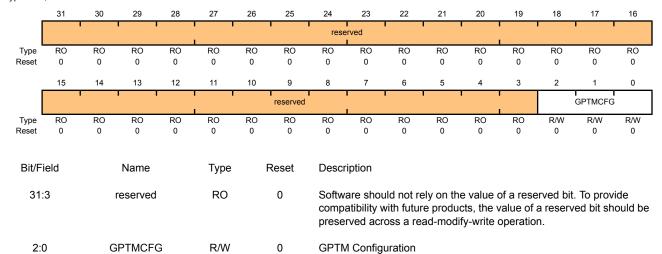
This register configures the global operation of the GPTM module. The value written to this register determines whether the GPTM is in 32- or 16-bit mode.

GPTM Configuration (GPTMCFG)

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000

Offset 0x000

Type R/W, reset 0x0x0000.0000



0x0: 32-bit timer configuration.

0x1: 32-bit real-time clock (RTC) counter configuration.

0x2: Reserved.

0x3: Reserved.

0x4-0x7: 16-bit timer configuration, function is controlled by bits 1:0 of **GPTMTAMR** and **GPTMTBMR**.

Register 2: GPTM TimerA Mode (GPTMTAMR), offset 0x004

This register configures the GPTM based on the configuration selected in the **GPTMCFG** register. When in 16-bit PWM mode, set the TAAMS bit to 0x1, the TACMR bit to 0x0, and the TAMR field to 0x2.

GPTM TimerA Mode (GPTMTAMR)

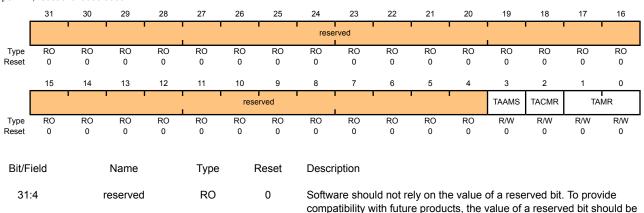
Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000

Offset 0x004

3

TAAMS

Type R/W, reset 0x0x0000.0000



GPTM TimerA Alternate Mode Select

0: Capture mode is enabled.

1: PWM mode is enabled.

Note: To enable PWM mode, you must also clear the TACMR bit and

set the TAMR field to 0x2.

preserved across a read-modify-write operation.

2 TACMR R/W 0 GPTM TimerA Capture Mode

0

0: Edge-Count mode.

1: Edge-Time mode.

1:0 TAMR R/W 0 GPTM TimerA Mode

R/W

0x0: Reserved.

0x1: One-Shot Timer mode.

0x2: Periodic Timer mode.

0x3: Capture mode.

The Timer mode is based on the timer configuration defined by bits 2:0 in the **GPTMCFG** register (16-or 32-bit).

In 32-bit timer configuration, this register controls the mode and the contents of $\mbox{\bf GPTMTBMR}$ are ignored.

Register 3: GPTM TimerB Mode (GPTMTBMR), offset 0x008

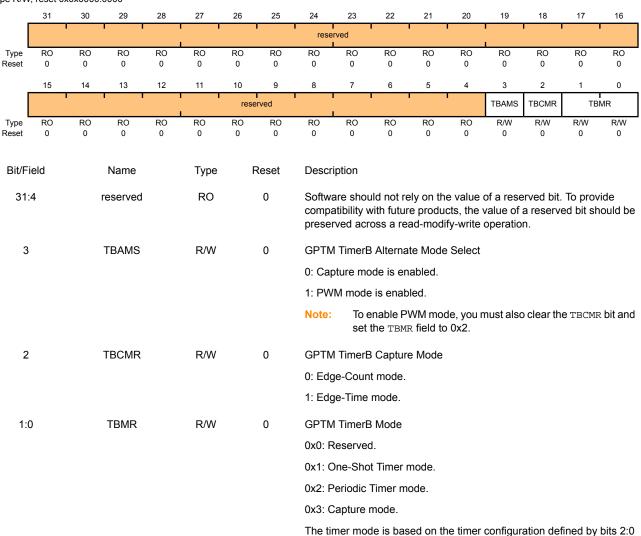
This register configures the GPTM based on the configuration selected in the **GPTMCFG** register. When in 16-bit PWM mode, set the TBAMS bit to 0x1, the TBCMR bit to 0x0, and the TBMR field to 0x2.

GPTM TimerB Mode (GPTMTBMR)

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000

Offset 0x008

Type R/W, reset 0x0x0000.0000



in the GPTMCFG register.

GPTMTAMR is used.

for TimerB.

In 16-bit timer configuration, these bits control the 16-bit timer modes

In 32-bit timer configuration, this register's contents are ignored and

Register 4: GPTM Control (GPTMCTL), offset 0x00C

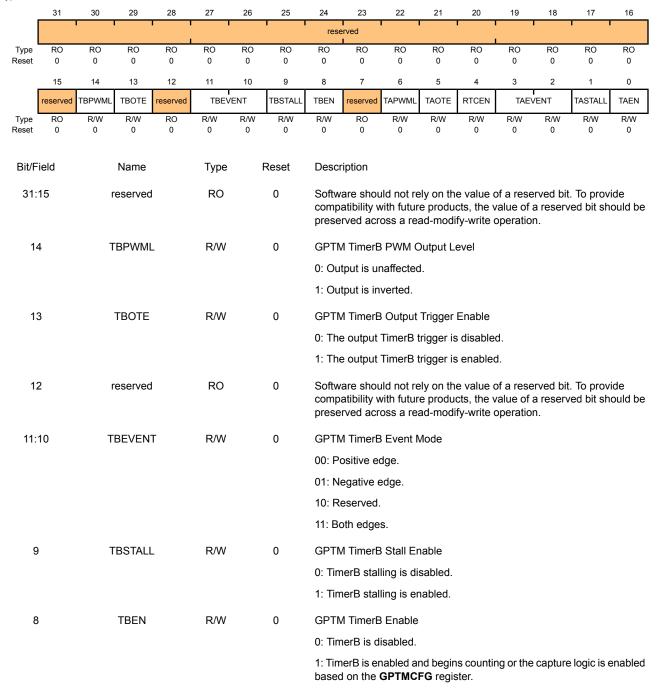
This register is used alongside the **GPTMCFG** and **GMTMTnMR** registers to fine-tune the timer configuration, and to enable other features such as timer stall and the output trigger. The output trigger can be used to initiate transfers on the ADC module.

GPTM Control (GPTMCTL)

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000

Offset 0x00C

Type R/W, reset 0x0x0000.0000



Bit/Field	Name	Туре	Reset	Description
7	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
6	TAPWML	R/W	0	GPTM TimerA PWM Output Level
				0: Output is unaffected.
				1: Output is inverted.
5	TAOTE	R/W	0	GPTM TimerA Output Trigger Enable
				0: The output TimerA trigger is disabled.
				1: The output TimerA trigger is enabled.
4	RTCEN	R/W	0	GPTM RTC Enable
				0: RTC counting is disabled.
				1: RTC counting is enabled.
3:2	TAEVENT	R/W	0	GPTM TimerA Event Mode
				00: Positive edge.
				01: Negative edge.
				10: Reserved.
				11: Both edges.
1	TASTALL	R/W	0	GPTM TimerA Stall Enable
				0: TimerA stalling is disabled.
				1: TimerA stalling is enabled.
0	TAEN	R/W	0	GPTM TimerA Enable
				0: TimerA is disabled.
				1: TimerA is enabled and begins counting or the capture logic is enabled based on the GPTMCFG register.

Register 5: GPTM Interrupt Mask (GPTMIMR), offset 0x018

This register allows software to enable/disable GPTM controller-level interrupts. Writing a 1 enables the interrupt, while writing a 0 disables it.

GPTM Interrupt Mask (GPTMIMR)

Timer0 base: 0x4003.0000
Timer1 base: 0x4003.1000
Timer2 base: 0x4003.2000
Offset 0x018
Type R/W, reset 0x0x0000.0000

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	
			reserved														
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	
_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
			reserved			CBEIM	СВМІМ	твтоім		rese	ved		RTCIM	CAEIM	CAMIM	TATOIM	
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0	RO 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0	R/W 0	
Bit/Fi	ield		Name		Туре	F	Reset	Descr	iption								
31:	11		reserved		RO		0	compa	atibility v	uld not re vith futur oss a rea	e produc	cts, the	value of	a reserv			
10)		CBEIM		R/W		0	GPTM	1 Captur	eB Even	t Interru	pt Mask					
								0: Inte	errupt is	disabled							
								1: Inte	errupt is	enabled.							
9			СВМІМ		R/W		0	GPTM CaptureB Match Interrupt Mask									
								0: Inte	0: Interrupt is disabled.								
								1: Inte	errupt is	enabled.							
8			ТВТОІМ		R/W		0	GPTM	1 TimerE	3 Time-O	ut Interr	upt Mas	k				
								0: Interrupt is disabled.									
						1: Interrupt is enabled.											
7:4	4		reserved		RO		0	compa	atibility v	uld not re vith futur oss a rea	e produc	cts, the	value of	a reserv			
3			RTCIM		R/W		0	GPTM	1 RTC Ir	iterrupt N	/lask						
								0: Inte	errupt is	disabled	=						
								1: Inte	errupt is	enabled.							
2			CAEIM		R/W		0	GPTM	1 Captur	eA Even	t Interru	pt Mask					
								0: Inte	errupt is	disabled							
								1: Inte	errupt is	enabled.							
1			CAMIM		R/W		0	GPTM	1 Captur	eA Matc	h Interru	ıpt Mask	(
								0: Inte	errupt is	disabled	-						
								1: Inte	errupt is	enabled.							

Bit/Field	Name	Type	Reset	Description
0	TATOIM	R/W	0	GPTM TimerA Time-Out Interrupt Mask
				0: Interrupt is disabled.
				1: Interrupt is enabled.

Register 6: GPTM Raw Interrupt Status (GPTMRIS), offset 0x01C

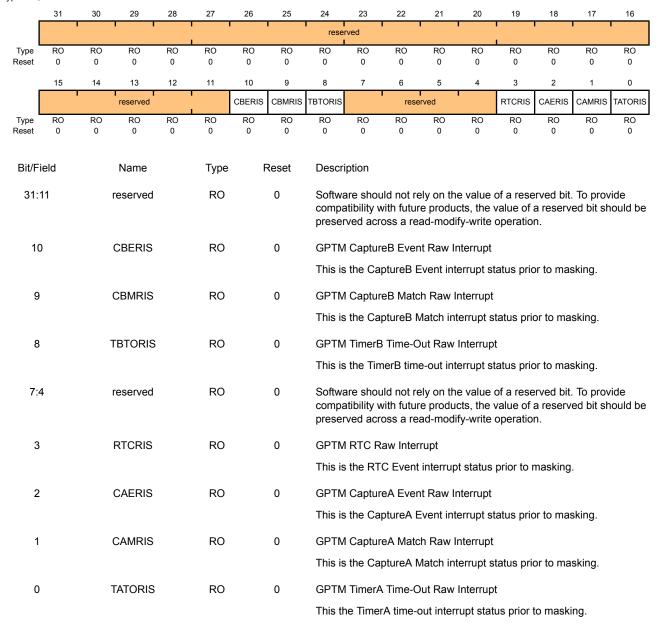
This register shows the state of the GPTM's internal interrupt signal. These bits are set whether or not the interrupt is masked in the **GPTMIMR** register. Each bit can be cleared by writing a 1 to its corresponding bit in **GPTMICR**.

GPTM Raw Interrupt Status (GPTMRIS)

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000

Offset 0x01C

Type RO, reset 0x0x0000.0000



Register 7: GPTM Masked Interrupt Status (GPTMMIS), offset 0x020

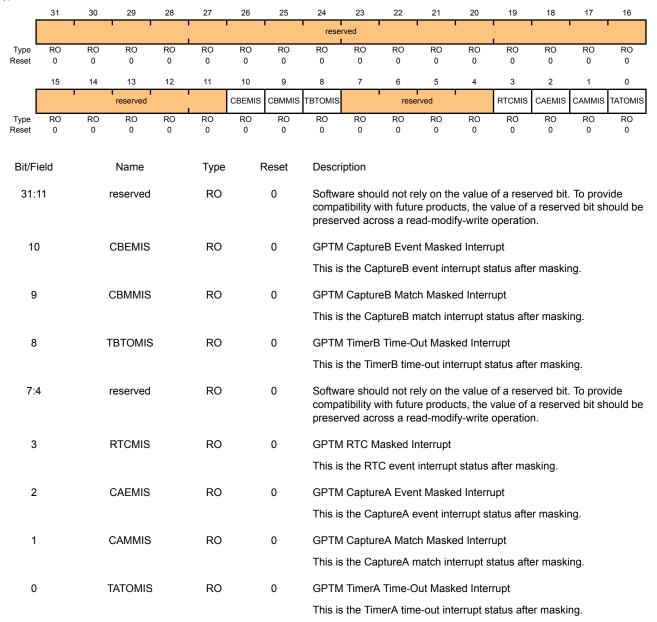
This register show the state of the GPTM's controller-level interrupt. If an interrupt is unmasked in **GPTMIMR**, and there is an event that causes the interrupt to be asserted, the corresponding bit is set in this register. All bits are cleared by writing a 1 to the corresponding bit in **GPTMICR**.

GPTM Masked Interrupt Status (GPTMMIS)

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000

Offset 0x020

Type RO, reset 0x0x0000.0000



Register 8: GPTM Interrupt Clear (GPTMICR), offset 0x024

This register is used to clear the status bits in the GPTMRIS and GPTMMIS registers. Writing a 1 to a bit clears the corresponding bit in the **GPTMRIS** and **GPTMMIS** registers.

GPTM Interrupt Clear (GPTMICR)

Timer0 base: 0x4003.0000
Timer1 base: 0x4003.1000
Timer2 base: 0x4003.2000
Offset 0x024
Type W1C, reset 0x0x0000.0000

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
		l	'					rese	rved	•		l				
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	1		reserved			CBECINT	CBMCINT	TBTOCINT		reser	ved		RTCCINT	CAECINT	CAMCINT	TATOCINT
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	W1C 0	W1C 0	W1C 0	RO 0	RO 0	RO 0	RO 0	W1C 0	W1C 0	W1C 0	W1C 0
Bit/Fi	ield		Name		Туре	F	Reset	Descr	iption							
31:	11		reserved		RO		0	compa	atibility w	ld not re vith future oss a rea	e produc	cts, the	value of	a reserv		
10)	(CBECINT		W1C		0	GPTM	l Captur	eB Even	t Interru	pt Clear				
								0: The	interrup	ot is unaf	fected.					
								1: The	interrup	t is clea	red.					
9		C	CBMCINT	-	W1C		0	GPTM	l Captur	eB Matcl	n Interru	ıpt Clea	r			
								0: The	interrup	ot is unaf	fected.					
								1: The	interrup	ot is clea	red.					
8		Т	BTOCIN	Г	W1C		0	GPTM	1 TimerB	Time-O	ut Interr	upt Clea	ar			
								0: The	interrup	t is unaf	fected.					
								1: The	interrup	t is clea	red.					
7:4	4		reserved		RO		0	compa	atibility w	ld not re vith future oss a rea	e produc	cts, the	value of	a reserv	•	
3		F	RTCCINT		W1C		0	GPTM	RTC In	terrupt C	lear					
								0: The	interrup	ot is unaf	fected.					
								1: The	interrup	t is clea	red.					
2		(CAECINT		W1C		0	GPTM	l Captur	eA Even	t Interru	pt Clear				
								0: The	interrup	ot is unaf	fected.					
								1: The	interrup	t is clea	red.					
1		(CAMCINT	-	W1C		0	GPTM	l Captur	eA Matcl	n Raw Ir	nterrupt				
								This is	the Ca	otureA m	atch int	errupt s	tatus aft	er maski	ng.	

Bit/Field	Name	Type	Reset	Description
0	TATOCINT	W1C	0	GPTM TimerA Time-Out Raw Interrupt
				0: The interrupt is unaffected.
				1: The interrupt is cleared.

Register 9: GPTM TimerA Interval Load (GPTMTAILR), offset 0x028

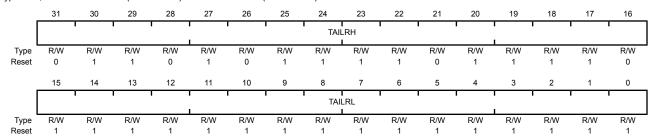
This register is used to load the starting count value into the timer. When GPTM is configured to one of the 32-bit modes, **GPTMTAILR** appears as a 32-bit register (the upper 16-bits correspond to the contents of the **GPTM TimerB Interval Load (GPTMTBILR)** register). In 16-bit mode, the upper 16 bits of this register read as 0s and have no effect on the state of **GPTMTBILR**.

GPTM TimerA Interval Load (GPTMTAILR)

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000

Offset 0x028

Type R/W, reset 0x0000.FFFF (16-bit mode) and 0xFFFF.FFFF (32-bit mode)



Bit/Field	Name	Туре	Reset	Description
31:16	TAILRH	R/W	0xFFFF (32-bit mode) 0x0000 (16-bit mode)	GPTM TimerA Interval Load Register High When configured for 32-bit mode via the GPTMCFG register, the GPTM TimerB Interval Load (GPTMTBILR) register loads this value on a write. A read returns the current value of GPTMTBILR.
				In 16-bit mode, this field reads as 0 and does not have an effect on the state of $\ensuremath{\mathbf{GPTMTBILR}}.$
15:0	TAILRL	R/W	0xFFFF	GPTM TimerA Interval Load Register Low

For both 16- and 32-bit modes, writing this field loads the counter for TimerA. A read returns the current value of **GPTMTAILR**.

Register 10: GPTM TimerB Interval Load (GPTMTBILR), offset 0x02C

This register is used to load the starting count value into TimerB. When the GPTM is configured to a 32-bit mode, **GPTMTBILR** returns the current value of TimerB and ignores writes.

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GPTM TimerB Interval Load (GPTMTBILR)

30

29

28

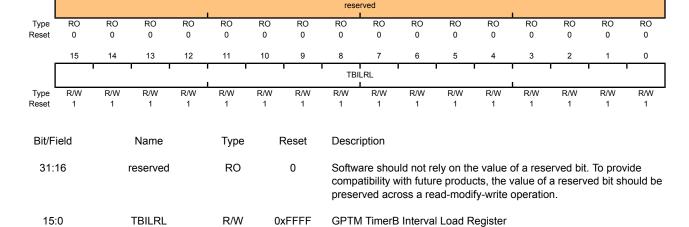
27

26

25

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000 Offset 0x02C

Type R/W, reset 0x0000.FFFF 31



24

When the GPTM is not configured as a 32-bit timer, a write to this field updates GPTMTBILR. In 32-bit mode, writes are ignored, and reads return the current value of **GPTMTBILR**.

Register 11: GPTM TimerA Match (GPTMTAMATCHR), offset 0x030

This register is used in 32-bit Real-Time Clock mode and 16-bit PWM and Input Edge Count modes.

GPTM TimerA Match (GPTMTAMATCHR)

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000

Offset 0x030

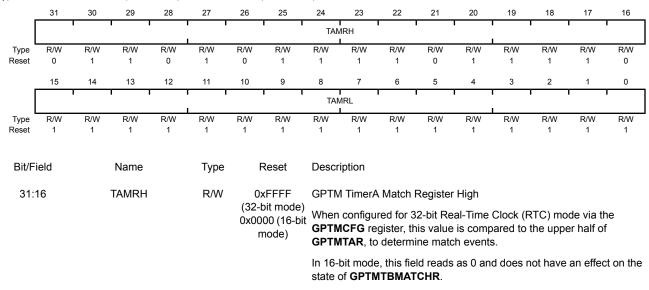
15:0

Type R/W, reset 0x0000.FFFF (16-bit mode) and 0xFFFF.FFFF (32-bit mode)

TAMRL

R/W

0xFFFF



When configured for 32-bit Real-Time Clock (RTC) mode via the **GPTMCFG** register, this value is compared to the lower half of **GPTMTAR**, to determine match events.

GPTM TimerA Match Register Low

When configured for PWM mode, this value along with **GPTMTAILR**, determines the duty cycle of the output PWM signal.

When configured for Edge Count mode, this value along with **GPTMTAILR**, determines how many edge events are counted. The total number of edge events counted is equal to the value in **GPTMTAILR** minus this value.

Register 12: GPTM TimerB Match (GPTMTBMATCHR), offset 0x034

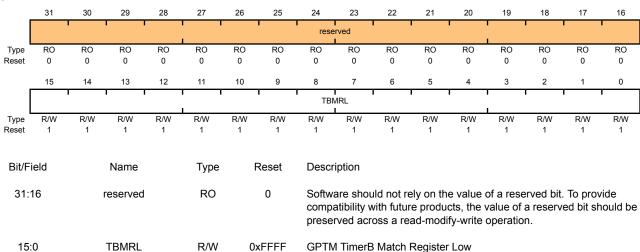
This register is used in 32-bit Real-Time Clock mode and 16-bit PWM and Input Edge Count modes.

GPTM TimerB Match (GPTMTBMATCHR)

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000

Offset 0x034

Type R/W, reset 0x0000.FFFF



When configured for PWM mode, this value along with **GPTMTBILR**, determines the duty cycle of the output PWM signal.

When configured for Edge Count mode, this value along with **GPTMTBILR**, determines how many edge events are counted. The total number of edge events counted is equal to the value in **GPTMTBILR** minus this value.

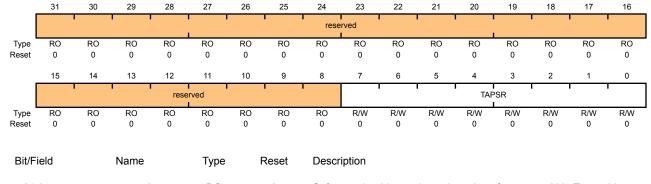
Register 13: GPTM TimerA Prescale (GPTMTAPR), offset 0x038

This register allows software to extend the range of the 16-bit timers when operating in one-shot or periodic mode.

GPTM TimerA Prescale (GPTMTAPR)

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000 Offset 0x038

Type R/W, reset 0x0000.0000



31:8 reserved RO 0 Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

7:0 TAPSR R/W 0 GPTM TimerA Prescale

The register loads this value on a write. A read returns the current value of the register.

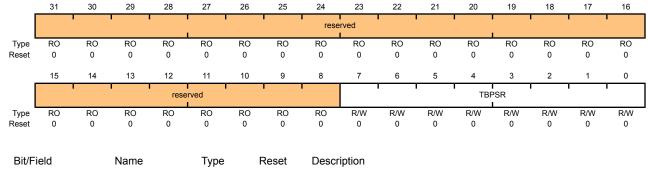
Refer to Table 10-1 on page 200 for more details and an example.

Register 14: GPTM TimerB Prescale (GPTMTBPR), offset 0x03C

This register allows software to extend the range of the 16-bit timers when operating in one-shot or periodic mode.

GPTM TimerB Prescale (GPTMTBPR)

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000 Offset 0x03C Type R/W, reset 0x0000.0000



31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
------	----------	----	---	---

R/W 7:0 **TBPSR** 0 **GPTM TimerB Prescale**

> The register loads this value on a write. A read returns the current value of this register.

Refer to Table 10-1 on page 200 for more details and an example.

Register 15: GPTM TimerA Prescale Match (GPTMTAPMR), offset 0x040

This register effectively extends the range of **GPTMTAMATCHR** to 24 bits when operating in 16-bit one-shot or periodic mode.

GPTM TimerA Prescale Match (GPTMTAPMR)

TAPSMR

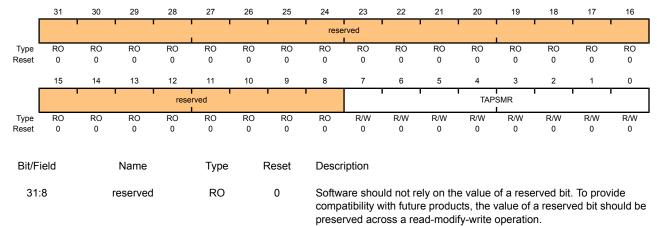
R/W

0

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000 Offset 0x040

Type R/W, reset 0x0000.0000

7:0



GPTM TimerA Prescale Match

This value is used alongside **GPTMTAMATCHR** to detect timer match events while using a prescaler.

Register 16: GPTM TimerB Prescale Match (GPTMTBPMR), offset 0x044

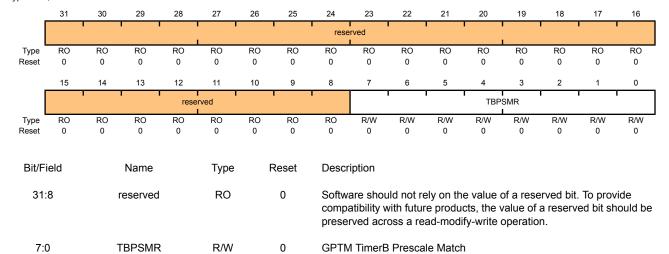
This register effectively extends the range of GPTMTBMATCHR to 24 bits when operating in 16-bit one-shot or periodic mode.

GPTM TimerB Prescale Match (GPTMTBPMR)

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000 Offset 0x044

Type R/W, reset 0x0000.0000

7:0



0

This value is used alongside **GPTMTBMATCHR** to detect timer match events while using a prescaler.

Register 17: GPTM TimerA (GPTMTAR), offset 0x048

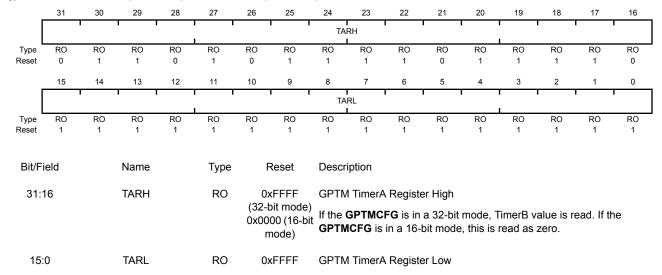
This register shows the current value of the TimerA counter in all cases except for Input Edge Count mode. When in this mode, this register contains the time at which the last edge event took place.

GPTM TimerA (GPTMTAR)

Timer0 base: 0x4003.0000 Timer1 base: 0x4003.1000 Timer2 base: 0x4003.2000

Offset 0x048

Type RO, reset 0x0000.FFFF (16-bit mode) and 0xFFFF.FFFF (32-bit mode)



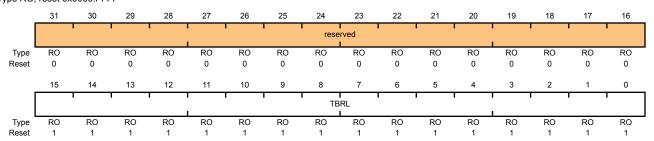
A read returns the current value of the **GPTM TimerA Count Register**, except in Input Edge Count mode, when it returns the timestamp from the last edge event.

Register 18: GPTM TimerB (GPTMTBR), offset 0x04C

This register shows the current value of the TimerB counter in all cases except for Input Edge Count mode. When in this mode, this register contains the time at which the last edge event took place.

GPTM TimerB (GPTMTBR)

Timer0 base: 0x4003.0000
Timer1 base: 0x4003.1000
Timer2 base: 0x4003.2000
Offset 0x04C
Type RO, reset 0x0000.FFFF



Bit/Field	Name	Туре	Reset	Description
31:16	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15:0	TBRL	RO	0xFFFF	GPTM TimerB

A read returns the current value of the **GPTM TimerB Count Register**, except in Input Edge Count mode, when it returns the timestamp from the last edge event.

11 Watchdog Timer

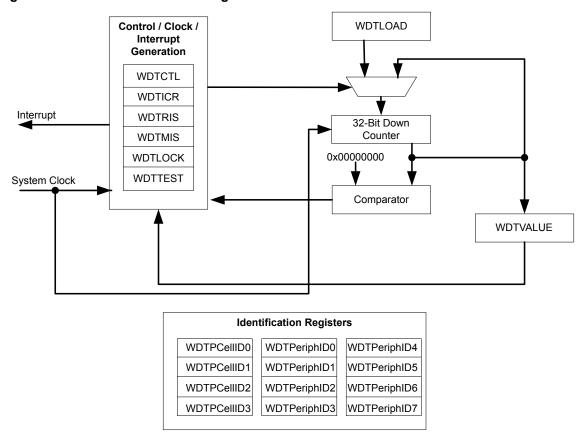
A watchdog timer can generate nonmaskable interrupts (NMIs) or a reset when a time-out value is reached. The watchdog timer is used to regain control when a system has failed due to a software error or due to the failure of an external device to respond in the expected way.

The Stellaris[®] Watchdog Timer module consists of a 32-bit down counter, a programmable load register, interrupt generation logic, a locking register, and user-enabled stalling.

The Watchdog Timer can be configured to generate an interrupt to the controller on its first time-out, and to generate a reset signal on its second time-out. Once the Watchdog Timer has been configured, the lock register can be written to prevent the timer configuration from being inadvertently altered.

11.1 Block Diagram

Figure 11-1. WDT Module Block Diagram



11.2 Functional Description

The Watchdog Timer module consists of a 32-bit down counter, a programmable load register, interrupt generation logic, and a locking register. Once the Watchdog Timer has been configured, the **Watchdog Timer Lock (WDTLOCK)** register is written, which prevents the timer configuration from being inadvertently altered by software.

The Watchdog Timer module generates the first time-out signal when the 32-bit counter reaches the zero state after being enabled; enabling the counter also enables the watchdog timer interrupt. After the first time-out event, the 32-bit counter is re-loaded with the value of the **Watchdog Timer Load (WDTLOAD)** register, and the timer resumes counting down from that value.

If the timer counts down to its zero state again before the first time-out interrupt is cleared, and the reset signal has been enabled (via the WatchdogResetEnable function), the Watchdog timer asserts its reset signal to the system. If the interrupt is cleared before the 32-bit counter reaches its second time-out, the 32-bit counter is loaded with the value in the **WDTLOAD** register, and counting resumes from that value.

If **WDTLOAD** is written with a new value while the Watchdog Timer counter is counting, then the counter is loaded with the new value and continues counting.

Writing to **WDTLOAD** does not clear an active interrupt. An interrupt must be specifically cleared by writing to the **Watchdog Interrupt Clear (WDTICR)** register.

The Watchdog module interrupt and reset generation can be enabled or disabled as required. When the interrupt is re-enabled, the 32-bit counter is preloaded with the load register value and not its last state.

11.3 Initialization and Configuration

To use the WDT, its peripheral clock must be enabled by setting the WDT bit in the **RCGC0** register. The Watchdog Timer is configured using the following sequence:

- 1. Load the WDTLOAD register with the desired timer load value.
- If the Watchdog is configured to trigger system resets, set the RESEN bit in the WDTCTL register.
- Set the INTEN bit in the WDTCTL register to enable the Watchdog and lock the control register.

If software requires that all of the watchdog registers are locked, the Watchdog Timer module can be fully locked by writing any value to the **WDTLOCK** register. To unlock the Watchdog Timer, write a value of 0x1ACCE551.

11.4 Register Map

"Register Map" on page 230 lists the Watchdog registers. The offset listed is a hexadecimal increment to the register's address, relative to the Watchdog Timer base address of 0x4000.0000.

Table 11-1. Watchdog Timer Register Map

Offset	Name	Туре	Reset	Description	See page
0x000	WDTLOAD	R/W	0xFFFF.FFFF	Watchdog Load	232
0x004	WDTVALUE	RO	0xFFFF.FFFF	Watchdog Value	233
0x008	WDTCTL	R/W	0x0000.0000	Watchdog Control	234
0x00C	WDTICR	WO	-	Watchdog Interrupt Clear	235
0x010	WDTRIS	RO	0x0000.0000	Watchdog Raw Interrupt Status	236
0x014	WDTMIS	RO	0x0000.0000	Watchdog Masked Interrupt Status	237
0x418	WDTTEST	R/W	0x0000.0000	Watchdog Test	238

Offset	Name	Туре	Reset	Description	See page
0xC00	WDTLOCK	R/W	0x0000.0000	Watchdog Lock	239
0xFD0	WDTPeriphID4	RO	0x0000.0000	Watchdog Peripheral Identification 4	240
0xFD4	WDTPeriphID5	RO	0x0000.0000	Watchdog Peripheral Identification 5	241
0xFD8	WDTPeriphID6	RO	0x0000.0000	Watchdog Peripheral Identification 6	242
0xFDC	WDTPeriphID7	RO	0x0000.0000	Watchdog Peripheral Identification 7	243
0xFE0	WDTPeriphID0	RO	0x0000.0005	Watchdog Peripheral Identification 0	244
0xFE4	WDTPeriphID1	RO	0x0000.0018	Watchdog Peripheral Identification 1	245
0xFE8	WDTPeriphID2	RO	0x0000.0018	Watchdog Peripheral Identification 2	246
0xFEC	WDTPeriphID3	RO	0x0000.0001	Watchdog Peripheral Identification 3	247
0xFF0	WDTPCellID0	RO	0x0000.000D	Watchdog PrimeCell Identification 0	248
0xFF4	WDTPCellID1	RO	0x0000.00F0	Watchdog PrimeCell Identification 1	249
0xFF8	WDTPCellID2	RO	0x0000.0005	Watchdog PrimeCell Identification 2	250
0xFFC	WDTPCellID3	RO	0x0000.00B1	Watchdog PrimeCell Identification 3	251

11.5 Register Descriptions

The remainder of this section lists and describes the WDT registers, in numerical order by address offset.

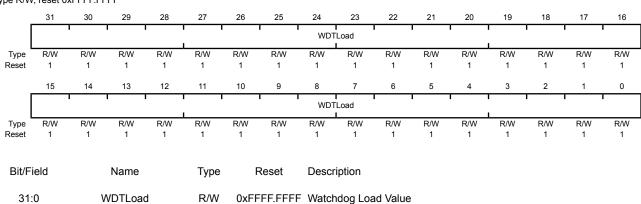
Register 1: Watchdog Load (WDTLOAD), offset 0x000

This register is the 32-bit interval value used by the 32-bit counter. When this register is written, the value is immediately loaded and the counter restarts counting down from the new value. If the **WDTLOAD** register is loaded with 0x0000.0000, an interrupt is immediately generated.

Watchdog Load (WDTLOAD)

Base 0x4000.0000

Offset 0x000 Type R/W, reset 0xFFFF.FFF



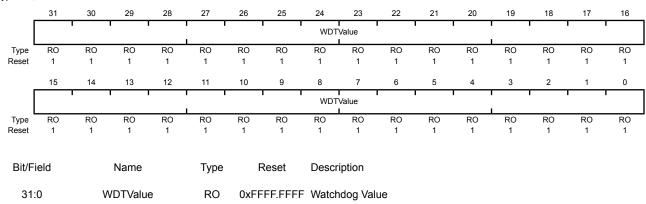
Register 2: Watchdog Value (WDTVALUE), offset 0x004

This register contains the current count value of the timer.

Watchdog Value (WDTVALUE)

Base 0x4000.0000

Offset 0x004
Type RO, reset 0xFFFF.FFF



Current value of the 32-bit down counter.

Register 3: Watchdog Control (WDTCTL), offset 0x008

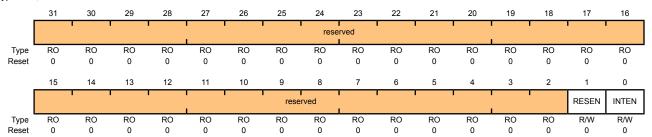
This register is the watchdog control register. The watchdog timer can be configured to generate a reset signal (on second time-out) or an interrupt on time-out.

When the watchdog interrupt has been enabled, all subsequent writes to the control register are ignored. The only mechanism that can re-enable writes is a hardware reset.

Watchdog Control (WDTCTL)

Base 0x4000.0000 Offset 0x008

Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	RESEN	R/W	0	Watchdog Reset Enable
				0: Disabled.
				1: Enable the Watchdog module reset output.
0	INTEN	R/W	0	Watchdog Interrupt Enable

^{0:} Interrupt event disabled (once this bit is set, it can only be cleared by a hardware reset).

^{1:} Interrupt event enabled. Once enabled, all writes are ignored.

Register 4: Watchdog Interrupt Clear (WDTICR), offset 0x00C

This register is the interrupt clear register. A write of any value to this register clears the Watchdog interrupt and reloads the 32-bit counter from the **WDTLOAD** register. Value for a read or reset is indeterminate.

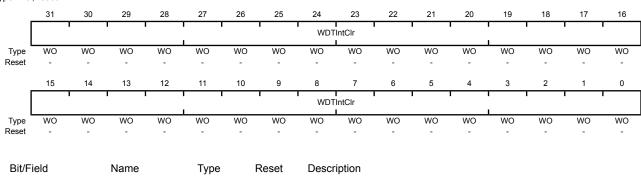
Watchdog Interrupt Clear (WDTICR)

WDTIntClr

WO

Base 0x4000.0000 Offset 0x00C Type WO, reset -

31:0



Watchdog Interrupt Clear

Register 5: Watchdog Raw Interrupt Status (WDTRIS), offset 0x010

This register is the raw interrupt status register. Watchdog interrupt events can be monitored via this register if the controller interrupt is masked.

Watchdog Raw Interrupt Status (WDTRIS)

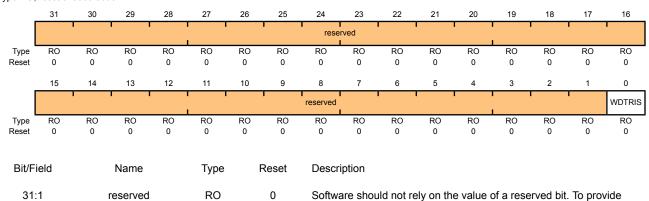
WDTRIS

RO

0

0

Base 0x4000.0000 Offset 0x010 Type RO, reset 0x0000.0000



Gives the raw interrupt state (prior to masking) of WDTINTR.

preserved across a read-modify-write operation.

Watchdog Raw Interrupt Status

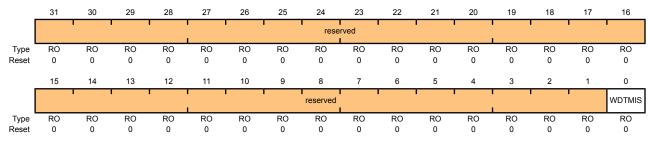
compatibility with future products, the value of a reserved bit should be

Register 6: Watchdog Masked Interrupt Status (WDTMIS), offset 0x014

This register is the masked interrupt status register. The value of this register is the logical AND of the raw interrupt bit and the Watchdog interrupt enable bit.

Watchdog Masked Interrupt Status (WDTMIS)

Base 0x4000.0000 Offset 0x014 Type RO, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	WDTMIS	RO	0	Watchdog Masked Interrupt Status

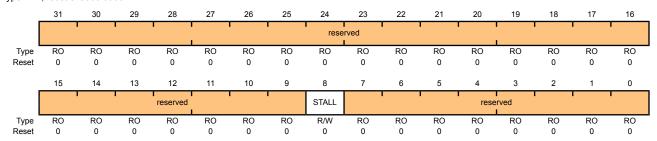
Gives the masked interrupt state (after masking) of the WDTINTR interrupt.

Register 7: Watchdog Test (WDTTEST), offset 0x418

This register provides user-enabled stalling when the microcontroller asserts the CPU halt flag during debug.

Watchdog Test (WDTTEST)

Base 0x4000.0000 Offset 0x418 Type R/W, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:9	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
8	STALL	R/W	0	Watchdog Stall Enable When set to 1, if the Stellaris [®] microcontroller is stopped with a debugger, the watchdog timer stops counting. Once the microcontroller is restarted, the watchdog timer resumes counting.
7:0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation

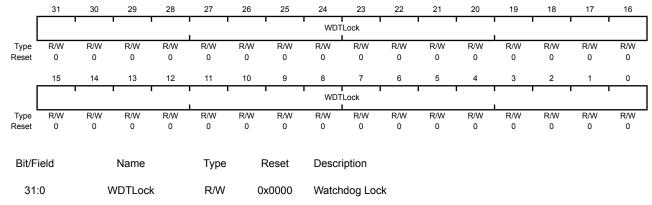
Register 8: Watchdog Lock (WDTLOCK), offset 0xC00

Writing 0x1ACCE551 to the **WDTLOCK** register enables write access to all other registers. Writing any other value to the **WDTLOCK** register re-enables the locked state for register writes to all the other registers. Reading the **WDTLOCK** register returns the lock status rather than the 32-bit value written. Therefore, when write accesses are disabled, reading the **WDTLOCK** register returns 0x0000.0001 (when locked; otherwise, the returned value is 0x0000.0000 (unlocked)).

Watchdog Lock (WDTLOCK)

Base 0x4000.0000 Offset 0xC00

Type R/W, reset 0x0000.0000



A write of the value 0x1ACCE551 unlocks the watchdog registers for write access. A write of any other value reapplies the lock, preventing any register updates.

A read of this register returns the following values:

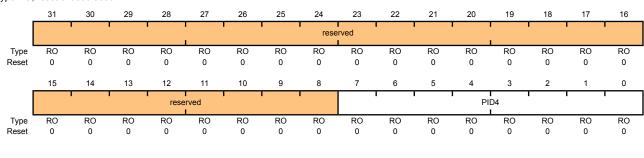
Locked: 0x0000.0001 Unlocked: 0x0000.0000

Register 9: Watchdog Peripheral Identification 4 (WDTPeriphID4), offset 0xFD0

The WDTPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

Watchdog Peripheral Identification 4 (WDTPeriphID4)

Base 0x4000.0000 Offset 0xFD0 Type RO, reset 0x0000.0000

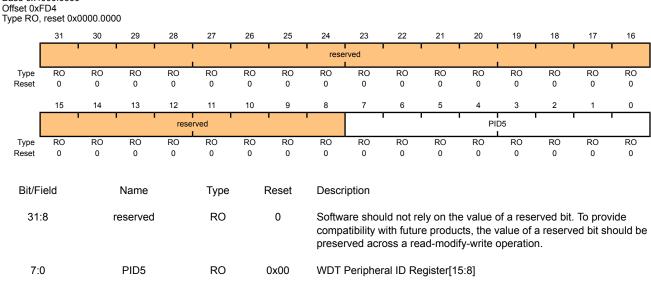


Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID4	RO	0x00	WDT Peripheral ID Register[7:0]

Register 10: Watchdog Peripheral Identification 5 (WDTPeriphID5), offset 0xFD4

The WDTPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

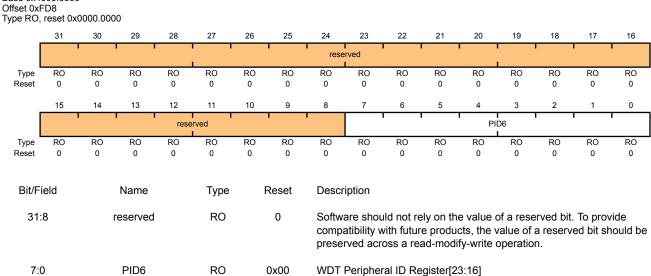
Watchdog Peripheral Identification 5 (WDTPeriphID5)



Register 11: Watchdog Peripheral Identification 6 (WDTPeriphID6), offset 0xFD8

The WDTPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

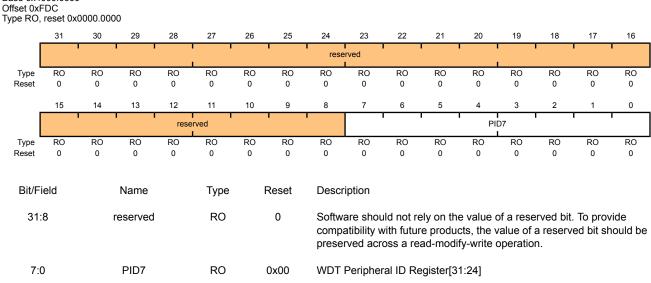
Watchdog Peripheral Identification 6 (WDTPeriphID6)



Register 12: Watchdog Peripheral Identification 7 (WDTPeriphID7), offset 0xFDC

The WDTPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

Watchdog Peripheral Identification 7 (WDTPeriphID7)



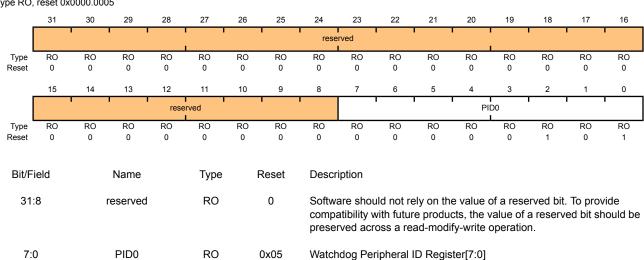
Register 13: Watchdog Peripheral Identification 0 (WDTPeriphID0), offset 0xFE0

The WDTPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

Watchdog Peripheral Identification 0 (WDTPeriphID0)

Base 0x4000.0000

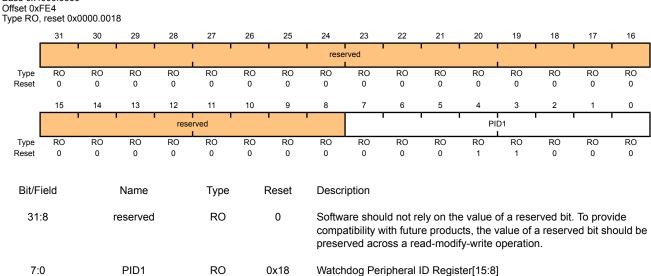
Offset 0xFE0
Type RO, reset 0x0000.0005



Register 14: Watchdog Peripheral Identification 1 (WDTPeriphID1), offset 0xFE4

The WDTPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

Watchdog Peripheral Identification 1 (WDTPeriphID1)



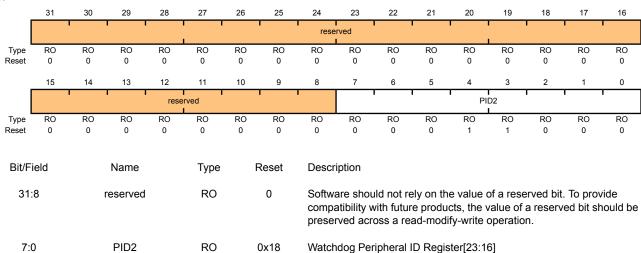
Register 15: Watchdog Peripheral Identification 2 (WDTPeriphID2), offset 0xFE8

The WDTPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

Watchdog Peripheral Identification 2 (WDTPeriphID2)

Base 0x4000.0000

Offset 0xFE8
Type RO, reset 0x0000.0018



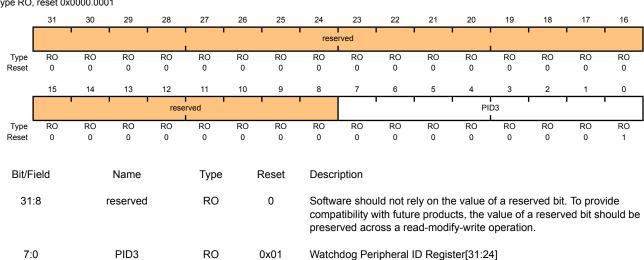
Register 16: Watchdog Peripheral Identification 3 (WDTPeriphID3), offset 0xFEC

The **WDTPeriphIDn** registers are hard-coded and the fields within the register determine the reset value.

Watchdog Peripheral Identification 3 (WDTPeriphID3)

Base 0x4000.0000

Offset 0xFEC Type RO, reset 0x0000.0001

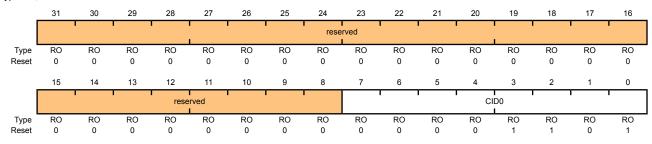


Register 17: Watchdog PrimeCell Identification 0 (WDTPCellID0), offset 0xFF0

The WDTPCellIDn registers are hard-coded and the fields within the register determine the reset value.

Watchdog PrimeCell Identification 0 (WDTPCellID0)

Base 0x4000.0000 Offset 0xFF0 Type RO, reset 0x0000.000D



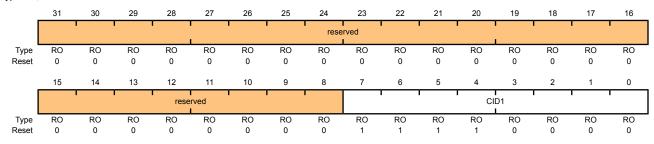
Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CID0	RO	0x0D	Watchdog PrimeCell ID Register[7:0]

Register 18: Watchdog PrimeCell Identification 1 (WDTPCellID1), offset 0xFF4

The WDTPCellIDn registers are hard-coded and the fields within the register determine the reset value.

Watchdog PrimeCell Identification 1 (WDTPCellID1)

Base 0x4000.0000 Offset 0xFF4 Type RO, reset 0x0000.00F0



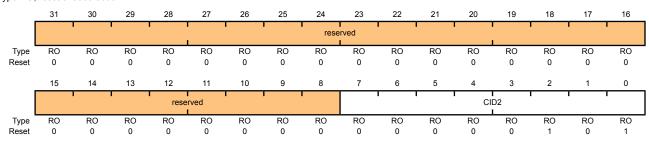
Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CID1	RO	0xF0	Watchdog PrimeCell ID Register[15:8]

Register 19: Watchdog PrimeCell Identification 2 (WDTPCellID2), offset 0xFF8

The WDTPCellIDn registers are hard-coded and the fields within the register determine the reset value.

Watchdog PrimeCell Identification 2 (WDTPCellID2)

Base 0x4000.0000 Offset 0xFF8 Type RO, reset 0x0000.0005



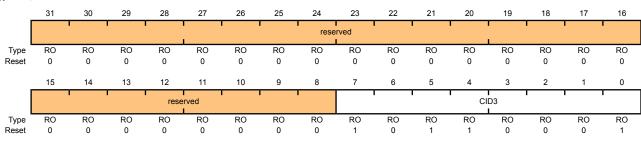
Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CID2	RO	0x05	Watchdog PrimeCell ID Register[23:16]

Register 20: Watchdog PrimeCell Identification 3 (WDTPCellID3), offset 0xFFC

The WDTPCellIDn registers are hard-coded and the fields within the register determine the reset value.

Watchdog PrimeCell Identification 3 (WDTPCellID3)

Base 0x4000.0000 Offset 0xFFC Type RO, reset 0x0000.00B1



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CID3	RO	0xB1	Watchdog PrimeCell ID Register[31:24]

12 Analog-to-Digital Converter (ADC)

An analog-to-digital converter (ADC) is a peripheral that converts a continuous analog voltage to a discrete digital number.

The Stellaris[®] ADC module features 10-bit conversion resolution and supports four input channels, plus an internal temperature sensor. The ADC module contains a programmable sequencer which allows for the sampling of multiple analog input sources without controller intervention. Each sample sequence provides flexible programming with fully configurable input source, trigger events, interrupt generation, and sequence priority.

The Stellaris® ADC provides the following features:

- Four analog input channels
- Single-ended and differential-input configurations
- Internal temperature sensor
- Sample rate of 500 thousand samples/second
- Four programmable sample conversion sequences from one to eight entries long, with corresponding conversion result FIFOs
- Flexible trigger control
 - Controller (software)
 - Timers
 - Analog Comparators
 - PWM
 - GPIO
- Hardware averaging of up to 64 samples for improved accuracy

ADCSSFIFO3

12.1 Block Diagram

Trigger Events Analog Inputs Comparator GPIO (PB4) Sample Control/Status Sequencer 0 ADCACTSS ADCSSMUX0 **PWM** Analog-to-Digital ADCOSTAT ADCSSCTL0 ADCUSTAT ADCSSFSTAT0 Comparator GPIO (PB4) ADCSSPRI PWM Sequencer 1 ADCSSMUX1 Comparator GPIO (PB4) ADCSSCTL1 Hardware Averager Timer ADCSSFSTAT1 **PWM** ADCSAC Sample Comparator GPIO (PB4) Timer Sequencer 2 ADCSSMUX2 PWM ADCSSCTL2 FIFO Block ADCSSFSTAT2 ADCSSFIFO0 **ADCEMUX** ADCSSFIFO1 Sample ADCSSFIFO2 ADCPSSI Interrupt Control Sequencer 3

ADCSSMUX3

ADCSSCTL3

ADCSSFSTAT3

Figure 12-1. ADC Module Block Diagram

12.2 Functional Description

SS0 Interrupt

SS1 Interrupt

The Stellaris[®] ADC collects sample data by using a programmable sequence-based approach instead of the traditional single or double-sampling approach found on many ADC modules. Each *sample sequence* is a fully programmed series of consecutive (back-to-back) samples, allowing the ADC to collect data from multiple input sources without having to be re-configured or serviced by the controller. The programming of each sample in the sample sequence includes parameters such as the input source and mode (differential versus single-ended input), interrupt generation on sample completion, and the indicator for the last sample in the sequence.

12.2.1 Sample Sequencers

The sampling control and data capture is handled by the Sample Sequencers. All of the sequencers are identical in implementation except for the number of samples that can be captured and the depth of the FIFO. Table 12-1 on page 253 shows the maximum number of samples that each Sequencer can capture and its corresponding FIFO depth. In this implementation, each FIFO entry is a 32-bit word, with the lower 10 bits containing the conversion result.

Table 12-1. Samples and FIFO Depth of Sequencers

ADCIM

ADCRIS

ADCISC

Sequencer	Number of Samples	Depth of FIFO
SS3	1	1
SS2	4	4
SS1	4	4
SS0	8	8

For a given sample sequence, each sample is defined by two 4-bit nibbles in the ADC Sample Sequence Input Multiplexer Select (ADCSSMUXn) and ADC Sample Sequence Control (ADCSSCTLn) registers, where "n" corresponds to the sequence number. The ADCSSMUXn nibbles select the input pin, while the ADCSSCTLn nibbles contain the sample control bits corresponding to parameters such as temperature sensor selection, interrupt enable, end of sequence, and differential input mode. Sample Sequencers are enabled by setting the respective ASENn bit in the ADC Active Sample Sequencer (ADCACTSS) register, but can be configured before being enabled.

When configuring a sample sequence, multiple uses of the same input pin within the same sequence is allowed. In the ADCSSCTLn register, the Interrupt Enable (IE) bits can be set for any combination of samples, allowing interrupts to be generated after every sample in the sequence if necessary. Also, the END bit can be set at any point within a sample sequence. For example, if Sequencer 0 is used, the END bit can be set in the nibble associated with the fifth sample, allowing Sequencer 0 to complete execution of the sample sequence after the fifth sample.

After a sample sequence completes execution, the result data can be retrieved from the **ADC Sample Sequence Result FIFO** (**ADCSSFIFOn**) registers. The FIFOs are simple circular buffers that read a single address to "pop" result data. For software debug purposes, the positions of the FIFO head and tail pointers are visible in the **ADC Sample Sequence FIFO Status** (**ADCSSFSTATn**) registers along with FULL and EMPTY status flags. Overflow and underflow conditions are monitored using the **ADCOSTAT** and **ADCUSTAT** registers.

12.2.2 Module Control

Outside of the Sample Sequencers, the remainder of the control logic is responsible for tasks such as interrupt generation, sequence prioritization, and trigger configuration.

Most of the ADC control logic runs at the ADC clock rate of 14-18 MHz. The internal ADC divider is configured automatically by hardware when the system XTAL is selected. The automatic clock divider configuration targets 16.667 MHz operation for all Stellaris[®] devices.

12.2.2.1 Interrupts

The Sample Sequencers dictate the events that cause interrupts, but they don't have control over whether the interrupt is actually sent to the interrupt controller. The ADC module's interrupt signal is controlled by the state of the MASK bits in the ADC Interrupt Mask (ADCIM) register. Interrupt status can be viewed at two locations: the ADC Raw Interrupt Status (ADCRIS) register, which shows the raw status of a Sample Sequencer's interrupt signal, and the ADC Interrupt Status and Clear (ADCISC) register, which shows the logical AND of the ADCRIS register's INR bit and the ADCIM register's MASK bits. Interrupts are cleared by writing a 1 to the corresponding IN bit in ADCISC.

12.2.2.2 Prioritization

When sampling events (triggers) happen concurrently, they are prioritized for processing by the values in the **ADC Sample Sequencer Priority (ADCSSPRI)** register. Valid priority values are in the range of 0-3, with 0 being the highest priority and 3 being the lowest. Multiple active Sample Sequencer units with the same priority do not provide consistent results, so software must ensure that all active Sample Sequencer units have a unique priority value.

12.2.2.3 Sampling Events

Sample triggering for each Sample Sequencer is defined in the **ADC Event Multiplexer Select** (**ADCEMUX**) register. The external peripheral triggering sources vary by Stellaris[®] family member,

but all devices share the "Controller" and "Always" triggers. Software can initiate sampling by setting the CH bits in the **ADC Processor Sample Sequence Initiate (ADCPSSI)** register.

When using the "Always" trigger, care must be taken. If a sequence's priority is too high, it is possible to starve other lower priority sequences.

12.2.3 Hardware Sample Averaging Circuit

Higher precision results can be generated using the hardware averaging circuit, however, the improved results are at the cost of throughput. Up to 64 samples can be accumulated and averaged to form a single data entry in the sequencer FIFO. Throughput is decreased proportionally to the number of samples in the averaging calculation. For example, if the averaging circuit is configured to average 16 samples, the throughput is decreased by a factor of 16.

By default the averaging circuit is off and all data from the converter passes through to the sequencer FIFO. The averaging hardware is controlled by the **ADC Sample Averaging Control (ADCSAC)** register (see page 268). There is a single averaging circuit and all input channels receive the same amount of averaging whether they are single-ended or differential.

12.2.4 Analog-to-Digital Converter

The converter itself generates a 10-bit output value for selected analog input. Special analog pads are used to minimize the distortion on the input.

12.2.5 Test Modes

There is a user-available test mode that allows for loopback operation within the digital portion of the ADC module. This can be useful for debugging software without having to provide actual analog stimulus. This mode is available through the **ADC Test Mode Loopback (ADCTMLB)** register (see page 283).

12.2.6 Internal Temperature Sensor

The internal temperature sensor provides an analog temperature reading as well as a reference voltage. The voltage at the output terminal SENSO is given by the following equation:

```
SENSO = 2.7 - ((T + 55) / 75)
```

This relation is shown in Figure 12-2 on page 256.

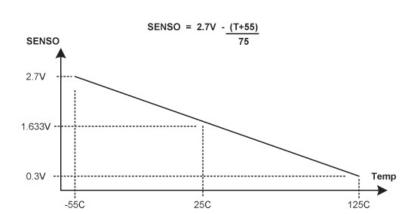


Figure 12-2. Internal Temperature Sensor Characteristic

12.3 Initialization and Configuration

In order for the ADC module to be used, the PLL must be enabled and using a supported crystal frequency (see the **RCC** register). Using unsupported frequencies can cause faulty operation in the ADC module.

12.3.1 Module Initialization

Initialization of the ADC module is a simple process with very few steps. The main steps include enabling the clock to the ADC and reconfiguring the Sample Sequencer priorities (if needed).

The initialization sequence for the ADC is as follows:

- 1. Enable the ADC clock by writing a value of 0x0001.0000 to the RCGC1 register (see page 98).
- If required by the application, reconfigure the Sample Sequencer priorities in the ADCSSPRI
 register. The default configuration has Sample Sequencer 0 with the highest priority, and Sample
 Sequencer 3 as the lowest priority.

12.3.2 Sample Sequencer Configuration

Configuration of the Sample Sequencers is slightly more complex than the module initialization since each sample sequence is completely programmable.

The configuration for each Sample Sequencer should be as follows:

- Ensure that the Sample Sequencer is disabled by writing a 0 to the corresponding ASEN bit in the ADCACTSS register. Programming of the Sample Sequencers is allowed without having them enabled. Disabling the Sequencer during programming prevents erroneous execution if a trigger event were to occur during the configuration process.
- 2. Configure the trigger event for the Sample Sequencer in the ADCEMUX register.
- For each sample in the sample sequence, configure the corresponding input source in the ADCSSMUXn register.

- 4. For each sample in the sample sequence, configure the sample control bits in the corresponding nibble in the ADCSSCTLn register. When programming the last nibble, ensure that the END bit is set. Failure to set the END bit causes unpredictable behavior.
- 5. If interrupts are to be used, write a 1 to the corresponding MASK bit in the ADCIM register.
- 6. Enable the Sample Sequencer logic by writing a 1 to the corresponding ASEN bit in the ADCACTSS register.

12.4 Register Map

"Register Map" on page 257 lists the ADC registers. The offset listed is a hexadecimal increment to the register's address, relative to the ADC base address of 0x4003.8000.

Table 12-2. ADC Register Map

Offset	Name	Туре	Reset	Description	See page
0x000	ADCACTSS	R/W	0x0000.0000	ADC Active Sample Sequencer	259
0x004	ADCRIS	RO	0x0000.0000	ADC Raw Interrupt Status	260
0x008	ADCIM	R/W	0x0000.0000	ADC Interrupt Mask	261
0x00C	ADCISC	R/W1C	0x0000.0000	ADC Interrupt Status and Clear	262
0x010	ADCOSTAT	R/W1C	0x0000.0000	ADC Overflow Status	263
0x014	ADCEMUX	R/W	0x0000.0000	ADC Event Multiplexer Select	264
0x018	ADCUSTAT	R/W1C	0x0000.0000	ADC Underflow Status	265
0x020	ADCSSPRI	R/W	0x0000.3210	ADC Sample Sequencer Priority	266
0x028	ADCPSSI	WO	-	ADC Processor Sample Sequence Initiate	267
0x030	ADCSAC	R/W	0x0000.0000	ADC Sample Averaging Control	268
0x040	ADCSSMUX0	R/W	0x0000.0000	ADC Sample Sequence Input Multiplexer Select 0	269
0x044	ADCSSCTL0	R/W	0x0000.0000	ADC Sample Sequence Control 0	271
0x048	ADCSSFIFO0	RO	0x0000.0000	ADC Sample Sequence Result FIFO 0	273
0x04C	ADCSSFSTAT0	RO	0x0000.0100	ADC Sample Sequence FIFO 0 Status	274
0x060	ADCSSMUX1	R/W	0x0000.0000	ADC Sample Sequence Input Multiplexer Select 1	275
0x064	ADCSSCTL1	R/W	0x0000.0000	ADC Sample Sequence Control 1	276
0x068	ADCSSFIFO1	RO	0x0000.0000	ADC Sample Sequence Result FIFO 1	273
0x06C	ADCSSFSTAT1	RO	0x0000.0100	ADC Sample Sequence FIFO 1 Status	274
0x080	ADCSSMUX2	R/W	0x0000.0000	ADC Sample Sequence Input Multiplexer Select 2	277
0x084	ADCSSCTL2	R/W	0x0000.0000	ADC Sample Sequence Control 2	278
0x0A0	ADCSSMUX3	R/W	0x0000.0000	ADC Sample Sequence Input Multiplexer Select 3	279
0x0A4	ADCSSCTL3	R/W	0x0000.0002	ADC Sample Sequence Control 3	280
0x0A8	ADCSSFIFO3	RO	0x0000.0000	ADC Sample Sequence Result FIFO 3	281

Offset	Name	Туре	Reset	Description	See page
0x0AC	ADCSSFSTAT3	RO	0x0000.0100	ADC Sample Sequence FIFO 3 Status	282
0x100	ADCTMLB	RO	0x0000.0000	ADC Test Mode Loopback	283
0x100	ADCTMLB	RO	0x0000.0000	ADC Test Mode Loopback	283

12.5 Register Descriptions

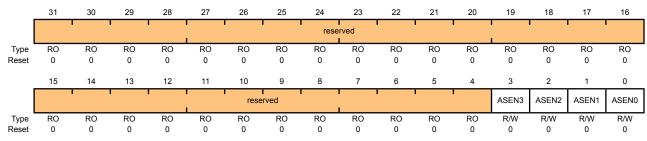
The remainder of this section lists and describes the ADC registers, in numerical order by address offset.

Register 1: ADC Active Sample Sequencer (ADCACTSS), offset 0x000

This register controls the activation of the Sample Sequencers. Each Sample Sequencer can be enabled/disabled independently.

ADC Active Sample Sequencer (ADCACTSS)

Base 0x4003.8000 Offset 0x000 Type R/W, reset 0x0000.0000



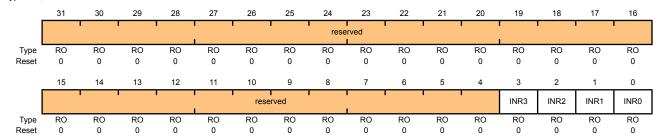
Bit/Field	Name	Туре	Reset	Description
31:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	ASEN3	R/W	0	Specifies whether Sample Sequencer 3 is enabled. If set, the sample sequence logic for Sequencer 3 is active. Otherwise, the Sequencer is inactive.
2	ASEN2	R/W	0	Specifies whether Sample Sequencer 2 is enabled. If set, the sample sequence logic for Sequencer 2 is active. Otherwise, the Sequencer is inactive.
1	ASEN1	R/W	0	Specifies whether Sample Sequencer 1 is enabled. If set, the sample sequence logic for Sequencer 1 is active. Otherwise, the Sequencer is inactive.
0	ASEN0	R/W	0	Specifies whether Sample Sequencer 0 is enabled. If set, the sample sequence logic for Sequencer 0 is active. Otherwise, the Sequencer is inactive.

Register 2: ADC Raw Interrupt Status (ADCRIS), offset 0x004

This register shows the status of the raw interrupt signal of each Sample Sequencer. These bits may be polled by software to look for interrupt conditions without having to generate controller interrupts.

ADC Raw Interrupt Status (ADCRIS)

Base 0x4003.8000 Offset 0x004 Type RO, reset 0x0000.0000



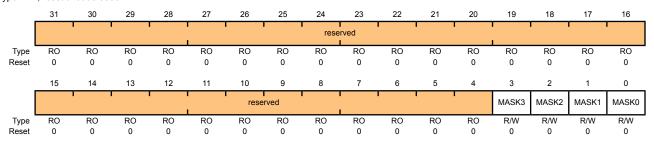
Bit/Field	Name	Туре	Reset	Description
31:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	INR3	RO	0	Set by hardware when a sample with its respective ADCSSCTL3 IE bit has completed conversion. This bit is cleared by writing a 1 to the ADCISC IN3 bit.
2	INR2	RO	0	Set by hardware when a sample with its respective ADCSSCTL2 IE bit has completed conversion. This bit is cleared by writing a 1 to the ADCISC IN2 bit.
1	INR1	RO	0	Set by hardware when a sample with its respective ADCSSCTL1 IE bit has completed conversion. This bit is cleared by writing a 1 to the ADCISC IN1 bit.
0	INR0	RO	0	Set by hardware when a sample with its respective ADCSSCTL0 IE bit has completed conversion. This bit is cleared by writing a 1 to the ADCISC IN0 bit.

Register 3: ADC Interrupt Mask (ADCIM), offset 0x008

This register controls whether the Sample Sequencer raw interrupt signals are promoted to controller interrupts. The raw interrupt signal for each Sample Sequencer can be masked independently.

ADC Interrupt Mask (ADCIM)

Base 0x4003.8000 Offset 0x008 Type R/W, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	MASK3	R/W	0	Specifies whether the raw interrupt signal from Sample Sequencer 3 (ADCRIS register INR3 bit) is promoted to a controller interrupt. If set, the raw interrupt signal is promoted to a controller interrupt. Otherwise, it is not.
2	MASK2	R/W	0	Specifies whether the raw interrupt signal from Sample Sequencer 2 (ADCRIS register INR2 bit) is promoted to a controller interrupt. If set, the raw interrupt signal is promoted to a controller interrupt. Otherwise, it is not.
1	MASK1	R/W	0	Specifies whether the raw interrupt signal from Sample Sequencer 1 (ADCRIS register INR1 bit) is promoted to a controller interrupt. If set, the raw interrupt signal is promoted to a controller interrupt. Otherwise, it is not.
0	MASK0	R/W	0	Specifies whether the raw interrupt signal from Sample Sequencer 0 (ADCRIS register INR0 bit) is promoted to a controller interrupt. If set, the raw interrupt signal is promoted to a controller interrupt. Otherwise, it is not.

Register 4: ADC Interrupt Status and Clear (ADCISC), offset 0x00C

This register provides the mechanism for clearing interrupt conditions, and shows the status of controller interrupts generated by the Sample Sequencers. When read, each bit field is the logical AND of the respective INR and MASK bits. Interrupts are cleared by writing a 1 to the corresponding bit position. If software is polling the ADCRIS instead of generating interrupts, the INR bits are still cleared via the **ADCISC** register, even if the IN bit is not set.

ADC Interrupt Status and Clear (ADCISC)

Base 0x4003.8000 Offset 0x00C

2

1

0

IN0

R/W1C

0

Type R/W	/1C, rese	et 0x0000	.0000													
	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
		1	1		, , ,		1	rese	rved I		1	1				
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		I				rese	erved	!	! !		l	ı	IN3	IN2	IN1	IN0
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	R/W1C	R/W1C	R/W1C	R/W1C
Reset Bit/F	0 ield	0	0 Name	0	0 Type	0	o Reset	0 Descr	0 ription	0	0	0	0	0	0	0
2.0.					.,,,,			2000.								
31:	:4		reserved		RO		0	comp	are shou atibility w rved acr	ith futur	e produ	cts, the	value of	a reserv		
3			IN3		R/W1C		0		it is set l ling a lev	,						-

a 1, and also clears the INR3 bit.

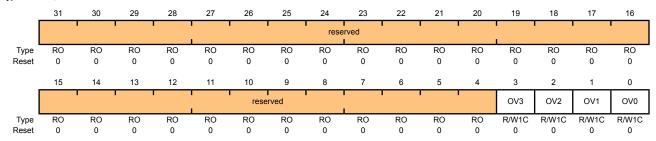
Register 5: ADC Overflow Status (ADCOSTAT), offset 0x010

This register indicates overflow conditions in the Sample Sequencer FIFOs. Once the overflow condition has been handled by software, the condition can be cleared by writing a 1 to the corresponding bit position.

ADC Overflow Status (ADCOSTAT)

Base 0x4003.8000

Offset 0x010
Type R/W1C, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	OV3	R/W1C	0	This bit specifies that the FIFO for Sample Sequencer 3 has hit an overflow condition where the FIFO is full and a write was requested. When an overflow is detected, the most recent write is dropped and this bit is set by hardware to indicate the occurrence of dropped data. This bit is cleared by writing a 1.
2	OV2	R/W1C	0	This bit specifies that the FIFO for Sample Sequencer 2 has hit an overflow condition where the FIFO is full and a write was requested. When an overflow is detected, the most recent write is dropped and this bit is set by hardware to indicate the occurrence of dropped data. This bit is cleared by writing a 1.
1	OV1	R/W1C	0	This bit specifies that the FIFO for Sample Sequencer 1 has hit an overflow condition where the FIFO is full and a write was requested. When an overflow is detected, the most recent write is dropped and this bit is set by hardware to indicate the occurrence of dropped data. This bit is cleared by writing a 1.
0	OV0	R/W1C	0	This bit specifies that the FIFO for Sample Sequencer 0 has hit an overflow condition where the FIFO is full and a write was requested.

bit is cleared by writing a 1.

When an overflow is detected, the most recent write is dropped and this bit is set by hardware to indicate the occurrence of dropped data. This

Register 6: ADC Event Multiplexer Select (ADCEMUX), offset 0x014

The ADCEMUX selects the event (trigger) that initiates sampling for each Sample Sequencer. Each Sample Sequencer can be configured with a unique trigger source.

ADC Event Multiplexer Select (ADCEMUX)

11:8

7:4

3:0

EM2

EM1

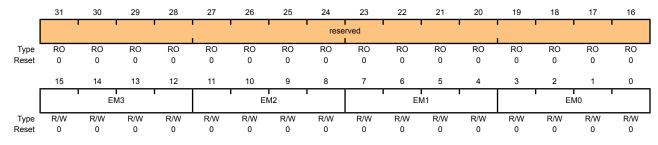
EM0

R/W

R/W

R/W

Base 0x4003.8000 Offset 0x014 Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:16	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15:12	EM3	R/W	0	This field selects the trigger source for Sample Sequencer 3.

The valid configurations for this field are:

EM	Binary	Value	Event

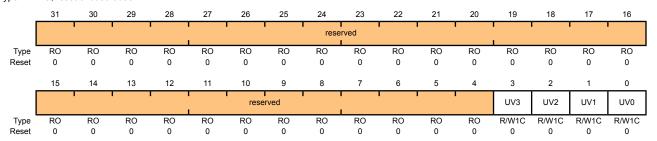
	0000	Controller (default)					
	0001	Analog Comparator 0					
	0010	Reserved					
	0011	Reserved					
	0100	External (GPIO PB4)					
	0101	Timer					
	0110	PWM0					
	0111	PWM1					
	1000	PWM2					
	1001-1110	reserved					
	1111	Always (continuously sample)					
0		This field selects the trigger source for Sample Sequencer 2. The encodings are the same as those for EM3.					
0	This field selects the trigger source for Sample Sequencer 1. The encodings are the same as those for EM3.						
0	This field selects the trigger source for Sample Sequencer 0. The encodings are the same as those for EM3.						

Register 7: ADC Underflow Status (ADCUSTAT), offset 0x018

This register indicates underflow conditions in the Sample Sequencer FIFOs. The corresponding underflow condition can be cleared by writing a 1 to the relevant bit position.

ADC Underflow Status (ADCUSTAT)

Base 0x4003.8000 Offset 0x018 Type R/W1C, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	UV3	R/W1C	0	This bit specifies that the FIFO for Sample Sequencer 3 has hit an underflow condition where the FIFO is empty and a read was requested. The problematic read does not move the FIFO pointers, and 0s are returned. This bit is cleared by writing a 1.
2	UV2	R/W1C	0	This bit specifies that the FIFO for Sample Sequencer 2 has hit an underflow condition where the FIFO is empty and a read was requested. The problematic read does not move the FIFO pointers, and 0s are returned. This bit is cleared by writing a 1.
1	UV1	R/W1C	0	This bit specifies that the FIFO for Sample Sequencer 1 has hit an underflow condition where the FIFO is empty and a read was requested. The problematic read does not move the FIFO pointers, and 0s are returned. This bit is cleared by writing a 1.
0	UVO	R/W1C	0	This bit specifies that the FIFO for Sample Sequencer 0 has hit an underflow condition where the FIFO is empty and a read was requested. The problematic read does not move the FIFO pointers, and 0s are returned. This bit is cleared by writing a 1.

Register 8: ADC Sample Sequencer Priority (ADCSSPRI), offset 0x020

This register sets the priority for each of the Sample Sequencers. Out of reset, Sequencer 0 has the highest priority, and sample sequence 3 has the lowest priority. When reconfiguring sequence priorities, each sequence must have a unique priority or the ADC behavior is inconsistent.

ADC Sample Sequencer Priority (ADCSSPRI)

SS0

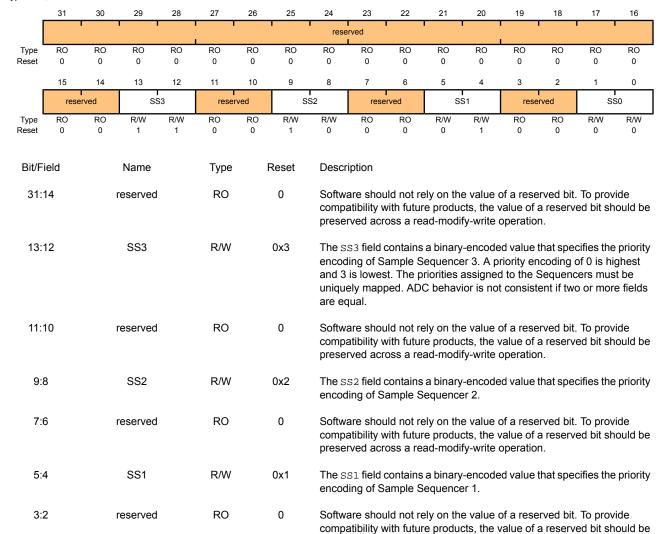
1:0

R/W

0x0

Base 0x4003.8000 Offset 0x020

Type R/W, reset 0x0000.3210



preserved across a read-modify-write operation.

encoding of Sample Sequencer 0.

The SSO field contains a binary-encoded value that specifies the priority

Register 9: ADC Processor Sample Sequence Initiate (ADCPSSI), offset 0x028

This register provides a mechanism for application software to initiate sampling in the Sample Sequencers. Sample sequences can be initiated individually or in any combination. When multiple sequences are triggered simultaneously, the priority encodings in **ADCSSPRI** dictate execution order.

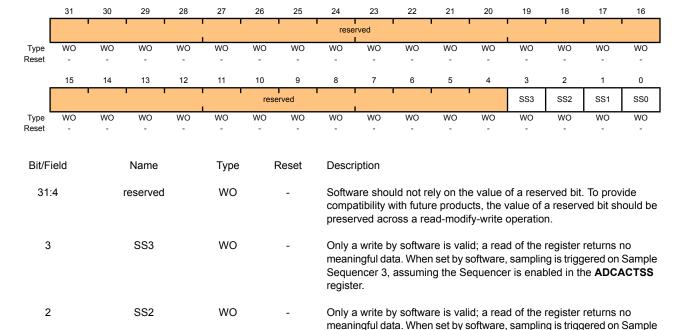
ADC Processor Sample Sequence Initiate (ADCPSSI)

SS₁

WO

Base 0x4003.8000 Offset 0x028 Type WO, reset -

1



register.

Only a write by software is valid; a read of the register returns no meaningful data. When set by software, sampling is triggered on Sample Sequencer 1, assuming the Sequencer is enabled in the ADCACTSS register.

Sequencer 2, assuming the Sequencer is enabled in the **ADCACTSS**

Only a write by software is valid; a read of the register returns no meaningful data. When set by software, sampling is triggered on Sample Sequencer 0, assuming the Sequencer is enabled in the **ADCACTSS** register.

Register 10: ADC Sample Averaging Control (ADCSAC), offset 0x030

This register controls the amount of hardware averaging applied to conversion results. The final conversion result stored in the FIFO is averaged from 2^{AVG} consecutive ADC samples at the specified ADC speed. If AVG is 0, the sample is passed directly through without any averaging. If AVG=6, then 64 consecutive ADC samples are averaged to generate one result in the sequencer FIFO. An AVG = 7 provides unpredictable results.

ADC Sample Averaging Control (ADCSAC)

Base 0x4003.8000 Offset 0x030 Type R/W, reset 0x0000.0000

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
			'		' '		•	rese	rved •					'	'	
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
			, ,		, , , , , , , , , , , , , , , , , , ,		reserved	i					1		AVG	
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0
Bit/F	ield		Name		Туре	F	Reset	Descr	ription							
31:	:3		reserved		RO		0	comp	are shou atibility w	ith futur	e produ	cts, the v	alue of	a reserv	•	
2:	0		AVG		R/W		0	Speci samp	fies the a les. The of 7 crea	amount o	of hardwa d can be	are aver	aging th ue betw	at will be		

Register 11: ADC Sample Sequence Input Multiplexer Select 0 (ADCSSMUX0), offset 0x040

This register defines the analog input configuration for each sample in a sequence executed with Sample Sequencer 0.

This register is 32-bits wide and contains information for eight possible samples.

ADC Sample Sequence Input Multiplexer Select 0 (ADCSSMUX0)

Base 0x4003.8000 Offset 0x040 Type R/W, reset 0x0000.0000

Type R/W	, reset ux	KUUUU.UU	00													
_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
	rese	rved	MU	IX7	rese	rved	MU	JX6	rese	rved	MU	JX5	rese	rved	MU	X4
Type Reset	RO 0	RO 0	R/W 0	R/W 0	RO 0	RO 0	R/W 0	R/W 0	RO 0	RO 0	R/W 0	R/W 0	RO 0	RO 0	R/W 0	R/W 0
_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	rese	rved	MU	IX3	rese	rved	MU	JX2	rese	rved	MU	JX1	rese	rved	MU	X0
Type Reset	RO 0	RO 0	R/W 0	R/W 0	RO 0	RO 0	R/W 0	R/W 0	RO 0	RO 0	R/W 0	R/W 0	RO 0	RO 0	R/W 0	R/W 0
Bit/Fi	eld		Name		Туре		Reset	Descr	iption							
31:3	30	ı	reserved		RO		0	comp	atibility v	vith futur	e produ	e value of cts, the v fy-write of	alue of	a reserv		
29:2	28		MUX7		R/W		0	with the sample	ne Samp ed for the orrespon	le Sequ e analog	encer. It -to-digita	ne eighth specifie al convers mple, a v	s which sion. The	of the a	nalog inp et here ir	outs is ndicates
27:2	26	1	reserved		RO		0	comp	atibility v	vith futur	e produ	e value o cts, the v fy-write o	alue of	a reserv		
25:2	24		MUX6		R/W		0	execu	ted with	the Sam	nple Seq	the seve uencer a og-to-dig	and spec	ifies whi		
23:2	22	ı	reserved		RO		0	comp	atibility v	vith futur	e produ	e value o cts, the v fy-write o	alue of	a reserv		
21:2	20		MUX5		R/W		0	with th	ne Samp	le Sequ	encer ar	the sixth nd specif tal conve	fies whic			
19:1	8	1	reserved		RO		0	comp	atibility v	vith futur	e produ	e value o cts, the v fy-write o	alue of	a reserv		
17:1	6	MUX4 R/W 0			0	The $\mathtt{MUX4}$ field is used during the fifth sample of a sequence executed with the Sample Sequencer and specifies which of the analog inputs is sampled for the analog-to-digital conversion.										

Bit/Field	Name	Туре	Reset	Description
15:14	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
13:12	MUX3	R/W	0	The ${\tt MUX3}$ field is used during the fourth sample of a sequence executed with the Sample Sequencer and specifies which of the analog inputs is sampled for the analog-to-digital conversion.
11:10	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
9:8	MUX2	R/W	0	The ${\tt MUX2}$ field is used during the third sample of a sequence executed with the Sample Sequencer and specifies which of the analog inputs is sampled for the analog-to-digital conversion.
7:6	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
5:4	MUX1	R/W	0	The MUX1 field is used during the second sample of a sequence executed with the Sample Sequencer and specifies which of the analog inputs is sampled for the analog-to-digital conversion.
3:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1:0	MUX0	R/W	0	The ${\tt MUX0}$ field is used during the first sample of a sequence executed with the Sample Sequencer and specifies which of the analog inputs is sampled for the analog-to-digital conversion.

Register 12: ADC Sample Sequence Control 0 (ADCSSCTL0), offset 0x044

This register contains the configuration information for each sample for a sequence executed with Sample Sequencer 0. When configuring a sample sequence, the END bit must be set at some point, whether it be after the first sample, last sample, or any sample in between.

23

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18

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16

This register is 32-bits wide and contains information for eight possible samples.

ADC Sample Sequence Control 0 (ADCSSCTL0)

28

27

26

25

Base 0x4003.8000 Offset 0x044

Type R/W, reset 0x0000.0000 31

30

	31	30	29	20	21		20	24	23		21		19	10	17	10
	TS7	IE7	END7	D7	TS6	IE6	END6	D6	TS5	IE5	END5	D5	TS4	IE4	END4	D4
Type Reset	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0							
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	TS3	IE3	END3	D3	TS2	IE2	END2	D2	TS1	IE1	END1	D1	TS0	IE0	END0	D0
Type Reset	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0							
Bit/F	ield		Name		Туре	F	Reset	Descr	iption							
3.	1		TS7		R/W		0	and sp senso	pecifies	the inpu	t source	of the sa	ample. It	f set, the	mple sec tempera e ADCS	ature
30)		IE7		R/W		0	and specified the error than error the error the error than error tha	pecifies on the per is set, this bit is	whether sample' the inte s set, th	the raw 's conve rrupt is p e raw in	interrup rsion. If to promoted terrupt is	t signal (the MASI d to a co asserte	(INRO bit in ontroller- ed, other	mple sec it) is asse the ADC level inte wise it is erate inte	erted at IM errupt. not. It
29	9		END7		R/W		0	possible after the even the EN which	ole to enche samp he samp hough the D bit so	d the secole containe fields mewher a singl	quence of ining a semay be in the within the within the within the contract of	on any sa et END a non-zero the sequ	ample po are not r . It is rec ience. (S	osition. Sequeste puired the Sample Sample	e sequen Samples d for con at softwa Sequenc dwired to	defined version are write eer 3,
								Settin	g this bit	indicate	es that th	nis samp	le is the	last in t	he seque	ence.
28	3		D7		R/W		0	The co "i", wh does i	orrespor nere the	nding AD paired ir a differe	CSSMU nputs are ential op	IXx nibble "2i and	e must b 2i+1". T	e set to he temp	entially sa the pair operature og inputs	number sensor
2	7		TS6		R/W		0	Same	definitio	n as TS	7 but us	ed durin	g the se	venth sa	ample.	
26	6		IE6		R/W		0	Same	definitio	n as IE	7 but us	ed durin	g the se	venth sa	ample.	
2	5		END6		R/W		0	Same	definitio	n as EN	D7 but u	sed duri	ng the s	eventh s	sample.	
24	1		D6		R/W	0 5		Same	definitio	n as D7	but use	d during	the sev	enth sar	nple.	
23	3		TS5		R/W	v 0 5			definitio	n as TS	7 but us	ed durin	g the six	th samp	ole.	

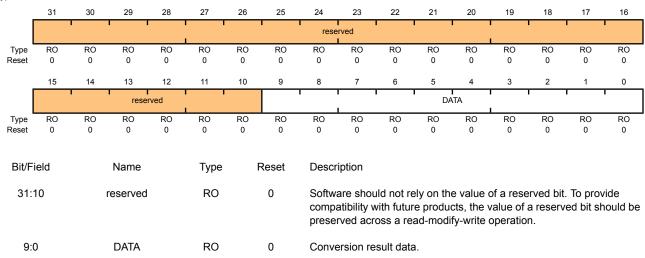
Bit/Field	Name	Туре	Reset	Description
22	IE5	R/W	0	Same definition as IE7 but used during the sixth sample.
21	END5	R/W	0	Same definition as ${\tt END7}$ but used during the sixth sample.
20	D5	R/W	0	Same definition as ${\tt D7}$ but used during the sixth sample.
19	TS4	R/W	0	Same definition as ${\tt TS7}$ but used during the fifth sample.
18	IE4	R/W	0	Same definition as IE7 but used during the fifth sample.
17	END4	R/W	0	Same definition as END7 but used during the fifth sample.
16	D4	R/W	0	Same definition as $\mathtt{D7}$ but used during the fifth sample.
15	TS3	R/W	0	Same definition as ${\tt TS7}$ but used during the fourth sample.
14	IE3	R/W	0	Same definition as IE7 but used during the fourth sample.
13	END3	R/W	0	Same definition as END7 but used during the fourth sample.
12	D3	R/W	0	Same definition as $\mathtt{D7}$ but used during the fourth sample.
11	TS2	R/W	0	Same definition as ${\tt TS7}$ but used during the third sample.
10	IE2	R/W	0	Same definition as IE7 but used during the third sample.
9	END2	R/W	0	Same definition as ${\tt END7}$ but used during the third sample.
8	D2	R/W	0	Same definition as ${\tt D7}$ but used during the third sample.
7	TS1	R/W	0	Same definition as ${\tt TS7}$ but used during the second sample.
6	IE1	R/W	0	Same definition as IE7 but used during the second sample.
5	END1	R/W	0	Same definition as ${\tt END7}$ but used during the second sample.
4	D1	R/W	0	Same definition as $\mathtt{D7}$ but used during the second sample.
3	TS0	R/W	0	Same definition as ${\tt TS7}$ but used during the first sample.
2	IE0	R/W	0	Same definition as IE7 but used during the first sample.
1	END0	R/W	0	Same definition as END7 but used during the first sample.
				Since this sequencer has only one entry, this bit must be set.
0	D0	R/W	0	Same definition as ${\tt D7}$ but used during the first sample.

Register 13: ADC Sample Sequence Result FIFO 0 (ADCSSFIFO0), offset 0x048 Register 14: ADC Sample Sequence Result FIFO 1 (ADCSSFIFO1), offset 0x068 Register 15: ADC Sample Sequence Result FIFO 2 (ADCSSFIFO2), offset 0x088

This register contains the conversion results for samples collected with the Sample Sequencer (the ADCSSFIF0 register is used for Sample Sequencer 0, ADCSSFIF01 for Sequencer 1, and ADCSSFIF02 for Sequencer 2). Reads of this register return conversion result data in the order sample 0, sample 1, and so on, until the FIFO is empty. If the FIFO is not properly handled by software, overflow and underflow conditions are registered in the ADCOSTAT and ADCUSTAT registers.

ADC Sample Sequence Result FIFO 0 (ADCSSFIFO0)

Base 0x4003.8000 Offset 0x048 Type RO, reset 0x0000.0000



Register 16: ADC Sample Sequence FIFO 0 Status (ADCSSFSTAT0), offset 0x04C

Register 17: ADC Sample Sequence FIFO 1 Status (ADCSSFSTAT1), offset 0x06C

Register 18: ADC Sample Sequence FIFO 2 Status (ADCSSFSTAT2), offset 0x08C

This register provides a window into the Sample Sequencer, providing full/empty status information as well as the positions of the head and tail pointers. The reset value of 0x100 indicates an empty FIFO. The ADCSSFSTAT0 register provides status on FIF0, ADCSSFSTAT1 on FIFO1, and ADCSSFSTAT2 on FIFO2.

ADC Sample Sequence FIFO 0 Status (ADCSSFSTAT0)

Base 0x4003.8000

Offset 0x04C Type RO, reset 0x0000.0100

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
		' '				' '		rese	rved							
Type	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		reserved		FULL		reserved		EMPTY		HP	TR			TP	TR	
Type	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0

Bit/Field	Name	Туре	Reset	Description
31:13	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
12	FULL	RO	0	When set, indicates that the FIFO is currently full.
11:9	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
8	EMPTY	RO	1	When set, indicates that the FIFO is currently empty.
7:4	HPTR	RO	0	This field contains the current "head" pointer index for the FIFO, that is, the next entry to be written.
3:0	TPTR	RO	0	This field contains the current "tail" pointer index for the FIFO, that is, the next entry to be read.

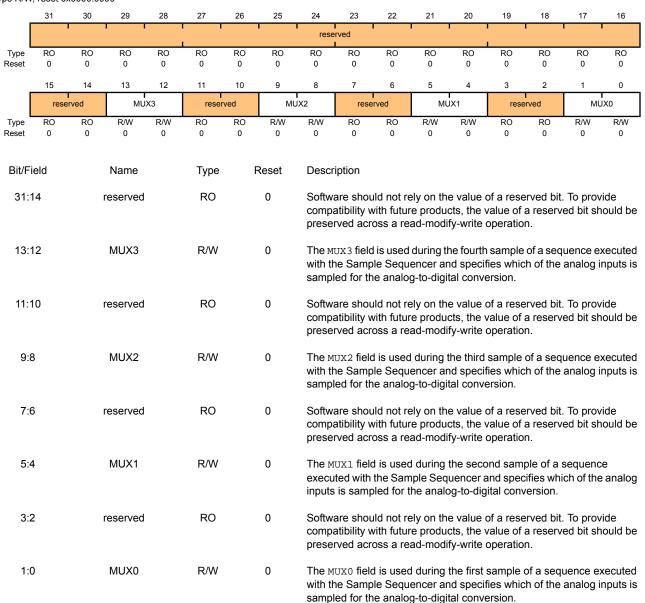
Register 19: ADC Sample Sequence Input Multiplexer Select 1 (ADCSSMUX1), offset 0x060

This register defines the analog input configuration for each sample in a sequence executed with Sample Sequencer 1. This register is 16-bits wide and contains information for four possible samples.

ADC Sample Sequence Input Multiplexer Select 1 (ADCSSMUX1)

Base 0x4003.8000 Offset 0x060

Type R/W, reset 0x0000.0000



Register 20: ADC Sample Sequence Control 1 (ADCSSCTL1), offset 0x064

This register contains the configuration information for each sample for a sequence executed with Sample Sequencer 1. When configuring a sample sequence, the END bit must be set at some point, whether it be after the first sample, last sample, or any sample in between. This register is 16-bits wide and contains information for four possible samples.

ADC Sample Sequence Control 1 (ADCSSCTL1)

Base 0x4003.8000

Offset 0x064 Type R/W, reset 0x0000.0000

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
					l I		'	rese	rved •		'		1	'	1	
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0								
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	TS3	IE3	END3	D3	TS2	IE2	END2	D2	TS1	IE1	END1	D1	TS0	IE0	END0	D0
Type Reset	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0								

Bit/Field	Name	Туре	Reset	Description
31:16	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15	TS3	R/W	0	Same definition as ${\tt TS7}$ but used during the fourth sample.
14	IE3	R/W	0	Same definition as IE7 but used during the fourth sample.
13	END3	R/W	0	Same definition as END7 but used during the fourth sample.
12	D3	R/W	0	Same definition as ${\tt D7}$ but used during the fourth sample.
11	TS2	R/W	0	Same definition as ${\tt TS7}$ but used during the third sample.
10	IE2	R/W	0	Same definition as IE7 but used during the third sample.
9	END2	R/W	0	Same definition as END7 but used during the third sample.
8	D2	R/W	0	Same definition as D7 but used during the third sample.
7	TS1	R/W	0	Same definition as ${\tt TS7}$ but used during the second sample.
6	IE1	R/W	0	Same definition as IE7 but used during the second sample.
5	END1	R/W	0	Same definition as END7 but used during the second sample.
4	D1	R/W	0	Same definition as D7 but used during the second sample.
3	TS0	R/W	0	Same definition as ${\tt TS7}$ but used during the first sample.
2	IE0	R/W	0	Same definition as IE7 but used during the first sample.
1	END0	R/W	0	Same definition as END7 but used during the first sample.
				Since this sequencer has only one entry, this bit must be set.
0	D0	R/W	0	Same definition as ${\tt D7}$ but used during the first sample.

Register 21: ADC Sample Sequence Input Multiplexer Select 2 (ADCSSMUX2). offset 0x080

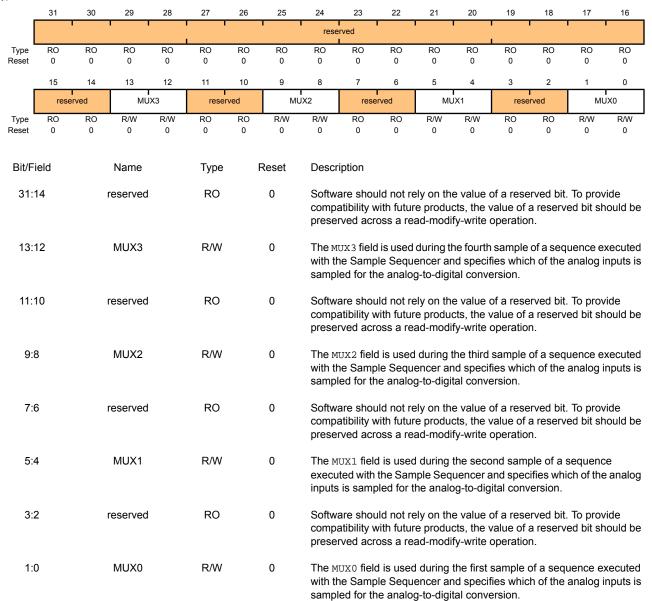
This register defines the analog input configuration for each sample in a sequence executed with Sample Sequencer 2. This register is 16-bits wide and contains information for four possible samples.

ADC Sample Sequence Input Multiplexer Select 2 (ADCSSMUX2)

Base 0x4003.8000

Offset 0x080

Type R/W, reset 0x0000.0000



Register 22: ADC Sample Sequence Control 2 (ADCSSCTL2), offset 0x084

This register contains the configuration information for each sample for a sequence executed with Sample Sequencer 2. When configuring a sample sequence, the END bit must be set at some point, whether it be after the first sample, last sample, or any sample in between. This register is 16-bits wide and contains information for four possible samples.

ADC Sample Sequence Control 2 (ADCSSCTL2)

Base 0x4003.8000

Offset 0x084
Type R/W, reset 0x0000.0000

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
								rese	rved I		1					
Туре	RO	RO	RO	RO	RO	RO	RO	RO								
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	TS3	IE3	END3	D3	TS2	IE2	END2	D2	TS1	IE1	END1	D1	TS0	IE0	END0	D0
Type Reset	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0								

Bit/Field	Name	Туре	Reset	Description
31:16	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15	TS3	R/W	0	Same definition as TS7 but used during the fourth sample.
14	IE3	R/W	0	Same definition as IE7 but used during the fourth sample.
13	END3	R/W	0	Same definition as END7 but used during the fourth sample.
12	D3	R/W	0	Same definition as D7 but used during the fourth sample.
11	TS2	R/W	0	Same definition as TS7 but used during the third sample.
10	IE2	R/W	0	Same definition as IE7 but used during the third sample.
9	END2	R/W	0	Same definition as END7 but used during the third sample.
8	D2	R/W	0	Same definition as D7 but used during the third sample.
7	TS1	R/W	0	Same definition as TS7 but used during the second sample.
6	IE1	R/W	0	Same definition as IE7 but used during the second sample.
5	END1	R/W	0	Same definition as END7 but used during the second sample.
4	D1	R/W	0	Same definition as D7 but used during the second sample.
3	TS0	R/W	0	Same definition as TS7 but used during the first sample.
2	IE0	R/W	0	Same definition as IE7 but used during the first sample.
1	END0	R/W	0	Same definition as END7 but used during the first sample.
				Since this sequencer has only one entry, this bit must be set.
0	D0	R/W	0	Same definition as D7 but used during the first sample.

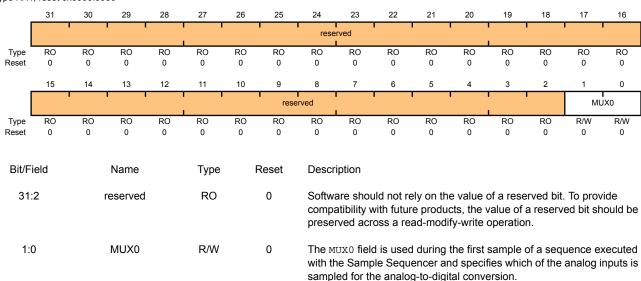
Register 23: ADC Sample Sequence Input Multiplexer Select 3 (ADCSSMUX3), offset 0x0A0

This register defines the analog input configuration for each sample in a sequence executed with Sample Sequencer 3. This register is 4-bits wide and contains information for one possible sample.

ADC Sample Sequence Input Multiplexer Select 3 (ADCSSMUX3)

Base 0x4003.8000

Offset 0x0A0 Type R/W, reset 0x0000.0000



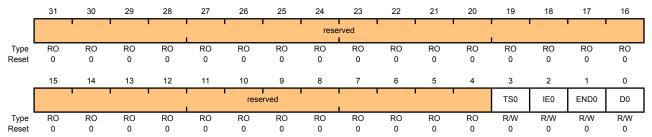
Register 24: ADC Sample Sequence Control 3 (ADCSSCTL3), offset 0x0A4

This register contains the configuration information for each sample for a sequence executed with Sample Sequencer 3. The END bit is always set since there is only one sample in this sequencer. This register is 4-bits wide and contains information for one possible sample.

ADC Sample Sequence Control 3 (ADCSSCTL3)

Base 0x4003.8000

Offset 0x0A4
Type R/W, reset 0x0000.0002



Bit/Field	Name	Type	Reset	Description
31:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	TS0	R/W	0	Same definition as ${\tt TS7}$ but used during the first sample.
2	IE0	R/W	0	Same definition as IE7 but used during the first sample.
1	END0	R/W	0	Same definition as END7 but used during the first sample.
				Since this sequencer has only one entry, this bit must be set.
0	D0	R/W	0	Same definition as D7 but used during the first sample.

Register 25: ADC Sample Sequence Result FIFO 3 (ADCSSFIFO3), offset 0x0A8

This register contains the conversion results for samples collected with Sample Sequencer 3. Reads of this register return the conversion result data. If the FIFO is not properly handled by software, overflow and underflow conditions are registered in the **ADCOSTAT** and **ADCUSTAT** registers.

Bit fields and definitions are the same as **ADCSSFIFO0** (see page 273) but are for FIFO 3.

Register 26: ADC Sample Sequence FIFO 3 Status (ADCSSFSTAT3), offset 0x0AC

This register provides a window into the Sample Sequencer FIFO 3, providing full/empty status information as well as the positions of the head and tail pointers. The reset value of 0x100 indicates an empty FIFO.

This register has the same bit fields and definitions as **ADCSSFSTAT0** (see page 274) but is for FIFO 3.

Register 27: ADC Test Mode Loopback (ADCTMLB), offset 0x100

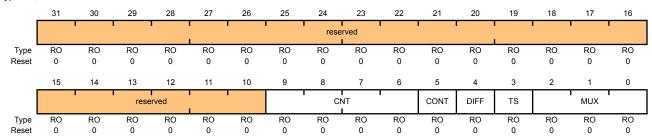
This register provides loopback operation within the digital logic of the ADC, which can be useful in debugging software without having to provide actual analog stimulus. This test mode is entered by writing a value of 0x0000.0001 to this register. When data is read from the FIFO in loopback mode, the read-only portion of this register is returned.

Read-Only Register

ADC Test Mode Loopback (ADCTMLB)

Base 0x4003.8000

Offset 0x100 Type RO, reset 0x0000.0000

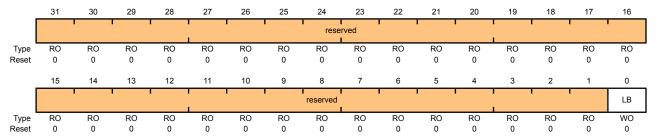


Bit/Field	Name	Type	Reset	Description
31:10	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
9:6	CNT	RO	0	Continuous sample counter that is initialized to 0 and counts each sample as it processed. This helps provide a unique value for the data received.
5	CONT	RO	0	When set, indicates that this is a continuation sample. For example if two sequencers were to run back-to-back, this indicates that the controller kept continuously sampling at full rate.
4	DIFF	RO	0	When set, indicates that this is a differential sample.
3	TS	RO	0	When set, indicates that this is a temperature sensor sample.
2:0	MUX	RO	0	Indicates which analog input is to be sampled.

Write-Only Register

ADC Test Mode Loopback (ADCTMLB)

Base 0x4003.8000 Offset 0x100 Type RO, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	LB	WO	0	When set, forces a loopback within the digital block to provide information on input and unique numbering.
				The 10-bit loopback data is defined as shown in the read for bits 9:0 below.

13 Universal Asynchronous Receivers/Transmitters (UARTs)

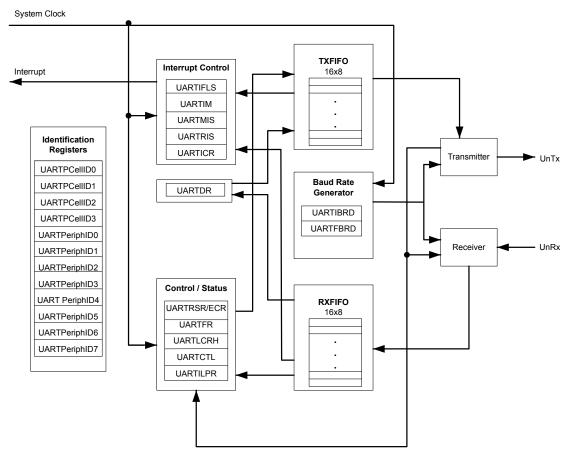
The Stellaris[®] Universal Asynchronous Receiver/Transmitter (UART) provides fully programmable, 16C550-type serial interface characteristics. The LM3S2739 controller is equipped with two UART modules.

Each UART has the following features:

- Separate transmit and receive FIFOs
- Programmable FIFO length, including 1-byte deep operation providing conventional double-buffered interface
- FIFO trigger levels of 1/8, 1/4, 1/2, 3/4, and 7/8
- Programmable baud-rate generator allowing rates up to 460.8 Kbps
- Standard asynchronous communication bits for start, stop and parity
- False start bit detection
- Line-break generation and detection
- Fully programmable serial interface characteristics:
 - 5, 6, 7, or 8 data bits
 - Even, odd, stick, or no-parity bit generation/detection
 - 1 or 2 stop bit generation
- IrDA serial-IR (SIR) encoder/decoder providing:
 - Programmable use of IrDA Serial InfraRed (SIR) or UART input/output
 - Support of IrDA SIR encoder/decoder functions for data rates up to 115.2 Kbps half-duplex
 - Support of normal 3/16 and low-power (1.41-2.23 µs) bit durations
 - Programmable internal clock generator enabling division of reference clock by 1 to 256 for low-power mode bit duration

13.1 Block Diagram

Figure 13-1. UART Module Block Diagram



13.2 Functional Description

Each Stellaris[®] UART performs the functions of parallel-to-serial and serial-to-parallel conversions. It is similar in functionality to a 16C550 UART, but is not register compatible.

The UART is configured for transmit and/or receive via the TXE and RXE bits of the **UART Control** (**UARTCTL**) register (see page 304). Transmit and receive are both enabled out of reset. Before any control registers are programmed, the UART must be disabled by clearing the UARTEN bit in **UARTCTL**. If the UART is disabled during a TX or RX operation, the current transaction is completed prior to the UART stopping.

The UART peripheral also includes a serial IR (SIR) encoder/decoder block that can be connected to an infrared transceiver to implement an IrDA SIR physical layer. The SIR function is programmed using the UARTCTL register.

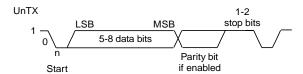
13.2.1 Transmit/Receive Logic

The transmit logic performs parallel-to-serial conversion on the data read from the transmit FIFO. The control logic outputs the serial bit stream beginning with a start bit, and followed by the data

bits (LSB first), parity bit, and the stop bits according to the programmed configuration in the control registers. See Figure 13-2 on page 287 for details.

The receive logic performs serial-to-parallel conversion on the received bit stream after a valid start pulse has been detected. Overrun, parity, frame error checking, and line-break detection are also performed, and their status accompanies the data that is written to the receive FIFO.

Figure 13-2. UART Character Frame



13.2.2 Baud-Rate Generation

The baud-rate divisor is a 22-bit number consisting of a 16-bit integer and a 6-bit fractional part. The number formed by these two values is used by the baud-rate generator to determine the bit period. Having a fractional baud-rate divider allows the UART to generate all the standard baud rates.

The 16-bit integer is loaded through the **UART Integer Baud-Rate Divisor (UARTIBRD)** register (see page 300) and the 6-bit fractional part is loaded with the **UART Fractional Baud-Rate Divisor (UARTFBRD)** register (see page 301). The baud-rate divisor (BRD) has the following relationship to the system clock (where *BRDI* is the integer part of the *BRD* and *BRDF* is the fractional part, separated by a decimal place.):

```
BRD = BRDI + BRDF = SysClk / (16 * Baud Rate)
```

The 6-bit fractional number (that is to be loaded into the DIVFRAC bit field in the **UARTFBRD** register) can be calculated by taking the fractional part of the baud-rate divisor, multiplying it by 64, and adding 0.5 to account for rounding errors:

```
UARTFBRD[DIVFRAC] = integer(BRDF * 64 + 0.5)
```

The UART generates an internal baud-rate reference clock at 16x the baud-rate (referred to as Baud16). This reference clock is divided by 16 to generate the transmit clock, and is used for error detection during receive operations.

Along with the **UART Line Control**, **High Byte (UARTLCRH)** register (see page 302), the **UARTIBRD** and **UARTFBRD** registers form an internal 30-bit register. This internal register is only updated when a write operation to **UARTLCRH** is performed, so any changes to the baud-rate divisor must be followed by a write to the **UARTLCRH** register for the changes to take effect.

To update the baud-rate registers, there are four possible sequences:

- UARTIBRD write, UARTFBRD write, and UARTLCRH write
- UARTFBRD write, UARTIBRD write, and UARTLCRH write
- UARTIBRD write and UARTLCRH write
- UARTFBRD write and UARTLCRH write

13.2.3 Data Transmission

Data received or transmitted is stored in two 16-byte FIFOs, though the receive FIFO has an extra four bits per character for status information. For transmission, data is written into the transmit FIFO. If the UART is enabled, it causes a data frame to start transmitting with the parameters indicated in the **UARTLCRH** register. Data continues to be transmitted until there is no data left in the transmit FIFO. The BUSY bit in the **UART Flag (UARTFR)** register (see page 297) is asserted as soon as data is written to the transmit FIFO (that is, if the FIFO is non-empty) and remains asserted while data is being transmitted. The BUSY bit is negated only when the transmit FIFO is empty, and the last character has been transmitted from the shift register, including the stop bits. The UART can indicate that it is busy even though the UART may no longer be enabled.

When the receiver is idle (the UnRx is continuously 1) and the data input goes Low (a start bit has been received), the receive counter begins running and data is sampled on the eighth cycle of Baud16 (described in "Transmit/Receive Logic" on page 286).

The start bit is valid if UnRx is still low on the eighth cycle of Baud16, otherwise a false start bit is detected and it is ignored. Start bit errors can be viewed in the **UART Receive Status (UARTRSR)** register (see page 295). If the start bit was valid, successive data bits are sampled on every 16th cycle of Baud16 (that is, one bit period later) according to the programmed length of the data characters. The parity bit is then checked if parity mode was enabled. Data length and parity are defined in the **UARTLCRH** register.

Lastly, a valid stop bit is confirmed if UnRx is High, otherwise a framing error has occurred. When a full word is received, the data is stored in the receive FIFO, with any error bits associated with that word.

13.2.4 **Serial IR (SIR)**

The UART peripheral includes an IrDA serial-IR (SIR) encoder/decoder block. The IrDA SIR block provides functionality that converts between an asynchronous UART data stream, and half-duplex serial SIR interface. No analog processing is performed on-chip. The role of the SIR block is to provide a digital encoded output, and decoded input to the UART. The UART signal pins can be connected to an infrared transceiver to implement an IrDA SIR physical layer link. The SIR block has two modes of operation:

- In normal IrDA mode, a zero logic level is transmitted as high pulse of 3/16th duration of the selected baud rate bit period on the output pin, while logic one levels are transmitted as a static LOW signal. These levels control the driver of an infrared transmitter, sending a pulse of light for each zero. On the reception side, the incoming light pulses energize the photo transistor base of the receiver, pulling its output LOW. This drives the UART input pin LOW.
- In low-power IrDA mode, the width of the transmitted infrared pulse is set to three times the period of the internally generated IrLPBaud16 signal (1.63 μs, assuming a nominal 1.8432 MHz frequency) by changing the appropriate bit in the UARTCR register.

Figure 13-3 on page 289 shows the UART transmit and receive signals, with and without IrDA modulation.

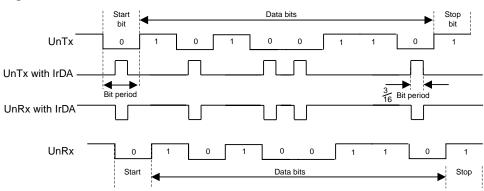


Figure 13-3. IrDA Data Modulation

In both normal and low-power IrDA modes:

- During transmission, the UART data bit is used as the base for encoding
- During reception, the decoded bits are transferred to the UART receive logic

The IrDA SIR physical layer specifies a half-duplex communication link, with a minimum 10 ms delay between transmission and reception. This delay must be generated by software because it is not automatically supported by the UART. The delay is required because the infrared receiver electronics might become biased, or even saturated from the optical power coupled from the adjacent transmitter LED. This delay is known as latency, or receiver setup time.

13.2.5 FIFO Operation

The UART has two 16-entry FIFOs; one for transmit and one for receive. Both FIFOs are accessed via the **UART Data (UARTDR)** register (see page 293). Read operations of the **UARTDR** register return a 12-bit value consisting of 8 data bits and 4 error flags while write operations place 8-bit data in the transmit FIFO.

Out of reset, both FIFOs are disabled and act as 1-byte-deep holding registers. The FIFOs are enabled by setting the FEN bit in **UARTLCRH** (page 302).

FIFO status can be monitored via the **UART Flag (UARTFR)** register (see page 297) and the **UART Receive Status (UARTRSR)** register. Hardware monitors empty, full and overrun conditions. The **UARTFR** register contains empty and full flags (TXFE, TXFF, RXFE and RXFF bits) and the **UARTRSR** register shows overrun status via the OE bit.

The trigger points at which the FIFOs generate interrupts is controlled via the **UART Interrupt FIFO Level Select (UARTIFLS)** register (see page 306). Both FIFOs can be individually configured to trigger interrupts at different levels. Available configurations include 1/8, ½, ½, ¾, and 7/8. For example, if the ¼ option is selected for the receive FIFO, the UART generates a receive interrupt after 4 data bytes are received. Out of reset, both FIFOs are configured to trigger an interrupt at the ½ mark.

13.2.6 Interrupts

The UART can generate interrupts when the following conditions are observed:

- Overrun Error
- Break Error

- Parity Error
- Framing Error
- Receive Timeout
- Transmit (when condition defined in the TXIFLSEL bit in the UARTIFLS register is met)
- Receive (when condition defined in the RXIFLSEL bit in the UARTIFLS register is met)

All of the interrupt events are ORed together before being sent to the interrupt controller, so the UART can only generate a single interrupt request to the controller at any given time. Software can service multiple interrupt events in a single interrupt service routine by reading the **UART Masked Interrupt Status (UARTMIS)** register (see page 310).

The interrupt events that can trigger a controller-level interrupt are defined in the **UART Interrupt Mask (UARTIM**) register (see page 307) by setting the corresponding IM bit to 1. If interrupts are not used, the raw interrupt status is always visible via the **UART Raw Interrupt Status (UARTRIS)** register (see page 309).

Interrupts are always cleared (for both the **UARTMIS** and **UARTRIS** registers) by setting the corresponding bit in the **UART Interrupt Clear (UARTICR)** register (see page 311).

13.2.7 Loopback Operation

The UART can be placed into an internal loopback mode for diagnostic or debug work. This is accomplished by setting the LBE bit in the **UARTCTL** register (see page 304). In loopback mode, data transmitted on UnTx is received on the UnRx input.

13.2.8 IrDA SIR block

The IrDA SIR block contains an IrDA serial IR (SIR) protocol encoder/decoder. When enabled, the SIR block uses the \mathtt{UnTx} and \mathtt{UnRx} pins for the SIR protocol, which should be connected to an IR transceiver.

The SIR block can receive and transmit, but it is only half-duplex so it cannot do both at the same time. Transmission must be stopped before data can be received. The IrDA SIR physical layer specifies a minimum 10-ms delay between transmission and reception.

13.3 Initialization and Configuration

To use the UART, the peripheral clock must be enabled by setting the UART0 bit in the **RCGC1** register. To use the UARTs, the peripheral clock must be enabled by setting the UART0 or UART1 bits in the **RCGC1** register.

This section discusses the steps that are required for using a UART module. For this example, the system clock is assumed to be 20 MHz and the desired UART configuration is:

- 115200 baud rate
- Data length of 8 bits
- One stop bit
- No parity
- FIFOs disabled

No interrupts

The first thing to consider when programming the UART is the baud-rate divisor (BRD), since the **UARTIBRD** and **UARTFBRD** registers must be written before the **UARTLCRH** register. Using the equation described in "Baud-Rate Generation" on page 287, the BRD can be calculated:

```
BRD = 20,000,000 / (16 * 115,200) = 10.8507
```

which means that the DIVINT field of the **UARTIBRD** register (see page 300) should be set to 10. The value to be loaded into the **UARTFBRD** register (see page 301) is calculated by the equation:

```
UARTFBRD[DIVFRAC] = integer(0.8507 * 64 + 0.5) = 54
```

With the BRD values in hand, the UART configuration is written to the module in the following order:

- Disable the UART by clearing the UARTEN bit in the UARTCTL register.
- Write the integer portion of the BRD to the UARTIBRD register.
- 3. Write the fractional portion of the BRD to the **UARTFBRD** register.
- **4.** Write the desired serial parameters to the **UARTLCRH** register (in this case, a value of 0x0000.0060).
- 5. Enable the UART by setting the UARTEN bit in the **UARTCTL** register.

13.4 Register Map

"Register Map" on page 291 lists the UART registers. The offset listed is a hexadecimal increment to the register's address, relative to that UART's base address:

UART0: 0x4000.C000

UART1: 0x4000.D000

Note: The UART must be disabled (see the UARTEN bit in the **UARTCTL** register on page 304) before any of the control registers are reprogrammed. When the UART is disabled during a TX or RX operation, the current transaction is completed prior to the UART stopping.

Table 13-1. UART Register Map

Offset	Name	Туре	Reset	Description	See page
0x000	UARTDR	RO	0x0000.0000	UART Data	293
0x004	UARTRSR/UARTECR	RO	0x0000.0000	UART Receive Status/Error Clear	295
0x004	UARTRSR/UARTECR	RO	0x0000.0000	UART Receive Status/Error Clear	295
0x018	UARTFR	RO	0x0000.0090	UART Flag	297
0x020	UARTILPR	R/W	0x0000.0000	UART IrDA Low-Power Register	299
0x024	UARTIBRD	R/W	0x0000.0000	UART Integer Baud-Rate Divisor	300
0x028	UARTFBRD	R/W	0x0000.0000	UART Fractional Baud-Rate Divisor	301
0x02C	UARTLCRH	R/W	0x0000.0000	UART Line Control	302

Offset	Name	Туре	Reset	Description	See page
0x030	UARTCTL	R/W	0x0000.0300	UART Control	304
0x034	UARTIFLS	R/W	0x0000.0012	UART Interrupt FIFO Level Select	306
0x038	UARTIM	R/W	0x0000.0000	UART Interrupt Mask	307
0x03C	UARTRIS	RO	0x0000.000F	UART Raw Interrupt Status	309
0x040	UARTMIS	RO	0x0000.0000	UART Masked Interrupt Status	310
0x044	UARTICR	W1C	0x0000.0000	UART Interrupt Clear	311
0xFD0	UARTPeriphID4	RO	0x0000.0000	UART Peripheral Identification 4	313
0xFD4	UARTPeriphID5	RO	0x0000.0000	UART Peripheral Identification 5	314
0xFD8	UARTPeriphID6	RO	0x0000.0000	UART Peripheral Identification 6	315
0xFDC	UARTPeriphID7	RO	0x0000.0000	UART Peripheral Identification 7	316
0xFE0	UARTPeriphID0	RO	0x0000.0011	UART Peripheral Identification 0	317
0xFE4	UARTPeriphID1	RO	0x0000.0000	UART Peripheral Identification 1	318
0xFE8	UARTPeriphID2	RO	0x0000.0018	UART Peripheral Identification 2	319
0xFEC	UARTPeriphID3	RO	0x0000.0001	UART Peripheral Identification 3	320
0xFF0	UARTPCellID0	RO	0x0000.000D	UART PrimeCell Identification 0	321
0xFF4	UARTPCellID1	RO	0x0000.00F0	UART PrimeCell Identification 1	322
0xFF8	UARTPCellID2	RO	0x0000.0005	UART PrimeCell Identification 2	323
0xFFC	UARTPCellID3	RO	0x0000.00B1	UART PrimeCell Identification 3	324

13.5 Register Descriptions

The remainder of this section lists and describes the UART registers, in numerical order by address offset.

Register 1: UART Data (UARTDR), offset 0x000

This register is the data register (the interface to the FIFOs).

When FIFOs are enabled, data written to this location is pushed onto the transmit FIFO. If FIFOs are disabled, data is stored in the transmitter holding register (the bottom word of the transmit FIFO). A write to this register initiates a transmission from the UART.

For received data, if the FIFO is enabled, the data byte and the 4-bit status (break, frame, parity and overrun) is pushed onto the 12-bit wide receive FIFO. If FIFOs are disabled, the data byte and status are stored in the receiving holding register (the bottom word of the receive FIFO). The received data can be retrieved by reading this register.

UART Data (UARTDR)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0x000

								rese	rved							
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		rese	erved		OE	BE	PE	FE	'		1	DA	TA		1	
Type L	RO	RO	RO	RO	RO	RO	RO	RO	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
D:t/E:	: - 1 - 1		Mana		T	-	2	D								
Bit/Fi	ieia		Name		Type	r	Reset	Descr	iption							
31:′	12	ı	reserved		RO		0	comp	are shou atibility w rved acro	ith futur	e produ	cts, the v	alue of	a reserv		
11			OE		RO		0	UART	Overrur	Error						
								1=Ne	w data wa	as recei	ved whe	n the FIF	O was f	ull, resul	ting in da	ata loss.
								0=The	ere has b	een no	data los	s due to	a FIFO	overrun	-	
10)		BE		RO		0	UART	Break E	rror						
								the re	oit is set t ceive da mission ti	ta input	was held	d Low fo	r longer	than a f	ull-word	g that
								the FI FIFO.	O mode, FO. Whe The nex to a 1 (m	en a brea et charac	ak occur cter is or	s, only o nly enabl	ne 0 cha ed after	racter is the rece	s loaded eived dat	into the ta input
9			PE		RO		0	UART	Parity E	rror						
									oit is set t atch the p			•				
								In FIF the FI	O mode, FO.	this err	or is ass	sociated	with the	charact	er at the	top of
8			FE		RO		0	UART	Framing	g Error						
									oit is set t oit (a valid			ceived c	haracter	does n	ot have a	a valid

Bit/Field	Name	Туре	Reset	Description
7:0	DATA	R/W	0	When written, the data that is to be transmitted via the UART. When read, the data that was received by the UART.

Register 2: UART Receive Status/Error Clear (UARTRSR/UARTECR), offset 0x004

The **UARTRSR/UARTECR** register is the receive status register/error clear register.

In addition to the **UARTDR** register, receive status can also be read from the **UARTRSR** register. If the status is read from this register, then the status information corresponds to the entry read from **UARTDR** prior to reading **UARTRSR**. The status information for overrun is set immediately when an overrun condition occurs.

A write of any value to the **UARTECR** register clears the framing, parity, break, and overrun errors. All the bits are cleared to 0 on reset.

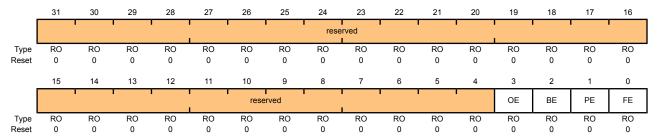
Read-Only Receive Status (UARTRSR) Register

UART Receive Status/Error Clear (UARTRSR/UARTECR)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0x004

Type RO, reset 0x0000.0000

3



Bit/Field	Name	Туре	Reset	Description
31:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
				The UARTRSR register cannot be written.

OE RO 0 UART Overrun Error

When this bit is set to 1, data is received and the FIFO is already full. This bit is cleared to 0 by a write to **UARTECR**.

The FIFO contents remain valid since no further data is written when the FIFO is full, only the contents of the shift register are overwritten. The CPU must now read the data in order to empty the FIFO.

2 BE RO 0 UART Break Error

This bit is set to 1 when a break condition is detected, indicating that the received data input was held Low for longer than a full-word transmission time (defined as start, data, parity, and stop bits).

This bit is cleared to 0 by a write to **UARTECR**.

In FIFO mode, this error is associated with the character at the top of the FIFO. When a break occurs, only one 0 character is loaded into the FIFO. The next character is only enabled after the receive data input goes to a 1 (marking state) and the next valid start bit is received.

Bit/Field	Name	Туре	Reset	Description
1	PE	RO	0	UART Parity Error
				This bit is set to 1 when the parity of the received data character does not match the parity defined by bits 2 and 7 of the UARTLCRH register.
				This bit is cleared to 0 by a write to UARTECR .
0	FE	RO	0	UART Framing Error
				This bit is set to 1 when the received character does not have a valid stop bit (a valid stop bit is 1).

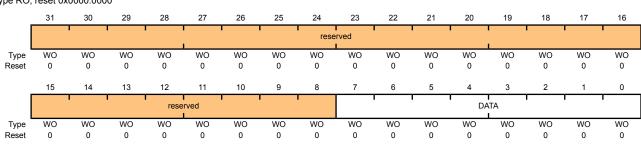
This bit is cleared to 0 by a write to **UARTECR**.

In FIFO mode, this error is associated with the character at the top of the FIFO.

Write-Only Error Clear (UARTECR) Register

UART Receive Status/Error Clear (UARTRSR/UARTECR)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0x004 Type RO, reset 0x0000.0000



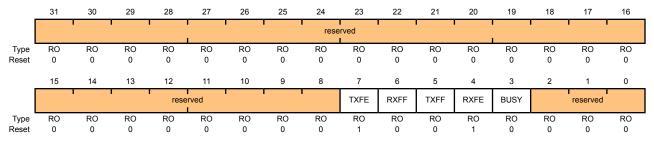
Bit/Field	Name	Type	Reset	Description
31:8	reserved	WO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	DATA	WO	0	A write to this register of any data clears the framing, parity, break and overrun flags.

Register 3: UART Flag (UARTFR), offset 0x018

The **UARTFR** register is the flag register. After reset, the TXFF, RXFF, and BUSY bits are 0, and TXFE and RXFE bits are 1.

UART Flag (UARTFR)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0x018 Type RO, reset 0x0000.0090



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7	TXFE	RO	1	UART Transmit FIFO Empty
				The meaning of this bit depends on the state of the ${\tt FEN}$ bit in the ${\tt UARTLCRH}$ register.
				If the FIFO is disabled (FEN is 0), this bit is set when the transmit holding register is empty.
				If the FIFO is enabled (FEN is 1), this bit is set when the transmit FIFO is empty.
6	RXFF	RO	0	UART Receive FIFO Full
				The meaning of this bit depends on the state of the ${\tt FEN}$ bit in the ${\tt UARTLCRH}$ register.
				If the FIFO is disabled, this bit is set when the receive holding register is full.
				If the FIFO is enabled, this bit is set when the receive FIFO is full.
5	TXFF	RO	0	UART Transmit FIFO Full
				The meaning of this bit depends on the state of the ${\tt FEN}$ bit in the ${\tt UARTLCRH}$ register.
				If the FIFO is disabled, this bit is set when the transmit holding register

If the FIFO is enabled, this bit is set when the transmit FIFO is full.

is full.

Bit/Field	Name	Туре	Reset	Description
4	RXFE	RO	1	UART Receive FIFO Empty
				The meaning of this bit depends on the state of the ${\tt FEN}$ bit in the ${\tt UARTLCRH}$ register.
				If the FIFO is disabled, this bit is set when the receive holding register is empty.
				If the FIFO is enabled, this bit is set when the receive FIFO is empty.
3	BUSY	RO	0	UART Busy
				When this bit is 1, the UART is busy transmitting data. This bit remains set until the complete byte, including all stop bits, has been sent from the shift register.
				This bit is set as soon as the transmit FIFO becomes non-empty (regardless of whether UART is enabled).
2:0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

Register 4: UART IrDA Low-Power Register (UARTILPR), offset 0x020

The **UARTILPR** register is an 8-bit read/write register that stores the low-power counter divisor value used to generate the <code>IrlPBaud16</code> signal by dividing down the system clock (SysClk). All the bits are cleared to 0 when reset.

The IrlpBaud16 internal signal is generated by dividing down the UARTCLK signal according to the low-power divisor value written to **UARTILPR**. The low-power divisor value is calculated as follows:

ILPDVSR = SysClk / F_{IrLPBaud16}

where $F_{IrLPBaud16}$ is nominally 1.8432 MHz.

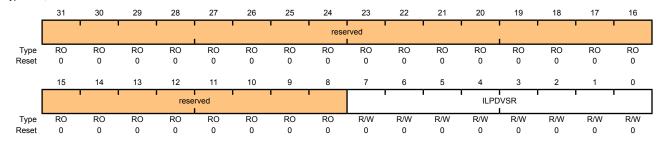
IrlpBaud16 is an internal signal used for SIR pulse generation when low-power mode is used. You must choose the divisor so that $1.42\,\mathrm{MHz} < \mathrm{F_{IrlpBaud16}} < 2.12\,\mathrm{MHz}$, which results in a low-power pulse duration of $1.41-2.11\,\mu\mathrm{s}$ (three times the period of IrlpBaud16). The minimum frequency of IrlpBaud16 ensures that pulses less than one period of IrlpBaud16 are rejected, but that pulses greater than $1.4\,\mu\mathrm{s}$ are accepted as valid pulses.

Note: Zero is an illegal value. Programming a zero value results in no IrlpBaud16 pulses being generated.

UART IrDA Low-Power Register (UARTILPR)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0x020

Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	ILPDVSR	R/W	0x0000	IrDA Low-Power Divisor

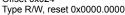
This is an 8-bit low-power divisor value.

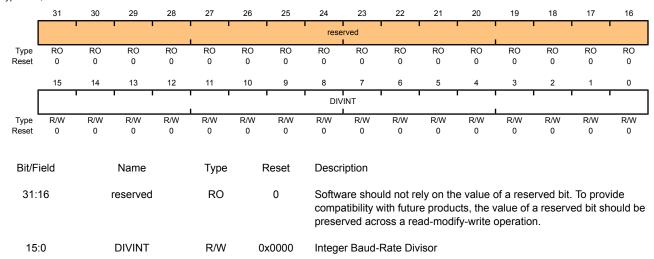
Register 5: UART Integer Baud-Rate Divisor (UARTIBRD), offset 0x024

The **UARTIBRD** register is the integer part of the baud-rate divisor value. All the bits are cleared on reset. The minimum possible divide ratio is 1 (when **UARTIBRD**=0), in which case the **UARTFBRD** register is ignored. When changing the **UARTIBRD** register, the new value does not take effect until transmission/reception of the current character is complete. Any changes to the baud-rate divisor must be followed by a write to the **UARTLCRH** register. See "Baud-Rate Generation" on page 287 for configuration details.

UART Integer Baud-Rate Divisor (UARTIBRD)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0x024



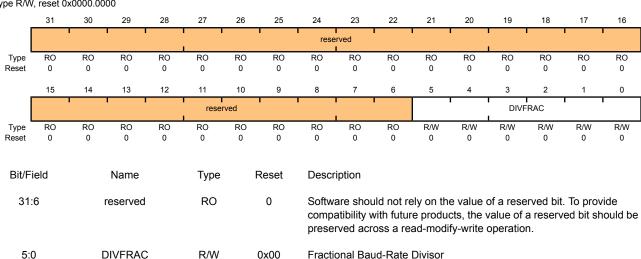


Register 6: UART Fractional Baud-Rate Divisor (UARTFBRD), offset 0x028

The **UARTFBRD** register is the fractional part of the baud-rate divisor value. All the bits are cleared on reset. When changing the UARTFBRD register, the new value does not take effect until transmission/reception of the current character is complete. Any changes to the baud-rate divisor must be followed by a write to the **UARTLCRH** register. See "Baud-Rate Generation" on page 287 for configuration details.

UART Fractional Baud-Rate Divisor (UARTFBRD)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0x028



Register 7: UART Line Control (UARTLCRH), offset 0x02C

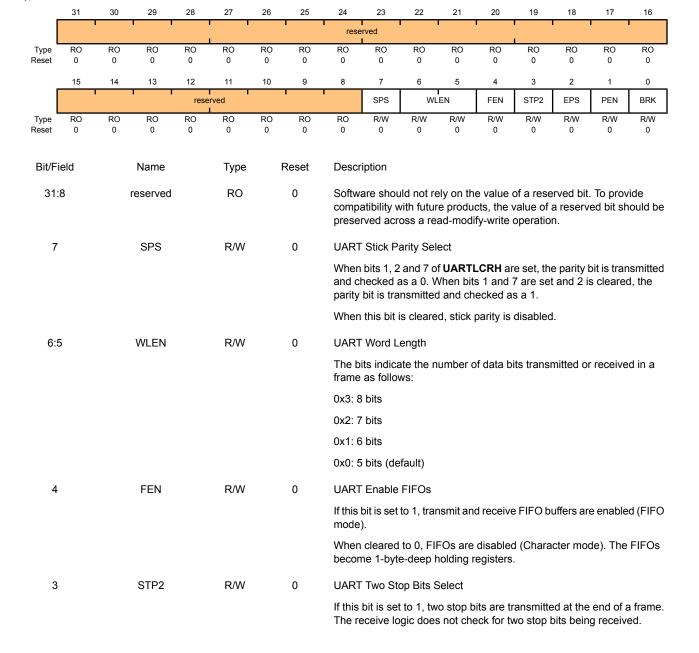
The **UARTLCRH** register is the line control register. Serial parameters such as data length, parity and stop bit selection are implemented in this register.

When updating the baud-rate divisor (**UARTIBRD** and/or **UARTIFRD**), the **UARTLCRH** register must also be written. The write strobe for the baud-rate divisor registers is tied to the **UARTLCRH** register.

UART Line Control (UARTLCRH)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000

Offset 0x02C



Bit/Field	Name	Туре	Reset	Description
2	EPS	R/W	0	UART Even Parity Select
				If this bit is set to 1, even parity generation and checking is performed during transmission and reception, which checks for an even number of 1s in data and parity bits.
				When cleared to 0, then odd parity is performed, which checks for an odd number of 1s.
				This bit has no effect when parity is disabled by the ${\tt PEN}$ bit.
1	PEN	R/W	0	UART Parity Enable
				If this bit is set to 1, parity checking and generation is enabled; otherwise, parity is disabled and no parity bit is added to the data frame.
0	BRK	R/W	0	UART Send Break
				If this bit is set to 1, a Low level is continually output on the ${\tt UnTX}$ output, after completing transmission of the current character. For the proper execution of the break command, the software must set this bit for at least two frames (character periods). For normal use, this bit must be cleared to 0.

Register 8: UART Control (UARTCTL), offset 0x030

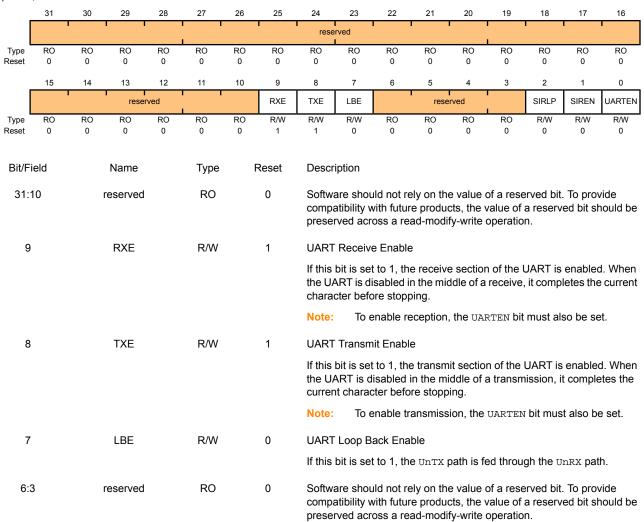
The **UARTCTL** register is the control register. All the bits are cleared on reset except for the Transmit Enable (TXE) and Receive Enable (RXE) bits, which are set to 1.

To enable the UART module, the UARTEN bit must be set to 1. If software requires a configuration change in the module, the UARTEN bit must be cleared before the configuration changes are written. If the UART is disabled during a transmit or receive operation, the current transaction is completed prior to the UART stopping.

UART Control (UARTCTL)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000

Offset 0x030



Bit/Field	Name	Туре	Reset	Description
2	SIRLP	R/W	0	UART SIR Low Power Mode
				This bit selects the IrDA encoding mode. If this bit is cleared to 0, low-level bits are transmitted as an active High pulse with a width of 3/16th of the bit period. If this bit is set to 1, low-level bits are transmitted with a pulse width which is 3 times the period of the IrlPBaud16 input signal, regardless of the selected bit rate. Setting this bit uses less power, but might reduce transmission distances. See page 299 for more information.
1	SIREN	R/W	0	UART SIR Enable
				If this bit is set to 1, the IrDA SIR block is enabled, and the UART will transmit and receive data using SIR protocol.
0	UARTEN	R/W	0	UART Enable
				If this bit is set to 1, the UART is enabled. When the UART is disabled in the middle of transmission or reception, it completes the current character before stopping.

Register 9: UART Interrupt FIFO Level Select (UARTIFLS), offset 0x034

The **UARTIFLS** register is the interrupt FIFO level select register. You can use this register to define the FIFO level at which the TXRIS and RXRIS bits in the UARTRIS register are triggered.

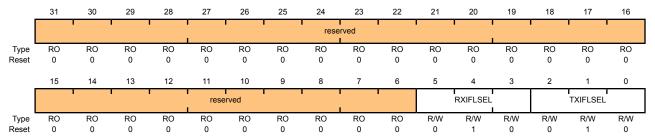
The interrupts are generated based on a transition through a level rather than being based on the level. That is, the interrupts are generated when the fill level progresses through the trigger level. For example, if the receive trigger level is set to the half-way mark, the interrupt is triggered as the module is receiving the 9th character.

Out of reset, the TXIFLSEL and RXIFLSEL bits are configured so that the FIFOs trigger an interrupt at the half-way mark.

UART Interrupt FIFO Level Select (UARTIFLS)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0x034

Type R/W, reset 0x0000.0012



Bit/Field	Name	Туре	Reset	Description
31:6	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
5:3	RXIFLSEL	R/W	0x2	UART Receive Interrupt FIFO Level Select
				The trigger points for the receive interrupt are as follows:
				000: RX FIFO ≥ 1/8 full
				001: RX FIFO ≥ ¼ full
				010: RX FIFO ≥ ½ full (default)
				011: RX FIFO ≥ ¾ full
				100: RX FIFO ≥ 7/8 full
				101-111: Reserved
2:0	TXIFLSEL	R/W	0x2	UART Transmit Interrupt FIFO Level Select
				The trigger points for the transmit interrupt are as follows:
				000: TX FIFO ≤ 1/8 full
				001: TX FIFO ≤ ¼ full

010: TX FIFO ≤ ½ full (default)

011: TX FIFO ≤ ¾ full 100: TX FIFO ≤ 7/8 full 101-111: Reserved

Register 10: UART Interrupt Mask (UARTIM), offset 0x038

The **UARTIM** register is the interrupt mask set/clear register.

On a read, this register gives the current value of the mask on the relevant interrupt. Writing a 1 to a bit allows the corresponding raw interrupt signal to be routed to the interrupt controller. Writing a 0 prevents the raw interrupt signal from being sent to the interrupt controller.

UART Interrupt Mask (UARTIM)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0x038

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
			' '			·		rese	rved •						1	
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0
_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
			reserved			OEIM	BEIM	PEIM	FEIM	RTIM	TXIM	RXIM		rese	erved	
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	RO 0	RO 0	RO 0	RO 0
Bit/Fi	ield		Name		Туре	F	Reset	Descr	iption							
31:	11		reserved		RO		0	compa	atibility v	vith futur	e produ		alue of	a reserv	. To prov ed bit sh	
10)		OEIM		R/W		0	UART	Overrui	n Error II	nterrupt	Mask				
								On a ı	read, the	current	mask fo	or the OE	Iм inter	rupt is re	eturned.	
								Setting	g this bit	to 1 pror	notes the	e OEIM ir	nterrupt t	to the int	errupt co	ontroller.
9			BEIM		R/W		0	UART	Break E	Error Inte	errupt Ma	ask				
								On a ı	read, the	current	mask fo	or the BE	Iм inter	rupt is re	eturned.	
								Setting	g this bit	to 1 pror	notes the	евеім ir	nterrupt t	to the int	errupt co	ntroller.
8			PEIM		R/W		0	UART	Parity E	Error Inte	errupt Ma	ask				
								On a ı	read, the	current	mask fo	or the PE	Iм inter	rupt is re	eturned.	
								Setting	g this bit	to 1 pror	notes the	ереім ir	nterrupt t	to the int	errupt co	ntroller.
7			FEIM		R/W		0	UART	Framin	g Error li	nterrupt	Mask				
								On a ı	read, the	current	mask fo	or the FE	Iм inter	rupt is re	eturned.	
								Setting	g this bit	to 1 pror	notes the	e FEIM ir	nterrupt t	to the int	errupt co	ntroller.
6			RTIM		R/W		0	UART	Receive	e Time-C	Out Inter	rupt Mas	sk			
								On a ı	read, the	current	mask fo	or the RT	Iм inter	rupt is re	eturned.	
								Setting	g this bit	to 1 pror	notes the	eRTIMir	nterrupt t	to the int	errupt co	ntroller.
5			TXIM		R/W		0	UART	Transm	it Interru	ıpt Mask					
								On a ı	read, the	current	mask fo	or the TX	Iм inter	rupt is re	eturned.	
								Setting	g this bit	to 1 pror	notes the	e TXIM ir	nterrupt t	to the int	errupt co	ntroller.

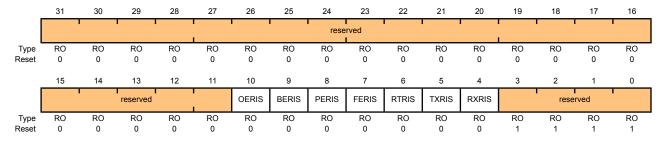
Bit/Field	Name	Type	Reset	Description
4	RXIM	R/W	0	UART Receive Interrupt Mask
				On a read, the current mask for the ${\tt RXIM}$ interrupt is returned.
				Setting this bit to 1 promotes the RXIM interrupt to the interrupt controller.
3:0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

Register 11: UART Raw Interrupt Status (UARTRIS), offset 0x03C

The **UARTRIS** register is the raw interrupt status register. On a read, this register gives the current raw status value of the corresponding interrupt. A write has no effect.

UART Raw Interrupt Status (UARTRIS)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0x03C Type RO, reset 0x0000.000F



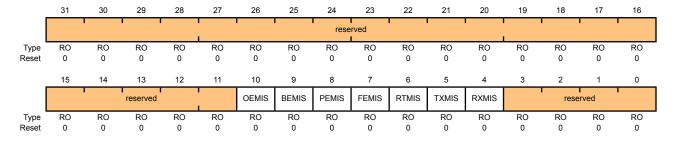
Bit/Field	Name	Туре	Reset	Description
31:11	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
10	OERIS	RO	0	UART Overrun Error Raw Interrupt Status
				Gives the raw interrupt state (prior to masking) of this interrupt.
9	BERIS	RO	0	UART Break Error Raw Interrupt Status
				Gives the raw interrupt state (prior to masking) of this interrupt.
8	PERIS	RO	0	UART Parity Error Raw Interrupt Status
				Gives the raw interrupt state (prior to masking) of this interrupt.
7	FERIS	RO	0	UART Framing Error Raw Interrupt Status
				Gives the raw interrupt state (prior to masking) of this interrupt.
6	RTRIS	RO	0	UART Receive Time-Out Raw Interrupt Status
				Gives the raw interrupt state (prior to masking) of this interrupt.
5	TXRIS	RO	0	UART Transmit Raw Interrupt Status
				Gives the raw interrupt state (prior to masking) of this interrupt.
4	RXRIS	RO	0	UART Receive Raw Interrupt Status
				Gives the raw interrupt state (prior to masking) of this interrupt.
3:0	reserved	RO	0xF	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

Register 12: UART Masked Interrupt Status (UARTMIS), offset 0x040

The **UARTMIS** register is the masked interrupt status register. On a read, this register gives the current masked status value of the corresponding interrupt. A write has no effect.

UART Masked Interrupt Status (UARTMIS)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0x040 Type RO, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:11	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
10	OEMIS	RO	0	UART Overrun Error Masked Interrupt Status
				Gives the masked interrupt state of this interrupt.
9	BEMIS	RO	0	UART Break Error Masked Interrupt Status
				Gives the masked interrupt state of this interrupt.
8	PEMIS	RO	0	UART Parity Error Masked Interrupt Status
				Gives the masked interrupt state of this interrupt.
7	FEMIS	RO	0	UART Framing Error Masked Interrupt Status
				Gives the masked interrupt state of this interrupt.
6	RTMIS	RO	0	UART Receive Time-Out Masked Interrupt Status
				Gives the masked interrupt state of this interrupt.
5	TXMIS	RO	0	UART Transmit Masked Interrupt Status
				Gives the masked interrupt state of this interrupt.
4	RXMIS	RO	0	UART Receive Masked Interrupt Status
				Gives the masked interrupt state of this interrupt.
3:0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

17

16

Register 13: UART Interrupt Clear (UARTICR), offset 0x044

The **UARTICR** register is the interrupt clear register. On a write of 1, the corresponding interrupt (both raw interrupt and masked interrupt, if enabled) is cleared. A write of 0 has no effect.

UART Interrupt Clear (UARTICR)

28

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0x044

		1	1 1					rese	rved			· · · · ·		•	· ·	
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		1	reserved			OEIC	BEIC	PEIC	FEIC	RTIC	TXIC	RXIC		rese	rved	
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	W1C 0	W1C 0	W1C 0	W1C 0	W1C 0	W1C 0	W1C 0	RO 0	RO 0	RO 0	RO 0
Bit/F	ield		Name		Туре	F	Reset	Descr	iption							
31:	11		reserved		RO		0	compa	atibility w	ith futur	e produ	e value o cts, the v fy-write o	alue of	a reserv		
10)		OEIC		W1C		0	Overr	un Error	Interrup	t Clear					
								0: No	effect or	the inte	errupt.					
								1: Cle	ars inter	rupt.						
9			BEIC		W1C		0	Break	Error In	terrupt C	Clear					
								0: No	effect or	the inte	errupt.					
								1: Cle	ars inter	rupt.						
8			PEIC		W1C		0	Parity	Error In	terrupt C	Clear					
								0: No	effect or	the inte	errupt.					
								1: Cle	ars inter	rupt.						
7			FEIC		W1C		0	Frami	ng Error	Interrup	t Clear					
								0: No	effect or	the inte	errupt.					
								1: Cle	ars inter	rupt.						
6			RTIC		W1C		0	Recei	ve Time-	Out Inte	errupt Cl	ear				
								0: No	effect or	the inte	errupt.					
								1: Cle	ars inter	rupt.						
5			TXIC		W1C		0	Trans	mit Inter	rupt Clea	ar					
								0: No	effect or	the inte	errupt.					
								1: Cle	ars inter	rupt.						

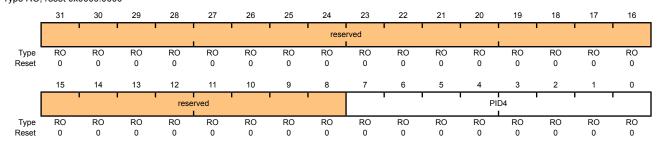
Bit/Field	Name	Type	Reset	Description
4	RXIC	W1C	0	Receive Interrupt Clear
				0: No effect on the interrupt.
				1: Clears interrupt.
3:0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

Register 14: UART Peripheral Identification 4 (UARTPeriphID4), offset 0xFD0

The **UARTPeriphIDn** registers are hard-coded and the fields within the registers determine the reset values.

UART Peripheral Identification 4 (UARTPeriphID4)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0xFD0 Type RO, reset 0x0000.0000



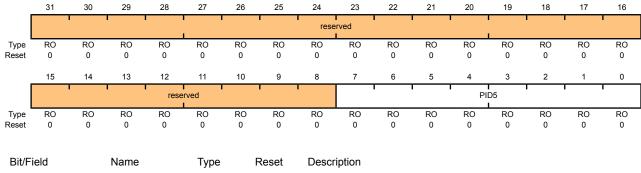
Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID4	RO	0x00	UART Peripheral ID Register[7:0]

Register 15: UART Peripheral Identification 5 (UARTPeriphID5), offset 0xFD4

The **UARTPeriphIDn** registers are hard-coded and the fields within the registers determine the reset values.

UART Peripheral Identification 5 (UARTPeriphID5)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0xFD4 Type RO, reset 0x0000.0000



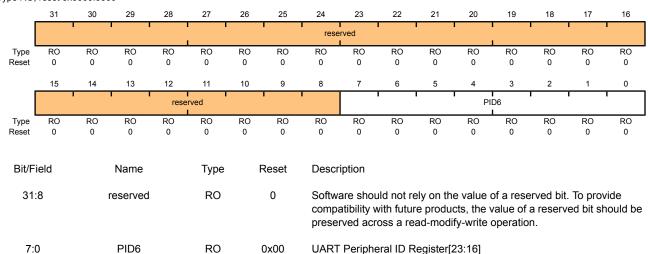
Bil/Fielu	Name	туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID5	RO	0x00	UART Peripheral ID Register[15:8]

Register 16: UART Peripheral Identification 6 (UARTPeriphID6), offset 0xFD8

The **UARTPeriphIDn** registers are hard-coded and the fields within the registers determine the reset values.

UART Peripheral Identification 6 (UARTPeriphID6)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0xFD8



0

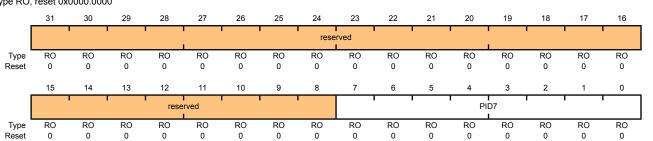
Register 17: UART Peripheral Identification 7 (UARTPeriphID7), offset 0xFDC

The **UARTPeriphIDn** registers are hard-coded and the fields within the registers determine the reset values.

UART Peripheral Identification 7 (UARTPeriphID7)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0xFDC Type RO, reset 0x0000.0000

0



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID7	RO	0x00	UART Peripheral ID Register[31:24]

0

0

0

0

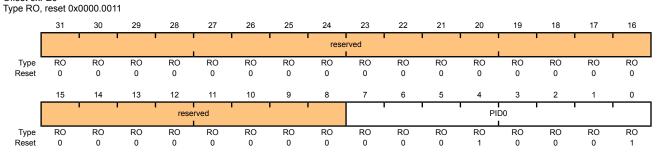
0

Register 18: UART Peripheral Identification 0 (UARTPeriphID0), offset 0xFE0

The **UARTPeriphIDn** registers are hard-coded and the fields within the registers determine the reset values.

UART Peripheral Identification 0 (UARTPeriphID0)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0xFE0



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID0	RO	0x11	UART Peripheral ID Register[7:0]

Can be used by software to identify the presence of this peripheral.

Register 19: UART Peripheral Identification 1 (UARTPeriphID1), offset 0xFE4

The **UARTPeriphIDn** registers are hard-coded and the fields within the registers determine the reset values.

UART Peripheral Identification 1 (UARTPeriphID1)

PID1

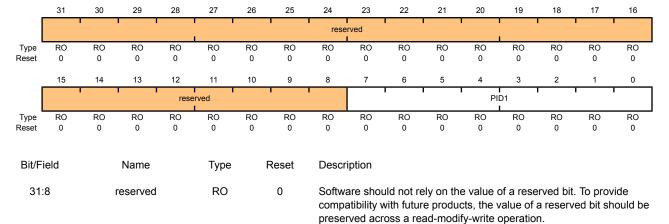
RO

0x00

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0xFE4

Offset 0xFE4
Type RO, reset 0x0000.0000

7:0



Can be used by software to identify the presence of this peripheral.

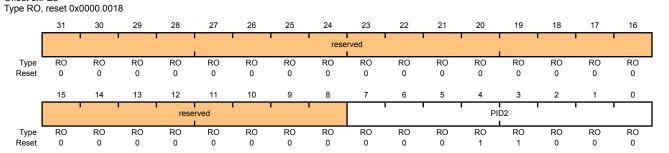
UART Peripheral ID Register[15:8]

Register 20: UART Peripheral Identification 2 (UARTPeriphID2), offset 0xFE8

The **UARTPeriphIDn** registers are hard-coded and the fields within the registers determine the reset values.

UART Peripheral Identification 2 (UARTPeriphID2)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0xFE8



Bit/Field	Name	туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID2	RO	0x18	UART Peripheral ID Register[23:16]

Can be used by software to identify the presence of this peripheral.

Register 21: UART Peripheral Identification 3 (UARTPeriphID3), offset 0xFEC

The **UARTPeriphIDn** registers are hard-coded and the fields within the registers determine the reset values.

UART Peripheral Identification 3 (UARTPeriphID3)

PID3

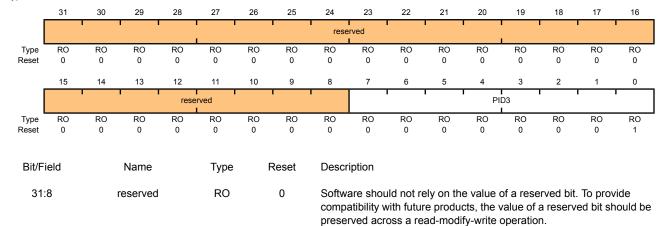
RO

0x01

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0xFEC

Type RO, reset 0x0000.0001

7:0



Can be used by software to identify the presence of this peripheral.

UART Peripheral ID Register[31:24]

Register 22: UART PrimeCell Identification 0 (UARTPCellID0), offset 0xFF0

The **UARTPCellIDn** registers are hard-coded and the fields within the registers determine the reset values.

UART PrimeCell Identification 0 (UARTPCellID0)

CID0

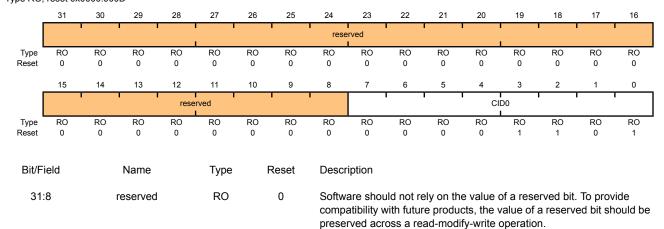
RO

0x0D

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0xFF0

Type RO, reset 0x0000.000D

7:0



Provides software a standard cross-peripheral identification system.

UART PrimeCell ID Register[7:0]

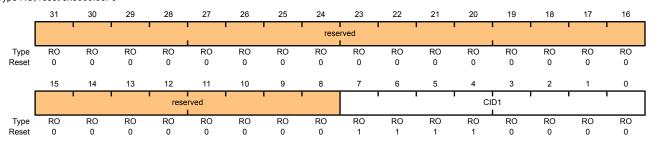
Register 23: UART PrimeCell Identification 1 (UARTPCellID1), offset 0xFF4

The **UARTPCellIDn** registers are hard-coded and the fields within the registers determine the reset values.

UART PrimeCell Identification 1 (UARTPCellID1)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0xFF4

Type RO, reset 0x0000.00F0



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CID1	RO	0xF0	UART PrimeCell ID Register[15:8]

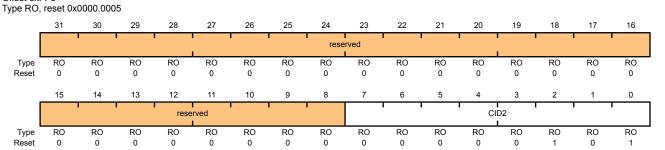
Provides software a standard cross-peripheral identification system.

Register 24: UART PrimeCell Identification 2 (UARTPCellID2), offset 0xFF8

The **UARTPCellIDn** registers are hard-coded and the fields within the registers determine the reset values.

UART PrimeCell Identification 2 (UARTPCellID2)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0xFF8



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CID2	RO	0x05	UART PrimeCell ID Register[23:16]

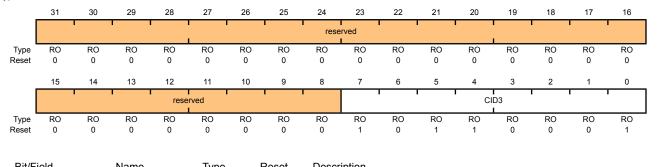
Provides software a standard cross-peripheral identification system.

Register 25: UART PrimeCell Identification 3 (UARTPCellID3), offset 0xFFC

The **UARTPCellIDn** registers are hard-coded and the fields within the registers determine the reset values.

UART PrimeCell Identification 3 (UARTPCellID3)

UART0 base: 0x4000.C000 UART1 base: 0x4000.D000 Offset 0xFFC Type RO, reset 0x0000.00B1



Bit/Field	Name	туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CID3	RO	0xB1	UART PrimeCell ID Register[31:24]

Provides software a standard cross-peripheral identification system.

14 Synchronous Serial Interface (SSI)

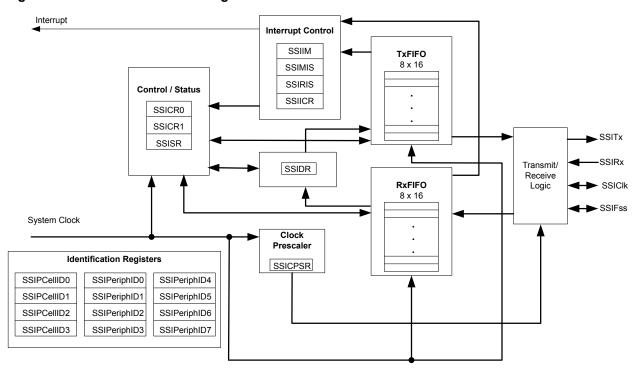
The Stellaris[®] Synchronous Serial Interface (SSI) is a master or slave interface for synchronous serial communication with peripheral devices that have either Freescale SPI, MICROWIRE, or Texas Instruments synchronous serial interfaces.

The Stellaris® SSI module has the following features:

- Master or slave operation
- Programmable clock bit rate and prescale
- Separate transmit and receive FIFOs, 16 bits wide, 8 locations deep
- Programmable interface operation for Freescale SPI, MICROWIRE, or Texas Instruments synchronous serial interfaces
- Programmable data frame size from 4 to 16 bits
- Internal loopback test mode for diagnostic/debug testing

14.1 Block Diagram

Figure 14-1. SSI Module Block Diagram



14.2 Functional Description

The SSI performs serial-to-parallel conversion on data received from a peripheral device. The CPU accesses data, control, and status information. The transmit and receive paths are buffered with

internal FIFO memories allowing up to eight 16-bit values to be stored independently in both transmit and receive modes.

14.2.1 Bit Rate Generation

The SSI includes a programmable bit rate clock divider and prescaler to generate the serial output clock. Bit rates are supported to 2 MHz and higher, although maximum bit rate is determined by peripheral devices.

The serial bit rate is derived by dividing down the 50-MHz input clock. The clock is first divided by an even prescale value CPSDVSR from 2 to 254, which is programmed in the **SSI Clock Prescale** (**SSICPSR**) register (see page 342). The clock is further divided by a value from 1 to 256, which is 1 + SCR, where SCR is the value programmed in the **SSI Control0** (**SSICR0**) register (see page 337).

The frequency of the output clock SSIClk is defined by:

```
FSSIClk = FSysClk / (CPSDVSR * (1 + SCR))
```

Note that although the SSIC1k transmit clock can theoretically be 25 MHz, the module may not be able to operate at that speed. For master mode, the system clock must be at least two times faster than the SSIC1k. For slave mode, the system clock must be at least 12 times faster than the SSIC1k.

See "Electrical Characteristics" on page 513 to view SSI timing parameters.

14.2.2 FIFO Operation

14.2.2.1 Transmit FIFO

The common transmit FIFO is a 16-bit wide, 8-locations deep, first-in, first-out memory buffer. The CPU writes data to the FIFO by writing the **SSI Data (SSIDR)** register (see page 340), and data is stored in the FIFO until it is read out by the transmission logic.

When configured as a master or a slave, parallel data is written into the transmit FIFO prior to serial conversion and transmission to the attached slave or master, respectively, through the SSITX pin.

14.2.2.2 Receive FIFO

The common receive FIFO is a 16-bit wide, 8-locations deep, first-in, first-out memory buffer. Received data from the serial interface is stored in the buffer until read out by the CPU, which accesses the read FIFO by reading the **SSIDR** register.

When configured as a master or slave, serial data received through the SSIRx pin is registered prior to parallel loading into the attached slave or master receive FIFO, respectively.

14.2.3 Interrupts

The SSI can generate interrupts when the following conditions are observed:

- Transmit FIFO service
- Receive FIFO service
- Receive FIFO time-out
- Receive FIFO overrun

All of the interrupt events are ORed together before being sent to the interrupt controller, so the SSI can only generate a single interrupt request to the controller at any given time. You can mask each

of the four individual maskable interrupts by setting the appropriate bits in the **SSI Interrupt Mask** (**SSIIM**) register (see page 343). Setting the appropriate mask bit to 1 enables the interrupt.

Provision of the individual outputs, as well as a combined interrupt output, allows use of either a global interrupt service routine, or modular device drivers to handle interrupts. The transmit and receive dynamic dataflow interrupts have been separated from the status interrupts so that data can be read or written in response to the FIFO trigger levels. The status of the individual interrupt sources can be read from the **SSI Raw Interrupt Status (SSIRIS)** and **SSI Masked Interrupt Status (SSIMIS)** registers (see page 344 and page 345, respectively).

14.2.4 Frame Formats

Each data frame is between 4 and 16 bits long, depending on the size of data programmed, and is transmitted starting with the MSB. There are three basic frame types that can be selected:

- Texas Instruments synchronous serial
- Freescale SPI
- MICROWIRE

For all three formats, the serial clock (SSIClk) is held inactive while the SSI is idle, and SSIClk transitions at the programmed frequency only during active transmission or reception of data. The idle state of SSIClk is utilized to provide a receive timeout indication that occurs when the receive FIFO still contains data after a timeout period.

For Freescale SPI and MICROWIRE frame formats, the serial frame (SSIFSS) pin is active Low, and is asserted (pulled down) during the entire transmission of the frame.

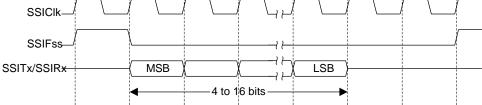
For Texas Instruments synchronous serial frame format, the SSIFss pin is pulsed for one serial clock period starting at its rising edge, prior to the transmission of each frame. For this frame format, both the SSI and the off-chip slave device drive their output data on the rising edge of SSIClk, and latch data from the other device on the falling edge.

Unlike the full-duplex transmission of the other two frame formats, the MICROWIRE format uses a special master-slave messaging technique, which operates at half-duplex. In this mode, when a frame begins, an 8-bit control message is transmitted to the off-chip slave. During this transmit, no incoming data is received by the SSI. After the message has been sent, the off-chip slave decodes it and, after waiting one serial clock after the last bit of the 8-bit control message has been sent, responds with the requested data. The returned data can be 4 to 16 bits in length, making the total frame length anywhere from 13 to 25 bits.

14.2.4.1 Texas Instruments Synchronous Serial Frame Format

Figure 14-2 on page 327 shows the Texas Instruments synchronous serial frame format for a single transmitted frame.



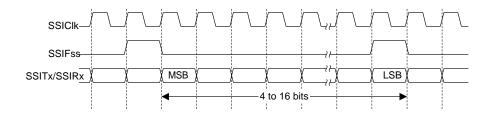


In this mode, SSIC1k and SSIFSS are forced Low, and the transmit data line SSITX is tristated whenever the SSI is idle. Once the bottom entry of the transmit FIFO contains data, SSIFSS is pulsed High for one SSIC1k period. The value to be transmitted is also transferred from the transmit FIFO to the serial shift register of the transmit logic. On the next rising edge of SSIC1k, the MSB of the 4 to 16-bit data frame is shifted out on the SSITX pin. Likewise, the MSB of the received data is shifted onto the SSIRX pin by the off-chip serial slave device.

Both the SSI and the off-chip serial slave device then clock each data bit into their serial shifter on the falling edge of each SSIClk. The received data is transferred from the serial shifter to the receive FIFO on the first rising edge of SSIClk after the LSB has been latched.

Figure 14-3 on page 328 shows the Texas Instruments synchronous serial frame format when back-to-back frames are transmitted.

Figure 14-3. TI Synchronous Serial Frame Format (Continuous Transfer)



14.2.4.2 Freescale SPI Frame Format

The Freescale SPI interface is a four-wire interface where the SSIFss signal behaves as a slave select. The main feature of the Freescale SPI format is that the inactive state and phase of the SSIC1k signal are programmable through the SPO and SPH bits within the **SSISCR0** control register.

SPO Clock Polarity Bit

When the SPO clock polarity control bit is Low, it produces a steady state Low value on the SSIClk pin. If the SPO bit is High, a steady state High value is placed on the SSIClk pin when data is not being transferred.

SPH Phase Control Bit

The SPH phase control bit selects the clock edge that captures data and allows it to change state. It has the most impact on the first bit transmitted by either allowing or not allowing a clock transition before the first data capture edge. When the SPH phase control bit is Low, data is captured on the first clock edge transition. If the SPH bit is High, data is captured on the second clock edge transition.

14.2.4.3 Freescale SPI Frame Format with SPO=0 and SPH=0

Single and continuous transmission signal sequences for Freescale SPI format with SPO=0 and SPH=0 are shown in Figure 14-4 on page 329 and Figure 14-5 on page 329.

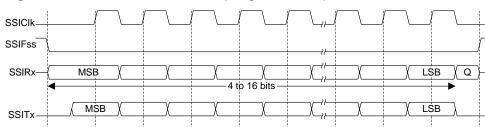
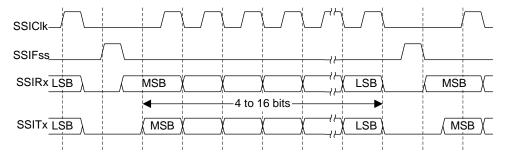


Figure 14-4. Freescale SPI Format (Single Transfer) with SPO=0 and SPH=0

Figure 14-5. Freescale SPI Format (Continuous Transfer) with SPO=0 and SPH=0



Note: Q is undefined.

In this configuration, during idle periods:

- SSIC1k is forced Low
- SSIFss is forced High
- The transmit data line SSITx is arbitrarily forced Low
- When the SSI is configured as a master, it enables the SSIClk pad
- When the SSI is configured as a slave, it disables the SSIClk pad

If the SSI is enabled and there is valid data within the transmit FIFO, the start of transmission is signified by the SSIFss master signal being driven Low. This causes slave data to be enabled onto the SSIRx input line of the master. The master SSITx output pad is enabled.

One half SSIC1k period later, valid master data is transferred to the SSITx pin. Now that both the master and slave data have been set, the SSIC1k master clock pin goes High after one further half SSIC1k period.

The data is now captured on the rising and propagated on the falling edges of the SSIClk signal.

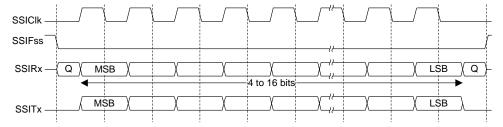
In the case of a single word transmission, after all bits of the data word have been transferred, the SSIFss line is returned to its idle High state one SSIClk period after the last bit has been captured.

However, in the case of continuous back-to-back transmissions, the SSIFss signal must be pulsed High between each data word transfer. This is because the slave select pin freezes the data in its serial peripheral register and does not allow it to be altered if the SPH bit is logic zero. Therefore, the master device must raise the SSIFss pin of the slave device between each data transfer to enable the serial peripheral data write. On completion of the continuous transfer, the SSIFss pin is returned to its idle state one SSIClk period after the last bit has been captured.

14.2.4.4 Freescale SPI Frame Format with SPO=0 and SPH=1

The transfer signal sequence for Freescale SPI format with SPO=0 and SPH=1 is shown in Figure 14-6 on page 330, which covers both single and continuous transfers.

Figure 14-6. Freescale SPI Frame Format with SPO=0 and SPH=1



Note: Q is undefined.

In this configuration, during idle periods:

- SSIC1k is forced Low
- SSIFss is forced High
- The transmit data line SSITx is arbitrarily forced Low
- When the SSI is configured as a master, it enables the SSIClk pad
- When the SSI is configured as a slave, it disables the SSIClk pad

If the SSI is enabled and there is valid data within the transmit FIFO, the start of transmission is signified by the SSIFss master signal being driven Low. The master SSITx output is enabled. After a further one half SSIClk period, both master and slave valid data is enabled onto their respective transmission lines. At the same time, the SSIClk is enabled with a rising edge transition.

Data is then captured on the falling edges and propagated on the rising edges of the SSIC1k signal.

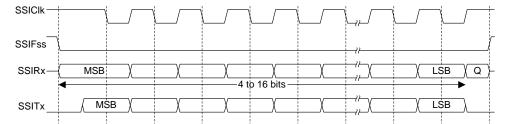
In the case of a single word transfer, after all bits have been transferred, the SSIFss line is returned to its idle High state one SSIClk period after the last bit has been captured.

For continuous back-to-back transfers, the SSIFss pin is held Low between successive data words and termination is the same as that of the single word transfer.

14.2.4.5 Freescale SPI Frame Format with SPO=1 and SPH=0

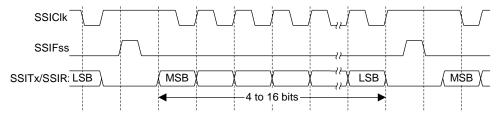
Single and continuous transmission signal sequences for Freescale SPI format with SPO=1 and SPH=0 are shown in Figure 14-7 on page 330 and Figure 14-8 on page 331.

Figure 14-7. Freescale SPI Frame Format (Single Transfer) with SPO=1 and SPH=0



Note: Q is undefined.

Figure 14-8. Freescale SPI Frame Format (Continuous Transfer) with SPO=1 and SPH=0



In this configuration, during idle periods:

- SSIC1k is forced High
- SSIFss is forced High
- The transmit data line SSITx is arbitrarily forced Low
- When the SSI is configured as a master, it enables the SSIClk pad
- When the SSI is configured as a slave, it disables the SSIClk pad

If the SSI is enabled and there is valid data within the transmit FIFO, the start of transmission is signified by the SSIFss master signal being driven Low, which causes slave data to be immediately transferred onto the SSIRx line of the master. The master SSITx output pad is enabled.

One half period later, valid master data is transferred to the SSITx line. Now that both the master and slave data have been set, the SSIClk master clock pin becomes Low after one further half SSIClk period. This means that data is captured on the falling edges and propagated on the rising edges of the SSIClk signal.

In the case of a single word transmission, after all bits of the data word are transferred, the SSIFss line is returned to its idle High state one SSIClk period after the last bit has been captured.

However, in the case of continuous back-to-back transmissions, the SSIFss signal must be pulsed High between each data word transfer. This is because the slave select pin freezes the data in its serial peripheral register and does not allow it to be altered if the SPH bit is logic zero. Therefore, the master device must raise the SSIFss pin of the slave device between each data transfer to enable the serial peripheral data write. On completion of the continuous transfer, the SSIFss pin is returned to its idle state one SSIClk period after the last bit has been captured.

14.2.4.6 Freescale SPI Frame Format with SPO=1 and SPH=1

The transfer signal sequence for Freescale SPI format with SPO=1 and SPH=1 is shown in Figure 14-9 on page 332, which covers both single and continuous transfers.

Figure 14-9. Freescale SPI Frame Format with SPO=1 and SPH=1

Note: Q is undefined.

In this configuration, during idle periods:

- SSIC1k is forced High
- SSIFss is forced High
- The transmit data line SSITx is arbitrarily forced Low
- When the SSI is configured as a master, it enables the SSIClk pad
- When the SSI is configured as a slave, it disables the SSIClk pad

If the SSI is enabled and there is valid data within the transmit FIFO, the start of transmission is signified by the SSIFss master signal being driven Low. The master SSITx output pad is enabled. After a further one-half SSIClk period, both master and slave data are enabled onto their respective transmission lines. At the same time, SSIClk is enabled with a falling edge transition. Data is then captured on the rising edges and propagated on the falling edges of the SSIClk signal.

After all bits have been transferred, in the case of a single word transmission, the SSIFss line is returned to its idle high state one SSIClk period after the last bit has been captured.

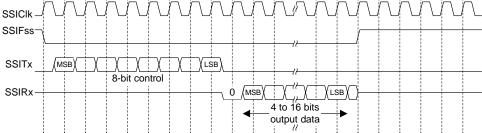
For continuous back-to-back transmissions, the SSIFss pin remains in its active Low state, until the final bit of the last word has been captured, and then returns to its idle state as described above.

For continuous back-to-back transfers, the SSIFss pin is held Low between successive data words and termination is the same as that of the single word transfer.

14.2.4.7 MICROWIRE Frame Format

Figure 14-10 on page 332 shows the MICROWIRE frame format, again for a single frame. Figure 14-11 on page 333 shows the same format when back-to-back frames are transmitted.

Figure 14-10. MICROWIRE Frame Format (Single Frame)



MICROWIRE format is very similar to SPI format, except that transmission is half-duplex instead of full-duplex, using a master-slave message passing technique. Each serial transmission begins with an 8-bit control word that is transmitted from the SSI to the off-chip slave device. During this transmission, no incoming data is received by the SSI. After the message has been sent, the off-chip slave decodes it and, after waiting one serial clock after the last bit of the 8-bit control message has been sent, responds with the required data. The returned data is 4 to 16 bits in length, making the total frame length anywhere from 13 to 25 bits.

In this configuration, during idle periods:

- SSIC1k is forced Low
- SSIFss is forced High
- The transmit data line SSITx is arbitrarily forced Low

A transmission is triggered by writing a control byte to the transmit FIFO. The falling edge of SSIFss causes the value contained in the bottom entry of the transmit FIFO to be transferred to the serial shift register of the transmit logic, and the MSB of the 8-bit control frame to be shifted out onto the SSITxpin. SSIFss remains Low for the duration of the frame transmission. The SSIRxpin remains tristated during this transmission.

The off-chip serial slave device latches each control bit into its serial shifter on the rising edge of each SSIClk. After the last bit is latched by the slave device, the control byte is decoded during a one clock wait-state, and the slave responds by transmitting data back to the SSI. Each bit is driven onto the SSIRx line on the falling edge of SSIClk. The SSI in turn latches each bit on the rising edge of SSIClk. At the end of the frame, for single transfers, the SSIFss signal is pulled High one clock period after the last bit has been latched in the receive serial shifter, which causes the data to be transferred to the receive FIFO.

Note: The off-chip slave device can tristate the receive line either on the falling edge of SSIClk after the LSB has been latched by the receive shifter, or when the SSIFss pin goes High.

For continuous transfers, data transmission begins and ends in the same manner as a single transfer. However, the SSIFss line is continuously asserted (held Low) and transmission of data occurs back-to-back. The control byte of the next frame follows directly after the LSB of the received data from the current frame. Each of the received values is transferred from the receive shifter on the falling edge of SSIClk, after the LSB of the frame has been latched into the SSI.

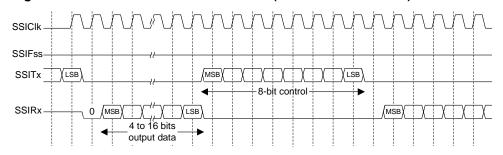


Figure 14-11. MICROWIRE Frame Format (Continuous Transfer)

In the MICROWIRE mode, the SSI slave samples the first bit of receive data on the rising edge of SSIClk after SSIFss has gone Low. Masters that drive a free-running SSIClk must ensure that the SSIFss signal has sufficient setup and hold margins with respect to the rising edge of SSIClk.

Figure 14-12 on page 334 illustrates these setup and hold time requirements. With respect to the SSIClk rising edge on which the first bit of receive data is to be sampled by the SSI slave, SSIFSS must have a setup of at least two times the period of SSIClk on which the SSI operates. With respect to the SSIClk rising edge previous to this edge, SSIFSS must have a hold of at least one SSIClk period.

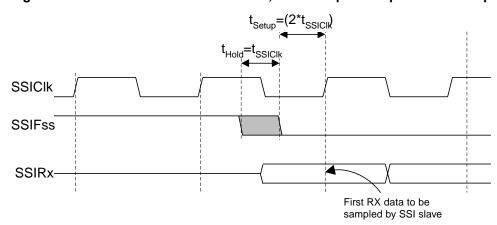


Figure 14-12. MICROWIRE Frame Format, SSIFss Input Setup and Hold Requirements

14.3 Initialization and Configuration

To use the SSI, its peripheral clock must be enabled by setting the SSI bit in the **RCGC1** register. For each of the frame formats, the SSI is configured using the following steps:

- Ensure that the SSE bit in the SSICR1 register is disabled before making any configuration changes.
- 2. Select whether the SSI is a master or slave:
 - a. For master operations, set the **SSICR1** register to 0x00000000.
 - **b.** For slave mode (output enabled), set the **SSICR1** register to 0x00000004.
 - c. For slave mode (output disabled), set the **SSICR1** register to 0x0000000C.
- Configure the clock prescale divisor by writing the SSICPSR register.
- 4. Write the **SSICR0** register with the following configuration:
 - Serial clock rate (SCR)
 - Desired clock phase/polarity, if using Freescale SPI mode (SPH and SPO)
 - The protocol mode: Freescale SPI, TI SSF, MICROWIRE (FRF)
 - The data size (DSS)
- 5. Enable the SSI by setting the SSE bit in the SSICR1 register.

As an example, assume the SSI must be configured to operate with the following parameters:

- Master operation
- Freescale SPI mode (SPO=1, SPH=1)
- 1 Mbps bit rate
- 8 data bits

Assuming the system clock is 20 MHz, the bit rate calculation would be:

```
FSSIClk = FSysClk / (CPSDVSR * (1 + SCR))
1x106 = 20x106 / (CPSDVSR * (1 + SCR))
```

In this case, if CPSDVSR=2, SCR must be 9.

The configuration sequence would be as follows:

- 1. Ensure that the SSE bit in the SSICR1 register is disabled.
- 2. Write the **SSICR1** register with a value of 0x00000000.
- 3. Write the **SSICPSR** register with a value of 0x00000002.
- 4. Write the **SSICR0** register with a value of 0x000009C7.
- 5. The SSI is then enabled by setting the SSE bit in the SSICR1 register to 1.

14.4 Register Map

"Register Map" on page 335 lists the SSI registers. The offset listed is a hexadecimal increment to the register's address, relative to that SSI module's base address:

SSI0: 0x4000.8000

Note: The SSI must be disabled (see the SSE bit in the **SSICR1** register) before any of the control registers are reprogrammed.

Table 14-1. SSI Register Map

Offset	Name	Type	Reset	Description	See page
0x000	SSICR0	R/W	0x0000.0000	SSI Control 0	337
0x004	SSICR1	R/W	0x0000.0000	SSI Control 1	339
0x008	SSIDR	R/W	0x0000.0000	SSI Data	340
0x00C	SSISR	RO	0x0000.0003	SSI Status	341
0x010	SSICPSR	R/W	0x0000.0000	SSI Clock Prescale	342
0x014	SSIIM	R/W	0x0000.0000	SSI Interrupt Mask	343
0x018	SSIRIS	RO	0x0000.0008	SSI Raw Interrupt Status	344
0x01C	SSIMIS	RO	0x0000.0000	SSI Masked Interrupt Status	345
0x020	SSIICR	W1C	0x0000.0000	SSI Interrupt Clear	346

Offset	Name	Type	Reset	Description	See page
0xFD0	SSIPeriphID4	RO	0x0000.0000	SSI Peripheral Identification 4	347
0xFD4	SSIPeriphID5	RO	0x0000.0000	SSI Peripheral Identification 5	348
0xFD8	SSIPeriphID6	RO	0x0000.0000	SSI Peripheral Identification 6	349
0xFDC	SSIPeriphID7	RO	0x0000.0000	SSI Peripheral Identification 7	350
0xFE0	SSIPeriphID0	RO	0x0000.0022	SSI Peripheral Identification 0	351
0xFE4	SSIPeriphID1	RO	0x0000.0000	SSI Peripheral Identification 1	352
0xFE8	SSIPeriphID2	RO	0x0000.0018	SSI Peripheral Identification 2	353
0xFEC	SSIPeriphID3	RO	0x0000.0001	SSI Peripheral Identification 3	354
0xFF0	SSIPCellID0	RO	0x0000.000D	SSI PrimeCell Identification 0	355
0xFF4	SSIPCellID1	RO	0x0000.00F0	SSI PrimeCell Identification 1	356
0xFF8	SSIPCellID2	RO	0x0000.0005	SSI PrimeCell Identification 2	357
0xFFC	SSIPCelIID3	RO	0x0000.00B1	SSI PrimeCell Identification 3	358

14.5 Register Descriptions

The remainder of this section lists and describes the SSI registers, in numerical order by address offset.

Register 1: SSI Control 0 (SSICR0), offset 0x000

SSICR0 is control register 0 and contains bit fields that control various functions within the SSI module. Functionality such as protocol mode, clock rate and data size are configured in this register.

SSI Control 0 (SSICR0)

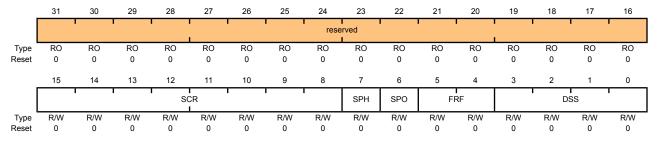
SSI0 base: 0x4000.8000 Offset 0x000 Type R/W, reset 0x0000.0000

6

SPO

R/W

0



Bit/Field	Name	Туре	Reset	Description
31:16	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15:8	SCR	R/W	0	SSI Serial Clock Rate
				The value ${\tt SCR}$ is used to generate the transmit and receive bit rate of the SSI. The bit rate is:
				BR=FSSIClk/(CPSDVSR * (1 + SCR))
				where CPSDVSR is an even value from 2-254 programmed in the SSICPSR register, and SCR is a value from 0-255.
7	SPH	R/W	0	SSI Serial Clock Phase
				This bit is only applicable to the Freescale SPI Format.
				The SPH control bit selects the clock edge that captures data and allows it to change state. It has the most impact on the first bit transmitted by either allowing or not allowing a clock transition before the first data capture edge.

SSI Serial Clock Polarity This bit is only applicable to the Freescale SPI Format.

When the SPO bit is 0, it produces a steady state Low value on the SSIC1k pin. If SPO is 1, a steady state High value is placed on the SSIC1k pin when data is not being transferred.

When the SPH bit is 0, data is captured on the first clock edge transition. If SPH is 1, data is captured on the second clock edge transition.

Bit/Field	Name	Туре	Reset	Description
5:4	FRF	R/W	0	SSI Frame Format Select
				The FRF values are defined as follows:
				FRF Value Frame Format
				00 Freescale SPI Frame Format
				01 Texas Intruments Synchronous Serial Frame Format
				10 MICROWIRE Frame Format
				11 Reserved
3:0	DSS	R/W	0	SSI Data Size Select
				The DSS values are defined as follows:
				DSS Value Data Size
				0000-0010 Reserved
				0011 4-bit data
				0100 5-bit data
				0101 6-bit data
				0110 7-bit data
				0111 8-bit data
				1000 9-bit data
				1001 10-bit data

1010

1011

1100

1101

1110

1111

11-bit data

12-bit data

13-bit data

14-bit data

15-bit data

16-bit data

Register 2: SSI Control 1 (SSICR1), offset 0x004

SSICR1 is control register 1 and contains bit fields that control various functions within the SSI module. Master and slave mode functionality is controlled by this register.

SSI Control 1 (SSICR1)

SSI0 base: 0x4000.8000 Offset 0x004 Type R/W, reset 0x0000.0000

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
		•	' '	, ,	'		•	rese	rved				' '	'		
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		1	1 1	1	-		erved	•					SOD	MS	SSE	LBM
Type	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Bit/Fi	eld		Name		Туре	F	Reset	Descr	iption							
31:	4		reserved		RO		0	compa	atibility w	ith futur	e produc	cts, the	of a rese alue of a operation	a reserv		
3			SOD		R/W		0	SSI S	lave Mod	de Outpu	ıt Disabl	le				
								syster slaves the se could	ns, it is p in the s rial outpo be tied t	oossible ystem w ut line. In ogether.	for the S hile ensu such sy To oper	SI mast uring tha stems, t ate in su	ode (MS= er to bro it only on he TXD li uch a sys not drive	adcast a e slave ines fron stem, the	a messa drives da n multiple sod bit	ge to all ata onto e slaves
								0: SSI	can driv	e ssit	x output	in Slave	e Output	mode.		
								1: SSI	must no	ot drive t	he ssit	∵x outpu	t in Slav	e mode.		
2			MS		R/W		0	SSI M	aster/Sla	ave Sele	ect					
										s Master d (SSE=0		e mode	and can	be mod	ified onl	y when
								0: Dev	ice conf	igured a	s a mas	ter.				
								1: Dev	ice conf	figured a	s a slav	e.				
1			SSE		R/W		0	SSI S	ynchron	ous Seria	al Port E	nable				
								Settin	g this bit	enables	SSI op	eration.				
								0: SSI	operation	on disab	led.					
								1: SSI	operation	on enabl	ed.					
								Note:		bit mus ogramm		to 0 bef	ore any o	control r	egisters	are
0			LBM		R/W		0	SSI Lo	oopback	Mode						
								Settin	g this bit	enables	Loopba	ack Test	mode.			
								0: Nor	mal seri	al port o	peration	enable	d.			
										e transn e receive			gister is o ster.	connecte	ed intern	ally to

Register 3: SSI Data (SSIDR), offset 0x008

SSIDR is the data register and is 16-bits wide. When **SSIDR** is read, the entry in the receive FIFO (pointed to by the current FIFO read pointer) is accessed. As data values are removed by the SSI receive logic from the incoming data frame, they are placed into the entry in the receive FIFO (pointed to by the current FIFO write pointer).

When **SSIDR** is written to, the entry in the transmit FIFO (pointed to by the write pointer) is written to. Data values are removed from the transmit FIFO one value at a time by the transmit logic. It is loaded into the transmit serial shifter, then serially shifted out onto the SSITX pin at the programmed bit rate.

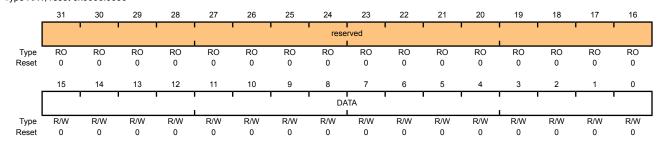
When a data size of less than 16 bits is selected, the user must right-justify data written to the transmit FIFO. The transmit logic ignores the unused bits. Received data less than 16 bits is automatically right-justified in the receive buffer.

When the SSI is programmed for MICROWIRE frame format, the default size for transmit data is eight bits (the most significant byte is ignored). The receive data size is controlled by the programmer. The transmit FIFO and the receive FIFO are not cleared even when the SSE bit in the **SSICR1** register is set to zero. This allows the software to fill the transmit FIFO before enabling the SSI.

SSI Data (SSIDR)

D:4/E:-14

SSI0 base: 0x4000.8000 Offset 0x008 Type R/W, reset 0x0000.0000



Bivrieid	name	туре	Reset	Description
31:16	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15:0	DATA	R/W	0	SSI Receive/Transmit Data

A read operation reads the receive FIFO. A write operation writes the transmit FIFO.

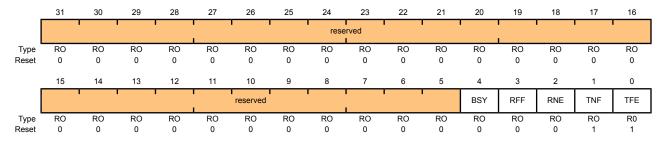
Software must right-justify data when the SSI is programmed for a data size that is less than 16 bits. Unused bits at the top are ignored by the transmit logic. The receive logic automatically right-justifies the data.

Register 4: SSI Status (SSISR), offset 0x00C

SSISR is a status register that contains bits that indicate the FIFO fill status and the SSI busy status.

SSI Status (SSISR)

SSI0 base: 0x4000.8000 Offset 0x00C Type RO, reset 0x0000.0003



Bit/Field	Name	Туре	Reset	Description
31:5	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
4	BSY	RO	0	SSI Busy Bit
				0: SSI is idle.
				1: SSI is currently transmitting and/or receiving a frame, or the transmit FIFO is not empty.
3	RFF	RO	0	SSI Receive FIFO Full
				0: Receive FIFO is not full.
				1: Receive FIFO is full.
2	RNE	RO	0	SSI Receive FIFO Not Empty
				0: Receive FIFO is empty.
				1: Receive FIFO is not empty.
1	TNF	RO	1	SSI Transmit FIFO Not Full
				0: Transmit FIFO is full.
				1: Transmit FIFO is not full.
0	TFE	R0	1	SSI Transmit FIFO Empty
				0: Transmit FIFO is not empty.

1: Transmit FIFO is empty.

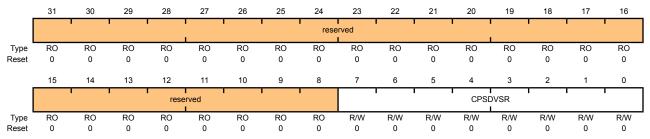
Register 5: SSI Clock Prescale (SSICPSR), offset 0x010

SSICPSR is the clock prescale register and specifies the division factor by which the system clock must be internally divided before further use.

The value programmed into this register must be an even number between 2 and 254. The least-significant bit of the programmed number is hard-coded to zero. If an odd number is written to this register, data read back from this register has the least-significant bit as zero.

SSI Clock Prescale (SSICPSR)

SSI0 base: 0x4000.8000 Offset 0x010 Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CPSDVSR	R/W	0	SSI Clock Prescale Divisor

This value must be an even number from 2 to 254, depending on the frequency of SSIC1k. The LSB always returns 0 on reads.

Register 6: SSI Interrupt Mask (SSIIM), offset 0x014

The **SSIIM** register is the interrupt mask set or clear register. It is a read/write register and all bits are cleared to 0 on reset.

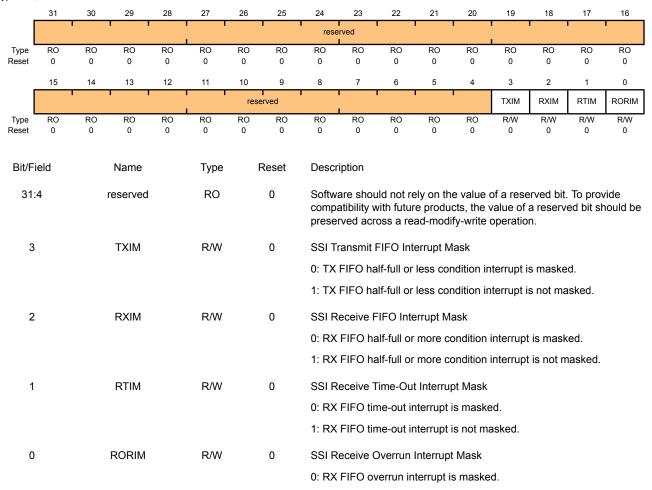
On a read, this register gives the current value of the mask on the relevant interrupt. A write of 1 to the particular bit sets the mask, enabling the interrupt to be read. A write of 0 clears the corresponding mask.

SSI Interrupt Mask (SSIIM)

SSI0 base: 0x4000.8000

Offset 0x014

Type R/W, reset 0x0000.0000



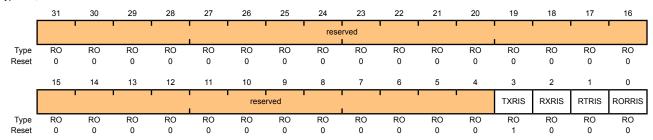
1: RX FIFO overrun interrupt is not masked.

Register 7: SSI Raw Interrupt Status (SSIRIS), offset 0x018

The SSIRIS register is the raw interrupt status register. On a read, this register gives the current raw status value of the corresponding interrupt prior to masking. A write has no effect.

SSI Raw Interrupt Status (SSIRIS)

SSI0 base: 0x4000.8000 Offset 0x018 Type RO, reset 0x0000.0008



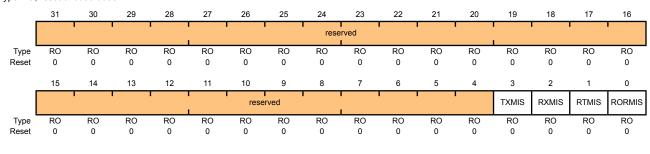
Bit/Field	Name	Туре	Reset	Description
31:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	TXRIS	RO	1	SSI Transmit FIFO Raw Interrupt Status Indicates that the transmit FIFO is half full or less, when set.
2	RXRIS	RO	0	SSI Receive FIFO Raw Interrupt Status Indicates that the receive FIFO is half full or more, when set.
1	RTRIS	RO	0	SSI Receive Time-Out Raw Interrupt Status Indicates that the receive time-out has occurred, when set.
0	RORRIS	RO	0	SSI Receive Overrun Raw Interrupt Status Indicates that the receive FIFO has overflowed, when set.

Register 8: SSI Masked Interrupt Status (SSIMIS), offset 0x01C

The **SSIMIS** register is the masked interrupt status register. On a read, this register gives the current masked status value of the corresponding interrupt. A write has no effect.

SSI Masked Interrupt Status (SSIMIS)

SSI0 base: 0x4000.8000 Offset 0x01C Type RO, reset 0x0000.0000



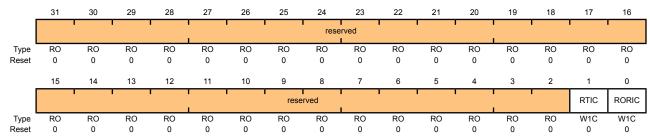
Bit/Field	Name	Туре	Reset	Description
31:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	TXMIS	RO	0	SSI Transmit FIFO Masked Interrupt Status Indicates that the transmit FIFO is half full or less, when set.
2	RXMIS	RO	0	SSI Receive FIFO Masked Interrupt Status Indicates that the receive FIFO is half full or more, when set.
1	RTMIS	RO	0	SSI Receive Time-Out Masked Interrupt Status Indicates that the receive time-out has occurred, when set.
0	RORMIS	RO	0	SSI Receive Overrun Masked Interrupt Status Indicates that the receive FIFO has overflowed, when set.

Register 9: SSI Interrupt Clear (SSIICR), offset 0x020

The SSIICR register is the interrupt clear register. On a write of 1, the corresponding interrupt is cleared. A write of 0 has no effect.

SSI Interrupt Clear (SSIICR)

SSI0 base: 0x4000.8000 Offset 0x020 Type W1C, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	RTIC	W1C	0	SSI Receive Time-Out Interrupt Clear 0: No effect on interrupt. 1: Clears interrupt.
0	RORIC	W1C	0	SSI Receive Overrun Interrupt Clear 0: No effect on interrupt.

1: Clears interrupt.

Register 10: SSI Peripheral Identification 4 (SSIPeriphID4), offset 0xFD0

The SSIPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

SSI Peripheral Identification 4 (SSIPeriphID4)

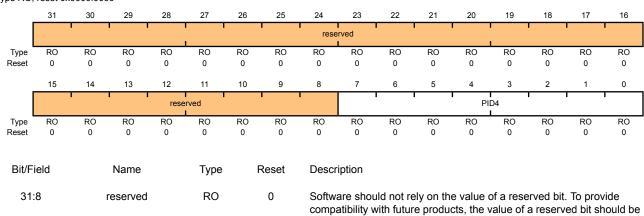
PID4

RO

0x00

SSI0 base: 0x4000.8000 Offset 0xFD0 Type RO, reset 0x0000.0000

7:0



Can be used by software to identify the presence of this peripheral.

preserved across a read-modify-write operation.

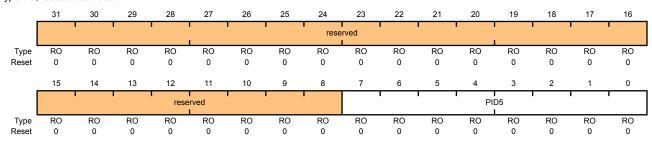
SSI Peripheral ID Register[7:0]

Register 11: SSI Peripheral Identification 5 (SSIPeriphID5), offset 0xFD4

The SSIPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

SSI Peripheral Identification 5 (SSIPeriphID5)

SSI0 base: 0x4000.8000 Offset 0xFD4 Type RO, reset 0x0000.0000



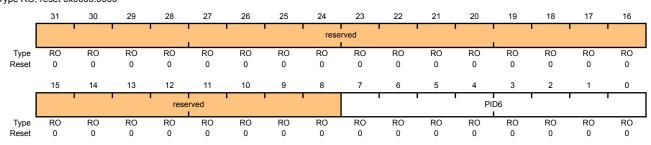
Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID5	RO	0x00	SSI Peripheral ID Register[15:8]

Register 12: SSI Peripheral Identification 6 (SSIPeriphID6), offset 0xFD8

The SSIPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

SSI Peripheral Identification 6 (SSIPeriphID6)

SSI0 base: 0x4000.8000 Offset 0xFD8 Type RO, reset 0x0000.0000



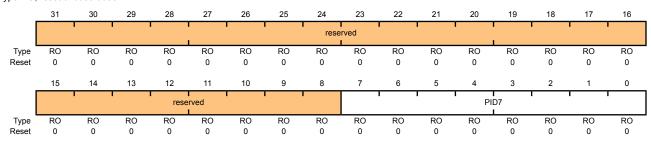
Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID6	RO	0x00	SSI Peripheral ID Register[23:16]

Register 13: SSI Peripheral Identification 7 (SSIPeriphID7), offset 0xFDC

The SSIPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

SSI Peripheral Identification 7 (SSIPeriphID7)

SSI0 base: 0x4000.8000 Offset 0xFDC Type RO, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID7	RO	0x00	SSI Peripheral ID Register[31:24]

Register 14: SSI Peripheral Identification 0 (SSIPeriphID0), offset 0xFE0

The SSIPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

SSI Peripheral Identification 0 (SSIPeriphID0)

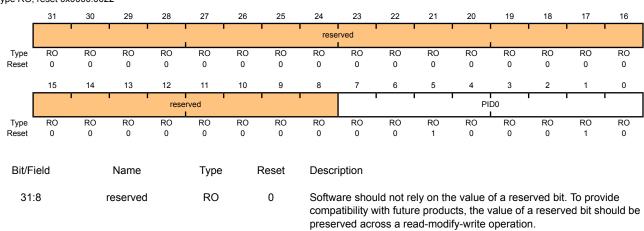
PID0

RO

0x22

SSI0 base: 0x4000.8000 Offset 0xFE0 Type RO, reset 0x0000.0022

7:0



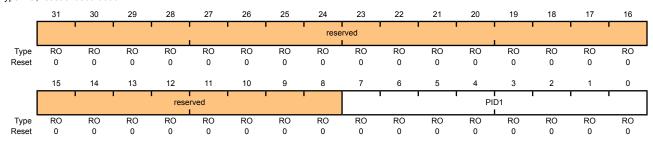
SSI Peripheral ID Register[7:0]

Register 15: SSI Peripheral Identification 1 (SSIPeriphID1), offset 0xFE4

The SSIPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

SSI Peripheral Identification 1 (SSIPeriphID1)

SSI0 base: 0x4000.8000 Offset 0xFE4 Type RO, reset 0x0000.0000



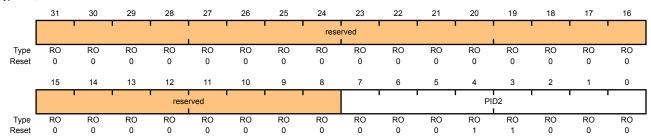
Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID1	RO	0x00	SSI Peripheral ID Register [15:8]

Register 16: SSI Peripheral Identification 2 (SSIPeriphID2), offset 0xFE8

The SSIPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

SSI Peripheral Identification 2 (SSIPeriphID2)

SSI0 base: 0x4000.8000 Offset 0xFE8 Type RO, reset 0x0000.0018



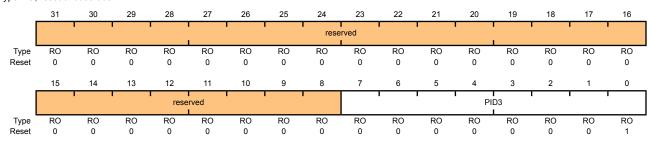
Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID2	RO	0x18	SSI Peripheral ID Register [23:16]

Register 17: SSI Peripheral Identification 3 (SSIPeriphID3), offset 0xFEC

The SSIPeriphIDn registers are hard-coded and the fields within the register determine the reset value.

SSI Peripheral Identification 3 (SSIPeriphID3)

SSI0 base: 0x4000.8000 Offset 0xFEC Type RO, reset 0x0000.0001



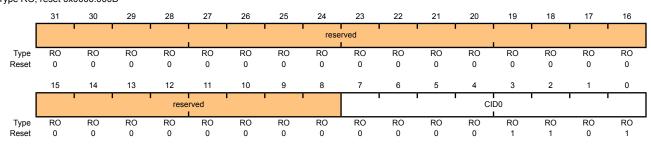
Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	PID3	RO	0x01	SSI Peripheral ID Register [31:24]

Register 18: SSI PrimeCell Identification 0 (SSIPCellID0), offset 0xFF0

The SSIPCeIIIDn registers are hard-coded and the fields within the register determine the reset value.

SSI PrimeCell Identification 0 (SSIPCellID0)

SSI0 base: 0x4000.8000 Offset 0xFF0 Type RO, reset 0x0000.000D



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CID0	RO	0x0D	SSI PrimeCell ID Register [7:0]

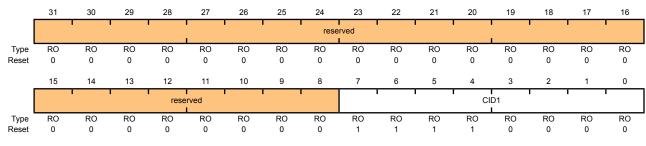
Provides software a standard cross-peripheral identification system.

Register 19: SSI PrimeCell Identification 1 (SSIPCellID1), offset 0xFF4

The SSIPCeIIIDn registers are hard-coded and the fields within the register determine the reset value.

SSI PrimeCell Identification 1 (SSIPCellID1)

SSI0 base: 0x4000.8000 Offset 0xFF4 Type RO, reset 0x0000.00F0



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	CID1	RO	0xF0	SSI PrimeCell ID Register [15:8]

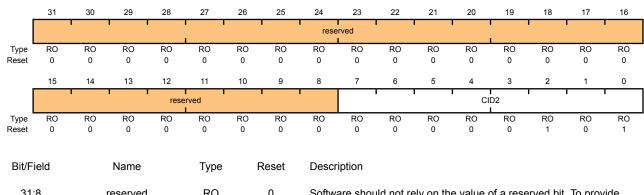
Provides software a standard cross-peripheral identification system.

Register 20: SSI PrimeCell Identification 2 (SSIPCellID2), offset 0xFF8

The SSIPCeIIIDn registers are hard-coded and the fields within the register determine the reset value.

SSI PrimeCell Identification 2 (SSIPCelIID2)

SSI0 base: 0x4000.8000 Offset 0xFF8 Type RO, reset 0x0000.0005



31:8 RO 0 Software should not rely on the value of a reserved bit. To provide reserved compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

CID2 7:0 RO 0x05 SSI PrimeCell ID Register [23:16]

Provides software a standard cross-peripheral identification system.

Register 21: SSI PrimeCell Identification 3 (SSIPCellID3), offset 0xFFC

The SSIPCellIDn registers are hard-coded and the fields within the register determine the reset value.

SSI PrimeCell Identification 3 (SSIPCelIID3)

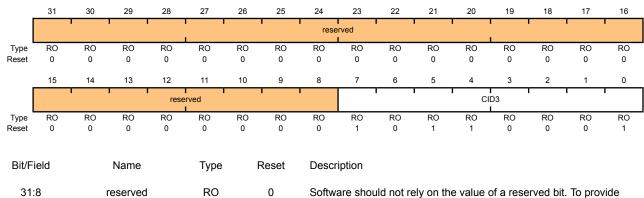
CID3

RO

0xB1

SSI0 base: 0x4000.8000 Offset 0xFFC Type RO, reset 0x0000.00B1

7:0



Provides software a standard cross-peripheral identification system.

compatibility with future products, the value of a reserved bit should be

preserved across a read-modify-write operation.

SSI PrimeCell ID Register [31:24]

15 Inter-Integrated Circuit (I²C) Interface

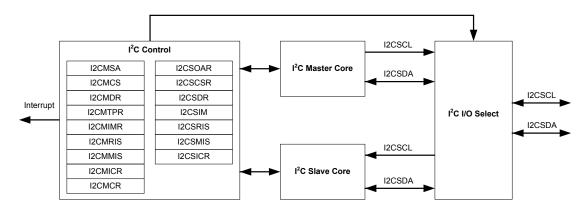
The Inter-Integrated Circuit (I²C) bus provides bi-directional data transfer through a two-wire design (a serial data line SDA and a serial clock line SCL), and interfaces to external I²C devices such as serial memory (RAMs and ROMs), networking devices, LCDs, tone generators, and so on. The I²C bus may also be used for system testing and diagnostic purposes in product development and manufacture. providing the ability to interact (both send and receive) with other I²C devices on the bus.

Devices on the I²C bus can be designated as either a master or a slave. TheEach Stellaris[®] I²C module supports both sending and receiving data as either a master or a slave, and also supports the simultaneous operation as both a master and a slave. There are a total of four I²C modes: Master Transmit, Master Receive, Slave Transmit, and Slave Receive. The Stellaris[®] I²C module can operate at two speeds: Standard (100 Kbps) and Fast (400 Kbps).

Both the I²C master and slave can generate interrupts; the I²C master generates interrupts when a transmit or receive operation completes (or aborts due to an error) and the I²C slave generates interrupts when data has been sent or requested by a master.

15.1 Block Diagram

Figure 15-1. I²C Block Diagram

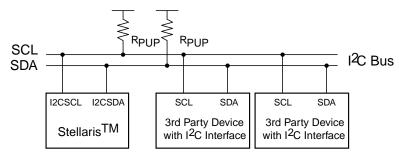


15.2 Functional Description

The Each I^2C module is comprised of both master and slave functions which are implemented as separate peripherals. For proper operation, the SDA and SCL pins must be connected to bi-directional open-drain pads. A typical I^2C bus configuration is shown in Figure 15-2 on page 360.

See "I²C" on page 518 for I²C timing diagrams.

Figure 15-2. I²C Bus Configuration



15.2.1 I²C Bus Functional Overview

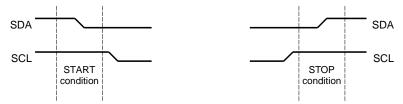
The I²C bus uses only two signals: SDA and SCL, named I2CSDA and I2CSCL on Stellaris[®] microcontrollers. SDA is the bi-directional serial data line and SCL is the bi-directional serial clock line. The bus is considered idle when both lines are high.

Every transaction on the I²C bus is nine bits long, consisting of eight data bits and a single acknowledge bit. The number of bytes per transfer (defined as the time between a valid START and STOP condition, described in "START and STOP Conditions" on page 360) is unrestricted, but each byte has to be followed by an acknowledge bit, and data must be transferred MSB first. When a receiver cannot receive another complete byte, it can hold the clock line SCL Low and force the transmitter into a wait state. The data transfer continues when the receiver releases the clock SCL.

15.2.1.1 START and STOP Conditions

The protocol of the I²C bus defines two states to begin and end a transaction: START and STOP. A high-to-low transition on the SDA line while the SCL is high is defined as a START condition, and a low-to-high transition on the SDA line while SCL is high is defined as a STOP condition. The bus is considered busy after a START condition and free after a STOP condition. See Figure 15-3 on page 360.

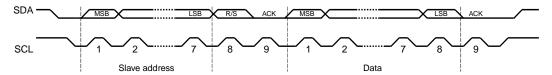
Figure 15-3. START and STOP Conditions



15.2.1.2 Data Format with 7-Bit Address

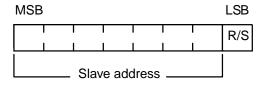
Data transfers follow the format shown in Figure 15-4 on page 361. After the START condition, a slave address is sent. This address is 7-bits long followed by an eighth bit, which is a data direction bit (\mathbb{R}/\mathbb{S} bit in the **I2CMSA** register). A zero indicates a transmit operation (send), and a one indicates a request for data (receive). A data transfer is always terminated by a STOP condition generated by the master, however, a master can initiate communications with another device on the bus by generating a repeated START condition and addressing another slave without first generating a STOP condition. Various combinations of receive/send formats are then possible within a single transfer.

Figure 15-4. Complete Data Transfer with a 7-Bit Address



The first seven bits of the first byte make up the slave address (see Figure 15-5 on page 361). The eighth bit determines the direction of the message. A zero in the R/S position of the first byte means that the master will write (send) data to the selected slave, and a one in this position means that the master will receive data from the slave.

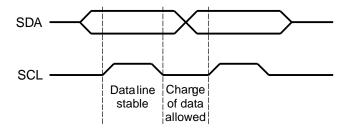
Figure 15-5. R/S Bit in First Byte



15.2.1.3 Data Validity

The data on the SDA line must be stable during the high period of the clock, and the data line can only change when SCL is low (see Figure 15-6 on page 361).

Figure 15-6. Data Validity During Bit Transfer on the I²C Bus



15.2.1.4 Acknowledge

All bus transactions have a required acknowledge clock cycle that is generated by the master. During the acknowledge cycle, the transmitter (which can be the master or slave) releases the SDA line. To acknowledge the transaction, the receiver must pull down SDA during the acknowledge clock cycle. The data sent out by the receiver during the acknowledge cycle must comply with the data validity requirements described in "Data Validity" on page 361.

When a slave receiver does not acknowledge the slave address, SDA must be left high by the slave so that the master can generate a STOP condition and abort the current transfer. If the master device is acting as a receiver during a transfer, it is responsible for acknowledging each transfer made by the slave. Since the master controls the number of bytes in the transfer, it signals the end of data to the slave transmitter by not generating an acknowledge on the last data byte. The slave transmitter must then release SDA to allow the master to generate the STOP or a repeated START condition.

15.2.1.5 Arbitration

A master may start a transfer only if the bus is idle. Its possible for two or more masters to generate a START condition within minimum hold time of the START condition. In these situations, an arbitration scheme takes place on the SDA line, while SCL is high. During arbitration, the first of the competing master devices to place a '1' (high) on SDA while another master transmits a '0' (low) will switch off its data output stage and retire until the bus is idle again.

Arbitration can take place over several bits. Its first stage is a comparison of address bits, and if both masters are trying to address the same device, arbitration continues on to the comparison of data bits.

15.2.2 Available Speed Modes

The I^2C clock rate is determined by the parameters: CLK_PRD , $TIMER_PRD$, SCL_LP , and SCL_HP .

where:

CLK_PRD is the system clock period

SCL_LP is the low phase of SCL (fixed at 6)

SCL_HP is the high phase of SCL (fixed at 4)

TIMER_PRD is the programmed value in the I²C Master Timer Period (I2CMTPR) register (see page 379).

The I²C clock period is calculated as follows:

```
SCL PERIOD = 2*(1 + TIMER PRD)*(SCL LP + SCL HP)*CLK PRD
```

For example:

```
CLK_PRD = 50 ns
TIMER_PRD = 2
SCL_LP=6
SCL_HP=4
```

yields a SCL frequency of:

```
1/T = 333 \text{ Khz}
```

Table 15-1 on page 362 gives examples of Timer period, system clock, and speed mode (Standard or Fast).

Table 15-1. Examples of I²C Master Timer Period versus Speed Mode

System Clock	Timer Period	Standard Mode	Timer Period	Fast Mode
4 Mhz	0x01	100 Kbps	-	-
6 Mhz	0x02	100 Kbps	-	-
12.5 Mhz	0x06	89 Kbps	0x01	312 Kbps
16.7 Mhz	0x08	93 Kbps	0x02	278 Kbps
20 Mhz	0x09	100 Kbps	0x02	333 Kbps
25 Mhz	0x0C	96.2 Kbps	0x03	312 Kbps
33Mhz	0x10	97.1 Kbps	0x04	330 Kbps
40Mhz	0x13	100 Kbps	0x04	400 Kbps

System Clock	Timer Period	Standard Mode	Timer Period	Fast Mode
50Mhz	0x18	100 Kbps	0x06	357 Kbps

15.2.3 Interrupts

The I²C can generate interrupts when the following conditions are observed:

- Master transaction completed
- Master transaction error
- Slave transaction received
- Slave transaction requested

There is a separate interrupt signal for the I²C master and I²C modules. While both modules can generate interrupts for multiple conditions, only a single interrupt signal is sent to the interrupt controller.

15.2.3.1 I²C Master Interrupts

The I^2C master module generates an interrupt when a transaction completes (either transmit or receive), or when an error occurs during a transaction. To enable the I^2C master interrupt, software must write a '1' to the I^2C Master Interrupt Mask (I2CMIMR) register. When an interrupt condition is met, software must check the ERROR bit in the I^2C Master Control/Status (I2CMCS) register to verify that an error didn't occur during the last transaction. An error condition is asserted if the last transaction wasn't acknowledge by the slave or if the master was forced to give up ownership of the bus due to a lost arbitration round with another master. If an error is not detected, the application can proceed with the transfer. The interrupt is cleared by writing a '1' to the I^2C Master Interrupt Clear (I2CMICR) register.

If the application doesn't require the use of interrupts, the raw interrupt status is always visible via the I^2C Master Raw Interrupt Status (I2CMRIS) register.

15.2.3.2 I²C Slave Interrupts

The slave module generates interrupts as it receives requests from an I^2C master. To enable the I^2C slave interrupt, write a '1' to the I^2C Slave Interrupt Mask (I2CSIMR) register. Software determines whether the module should write (transmit) or read (receive) data from the I^2C Slave Data (I2CSDR) register, by checking the RREQ and TREQ bits of the I^2C Slave Control/Status (I2CSCSR) register. If the slave module is in receive mode and the first byte of a transfer is received, the FBR bit is set along with the RREQ bit. The interrupt is cleared by writing a '1' to the I^2C Slave Interrupt Clear (I2CSICR) register.

If the application doesn't require the use of interrupts, the raw interrupt status is always visible via the I²C Slave Raw Interrupt Status (I2CSRIS) register.

15.2.4 Loopback Operation

The I 2 C modules can be placed into an internal loopback mode for diagnostic or debug work. This is accomplished by setting the LPBK bit in the I 2 C Master Configuration (I2CMCR) register. In loopback mode, the SDA and SCL signals from the master and slave modules are tied together.

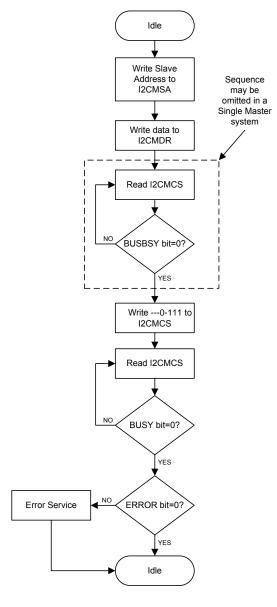
15.2.5 Command Sequence Flow Charts

This section details the steps required to perform the various I²C transfer types in both master and slave mode.

15.2.5.1 I²C Master Command Sequences

The figures that follow show the command sequences available for the I²C master.

Figure 15-7. Master Single SEND



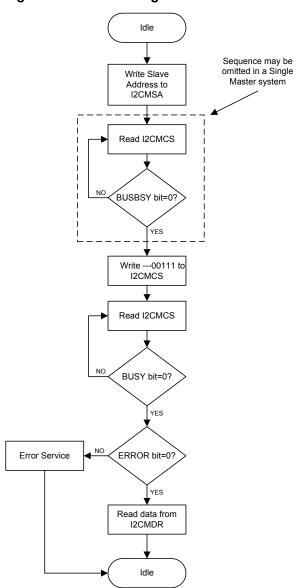


Figure 15-8. Master Single RECEIVE

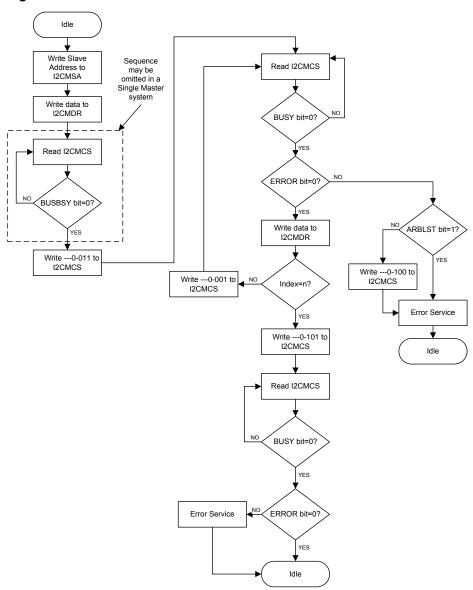


Figure 15-9. Master Burst SEND

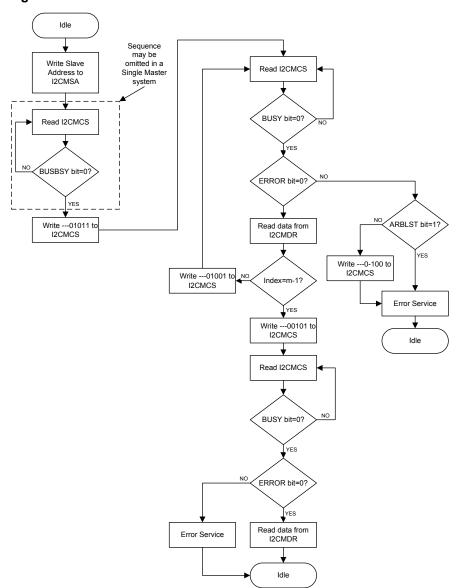


Figure 15-10. Master Burst RECEIVE

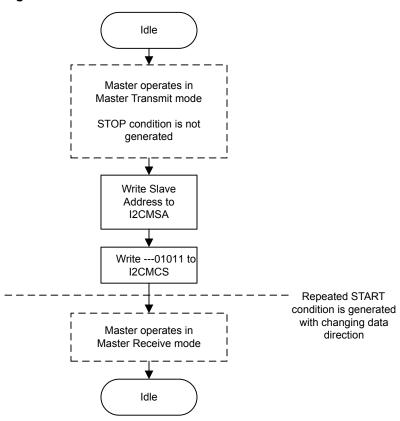


Figure 15-11. Master Burst RECEIVE after Burst SEND

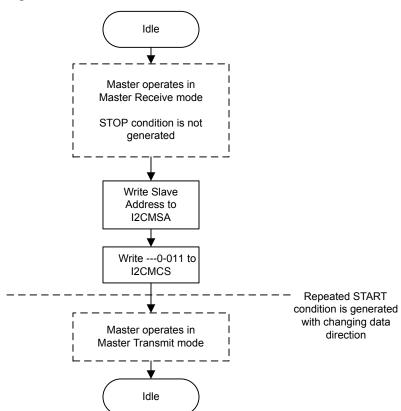


Figure 15-12. Master Burst SEND after Burst RECEIVE

15.2.5.2 I²C Slave Command Sequences

Figure 15-13 on page 370 presents the command sequence available for the $\ensuremath{\text{I}}^2\ensuremath{\text{C}}$ slave.

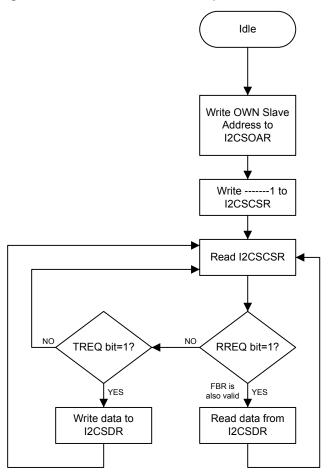


Figure 15-13. Slave Command Sequence

15.3 Initialization and Configuration

The following example shows how to configure the I²C module to send a single byte as a master. This assumes the system clock is 20 MHz.

- 1. Enable the I²C clock by writing a value of 0x0000.1000 to the **RCGC1** register in the System Control module.
- Enable the clock to the appropriate GPIO module via the RCGC2 register in the System Control module.
- 3. In the GPIO module, enable the appropriate pins for their alternate function using the **GPIOAFSEL** register. Also, be sure to enable the same pins for Open Drain operation.
- 4. Initialize the I²C Master by writing the **I2CMCR** register with a value of 0x0000.0020.
- 5. Set the desired SCL clock speed of 100 Kbps by writing the **I2CMTPR** register with the correct value. The value written to the **I2CMTPR** register represents the number of system clock periods in one SCL clock period. The TPR value is determined by the following equation:

```
TPR = (System Clock / (2 * (SCL_LP + SCL_HP) * SCL_CLK)) - 1;

TPR = (20MHz / (2 * (6 + 4) * 100000)) - 1;

TPR = 9
```

Write the **I2CMTPR** register with the value of 0x0000.0009.

- 6. Specify the slave address of the master and that the next operation will be a Send by writing the **I2CMSA** register with a value of 0x0000.0076. This sets the slave address to 0x3B.
- Place data (byte) to be sent in the data register by writing the I2CMDR register with the desired data.
- 8. Initiate a single byte send of the data from Master to Slave by writing the **I2CMCS** register with a value of 0x0000.0007 (STOP, START, RUN).
- 9. Wait until the transmission completes by polling the I2CMCS register's BUSBSY bit until it has been cleared.

15.4 I²C Register Map

"I²C Register Map" on page 371 lists the I²C registers. All addresses given are relative to the I²C base addresses for the master and slave:

I²C Master 0: 0x4002.0000

I²C Slave 0: 0x4002.0800

I²C Master 1: 0x4002.1000

I²C Slave 1: 0x4001.1800

Table 15-2. Inter-Integrated Circuit (I²C) Interface Register Map

Offset	Name	Туре	Reset	Description	See page
0x000	I2CMSA	R/W	0x0000.0000	I2C Master Slave Address	373
0x000	I2CSOAR	R/W	0x0000.0000	I2C Slave Own Address	386
0x004	I2CMCS	R/W	0x0000.0000	I2C Master Control/Status	374
0x004	I2CMCS	R/W	0x0000.0000	I2C Master Control/Status	374
0x004	I2CSCSR	RO	0x0000.0000	I2C Slave Control/Status	387
0x004	I2CSCSR	RO	0x0000.0000	I2C Slave Control/Status	387
0x008	I2CMDR	R/W	0x0000.0000	I2C Master Data	378
0x008	I2CSDR	R/W	0x0000.0000	I2C Slave Data	389
0x00C	I2CMTPR	R/W	0x0000.0001	I2C Master Timer Period	379
0x00C	I2CSIMR	R/W	0x0000.0000	I2C Slave Interrupt Mask	390
0x010	I2CMIMR	R/W	0x0000.0000	I2C Master Interrupt Mask	380
0x010	I2CSRIS	RO	0x0000.0000	I2C Slave Raw Interrupt Status	391

Offset	Name	Туре	Reset	Description	See page
0x014	I2CMRIS	RO	0x0000.0000	I2C Master Raw Interrupt Status	381
0x014	I2CSMIS	RO	0x0000.0000	I2C Slave Masked Interrupt Status	392
0x018	I2CMMIS	RO	0x0000.0000	I2C Master Masked Interrupt Status	382
0x018	I2CSICR	WO	0x0000.0000	I2C Slave Interrupt Clear	393
0x01C	I2CMICR	WO	0x0000.0000	I2C Master Interrupt Clear	383
0x020	I2CMCR	R/W	0x0000.0000	I2C Master Configuration	384

15.5 Register Descriptions (I²C Master)

The remainder of this section lists and describes the I²C master registers, in numerical order by address offset. See also "Register Descriptions (I2C Slave)" on page 385.

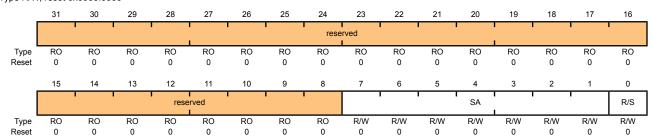
Register 1: I²C Master Slave Address (I2CMSA), offset 0x000

This register consists of eight bits: seven address bits (A6-A0), and a Receive/Send bit, which determines if the next operation is a Receive (High), or Send (Low).

I2C Master Slave Address (I2CMSA)

I2C Master 0 base: 0x4002.0000 I2C Master 1 base: 0x4002.1000 Offset 0x000

Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:1	SA	R/W	0	I ² C Slave Address This field specifies bits A6 through A0 of the slave address.
0	R/S	R/W	0	Receive/Send

The $\ensuremath{\mathbb{R}/S}$ bit specifies if the next operation is a Receive (High) or Send (Low).

0: Send

1: Receive

Register 2: I²C Master Control/Status (I2CMCS), offset 0x004

This register accesses four control bits when written, and accesses seven status bits when read.

The status register consists of seven bits, which when read determine the state of the I²C bus controller.

The control register consists of four bits: the RUN, START, STOP, and ACK bits. The START bit causes the generation of the START, or REPEATED START condition.

The STOP bit determines if the cycle stops at the end of the data cycle, or continues on to a burst. To generate a single send cycle, the I^2C Master Slave Address (I2CMSA) register is written with the desired address, the R/S bit is set to 0, and the Control register is written with ACK=X (0 or 1), STOP=1, START=1, and RUN=1 to perform the operation and stop. When the operation is completed (or aborted due an error), the interrupt pin becomes active and the data may be read from the I2CMDR register. When the I^2C module operates in Master receiver mode, the ACK bit must be set normally to logic 1. This causes the I^2C bus controller to send an acknowledge automatically after each byte. This bit must be reset when the I^2C bus controller requires no further data to be sent from the slave transmitter.

Read-Only Status Register

I2C Master Control/Status (I2CMCS)

I2C Master 0 base: 0x4002.0000 I2C Master 1 base: 0x4002.1000 Offset 0x004 Type R/W, reset 0x0000.0000

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
		1	1	1	, , ,		1	rese	rved I	1		1	1	1		1
Type	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
					reserved		1			BUSBSY	IDLE	ARBLST	DATACK	ADRACK	ERROR	BUSY
Type	RO	RO	RO	RO	RO	RO	RO	RO	RO	R	R	R	R	R	R	R
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Bit/Field	Name	Туре	Reset	Description
31:7	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
6	BUSBSY	R	0	This bit specifies the state of the I^2C bus. If set, the bus is busy; otherwise, the bus is idle. The bit changes based on the START and STOP conditions.
5	IDLE	R	0	This bit specifies the ${\rm I}^2{\rm C}$ controller state. If set, the controller is idle; otherwise the controller is not idle.
4	ARBLST	R	0	This bit specifies the result of bus arbitration. If set, the controller lost arbitration; otherwise, the controller won arbitration.
3	DATACK	R	0	This bit specifies the result of the last data operation. If set, the transmitted data was not acknowledged; otherwise, the data was acknowledged.

Bit/Field	Name	Type	Reset	Description
2	ADRACK	R	0	This bit specifies the result of the last address operation. If set, the transmitted address was not acknowledged; otherwise, the address was acknowledged.
1	ERROR	R	0	This bit specifies the result of the last bus operation. If set, an error occurred on the last operation; otherwise, no error was detected. The error can be from the slave address not being acknowledged, the transmit data not being acknowledged, or because the controller lost arbitration.
0	BUSY	R	0	This bit specifies the state of the controller. If set, the controller is busy; otherwise, the controller is idle. When the BUSY bit is set, the other status bits are not valid.

Write-Only Control Register

I2C Master Control/Status (I2CMCS)

I2C Master 0 base: 0x4002.0000 I2C Master 1 base: 0x4002.1000 Offset 0x004 Type R/W, reset 0x0000.0000

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
								rese	rved •					'		
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		'		'		reserved							ACK	STOP	START	RUN
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	W	W	W	W
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Bit/Field	Name	Туре	Reset	Description
31:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	ACK	W	0	When set, causes received data byte to be acknowledged automatically by the master. See field decoding in Table 15-3 on page 376.
2	STOP	W	0	When set, causes the generation of the STOP condition. See field decoding in Table 15-3 on page 376.
1	START	W	0	When set, causes the generation of a START or repeated START condition. See field decoding in Table 15-3 on page 376.
0	RUN	W	0	When set, allows the master to send or receive data. See field decoding in Table 15-3 on page 376.

Table 15-3. Write Field Decoding for I2CMCS[3:0] Field (Sheet 1 of 3)

	I2CMSA[0]		I2CMC	S[3:0]		Description
State	R/S	ACK	STOP	START	RUN	
Idle	0	X ^a	0	1	1	START condition followed by SEND (master goes to the Master Transmit state).
	0	Х	1	1	1	START condition followed by a SEND and STOP condition (master remains in Idle state).
	1	0	0	1	1	START condition followed by RECEIVE operation with negative ACK (master goes to the Master Receive state).
	1	0	1	1	1	START condition followed by RECEIVE and STOP condition (master remains in Idle state).
	1	1	0	1	1	START condition followed by RECEIVE (master goes to the Master Receive state).
	1	1	1	1	1	Illegal.
	All other co	mbinations	not listed	are non-or	perations.	NOP.
Master Transmit	Х	Х	0	0	1	SEND operation (master remains in Master Transmit state).
	Х	Х	1	0	0	STOP condition (master goes to Idle state).
	Х	Х	1	0	1	SEND followed by STOP condition (master goes to Idle state).
	0	Х	0	1	1	Repeated START condition followed by a SEND (master remains in Master Transmit state).
	0	Х	1	1	1	Repeated START condition followed by SEND and STOP condition (master goes to Idle state).
	1	0	0	1	1	Repeated START condition followed by a RECEIVE operation with a negative ACK (master goes to Master Receive state).
	1	0	1	1	1	Repeated START condition followed by a SEND and STOP condition (master goes to Idle state).
	1	1	0	1	1	Repeated START condition followed by RECEIVE (master goes to Master Receive state).
	1	1	1	1	1	Illegal.
	All other co	mbinations	s not listed	are non-or	perations.	NOP.

Current	I2CMSA[0]		I2CMC	S[3:0]		Description
State	R/S	ACK	STOP	START	RUN	
Master Receive	Х	0	0	0	1	RECEIVE operation with negative ACK (master remains in Master Receive state).
	Х	Х	1	0	0	STOP condition (master goes to Idle state). ^b
	Х	0	1	0	1	RECEIVE followed by STOP condition (master goes to Idle state).
	Х	1	0	0	1	RECEIVE operation (master remains in Master Receive state).
	Х	1	1	0	1	Illegal.
	1	0	0	1	1	Repeated START condition followed by RECEIVE operation with a negative ACK (master remains in Master Receive state).
	1	0	1	1	1	Repeated START condition followed by RECEIVE and STOP condition (master goes to Idle state).
	1	1	0	1	1	Repeated START condition followed by RECEIVE (master remains in Master Receive state).
	0	Х	0	1	1	Repeated START condition followed by SEND (master goes to Master Transmit state).
	0	Х	1	1	1	Repeated START condition followed by SEND and STOP condition (master goes to Idle state).
	All other co	mbinations	s not listed	are non-op	erations.	NOP.

a. An X in a table cell indicates the bit can be 0 or 1.

b. In Master Receive mode, a STOP condition should be generated only after a Data Negative Acknowledge executed by the master or an Address Negative Acknowledge executed by the slave.

Register 3: I²C Master Data (I2CMDR), offset 0x008

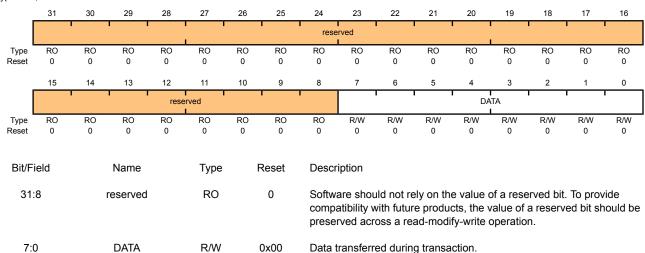
This register contains the data to be transmitted when in the Master Transmit state, and the data received when in the Master Receive state.

I2C Master Data (I2CMDR)

I2C Master 0 base: 0x4002.0000 I2C Master 1 base: 0x4002.1000

Offset 0x008

Type R/W, reset 0x0000.0000



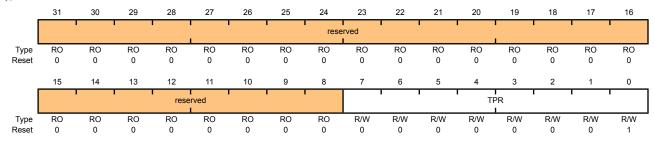
Register 4: I²C Master Timer Period (I2CMTPR), offset 0x00C

This register specifies the period of the SCL clock.

I2C Master Timer Period (I2CMTPR)

I2C Master 0 base: 0x4002.0000 I2C Master 1 base: 0x4002.1000 Offset 0x00C

Type R/W, reset 0x0000.0001



Bit/Field	Name	Type	Reset	Description
31:8	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7:0	TPR	R/W	0x1	This field specifies the period of the SCL clock.

SCL_PRD = 2*(1 + TPR)*(SCL_LP + SCL_HP)*CLK_PRD

where:

 SCL_PRD is the SCL line period (I 2 C clock).

 $\ensuremath{\mathtt{TPR}}$ is the Timer Period register value (range of 1 to 255).

 SCL_LP is the SCL Low period (fixed at 6).

SCL_HP is the SCL High period (fixed at 4).

Register 5: I²C Master Interrupt Mask (I2CMIMR), offset 0x010

This register controls whether a raw interrupt is promoted to a controller interrupt.

I2C Master Interrupt Mask (I2CMIMR)

I2C Master 0 base: 0x4002.0000 I2C Master 1 base: 0x4002.1000 Offset 0x010 Type R/W, reset 0x0000.0000

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
		'					'	rese	rved							•
Type	RO	RO	RO	RO	RO	RO	RO	RO	RO							
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		1														IM
					ı			reserved								IIVI
Type	RO	RO	RO	RO	RO	RO	RO	RO	R/W							
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Bit/Field	Name	Туре	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	IM	R/W	0	This bit controls whether a raw interrupt is promoted to a controller interrupt. If set, the interrupt is not masked and the interrupt is promoted;

otherwise, the interrupt is masked.

Register 6: I²C Master Raw Interrupt Status (I2CMRIS), offset 0x014

This register specifies whether an interrupt is pending.

I2C Master Raw Interrupt Status (I2CMRIS)

I2C Master 0 base: 0x4002.0000 I2C Master 1 base: 0x4002.1000 Offset 0x014 Type RO, reset 0x0000.0000

J1 ,																
	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
		1	1	1	· · ·		1	rese	i erved i		1	1	· ·	1		1
Type	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
				1			•	reserved	 			1				RIS
Type	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Bit/F	ield		Name		Туре	F	Reset	Descr	ription							
31:	:1		reserved	i	RO		0	Softw	are shou	ld not re	ely on th	e value	of a rese	rved bit.	To prov	vide .

Dil/Fielu	INAITIE	Type	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	RIS	RO	0	This bit specifies the raw interrupt state (prior to masking) of the I ² C

This bit specifies the raw interrupt state (prior to masking) of the I²C master block. If set, an interrupt is pending; otherwise, an interrupt is not pending.

Register 7: I²C Master Masked Interrupt Status (I2CMMIS), offset 0x018

This register specifies whether an interrupt was signaled.

I2C Master Masked Interrupt Status (I2CMMIS)

I2C Master 0 base: 0x4002.0000 I2C Master 1 base: 0x4002.1000 Offset 0x018 Type RO, reset 0x0000.0000

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
				'				rese	rved I							'
Type	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
					! !			reserved	! ! !							MIS
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Bit/Field	Name	Туре	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	MIS	RO	0	This bit specifies the raw interrupt state (after masking) of the I ² C master block. If set, an interrupt was signaled; otherwise, an interrupt has not been generated since the bit was last cleared.

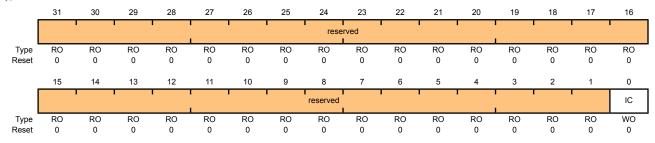
Register 8: I²C Master Interrupt Clear (I2CMICR), offset 0x01C

This register clears the raw interrupt.

I2C Master Interrupt Clear (I2CMICR)

I2C Master 0 base: 0x4002.0000 I2C Master 1 base: 0x4002.1000 Offset 0x01C

Type WO, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	IC	WO	0	Interrupt Clear

This bit controls the clearing of the raw interrupt. A write of 1 clears the interrupt; otherwise, a write of 0 has no affect on the interrupt state. A read of this register returns no meaningful data.

Register 9: I²C Master Configuration (I2CMCR), offset 0x020

This register configures the mode (Master or Slave) and sets the interface for test mode loopback.

I2C Master Configuration (I2CMCR)

I2C Master 0 base: 0x4002.0000 I2C Master 1 base: 0x4002.1000 Offset 0x020 Type R/W, reset 0x0000.0000

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
			1					rese	rved					' '		1
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0										
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
			'		rese	rved		•			SFE	MFE		reserved		LPBK
Type Reset	RO 0	R/W 0	R/W 0	RO 0	RO 0	RO 0	R/W 0									

Bit/Field	Name	Туре	Reset	Description
31:6	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
5	SFE	R/W	0	I ² C Slave Function Enable
				This bit specifies whether the interface may operate in Slave mode. If set, Slave mode is enabled; otherwise, Slave mode is disabled.
4	MFE	R/W	0	I ² C Master Function Enable
				This bit specifies whether the interface may operate in Master mode. If set, Master mode is enabled; otherwise, Master mode is disabled and the interface clock is disabled.
3:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	LPBK	R/W	0	I ² C Loopback

This bit specifies whether the interface is operating normally or in Loopback mode. If set, the device is put in a test mode loopback configuration; otherwise, the device operates normally.

15.6 Register Descriptions (I2C Slave)

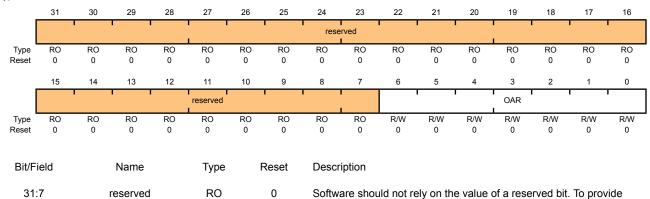
The remainder of this section lists and describes the I^2C slave registers, in numerical order by address offset. See also "Register Descriptions (I^2C Master)" on page 372.

Register 10: I²C Slave Own Address (I2CSOAR), offset 0x000

This register consists of seven address bits that identify the Stellaris[®] I²C device on the I²C bus.

I2C Slave Own Address (I2CSOAR)

I2C Slave 0 base: 0x4002.0800 I2C Slave 1 base: 0x4001.1800 Offset 0x000 Type R/W, reset 0x0000.0000



compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

OAR R/W 0 I²C Slave Own Address 6:0

This field specifies bits A6 through A0 of the slave address.

Register 11: I²C Slave Control/Status (I2CSCSR), offset 0x004

This register accesses one control bit when written, and three status bits when read.

The read-only Status register consists of three bits: the FBR, RREQ, and TREQ bits. The First Byte Received (FBR) bit is set only after the Stellaris® device detects its own slave address and receives the first data byte from the I^2C master. The Receive Request (RREQ) bit indicates that the Stellaris® I^2C device has received a data byte from an I^2C master. Read one data byte from the I^2C Slave Data (I2CSDR) register to clear the RREQ bit. The Transmit Request (TREQ) bit indicates that the Stellaris® I^2C device is addressed as a Slave Transmitter. Write one data byte into the I^2C Slave Data (I2CSDR) register to clear the TREQ bit.

The write-only Control register consists of one bit: the DA bit. The DA bit enables and disables the Stellaris $^{\$}$ I 2 C slave operation.

Read-Only Status Register

I2C Slave Control/Status (I2CSCSR)

Name

I2C Slave 0 base: 0x4002.0800 I2C Slave 1 base: 0x4001.1800 Offset 0x004 Type RO, reset 0x0000.0000

Bit/Field

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
		1	'					rese	rved							
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0						
_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		'	'		1		reserved							FBR	TREQ	RREQ
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0						

Description

Reset

Type

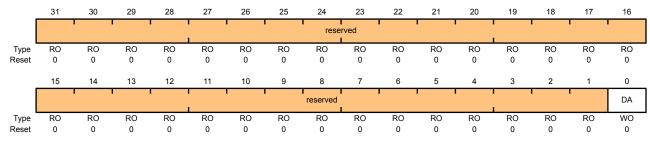
31:3	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
2	FBR	RO	0	Indicates that the first byte following the slave's own address is received. This bit is only valid when the RREQ bit is set, and is automatically cleared when data has been read from the I2CSDR register.
				Note: This bit is not used for slave transmit operations.
1	TREQ	RO	0	This bit specifies the state of the I^2C slave with regards to outstanding transmit requests. If set, the I^2C unit has been addressed as a slave transmitter and uses clock stretching to delay the master until data has been written to the I2CSDR register. Otherwise, there is no outstanding transmit request.
0	RREQ	RO	0	Receive Request

This bit specifies the status of the I^2C slave with regards to outstanding receive requests. If set, the I^2C unit has outstanding receive data from the I^2C master and uses clock stretching to delay the master until the data has been read from the **I2CSDR** register. Otherwise, no receive data is outstanding.

Write-Only Control Register

I2C Slave Control/Status (I2CSCSR)

I2C Slave 0 base: 0x4002.0800 I2C Slave 1 base: 0x4001.1800 Offset 0x004 Type RO, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	DA	WO	0	Device Active

1=Enables the I²C slave operation.

0=Disables the I²C slave operation.

Register 12: I²C Slave Data (I2CSDR), offset 0x008

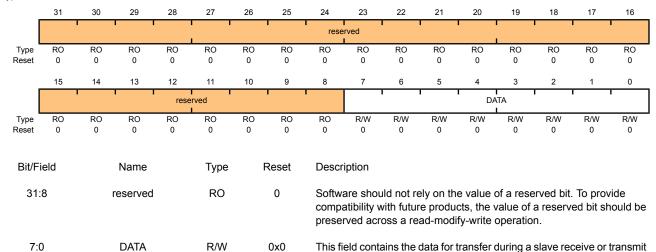
This register contains the data to be transmitted when in the Slave Transmit state, and the data received when in the Slave Receive state.

I2C Slave Data (I2CSDR)

I2C Slave 0 base: 0x4002.0800 I2C Slave 1 base: 0x4001.1800

Offset 0x008

Type R/W, reset 0x0000.0000



operation.

Register 13: I²C Slave Interrupt Mask (I2CSIMR), offset 0x00C

This register controls whether a raw interrupt is promoted to a controller interrupt.

I2C Slave Interrupt Mask (I2CSIMR)

I2C Slave 0 base: 0x4002.0800 I2C Slave 1 base: 0x4001.1800 Offset 0x00C Type R/W, reset 0x0000.0000

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
				_				rese	rved					1		'
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0							
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
								reserved								IM
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	R/W 0							

Bit/Field	Name	Type	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	IM	R/W	0	This bit controls whether a raw interrupt is promoted to a controller interrupt. If set, the interrupt is not masked and the interrupt is promoted:

otherwise, the interrupt is masked.

Register 14: I²C Slave Raw Interrupt Status (I2CSRIS), offset 0x010

This register specifies whether an interrupt is pending.

I2C Slave Raw Interrupt Status (I2CSRIS)

I2C Slave 0 base: 0x4002.0800 I2C Slave 1 base: 0x4001.1800 Offset 0x010 Type RO, reset 0x0000.0000

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
				'				rese	rved							'
Type	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
					! !			reserved	' '	<u> </u>						RIS
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Bit/Field	Name	Type	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	RIS	RO	0	This bit specifies the raw interrupt state (prior to masking) of the I ² C slave block. If set, an interrupt is pending; otherwise, an interrupt is not

pending.

Register 15: I²C Slave Masked Interrupt Status (I2CSMIS), offset 0x014

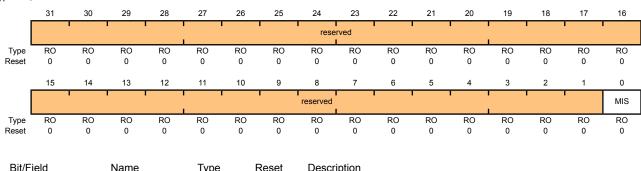
This register specifies whether an interrupt was signaled.

I2C Slave Masked Interrupt Status (I2CSMIS)

I2C Slave 0 base: 0x4002.0800 I2C Slave 1 base: 0x4001.1800

Offset 0x014

Type RO, reset 0x0000.0000



Birrieid	Name	туре	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	MIS	RO	0	This bit specifies the raw interrupt state (after masking) of the I ² C slave

block. If set, an interrupt was signaled; otherwise, an interrupt has not been generated since the bit was last cleared.

Register 16: I²C Slave Interrupt Clear (I2CSICR), offset 0x018

This register clears the raw interrupt.

I2C Slave Interrupt Clear (I2CSICR)

I2C Slave 0 base: 0x4002.0800 I2C Slave 1 base: 0x4001.1800 Offset 0x018 Type WO, reset 0x0000.0000

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
				•				rese	rved I							'
Type	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
				•	! !			reserved	' ' -							IC
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	WO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Bit/Field	Name	Type	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	IC	WO	0	This bit controls the clearing of the raw interrupt. A write of 1 clears the interrupt; otherwise a write of 0 has no affect on the interrupt state. A read of this register returns no meaningful data.

16 Controller Area Network (CAN) Module

16.1 Controller Area Network Overview

Controller Area Network (CAN) is a multicast shared serial bus standard for connecting electronic control units (ECUs). CAN was specifically designed to be robust in electromagnetically noisy environments and can utilize a differential balanced line like RS-485 or a more robust twisted-pair wire. Originally created for automotive purposes, it is also used in many embedded control applications (such as industrial and medical). Bit rates up to 1 Mbps are possible at network lengths below 40 meters. Decreased bit rates allow longer network distances (for example, 125 Kbps at 500 m).

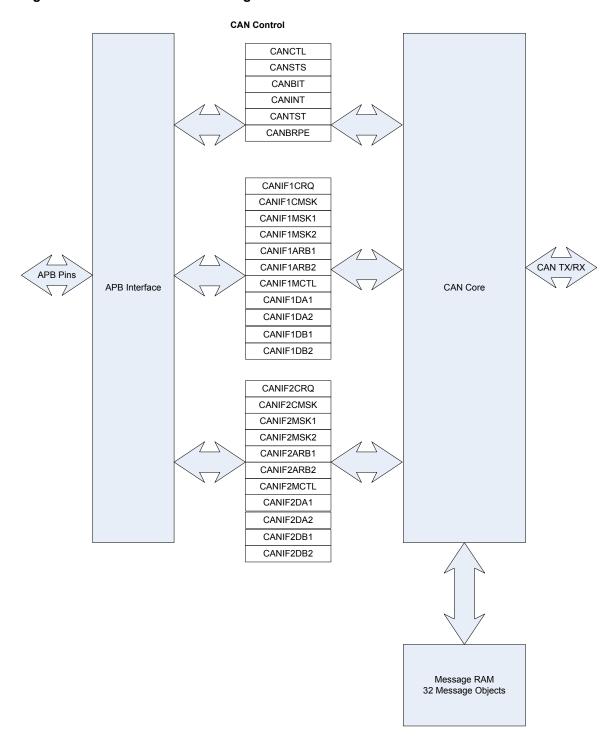
16.2 Controller Area Network Features

The Stellaris[®] CAN module supports the following features:

- CAN protocol version 2.0 part A/B.
- Bit rates up to 1 Mbps.
- 32 message objects.
- Each message object has its own identifier mask.
- Maskable interrupt.
- Disable Automatic Retransmission mode for Time Triggered CAN (TTCAN) applications.
- Programmable Loopback mode for self-test operation.
- Programmable FIFO mode.
- Gluelessly attach to an external CAN PHY through the CANOTX and CANORX pins.

16.3 Controller Area Network Block Diagram

Figure 16-1. CAN Module Block Diagram



16.4 Controller Area Network Functional Description

The CAN module conforms to the CAN protocol version 2.0 (parts A and B). Message transfers that include data, remote, error, and overload frames with an 11-bit identifier (standard) or a 29-bit identifier (extended) are supported. Transfer rates can be programmed up to 1 Mbps.

The CAN module consists of three major parts:

- CAN protocol controller and message handler
- Message memory
- CAN register interface

The protocol controller transfers and receives the serial data from the CAN bus and passes the data on to the message handler. The message handler then loads this information into the appropriate message object based on the current filtering and identifiers in the message object memory. The message handler is also responsible for generating interrupts based on events on the CAN bus.

The message object memory is a set of 32 identical memory blocks that hold the current configuration, status, and actual data for each message object. These are accessed via the CAN message object register interface. The message memory is not directly accessable in the Stellaris memory map, so the Stellaris[®] CAN controller provides an interface to communicate with the message memory.

The CAN message object register interface provides two register sets for communicating with the message objects. Since there is no direct access to the message object memory, these two interfaces must be used to read or write to each message object. The two message object interfaces allow parallel access to the CAN controller message objects when multiple objects may have new information that needs to be processed.

16.4.1 Initialization

The software initialization is started by setting the INIT bit in the **CAN Control (CANCTL)** register, with software or by a hardware reset, or by going bus-off, which occurs when the transmitter's error counter exceeds a count of 255. While INIT is set, all message transfers to and from the CAN bus are stopped and the status of the CAN transmit output is recessive (High). Entering the initialization state does not change the configuration of the CAN controller, the message objects or the error counters. However, some configuration registers are only accessible when in the initialization state.

To initialize the CAN controller, set the **CAN Bit Timing (CANBIT)** register and configure each message object. If a message object is not needed, it is sufficient to set it as not valid by clearing the MsgVal bit in the **CANIFnARB2** register. Otherwise, the whole message object has to be initialized, as the fields of the message object may not have valid information causing unexpected results. Access to the **CAN Bit Timing (CANBIT)** register and to the **CAN Baud Rate Prescalar Extension (CANBRPE)** register to configure the bit timing are enabled when both the INIT and CCE bits in the **CANCTL** register are set. To leave the initialization state, the INIT bit must be cleared. Afterwards, the internal Bit Stream Processor (BSP)synchronizes itself to the data transfer on the CAN bus by waiting for the occurrence of a sequence of 11 consecutive recessive bits (Bus Idle) before it takes part in bus activities and starts message transfers. The initialization of the message objects is independent of being in the initialization state and can be done on the fly, but message objects should all be configured to particular identifiers or set to not valid before the BSP starts the message transfer. To change the configuration of a message object during normal operation, set the MsgVal bit in the **CANIFnARB2** register to 0 (not valid). When the configuration is completed, MsgVal is set to 1 again (valid).

16.4.2 Operation

Once the CAN module is initialized and the INIT bit in the **CANCTL** register is reset to 0, the CAN module synchronizes itself to the CAN bus and starts the message transfer. As messages are received, they are stored in their appropriate message objects if they pass the message handler's filtering. The whole message (including all arbitration bits, data-length code, and eight data bytes) is stored in the message object. If the Identifier Mask (the Msk bits in the **CANIFnMSKn** registers) is used, the arbitration bits which are masked to "don't care" may be overwritten in the message object.

The CPU may read or write each message any time via the CAN Interface Registers (CANIFnCRQ, CANIFnCMSK, CANIFnMSKn, CANIFnARBn, CANIFnMCTL, CANIFnDAn, and CANIFnDBn). The message handler guarantees data consistency in case of concurrent accesses.

The transmission of message objects are under the control of the software that is managing the CAN hardware. These can be message objects used for one-time data transfers, or permanent message objects used to respond in a more periodic manner. Permanent message objects have all arbitration and control set up and only the data bytes are updated. To start the transmission, the \mathtt{TxRqst} bit in the **CANTXRQn** register and the \mathtt{NewDat} bit in the **CANNWDAn** register are set. If several transmit messages are assigned to the same message object (when the number of message objects is not sufficient), the whole message object has to be configured before the transmission of this message is requested.

The transmission of any number of message objects may be requested at the same time; they are transmitted according to their internal priority, which is based on the message identifier for the message object. Messages may be updated or set to not valid any time, even when their requested transmission is still pending. The old data is discarded when a message is updated before its pending transmission has started. Depending on the configuration of the message object, the transmission of a message may be requested autonomously by the reception of a remote frame with a matching identifier.

There are two sets of CAN Interface Registers (**CANIF1x** and **CANIF2x**) which are used to access the Message Objects in the Message RAM. The CAN controller coordinates transfers to and from the Message RAM to and from the registers. The function of the two sets are independent and identical and can be used to gueue transactions.

16.4.3 Transmitting Message Objects

If the internal transmit shift register of the CAN module is ready for loading, and if there is no data transfer between the CAN Interface Registers and message RAM, the valid message object with the highest priority and which has a pending transmission request is loaded into the transmit shift register by the message handler and the transmission is started. The message object's NewDat bit is reset and can be viewed in the CANNWDAn register. After a successful transmission, and if no new data was written to the message object since the start of the transmission, the TxRqst bit in the CANIFnCMSK register is reset. If the TxIE bit in the CANIFnMCTL register is set, the IntPnd bit in the CANIFnMCTL register is set after a successful transmission. If the CAN module has lost the arbitration or if an error occurred during the transmission, the message is re-transmitted as soon as the CAN bus is free again. If, meanwhile, the transmission of a message with higher priority has been requested, the messages are transmitted in the order of their priority.

16.4.4 Configuring a Transmit Message Object

Table 16-1 on page 398 specifies the bit settings for a transmit message object.

Table 16-1. Transmit Message Object Bit Settings

Register	CANIFnARB2	CAI	CANIFnCMSK (CANIFnMCTL	CANIFnARB2	CANIFnMCTL						
Bit	MsgVal	Arb	Data	Mask	EoB	Dir	NewDat	MsgLst	RxIE	TxIE	IntPnd	RmtEn	TxRqst
Value	1	appl	appl	appl	1	1	0	0	0	appl	0	appl	0

The Xtd and ID bit fields in the **CANIFnARBn** registers are set by an application. They define the identifier and type of the outgoing message. If an 11-bit Identifier (Standard Frame) is used, it is programmed to bits [28:18] of **CANIFnARB1**, as bits 17:0 of **CANIFnARBn** are not used by the CAN controller for 11-bit identifiers.

If the TxIE bit is set, the IntPnd bit is set after a successful transmission of the message object.

If the RmtEn bit is set, a matching received Remote Frame causes the TxRqst bit to be set and the Remote Frame is autonomously answered by a Data Frame with the data from the message object.

The DLC bit in the **CANIFNMCTL** register is set by an application. TxRqst and RmtEn may not be set before the data is valid.

The CAN mask registers (Msk bits in CANIFnMSKn, UMask bit in CANIFnMCTL register, and MXtd and MDir bits in CANIFnMSK2 register) may be used (UMask=1) to allow groups of Remote Frames with similar identifiers to set the TxRqst bit. The Dir bit should not be masked.

16.4.5 Updating a Transmit Message Object

The CPU may update the data bytes of a Transmit Message Object any time via the CAN Interface Registers and neither the MsgVal nor the TxRqst bits have to be reset before the update.

Even if only a part of the data bytes are to be updated, all four bytes of the corresponding **CANIFnDAn** or **CANIFnDBn** register have to be valid before the content of that register is transferred to the message object. Either the CPU has to write all four bytes into the **CANIFnDAn** or **CANIFnDBn** register or the message object is transferred to the **CANIFnDAn** or **CANIFnDBn** register before the CPU writes the new data bytes.

In order to just update the data in a message object, the WR, NewDat, DataA, and DataB bits are written to the CAN IFn Command Mask (CANIFnMSKn) register, followed by writing the CAN IFn Data registers, and then the number of the message object is written to the CAN IFn Command Request (CANIFnCRQ) register, to update the data bytes and the TxRqst bit at the same time.

To prevent the reset of TxRqst at the end of a transmission that may already be in progress while the data is updated, NewDat has to be set together with TxRqst. When NewDat is set together with TxRqst, NewDat is reset as soon as the new transmission has started.

16.4.6 Accepting Received Message Objects

When the arbitration and control field (ID + Xtd + RmtEn + DLC) of an incoming message is completely shifted into the CAN module, the message handling capability of the module starts scanning the message RAM for a matching valid message object. To scan the message RAM for a matching message object, the Acceptance Filtering unit is loaded with the arbitration bits from the core. Then the arbitration and mask fields (including MsgVal, UMask, NewDat, and EoB) of message object 1 are loaded into the Acceptance Filtering unit and compared with the arbitration field from the shift register. This is repeated with each following message object until a matching message object is found or until the end of the message RAM is reached. If a match occurs, the scanning is stopped and the message handler proceeds depending on the type of frame received.

16.4.7 Receiving a Data Frame

The message handler stores the message from the CAN module receive shift register into the respective message object in the message RAM. It stores the data bytes, all arbitration bits, and the Data Length Code into the corresponding message object. This is implemented to keep the data bytes connected with the identifier even if arbitration mask registers are used. The CANIFnMCTL.NewDat bit is set to indicate that new data has been received. The CPU should reset CANIFnMCTL.NewDat when it reads the message object to indicate to the controller that the message has been received and the buffer is free to receive more messages. If the CAN controller receives a message and the CANIFnMCTL.NewDat bit was already set, the MsgLst bit is set to indicate that the previous data was lost. If the CANIFnMCTL.RxIE bit is set, the CANIFnMCTL.IntPnd bit is set, causing the CANIFnMCTL.RxIE bit opinit to the message object that just received a message. The CANIFnMCTL.TxRqst bit of this message object is reset to prevent the transmission of a Remote Frame, while the requested Data Frame has just been received.

16.4.8 Receiving a Remote Frame

When a Remote Frame is received, three different configurations of the matching message object have to be considered:

- Dir = 1 (direction = transmit), RmtEn = 1, UMask = 1 or 0
 - At the reception of a matching Remote Frame, the TxRqst bit of this message object is set. The rest of the message object remains unchanged.
- Dir = 1 (direction = transmit), RmtEn = 0, UMask = 0

At the reception of a matching Remote Frame, the TxRqst bit of this message object remains unchanged; the Remote Frame is ignored. This remote frame is disabled and will not automatically respond or indicate that the remote frame ever happened.

■ Dir = 1 (direction = transmit), RmtEn = 0, UMask = 1

At the reception of a matching Remote Frame, the \mathtt{TxRqst} bit of this message object is reset. The arbitration and control field ($\mathtt{ID} + \mathtt{Xtd} + \mathtt{RmtEn} + \mathtt{DLC}$) from the shift register is stored into the message object in the message RAM and the \mathtt{NewDat} bit of this message object is set. The data field of the message object remains unchanged; the Remote Frame is treated similar to a received Data Frame. This is useful for a remote data request from another CAN device for which the Stellaris controller does not have readily available data The software must fill the data and answer the frame manually.

16.4.9 Receive/Transmit Priority

The receive/transmit priority for the message objects is controlled by the message number. Message object 1 has the highest priority, while message object 32 has the lowest priority. If more than one transmission request is pending, the message objects are transmitted in order based on the message object with the lowest message number. This should not be confused with the message identifier as that priority is enforced by the CAN bus. This means that if message object 1 and message object 2 both have valid messages that need to be transmitted, message object 1 will always be transmitted first regardless of the message identifier in the message object itself.

16.4.10 Configuring a Receive Message Object

Table 16-2 on page 400 specifies the bit settings for a transmit message object.

Table 16-2. Receive Message Object Bit Settings

Regi	ister	CANIFnARB2	CA	CANIFnCMSK C		CANIFnMCTL	CANIFnARB2	CANIFnMCTL						
В	it	MsgVal	Arb	Data	Mask	EoB	Dir	NewDat	MsgLst	RxIE	TxIE	IntPnd	RmtEn	TxRqst
Val	lue	1	appl	appl	appl	1	0	0	0	appl	0	0	0	0

The CAN arbitration registers (ID[28:0] and Xtd bit) are set by an application. They define the identifier and type of accepted received messages. If an 11-bit Identifier (Standard Frame) is used, it is programmed to ID[28:18] and ID[17:0] are ignored by the CAN controller. When a Data Frame with an 11-bit Identifier is received, the ID[17:0] field is set to 0.

If the RXIE bit is set, the IntPnd bit is set when a received Data Frame is accepted and stored in the message object.

When the message handler stores a Data Frame in the message object, it stores the received Data Length Code and eight data bytes. If the Data Length Code is less than 8, the remaining bytes of the message object are overwritten by nonspecified values.

The CAN mask registers (Msk bits in **CANIFnMSKn**, UMask bit in **CANIFnMCTL** register, and MXtd and MDir bits in **CANIFnMSK2** register) may be used (UMask=1) to allow groups of Data Frames with similar identifiers to be accepted. The Dir bit should not be masked in typical applications.

16.4.11 Handling of Received Message Objects

The CPU may read a received message any time via the CAN Interface registers because the data consistency is guaranteed by the message handler state machine.

Typically, the CPU first writes 0x007F to the CAN IFn Command Mask (CANIFnCMSK) register and then writes the number of the message object to the CAN IFn Command Request (CANIFnCRQ) register. That combination transfers the whole received message from the message RAM into the Message Buffer registers (CANIFnMSKn, CANIFnARBn, and CANIFnMCTL). Additionally, the NewDat and IntPnd bits are cleared in the message RAM, acknowledging that the message has been read and clearing the pending interrupt being generated by this message object.

If the message object uses masks for acceptance filtering, the arbitration bits show which of the matching messages has been received.

The actual value of NewDat shows whether a new message has been received since the last time this message object was read. The actual value of MsgLst shows whether more than one message has been received since the last time this message object was read. MsgLst is not automatically reset.

Using a Remote Frame, the CPU may request new data from another CAN node on the CAN bus. Setting the \mathtt{TxRqst} bit of a receive object causes the transmission of a Remote Frame with the receive object's identifier. This Remote Frame triggers the other CAN node to start the transmission of the matching Data Frame. If the matching Data Frame is received before the Remote Frame could be transmitted, the \mathtt{TxRqst} bit is automatically reset. This prevents the possible loss of data when the other device on the CAN bus has already transmitted the data, slightly earlier than expected.

16.4.12 Handling of Interrupts

If several interrupts are pending, the **CAN Interrupt (CANINT)** register points to the pending interrupt with the highest priority, disregarding their chronological order. An interrupt remains pending until the CPU has cleared it.

The Status Interrupt has the highest priority. Among the message interrupts, the message object's interrupt priority decreases with increasing message number. A message interrupt is cleared by clearing the message object's IntPnd bit. The Status Interrupt is cleared by reading the **CAN Status** (**CANSTS**) register.

The interrupt identifier Intid in the CANINT register indicates the cause of the interrupt. When no interrupt is pending, the register holds the value to 0. If the value of CANINT is different from 0, then there is an interrupt pending. If the IE bit is set in the CANCTL register, the interrupt line to the CPU is active. The interrupt line remains active until **CANINT** is 0, all interrupt sources have been cleared, (the cause of the interrupt is reset), or until IE is reset, which disables interrupts from the CAN controller.

The value 0x8000 in the **CANINT** register indicates that an interrupt is pending because the CAN module has updated, but not necessarily changed the **CANSTS** register (Error Interrupt or Status Interrupt). This indicates that there is either a new Error Interrupt or a new Status Interrupt. A write access can clear the RxOK, TxOK, and LEC flags in the **CANSTS** register, however, only a read access to the **CANSTS** register will clear the source of the status interrupt.

IntId points to the pending message interrupt with the highest interrupt priority. The SIE bit in the **CANCTL** register controls whether a change of the status register may cause an interrupt. The EIE bit in the **CANCTL** register controls whether any interrupt from the CAN controller actually generates an interrupt to the microcontroller's interrupt controller. The **CANINT** interrupt register is updated even when the IE bit is set to zero.

There are two possibilities when handling the source of a message interrupt. The first is to read the IntId bit in the **CANINT** interrupt register to determine the highest priority interrupt that is pending, and the second is to read the **CAN Message Interrupt Pending (CANMSGnINT)** register to see all of the message objects that have pending interrupts.

An interrupt service routine reading the message that is the source of the interrupt may read the message and reset the message object's IntPnd at the same time by setting the ClrIntPnd bit in the CAN IFn Command Mask (CANIFnCMSK) register. When the IntPnd bit is cleared, the CANINT register will contain the message number for the next message object with a pending interrupt.

16.4.13 Bit Timing Configuration Error Considerations

Even if minor errors in the configuration of the CAN bit timing do not result in immediate failure, the performance of a CAN network can be reduced significantly. In many cases, the CAN bit synchronization amends a faulty configuration of the CAN bit timing to such a degree that only occasionally an error frame is generated. In the case of arbitration, however, when two or more CAN nodes simultaneously try to transmit a frame, a misplaced sample point may cause one of the transmitters to become error passive. The analysis of such sporadic errors requires a detailed knowledge of the CAN bit synchronization inside a CAN node and of the CAN nodes' interaction on the CAN bus.

16.4.14 Bit Time and Bit Rate

The CAN system supports bit rates in the range of lower than 1 Kbps up to 1000 Kbps. Each member of the CAN network has its own clock generator. The timing parameter of the bit time can be configured individually for each CAN node, creating a common bit rate even though the CAN nodes' oscillator periods may be different.

Because of small variations in frequency caused by changes in temperature or voltage and by deteriorating components, these oscillators are not absolutely stable. As long as the variations

remain inside a specific oscillator's tolerance range, the CAN nodes are able to compensate for the different bit rates by periodically resynchronizing to the bit stream.

According to the CAN specification, the bit time is divided into four segments (see Figure 16-2 on page 402): the Synchronization Segment, the Propagation Time Segment, the Phase Buffer Segment 1, and the Phase Buffer Segment 2. Each segment consists of a specific, programmable number of time quanta (see Table 16-3 on page 402). The length of the time quantum (tq), which is the basic time unit of the bit time, is defined by the CAN controller's system clock (fsys) and the Baud Rate Prescaler (grap):

The CAN module's system clock fsys is the frequency of its CAN module clock (CAN_CLK) input.

The Synchronization Segment Sync_Seg is that part of the bit time where edges of the CAN bus level are expected to occur; the distance between an edge that occurs outside of Sync_Seg and the Sync_Seg is called the *phase error* of that edge.

The Propagation Time Segment Prop_Seg is intended to compensate for the physical delay times within the CAN network.

The Phase Buffer Segments Phase_Seg1 and Phase_Seg2 surround the Sample Point.

The (Re-)Synchronization Jump Width (SJW) defines how far a resynchronization may move the Sample Point inside the limits defined by the Phase Buffer Segments to compensate for edge phase errors.

A given bit rate may be met by different bit-time configurations, but for the proper function of the CAN network, the physical delay times and the oscillator's tolerance range have to be considered.

Figure 16-2. CAN Bit Time

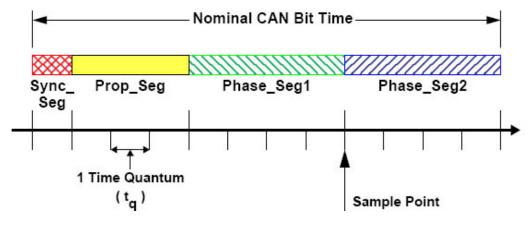


Table 16-3. CAN Protocol Ranges^a

Parameter	Range	Remark
BRP	[1 32]	Defines the length of the time quantum t _q
Sync_Seg	1 t _q	Fixed length, synchronization of bus input to system clock
Prop_Seg	[1 8] t _q	Compensates for the physical delay times
Phase_Seg1	[1 8] t _q	May be lengthened temporarily by synchronization
Phase_Seg2	[1 8] t _q	May be shortened temporarily by synchronization

Parameter	Range	Remark
SJW	[1 4] t _q	May not be longer than either Phase Buffer Segment

a. This table describes the minimum programmable ranges regired by the CAN protocol.

The bit timing configuration is programmed in two register bytes in the **CANBIT** register. The sum of Prop_Seg and Phase_Seg1 (as TSEG1) is combined with Phase_Seg2 (as TSEG2) in one byte, and SJW and BRP are combined in the other byte.

In these bit timing registers, the four components TSEG1, TSEG2, SJW, and BRP have to be programmed to a numerical value that is one less than its functional value; so instead of values in the range of [1..n], values in the range of [0..n-1] are programmed. That way, for example, SJW (functional range of [1..4]) is represented by only two bits. Therefore, the length of the bit time is (programmed values):

```
[TSEG1 + TSEG2 + 3] tq
or (functional values):
[Sync_Seg + Prop_Seg + Phase_Seg1 + Phase_Seg2] tq
```

The data in the bit timing registers are the configuration input of the CAN protocol controller. The Baud Rate Prescalar (configured by BRP) defines the length of the time quantum, the basic time unit of the bit time; the Bit Timing Logic (configured by TSEG1, TSEG2, and SJW) defines the number of time quanta in the bit time.

The processing of the bit time, the calculation of the position of the Sample Point, and occasional synchronizations are controlled by the CAN controller and are evaluated once per time quantum.

The CAN controller translates messages to and from frames. It generates and discards the enclosing fixed format bits, inserts and extracts stuff bits, calculates and checks the CRC code, performs the error management, and decides which type of synchronization is to be used. It is evaluated at the Sample Point and processes the sampled bus input bit. The time after the Sample Point that is needed to calculate the next bit to be sent (that is, the data bit, CRC bit, stuff bit, error flag, or idle) is called the Information Processing Time (IPT).

The IPT is application-specific but may not be longer than 2 tq; the CAN's IPT is 0 tq. Its length is the lower limit of the programmed length of $Phase_Seg2$. In case of synchronization, $Phase_Seg2$ may be shortened to a value less than IPT, which does not affect bus timing.

16.4.15 Calculating the Bit Timing Parameters

Usually, the calculation of the bit timing configuration starts with a desired bit rate or bit time. The resulting bit time (1/bit rate) must be an integer multiple of the system clock period.

The bit time may consist of 4 to 25 time quanta. Several combinations may lead to the desired bit time, allowing iterations of the following steps.

The first part of the bit time to be defined is the $Prop_Seg$. Its length depends on the delay times measured in the system. A maximum bus length as well as a maximum node delay has to be defined for expandable CAN bus systems. The resulting time for $Prop_Seg$ is converted into time quanta (rounded up to the nearest integer multiple of tq).

The $Sync_Seg$ is 1 tq long (fixed), which leaves (bit time - $Prop_Seg$ - 1) tq for the two Phase Buffer Segments. If the number of remaining tq is even, the Phase Buffer Segments have the same length, that is, $Phase_Seg2$ = $Phase_Seg1$, else $Phase_Seg2$ = $Phase_Seg1$ + 1.

The minimum nominal length of Phase_Seg2 has to be regarded as well. Phase_Seg2 may not be shorter than the CAN controller's Information Processing Time, which is, depending on the actual implementation, in the range of [0..2] tq.

The length of the Synchronization Jump Width is set to its maximum value, which is the minimum of 4 and Phase Seq1.

The oscillator tolerance range necessary for the resulting configuration is calculated by the formula given below:

```
(1 - df) \times fnom <= fosc <= (1 + df) \times fnom
```

where:

- df = maximum tolerance of oscillator frequency
- fosc = actual oscillator frequency
- fnom = nominal oscillator frequency

Maximum frequency tolerance must take into account the following formulas:

```
df <= (Phase_Seg1,Phase_Seg2)min/ 2 x (13 x tbit - Phase_Seg2)
dfmax = 2 x df x fnom</pre>
```

where:

- Phase_Seg1 and Phase_Seg2 are from Table 16-3 on page 402
- tbit = Bit Time
- dfmax = maximum difference between two oscillators

If more than one configuration is possible, that configuration allowing the highest oscillator tolerance range should be chosen.

CAN nodes with different system clocks require different configurations to come to the same bit rate. The calculation of the propagation time in the CAN network, based on the nodes with the longest delay times, is done once for the whole network.

The CAN system's oscillator tolerance range is limited by the node with the lowest tolerance range.

The calculation may show that bus length or bit rate have to be decreased or that the oscillator frequencies' stability has to be increased in order to find a protocol-compliant configuration of the CAN bit timing.

The resulting configuration is written into the CAN Bit Timing (CANBIT) register :

```
(Phase_Seg2-1)&(Phase_Seg1+Prop_Seg-1)&(SynchronizationJumpWidth-1)&(Prescaler-1)
```

16.4.15.1 Example for Bit Timing at High Baud Rate

In this example, the frequency of CAN_CLK is 10 MHz, BRP is 0, and the bit rate is 1 Mbps.

```
tq 100 ns = tCAN_CLK
delay of bus driver 50 ns
delay of receiver circuit 30 ns
delay of bus line (40m) 220 ns
```

```
tProp 600 ns = 6 × tq
tSJW 100 ns = 1 × tq
tTSeg1 700 ns = tProp + tSJW
tTSeg2 200 ns = Information Processing Time + 1 × tq
tSync-Seg 100 ns = 1 × tq
bit time 1000 ns = tSync-Seg + tTSeg1 + tTSeg2
tolerance for CAN_CLK 0.39 % =
    min(PB1,PB2)/ 2 × (13 x bit time - PB2) =
    0.1us/ 2 x (13x lus - 2us)
```

In the above example, the concatenated bit time parameters are (2-1)3&(7-1)4&(1-1)2&(1-1)6, and **CANBIT** is programmed to 0x1600.

16.4.15.2 Example for Bit Timing at Low Baud Rate

In this example, the frequency of CAN_CLK is 2 MHz, BRP is 1, and the bit rate is 100 Kbps.

```
tq 1 ms = 2 x tCAN_CLK
delay of bus driver 200 ns
delay of receiver circuit 80 ns
delay of bus line (40m) 220 ns
tProp 1 ms = 1 x tq
tSJW 4 ms = 4 x tq
tTSeg1 5 ms = tProp + tSJW
tTSeg2 4 ms = Information Processing Time + 3 x tq
tSync-Seg 1 ms = 1 x tq
bit time 10 ms = tSync-Seg + tTSeg1 + tTSeg2
tolerance for CAN_CLK 1.58 % =
   min(PB1,PB2)/ 2 x (13 x bit time - PB2) =
   4us/ 2 x (13 x 10us - 4us)
```

In this example, the concatenated bit time parameters are (4-1)3&(5-1)4&(4-1)2&(2-1)6, and **CANBIT** is programmed to 0x34C1.

16.5 Controller Area Network Register Map

"Controller Area Network Register Map" on page 405 lists the registers. All addresses given are relative to the CAN base address of:

CAN0: 0x4004.0000

All accesses are on word (32-bit) boundaries.

Table 16-4. CAN Register Map

Offset	Name	Туре	Reset	Description	See page
0x000	CANCTL	R/W	0x0000.0001	CAN Control	408
0x004	CANSTS	R/W	0x0000.0000	CAN Status	410
0x008	CANERR	RO	0x0000.0000	CAN Error Counter	413
0x00C	CANBIT	R/W	0x0000.2301	CAN Bit Timing	414
0x010	CANINT	RO	0x0000.0000	CAN Interrupt	416

0x014 0x018 0x020 0x024	CANTST CANBRPE	R/W			page
0x020			0x0000.0000	CAN Test	417
		R/W	0x0000.0000	CAN Baud Rate Prescalar Extension	419
0×024	CANIF1CRQ	R/W	0x0000.0001	CAN IF1 Command Request	420
0.024	CANIF1CMSK	R/W	0x0000.0000	CAN IF1 Command Mask	421
0x028	CANIF1MSK1	R/W	0x0000.FFFF	CAN IF1 Mask 1	424
0x02C	CANIF1MSK2	R/W	0x0000.FFFF	CAN IF1 Mask 2	425
0x030	CANIF1ARB1	R/W	0x0000.0000	CAN IF1 Arbitration 1	426
0x034	CANIF1ARB2	R/W	0x0000.0000	CAN IF1 Arbitration 2	427
0x038	CANIF1MCTL	R/W	0x0000.0000	CAN IF1 Message Control	428
0x03C	CANIF1DA1	R/W	0x0000.0000	CAN IF1 Data A1	430
0x040	CANIF1DA2	R/W	0x0000.0000	CAN IF1 Data A2	431
0x044	CANIF1DB1	R/W	0x0000.0000	CAN IF1 Data B1	432
0x048	CANIF1DB2	R/W	0x0000.0000	CAN IF1 Data B2	433
0x080	CANIF2CRQ	R/W	0x0000.0001	CAN IF2 Command Request	420
0x084	CANIF2CMSK	R/W	0x0000.0000	CAN IF2 Command Mask	421
0x088	CANIF2MSK1	R/W	0x0000.FFFF	CAN IF2 Mask 1	424
0x08C	CANIF2MSK2	R/W	0x0000.FFFF	CAN IF2 Mask 2	425
0x090	CANIF2ARB1	R/W	0x0000.0000	CAN IF2 Arbitration 1	426
0x094	CANIF2ARB2	R/W	0x0000.0000	CAN IF2 Arbitration 2	427
0x098	CANIF2MCTL	R/W	0x0000.0000	CAN IF2 Message Control	428
0x09C	CANIF2DA1	R/W	0x0000.0000	CAN IF2 Data A1	430
0x0A0	CANIF2DA2	R/W	0x0000.0000	CAN IF2 Data A2	431
0x0A4	CANIF2DB1	R/W	0x0000.0000	CAN IF2 Data B1	432
0x0A8	CANIF2DB2	R/W	0x0000.0000	CAN IF2 Data B2	433
0x100	CANTXRQ1	RO	0x0000.0000	CAN Transmission Request 1	434
0x104	CANTXRQ2	RO	0x0000.0000	CAN Transmission Request 2	434
0x120	CANNWDA1	RO	0x0000.0000	CAN New Data 1	435
0x124	CANNWDA2	RO	0x0000.0000	CAN New Data 2	435
0x140	CANMSG1INT	RO	0x0000.0000	CAN Message 1 Interrupt Pending	436
0x144	CANMSG2INT	RO	0x0000.0000	CAN Message 2 Interrupt Pending	436
0x160	CANMSG1VAL	RO	0x0000.0000	CAN Message 1 Valid	437
0x164	CANMSG2VAL	RO	0x0000.0000	CAN Message 2 Valid	437

16.6 Register Descriptions

The remainder of this section lists and describes the CAN registers, in numerical order by address offset. There are two sets of Interface Registers which are used to access the Message Objects in the Message RAM: **CANIF1x** and **CANIF2x**. The function of the two sets are identical and are used to queue transactions.

Register 1: CAN Control (CANCTL), offset 0x000

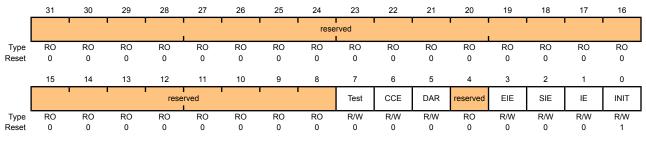
This control register initializes the module and enables test mode and interrupts.

The bus-off recovery sequence (see CAN Specification Rev. 2.0) cannot be shortened by setting or resetting Init. If the device goes bus-off, it sets Init, stopping all bus activities. Once Init has been cleared by the CPU, the device then waits for 129 occurrences of Bus Idle (129 * 11 consecutive High bits) before resuming normal operations. At the end of the bus-off recovery sequence, the Error Management Counters are reset.

During the waiting time after Init is reset, each time a sequence of 11 High bits has been monitored, a BitOError code is written to the **CANSTS** status register, enabling the CPU to readily check whether the CAN bus is stuck at dominant or continuously disturbed and to monitor the proceeding of the bus-off recovery sequence.

CAN Control (CANCTL)

CAN0 base: 0x4004.0000 Offset 0x000 Type R/W, reset 0x0000.0001



Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0x0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7	Test	R/W	0	Test Mode Enable
				0: Normal Operation
				1: Test Mode
6	CCE	R/W	0	Configuration Change Enable
				0: Do not allow write access to the CANBIT register.
				1: Allow write access to the CANBIT register if the Init bit is 1.
5	DAR	R/W	0	Disable Automatic Retransmission
				0: Auto retransmission of disturbed messages is enabled.
				1: Auto retransmission is disabled.
4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	EIE	R/W	0	Error Interrupt Enable
				0: Disabled. No Error Status interrupt is generated.

generates an interrupt.

1: Enabled. A change in the Boff or EWarn bits in the CANSTS register

Bit/Field	Name	Туре	Reset	Description
2	SIE	R/W	0	Status Change Interrupt Enable
				0: Disabled. No Status Change interrupt is generated.
				1: Enabled. An interrupt is generated when a message has successfully been transmitted or received, or a CAN bus error has been detected. A change in the \mathtt{TxOk} or \mathtt{RxOk} bits in the CANSTS register generates an interrupt.
1	IE	R/W	0	Module Interrupt Enable
				0: Interrupt disabled.
				1: Interrupt enabled.
0	INIT	R/W	1	Initialization
				0: Normal operation.
				1: Initialization started.

Register 2: CAN Status (CANSTS), offset 0x004

The status register contains information for interrupt servicing such as Bus-Off, error count threshold, and error types.

The **LEC** field holds the code that indicates the type of the last error to occur on the CAN bus. This field is cleared to 0 when a message has been transferred (reception or transmission) without error. The unused error code 7 may be written by the CPU to check for updates.

An Error Interrupt is generated by the BOff and EWarn bits and a Status Change Interrupt is generated by the RxOk, TxOk, and LEC bits, assuming that the corresponding enable bits in the **CAN Control (CANCTL)** register are set. A change of the EPass bit or a write to the RxOk, TxOk, or LEC bits does not generate an interrupt.

Reading the **CAN Status (CANSTS)** register clears the **CAN Interrupt (CANINT)** register, if it is pending.

CAN Status (CANSTS)

CAN0 base: 0x4004.0000 Offset 0x004

Type R/W, reset 0x0000.0000

		1	1	1	1											
								rese	rved •							
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0
_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		'	•	rese	rved				BOff	EWarn	EPass	RxOK	TxOK		LEC	
Type	RO 0	RO 0	RO 0	RO 0	RO	RO 0	RO 0	RO 0	RO	RO	RO	R/W	R/W	R/W	R/W	R/W 0
Reset	0 15	14	13	0 12 rese	0 11 erved	0 10	9	8	0 7 BOff	0 6 EWarn	0 5 EPass	0 4 RxOK	0 3 TxOK		2	0 0 2 1 LEC

Bit/Field	Name	Туре	Reset	Description
31:8	reserved	RO	0x0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
7	BOff	RO	0	Bus-Off Status
				0: Module is not in bus-off state.
				1: Module is in bus-off state.
6	EWarn	RO	0	Warning Status
				0: Both error counters are below the error warning limit of 96.
				1: At least one of the error counters has reached the error warning limit of 96.
5	EPass	RO	0	Error Passive
				0: The CAN module is in the Error Active state, that is, the receive or

0: The CAN module is in the Error Active state, that is, the receive or transmit error count is less than or equal to 127.

1: The CAN module is in the Error Passive state, that is, the receive or transmit error count is greater than 127.

Bit/Field	Name	Type	Reset	Description
4	RxOK	R/W	0	Received a Message Successfully
				0: Since this bit was last reset to 0, no message has been successfully received.
				1: Since this bit was last reset to 0, a message has been successfully received, independent of the result of the acceptance filtering.
				This bit is never reset by the CAN module.
3	TxOK	R/W	0	Transmitted a Message Successfully
				0: Since this bit was last reset to 0, no message has been successfully transmitted.
				1: Since this bit was last reset to 0, a message has been successfully transmitted error-free and acknowledged by at least one other node.
				This bit is never reset by the CAN module.

Bit/Field	Name	Type	Reset	Description
2:0	LEC	R/W	0x0	Last Error Code (type of the last error to occur on the CAN bus)
				Value Definition
				000 No Error
				001 Stuff Error
				More than 5 equal bits in a sequence have occurred in a part of a received message where this is not allowed.
				010 Form Error
				A fixed format part of the received frame has the wrong format.
				011 ACK Error
				The message transmitted was not acknowledged by another node.
				100 Bit 1 Error
				When a message is transmitted, the CAN controller monitors the data lines to detect any conflicts. When the arbitration field is transmitted, data conflicts are a part of the arbitration protocol. When other frame fields are transmitted, data conflicts are considered errors.
				A Bit 1 Error indicates that the device wanted to send a High

0). 101 Bit 0 Error

A Bit 0 Error indicates that the device wanted to send a Low level (logical 0) but the monitored bus value was High (logical 1).

level (logical 1) but the monitored bus value was Low (logical

During bus-off recovery, this status is set each time a sequence of 11 High bits has been monitored. This enables the CPU to monitor the proceeding of the bus-off recovery sequence without any disturbances to the bus.

110 CRC Error

The CRC checksum was incorrect in the received message indicate that the calculated value received did not match the calculated CRC of the data.

111 Unused

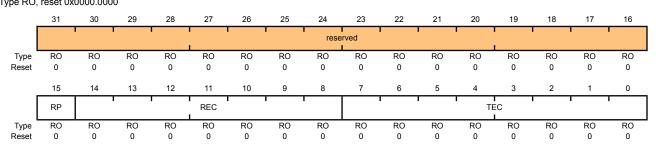
When the LEC bit shows this value, no CAN bus event was detected since the CPU wrote this value to LEC.

Register 3: CAN Error Counter (CANERR), offset 0x008

This register contains the error counter values, which can be used to analyze the cause of an error.

CAN Error Counter (CANERR)

CAN0 base: 0x4004.0000 Offset 0x008 Type RO, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:16	reserved	RO	0x0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15	RP	RO	0	Received Error Passive
				0: The Receive Error counter is below the Error Passive level (127 or less).
				1: The Receive Error counter has reached the Error Passive level (128 or greater).
14:8	REC	RO	0x0	Receive Error Counter
				State of the receiver error counter (0 to 127).
7:0	TEC	RO	0x0	Transmit Error Counter
				State of the transmit error counter (0 to 255).

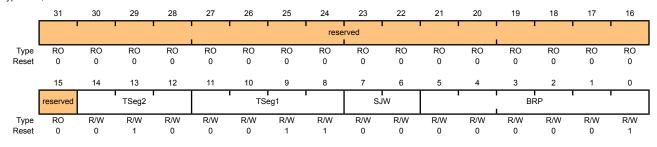
Register 4: CAN Bit Timing (CANBIT), offset 0x00C

This register is used to program the bit width and bit quantum. Values are to be programmed to an 8-MHz reference clock. This register is write-enabled by the CCE and Init bits in the CANCTL register.

With a CAN module clock (CAN CLK) of 8 MHz, the register reset value of 0x230 configures the CAN for a bit rate of 500 Kbps.

CAN Bit Timing (CANBIT)

CAN0 base: 0x4004.0000 Offset 0x00C Type R/W, reset 0x0000.2301



Bit/Field	Name	Туре	Reset	Description
31:15	reserved	RO	0x0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
14:12	TSeg2	R/W	0x2	Time Segment after Sample Point
				0x00-0x07: The actual interpretation by the hardware of this value is such that one more than the value programmed here is used.
				So, for example, a reset value of 0x2 defines that there is 3(2+1) bit time quanta defined for Phase_Seg2 (see Figure 16-2 on page 402). The bit time quanta is defined by BRP.
11:8	TSeg1	R/W	0x3	Time Segment Before Sample Point
				0x00-0x0F: The actual interpretation by the hardware of this value is such that one more than the value programmed here is used.
				So, for example, the reset value of 0x3 defines that there is 4(3+1) bit time quanta defined for Phase_Seg1 (see Figure 16-2 on page 402). The bit time quanta is define by BRP.
7:6	SJW	R/W	0x0	(Re)Synchronization Jump Width
				0v00-0v03: The actual interpretation by the hardware of this value is

0x00-0x03: The actual interpretation by the hardware of this value is such that one more than the value programmed here is used.

During the start of frame (SOF), if the CAN controller detects a phase error (misalignment), it can adjust the length of TSeg2 or TSeg1 by the value in SJW. So the reset value of 0 adjusts the length by 1 bit time quanta.

Bit/Field	Name	Туре	Reset	Description
5:0	BRP	R/W	0x1	Baud Rate Prescalar
				0x00-0x03F: The value by which the oscillator frequency is divided for generating the bit time quanta. The bit time is built up from a multiple of this quantum. The actual interpretation by the hardware of this value is such that one more than the value programmed here is used.
				$\tt BRP$ defines the number of CAN clock periods that make up 1 bit time quanta, so the reset value is 2 bit time quanta (1+1).
				The BRPRE register can be used to further divide the bit time.

Register 5: CAN Interrupt (CANINT), offset 0x010

This register indicates the source of the interrupt.

RO

Intld

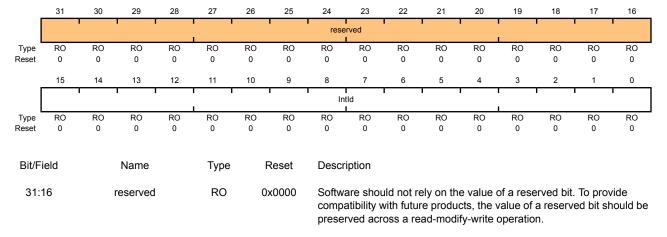
0x0000

If several interrupts are pending, the **CAN Interrupt (CANINT)** register points to the pending interrupt with the highest priority, disregarding their chronological order. An interrupt remains pending until the CPU has cleared it. If the IntId bit is not 0x0000 (the default) and the IE bit in the **CANCTL** register is set, the interrupt is active. The interrupt line remains active until the IntId bit is set back to 0x0000 when the cause of all interrupts are reset or until IE is reset.

CAN Interrupt (CANINT)

CAN0 base: 0x4004.0000 Offset 0x010 Type RO, reset 0x0000.0000

15:0



Interrupt Identifier

The number in this field indicates the source of the interrupt.

Value	Definition
0x0000	No interrupt pending
0x0001-0x0020	Number of the message object that caused the interrupt
0x0021-0x7FFF	Unused
0x8000	Status Interrupt
0x8001-0xFFFF	Unused

Register 6: CAN Test (CANTST), offset 0x014

This is the test mode register for self-test and external pin access. It is write-enabled by the Test bit in the **CANCTL** register. Different test functions may be combined but when the TX bit is not equal to 0x0, it disturbs message transmits.

CAN Test (CANTST)

CAN0 base: 0x4004.0000 Offset 0x014 Type R/W, reset 0x0000.0000

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
		'						rese	rved •							
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		'	1 1	rese	rved		1	'	Rx	Т	x	LBack	Silent	Basic	rese	rved
Type	RO	RO	RO	RO	RO	RO	RO	RO	RO	R/W	R/W	R/W	R/W	R/W	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Bit/F	ield		Name		Туре	I	Reset	Descr	iption							
31:	8		reserved		RO	0	0x0000	compa	atibility v	ith futur	e produ	e value of cts, the v fy-write of	alue of	a reserv		
7			Rx		RO		0	Recei	ve Obse	rvation						
								Displa	ys the v	alue on	the CAN	nRx pin .				
6:	5		Tx		R/W		0x0	Trans	mit Cont	rol						
0.0	3		17		1011		OXO		ides con		ANnTy r	nin				
											p					
									Descr	•	atrallad	by the C	AN mad	ulo (dofe	I4\	
								00 01	_			by the C				
								10				riven on	ine CAN	i_i x pin		
								11	_	TX drive TX drive						
								""	CAN_	i A unive	s a i ligi	i vaiue				
4			LBack		R/W		0	Looph	ack Mod	de						
								0: Dis								
								1: Ena								
2			Cilent		D///		0									
3			Silent		R/W		0		Mode	4 4-4		h	laa kaas	D	- 14:4-	
										i uaia, ii	ioriitor tr	ne bus. A	ISO KITOV	vii as bu	S IVIOTIILO	i mode.
									abled.							
								1: Ena	abled.							
2			Basic		R/W		0	Basic	Mode							
								0: Dis	abled.							
									e CANIF eive buf	-	ers as tra	ansmit b	uffer, an	d use C	ANIF2 re	egisters

Bit/Field	Name	Type	Reset	Description
1:0	reserved	RO	0x0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

Register 7: CAN Baud Rate Prescalar Extension (CANBRPE), offset 0x018

This register is used to further divide the bit time set with the BRP bit in the CANBIT register. It is write-enabled with the CCE bit in the CANCTL register.

CAN Baud Rate Prescalar Extension (CANBRPE)

BRPE

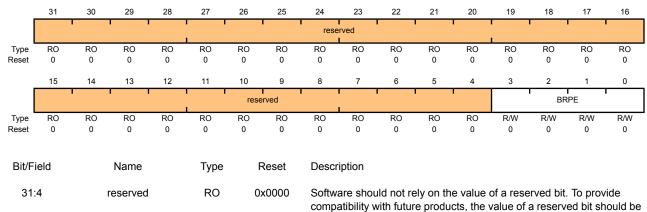
R/W

0x0

CAN0 base: 0x4004.0000

3:0

Offset 0x018 Type R/W, reset 0x0000.0000



0x00-0x0F: Extend the BRP bit to values up to 1023. The actual interpretation by the hardware is one more than the value programmed by BRPE (MSBs) and BRP (LSBs) are used.

preserved across a read-modify-write operation.

Baud Rate Prescalar Extension.

Register 8: CAN IF1 Command Request (CANIF1CRQ), offset 0x020 Register 9: CAN IF2 Command Request (CANIF2CRQ), offset 0x080

This register is used to start a transfer when its MNUM bit field is updated. Its Busy bit indicates that the information is transferring from the CAN Interface Registers to the internal message RAM.

A message transfer is started as soon as there is a write of the message object number with the MNUM bit. With this write operation, the Busy bit is automatically set to 1 to indicate that a transfer is in progress. After a wait time of 3 to 6 CAN_CLK periods, the transfer between the interface register and the message RAM completes, which then sets the Busy bit back to 0.

CAN IF1 Command Request (CANIF1CRQ)

CAN0 base: 0x4004.0000 Offset 0x020 Type R/W, reset 0x0000.0001

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
						1		rese	rved							
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	Busy					reserved					'		MN	UM	•	.
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 1

Bit/Field	Name	Type	Reset	Description
31:16	reserved	RO	0x0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15	Busy	RO	0x0	Busy Flag
				0: Reset when read/write action has finished.
				1: Set when a write occurs to the message number in this register.
14:6	reserved	RO	0x00	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
5:0	MNUM	R/W	0x01	Message Number

Selects one of the 32 message objects in the message RAM for data transfer. The message objects are numbered from 1 to 32.

Value	Description
0x00	0 is not a valid message number; it is interpreted as 0x20, or object 32. $ \\$
0x01-0x20	Indicates specified message object 1 to 32.
0x21-0x3F	Not a valid message number; values are shifted and it is interpreted as 0x01-0x1F.

Register 10: CAN IF1 Command Mask (CANIF1CMSK), offset 0x024 Register 11: CAN IF2 Command Mask (CANIF2CMSK), offset 0x084

The Command Mask registers specify the transfer direction and select which buffer registers are the source or target of the data transfer.

CAN IF1 Command Mask (CANIF1CMSK)

CAN0 base: 0x4004.0000

Offset 0x024 Type R/W, reset 0x0000.0000

.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	.,															
i	31	30	29	28	27	26	25	24 1	23	22	21	20	19 I	18	17	16
									erved I							
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		•		rese	rved		'	1	WRNRD	Mask	Arb	Control	ClrIntPnd	TxRq stN ewDat	DataA	DataB
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0
Bit/F	ield		Name		Туре	ſ	Reset	Desci	ription							
31:	:8	I	reserved		RO	0	×0000	comp	are shou atibility w rved acro	ith futur	e produ	cts, the	value of	a reserve		
7		,	WRNRD		R/W		0	Write	, Not Rea	ad						
								Comi regist CANI	ad. Trans mand Re ers (CAN FnCTL, (FnDB2).	quest (C IFnMSK CANIFn	CANIFN (1, CANI	CRQ) re	gister to 2, CANIF	the CAN FnARB1,	messag CANIF	e buffer
									te. Trans t address			-		-	to the m	essage
6			Mask		R/W		0x0	Acces	ss Mask I	Bits						
								When	WRNRD=	1 (write:	s):					
								0: Ma	sk bits ui	nchange	d.					
								1: Tra	nsfer ID	Mask +	Dir+M	xtd to r	nessage	object.		
								When	WRNRD=	0 (reads	s):					
								0: Ma	sk bits ui	nchange	d.					
									insfer ID ace Regi		Dir+M	Xtd of t	he mess	age obje	ect into t	he
5			Arb		R/W		0x0	Acces	ss Arbitra	ition Bits	i					
								When	WRNRD=	1 (write:	s):					
								0: Art	itration b	its unch	anged.					
								1: Tra	insfer ID	+ Dir +	Xtd + N	MsgVal	to mess	age obje	ct.	
								When	WRNRD=	0 (reads	s):					
								0: Art	itration b	its unch	anged.					

1: Transfer ID + Dir + Xtd + MsgVal to Message Buffer Register.

Bit/Field	Name	Туре	Reset	Description	
4	Control	R/W	0x0	Access Control Bits	
				When wrnrd=1 (writes):	
				0: Control bits unchanged.	
				1: Transfer control bits to message object.	
				When wrnrd=0 (reads):	
				0: Control bits unchanged.	
				1: Transfer control bits to Message Buffer Register.	
3	ClrIntPnd	R/W	0x0	Clear Interrupt Pending Bit	
				Note: This bit is not used when in write (WRNRD=1).	
				0: IntPnd bit in CANIFnMCTL register remains unchanged.	
				1: Clear IntPnd bit in the CANIFnMCTL register in the message object	t.
2	TxRqst/NewDat	R/W	0x0	When wrnrd=1 (writes):	
				Access Transmission Request Bit	
				0: TxRqst bit unchanged.	
				1: Set TxRqst bit	
				Note: If a transmission is requested by programming this TxRqst bit, the parallel TxRqst in the CANIFnMCTL register is ignored.	5
				When wrnrd=0 (reads):	
				Access New Data Bit	
				0: NewDat bit unchanged.	
				1: Clear NewDat bit in the message object.	
				Note: A read access to a message object can be combined with the reset of the control bits IntPdn and NewDat. The values of these bits that are transferred to the CANIFnMCTL register always reflect the status before resetting these bits.	of
1	DataA	R/W	0x0	Access Data Byte 0 to 3	
				When wrnrd=1 (writes):	
				0: Data bytes 0-3 are unchanged.	
				1: Transfer data bytes 0-3 (CANIFnDA1 and CANIFnDA2) to message object.	е
				When wrnrd=0 (reads):	
				0: Data bytes 0-3 are unchanged.	
				1: Transfer data bytes 0-3 in message object to CANIFnDA1 and CANIFnDA2 .	

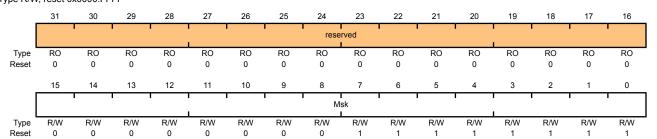
Bit/Field	Name	Type	Reset	Description
0	DataB	R/W	0x0	Access Data Byte 4 to 7
				When wrnrd=1 (writes):
				0: Data bytes 4-7 unchanged.
				1: Transfer data bytes 4-7 (CANIFnDB1 and CANIFnDB2) to message object.
				When wrnrd=0 (reads):
				0: Data bytes 4-7 unchanged.
				1: Transfer data bytes 4-7 in message object to CANIFnDB1 and CANIFnDB2 .

Register 12: CAN IF1 Mask 1 (CANIF1MSK1), offset 0x028 Register 13: CAN IF2 Mask 1 (CANIF2MSK1), offset 0x088

The mask information provided in this register accompanies the data (CANIFnDAn), arbitration information (CANIFnARBn), and control information (CANIFnMCTL) to the message object in the message RAM. The mask is used with the ID bit in the CANIFnARBn register for acceptance filtering. Additional mask information is contained in the CANIFnMSK2 register.

CAN IF1 Mask 1 (CANIF1MSK1)

CAN0 base: 0x4004.0000 Offset 0x028 Type R/W, reset 0x0000.FFFF



Bit/Field	Name	Type	Reset	Description
31:16	reserved	RO	0x0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15:0	Msk	R/W	0xFF	Identifier Mask

^{0:} The corresponding identifier bit (ID) in the message object cannot inhibit the match in acceptance filtering.

^{1:} The corresponding identifier bit (ID) is used for acceptance filtering.

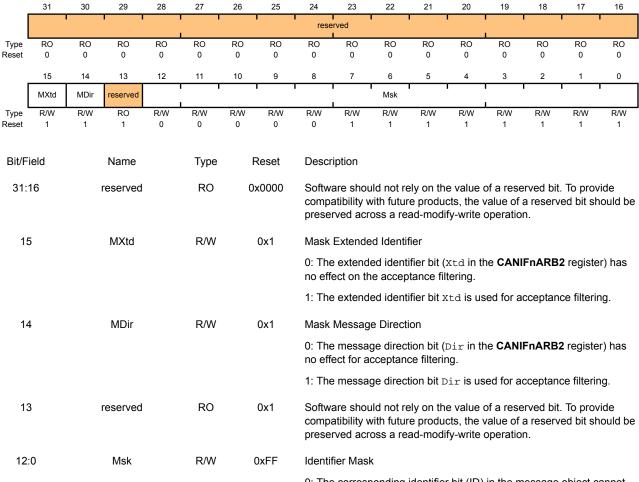
Register 14: CAN IF1 Mask 2 (CANIF1MSK2), offset 0x02C Register 15: CAN IF2 Mask 2 (CANIF2MSK2), offset 0x08C

This register holds extended mask information that accompanies the CANIFnMSK1 register.

CAN IF1 Mask 2 (CANIF1MSK2)

CAN0 base: 0x4004.0000 Offset 0x02C

Type R/W, reset 0x0000.FFFF



1: The corresponding identifier bit (ID) is used for acceptance filtering.

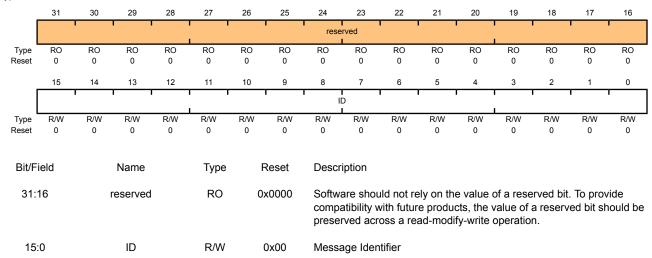
Register 16: CAN IF1 Arbitration 1 (CANIF1ARB1), offset 0x030 Register 17: CAN IF2 Arbitration 1 (CANIF2ARB1), offset 0x090

This register, along with CANIFnARB2, holds the identifiers for acceptance filtering.

CAN IF1 Arbitration 1 (CANIF1ARB1)

CAN0 base: 0x4004.0000

Offset 0x030 Type R/W, reset 0x0000.0000



This bit field is used with the ID field in the **CANIFnARB2** register to create the message identifier. ID[28:0] is the Extended Frame and ID[28:18] is the Standard Frame.

Register 18: CAN IF1 Arbitration 2 (CANIF1ARB2), offset 0x034 Register 19: CAN IF2 Arbitration 2 (CANIF2ARB2), offset 0x094

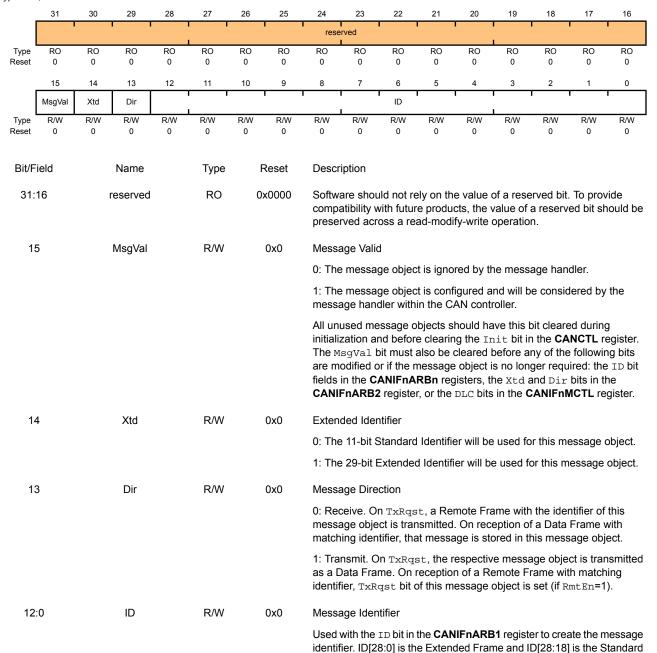
This register, along with CANIFnARB1, holds information for acceptance filtering.

CAN IF1 Arbitration 2 (CANIF1ARB2)

CAN0 base: 0x4004.0000

Offset 0x034

Type R/W, reset 0x0000.0000



Frame.

Register 20: CAN IF1 Message Control (CANIF1MCTL), offset 0x038 Register 21: CAN IF2 Message Control (CANIF2MCTL), offset 0x098

This register holds the control information associated with the message object to be sent to the Message RAM.

CAN IF1 Message Control (CANIF1MCTL)

27

CAN0 base: 0x4004.0000

Offset 0x038
Type R/W, reset 0x0000.0000

								rese	rved		1						
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
	NewDat	MsgLst	IntPnd	UMask	TxIE	RxIE	RmtEn	TxRqst	EoB		reserved			DI	_C		
Type Reset	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	R/W 0	RO 0	RO 0	RO 0	R/W 0	R/W 0	R/W 0	R/W 0	
iveset	U	U	Ü	U	U	U	Ü	U	U	O	U	U	Ü	Ü	U	O	
Bit/F	Bit/Field Name Type		F	Reset	Description												
31:	31:16 reserved RC		RO	0:	×0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.											
15	15 NewDat		R/W		0x0 New Data												
									by the n		een writte e handler					-	
											ler or the le object.		as writte	n new da	ata into t	he data	
14		MsgLst		R/W		0x0	Message Lost										
						$\ensuremath{\text{0}}$: No message was lost since the last time this bit was reset by the CPU.											
						1: The message handler stored a new message into this object when NewDat was set; the CPU has lost a message.											
									This bit is only valid for message objects with the Dir bit in the CANIFnARB2 register set to 0 (receive).								
13			IntPnd			0x0	Interrupt Pending										
								0: This message object is not the source of an interrupt.									
									1: This message object is the source of an interrupt. The interrupt identifier in the CAN Interrupt (CANINT) register will point to this message object if there is not another interrupt source with a higher priority.								
12	2		UMask		R/W		0x0	Use A	cceptan	ce Masl	<						
								0: Mas	0: Mask ignored.								
									1: Use mask (Msk, MXtd, and MDir) for acceptance filtering.								

Bit/Field	Name	Type	Reset	Description
11	TxIE	R/W	0x0	Transmit Interrupt Enable
				0: The IntPnd bit in the CANIFnMCTL register is unchanged after a successful transmission of a frame.
				1: The IntPnd bit in the CANIFnMCTL register is set after a successful transmission of a frame.
10	RxIE	R/W	0x0	Receive Interrupt Enable
				0: The IntPnd bit in the CANIFnMCTL register is unchanged after a successful reception of a frame.
				1: The IntPnd bit in the CANIFnMCTL register is set after a successful reception of a frame.
9	RmtEn	R/W	0x0	Remote Enable
				0: At the reception of a Remote Frame, the TxRqst bit in the CANIFnMCTL register is left unchanged.
				1: At the reception of a Remote Frame, the TxRqst bit in the CANIFnMCTL register is set.
8	TxRqst	R/W	0x0	Transmit Request
				0: This message object is not waiting for transmission.
				1: The transmission of this message object is requested and is not yet done.
7	EoB	R/W	0x0	End of Buffer
				0: Message object belongs to a FIFO Buffer and is not the last message object of that FIFO Buffer.
				1: Single message object or last message object of a FIFO Buffer.
				This bit is used to concatenate two or more message objects (up to 32) to build a FIFO buffer. For a single message object (thus not belonging to a FIFO buffer), this bit must be set to 1.
6:4	reserved	RO	0x0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3:0	DLC	R/W	0x0	Data Length Code
				Value Description

0x0-0x8 Specifies the number of bytes in the Data Frame.

0x9-0xF Defaults to a Data Frame with 8 bytes.

The DLC bit in the **CANIFnMCTL** register of a message object must be defined the same as in all the corresponding objects with the same identifier at other nodes. When the message handler stores a data frame, it writes DLC to the value given by the received message.

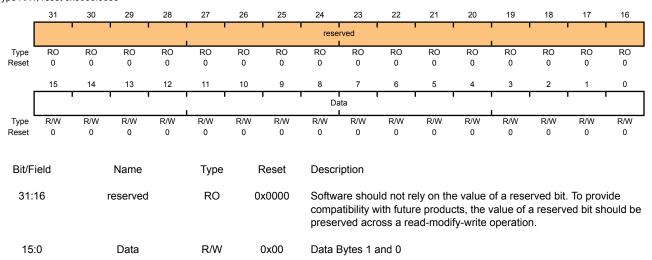
Register 22: CAN IF1 Data A1 (CANIF1DA1), offset 0x03C Register 23: CAN IF2 Data A1 (CANIF2DA1), offset 0x09C

This register (along with **CANIFnDA2**, **CANIFnDB1**, and **CANIFnDB2**) contains the data to be sent or that has been received. In a CAN Data Frame, data byte 0 is the first byte to be transmitted or received and data byte 7 is the last byte to be transmitted or received. In CAN's serial bit stream, the MSB of each byte is transmitted first.

CAN IF1 Data A1 (CANIF1DA1)

CAN0 base: 0x4004.0000 Offset 0x03C

Type R/W, reset 0x0000.0000

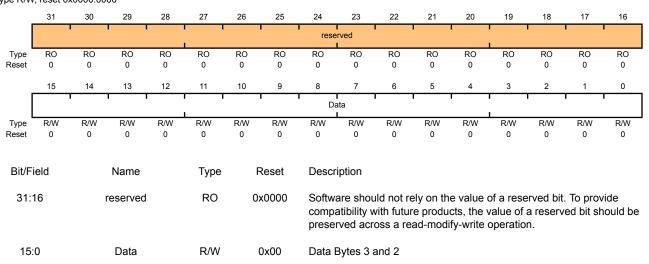


Register 24: CAN IF1 Data A2 (CANIF1DA2), offset 0x040 Register 25: CAN IF2 Data A2 (CANIF2DA2), offset 0x0A0

This register (along with **CANIFnDA1**, **CANIFnDB1**, and **CANIFnDB2**) contains the data to be sent or that has been received. In a CAN Data Frame, data byte 0 is the first byte to be transmitted or received and data byte 7 is the last byte to be transmitted or received. In CAN's serial bit stream, the MSB of each byte is transmitted first.

CAN IF1 Data A2 (CANIF1DA2)

CAN0 base: 0x4004.0000 Offset 0x040 Type R/W, reset 0x0000.0000



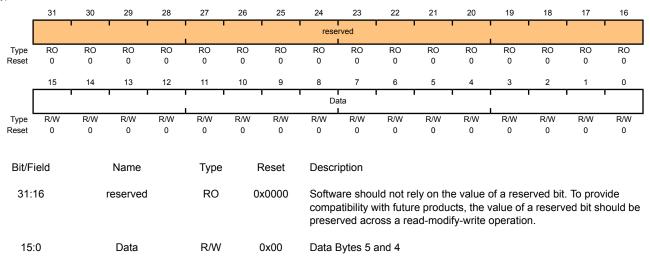
Register 26: CAN IF1 Data B1 (CANIF1DB1), offset 0x044 Register 27: CAN IF2 Data B1 (CANIF2DB1), offset 0x0A4

This register (along with CANIFnDA1, CANIFnDA2, and CANIFnDB2) contains the data to be sent or that has been received. In a CAN Data Frame, data byte 0 is the first byte to be transmitted or received and data byte 7 is the last byte to be transmitted or received. In CAN's serial bit stream, the MSB of each byte is transmitted first.

CAN IF1 Data B1 (CANIF1DB1)

CAN0 base: 0x4004.0000 Offset 0x044

Type R/W, reset 0x0000.0000

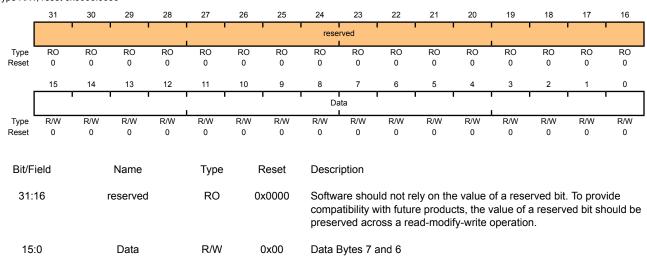


Register 28: CAN IF1 Data B2 (CANIF1DB2), offset 0x048 Register 29: CAN IF2 Data B2 (CANIF2DB2), offset 0x0A8

This register (along with **CANIF1DA1**, **CANIF1DA2**, and **CANIF1DB1**) contains the data to be sent or that has been received. In a CAN Data Frame, data byte 0 is the first byte to be transmitted or received and data byte 7 is the last byte to be transmitted or received. In CAN's serial bit stream, the MSB of each byte is transmitted first.

CAN IF1 Data B2 (CANIF1DB2)

CAN0 base: 0x4004.0000 Offset 0x048 Type R/W, reset 0x0000.0000



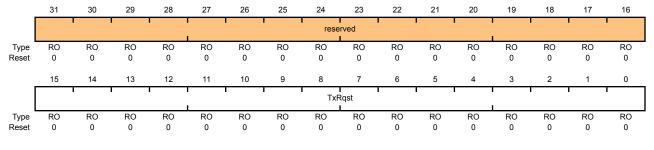
Register 30: CAN Transmission Request 1 (CANTXRQ1), offset 0x100 Register 31: CAN Transmission Request 2 (CANTXRQ2), offset 0x104

The **CANTXRQ1** and **CANTXRQ2** registers hold the \mathtt{TxRqst} bits of the 32 message objects. By reading out these bits, the CPU can check which message object has a transmission request pending. The \mathtt{TxRqst} bit of a specific message object can be changed by three sources: (1) the CPU via the **CAN IFn Message Control (CANIFnMCTL)** register, (2) the message handler state machine after the reception of a Remote Frame, or (3) the message handler state machine after a successful transmission.

The **CANTXRQ1** register contains the TxRqst bit of the first 16 message objects in the message RAM; the **CANTXRQ2** register contains the TxRqst bit of the second 16 message objects.

CAN Transmission Request 1 (CANTXRQ1)

CAN0 base: 0x4004.0000 Offset 0x100 Type RO, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:16	reserved	RO	0x0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15:0	TxRqst	RO	0x00	Transmission Request Bits (of all message objects)

^{0:} The message object is not waiting for transmission.

^{1:} The transmission of the message object is requested and is not yet done.

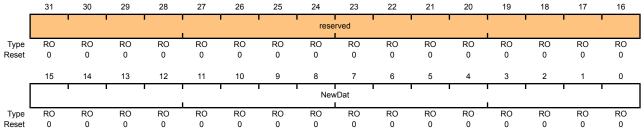
Register 32: CAN New Data 1 (CANNWDA1), offset 0x120 Register 33: CAN New Data 2 (CANNWDA2), offset 0x124

The **CANNWDA1** and **CANNWDA2** registers hold the NewDat bits of the 32 message objects. By reading these bits, the CPU can check which message object has its data portion updated. The NewDat bit of a specific message object can be changed by three sources: (1) the CPU via the **CAN IFn Message Control (CANIFnMCTL)** register, (2) the message handler state machine after the reception of a Data Frame, or (3) the message handler state machine after a successful transmission.

The **CANNWDA1** register contains the NewDat bit of the first 16 message objects in the message RAM; the **CANNWDA2** register contains the NewDat bit of the second 16 message objects.

CAN New Data 1 (CANNWDA1)

CAN0 base: 0x4004.0000 Offset 0x120 Type RO, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:16	reserved	RO	0x0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15:0	NewDat	RO	0x00	New Data Bits (of all message objects)

^{0:} No new data has been written into the data portion of this message object by the message handler since the last time this flag was cleared by the CPU.

Register 34: CAN Message 1 Interrupt Pending (CANMSG1INT), offset 0x140 Register 35: CAN Message 2 Interrupt Pending (CANMSG2INT), offset 0x144

The **CANMSG1INT** and **CANMSG2INT** registers hold the IntPnd bits of the 32 message objects. By reading these bits, the CPU can check which message object has an interrupt pending. The IntPnd bit of a specific message object can be changed through two sources: (1) the CPU via the **CAN IFN Message Control (CANIFNMCTL)** register, or (2) the message handler state machine after the reception or transmission of a frame.

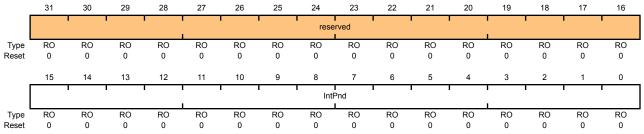
This field is also encoded in the CAN Interrupt (CANINT) register.

The **CANMSG1INT** register contains the IntPnd bit of the first 16 message objects in the message RAM; the **CANMSG2INT** register contains the IntPnd bit of the second 16 message objects.

CAN Message 1 Interrupt Pending (CANMSG1INT)

CAN0 base: 0x4004.0000 Offset 0x140

Type RO	reset 0x	0000.0000
	31	30



Bit/Field	Name	Type	Reset	Description
31:16	reserved	RO	0x0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15:0	IntPnd	RO	0x00	Interrupt Pending Bits (of all message objects)

^{0:} This message object is not the source of an interrupt.

^{1:} This message object is the source of an interrupt.

Register 36: CAN Message 1 Valid (CANMSG1VAL), offset 0x160 Register 37: CAN Message 2 Valid (CANMSG2VAL), offset 0x164

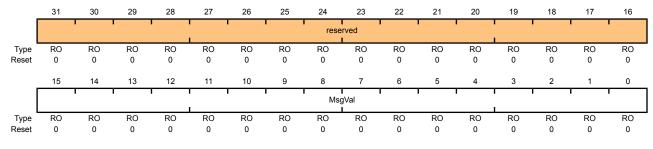
The CANMSG1VAL and CANMSG2VAL registers hold the MsqVal bits of the 32 message objects. By reading these bits, the CPU can check which message object is valid. The message value of a specific message object can be changed with the CAN IFn Message Control (CANIFnMCTL) register.

The CANMSG1VAL register contains the MsqVal bit of the first 16 message objects in the message RAM; the CANMSG2VAL register contains the MsgVal bit of the second 16 message objects in the message RAM

CAN Message 1 Valid (CANMSG1VAL)

CAN0 base: 0x4004.0000

Offset 0x160 Type RO, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:16	reserved	RO	0x0000	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15:0	MsgVal	RO	0x00	Message Valid Bits (of all message objects)

^{0:} This message object is not configured and is ignored by the message handler.

^{1:} This message object is configured and should be considered by the message handler.

17 Analog Comparator

An analog comparator is a peripheral that compares two analog voltages, and provides a logical output that signals the comparison result.

The LM3S2739 controller provides one analog comparator that can be configured to drive an output or generate an interrupt or ADC event.

Note: Not all comparators have the option to drive an output pin. See the Comparator Operating Mode tables for more information.

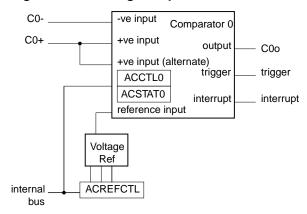
A comparator can compare a test voltage against any one of these voltages:

- An individual external reference voltage
- A shared single external reference voltage
- A shared internal reference voltage

The comparator can provide its output to a device pin, acting as a replacement for an analog comparator on the board, or it can be used to signal the application via interrupts or triggers to the ADC to cause it to start capturing a sample sequence. The interrupt generation and ADC triggering logic is separate. This means, for example, that an interrupt can be generated on a rising edge and the ADC triggered on a falling edge.

17.1 Block Diagram

Figure 17-1. Analog Comparator Module Block Diagram



17.2 Functional Description

Important: It is recommended that the Digital-Input enable (the GPIODEN bit in the GPIO module) for the analog input pin be disabled to prevent excessive current draw from the I/O pads.

The comparator compares the VIN- and VIN+ inputs to produce an output, VOUT.

```
VIN- < VIN+, VOUT = 1
VIN- > VIN+, VOUT = 0
```

As shown in Figure 17-2 on page 439, the input source for VIN- is an external input. In addition to an external input, input sources for VIN+ can be the +ve input of comparator 0 or an internal reference.

Figure 17-2. Structure of Comparator Unit

A comparator is configured through two status/control registers (ACCTL and ACSTAT). The internal reference is configured through one control register (ACREFCTL). Interrupt status and control is configured through three registers (ACMIS, ACRIS, and ACINTEN). The operating modes of the comparators are shown in the Comparator Operating Mode tables.

Typically, the comparator output is used internally to generate controller interrupts. It may also be used to drive an external pin or generate an analog-to-digital converter (ADC) trigger.

Important: Certain register bit values must be set before using the analog comparators. The proper pad configuration for the comparator input and output pins are described in the Comparator Operating Mode tables.

ACCNTL0 Comparator 0 **ASRCP** VIN- VIN+ Output Interrupt **ADC Trigger** 00 C0-C0+ C₀o yes yes 01 C0-C0+ C₀o yes 10 C0-Vref C₀o ves ves 11 C0reserved C₀o ves ves

Table 17-1. Comparator 0 Operating Modes

17.2.1 Internal Reference Programming

The structure of the internal reference is shown in Figure 17-3 on page 440. This is controlled by a single configuration register (**ACREFCTL**). Table 17-2 on page 440 shows the programming options to develop specific internal reference values, to compare an external voltage against a particular voltage generated internally.

Figure 17-3. Comparator Internal Reference Structure

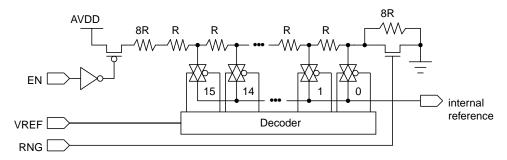


Table 17-2. Internal Reference Voltage and ACREFCTL Field Values

ACREFCTL Register		Output Reference Voltage Based on VREF Field Value				
EN Bit Value	RNG Bit Value					
EN=0	RNG=X	0 V (GND) for any value of VREF; however, it is recommended that RNG=1 and VREF=0 for the least noisy ground reference.				
EN=1	RNG=0	Total resistance in ladder is 32 R. $V_{REF} = AV_{DD} \times \frac{R_{VREF}}{R_{T}}$ $V_{REF} = AV_{DD} \times \frac{(VREF + 8)}{32}$ $V_{REF} = 0.825 + 0.103 VREF$ The range of internal reference in this mode is 0.825-2.37 V.				
	RNG=1	Total resistance in ladder is 24 R. $V_{REF} = AV_{DD} \times \frac{R_{VREF}}{R_{T}}$ $V_{REF} = AV_{DD} \times \frac{(VREF)}{24}$ $V_{REF} = 0.1375 \times V_{REF}$ The range of internal reference for this mode is 0.0-2.0625 V.				

17.3 Initialization and Configuration

The following example shows how to configure an analog comparator to read back its output value from an internal register.

- 1. Enable the analog comparator 0 clock by writing a value of 0x0010.0000 to the **RCGC1** register in the System Control module.
- 2. In the GPIO module, enable the GPIO port/pin associated with C0 as a GPIO input.

- **3.** Configure the internal voltage reference to 1.65 V by writing the **ACREFCTL** register with the value 0x0000.030C.
- 4. Configure comparator 0 to use the internal voltage reference and to *not* invert the output on the C0o pin by writing the **ACCTL0** register with the value of 0x0000.040C.
- 5. Delay for some time.
- Read the comparator output value by reading the ACSTAT0 register's OVAL value.

Change the level of the signal input on CO- to see the OVAL value change.

17.4 Register Map

"Register Map" on page 441 lists the comparator registers. The offset listed is a hexadecimal increment to the register's address, relative to the Analog Comparator base address of 0x4003.C000.

Table 17-3. Analog Comparators Register Map

Offset	Name	Туре	Reset	Description	See page
0x00	ACMIS	R/W1C	0x0000.0000	Analog Comparator Masked Interrupt Status	442
0x04	ACRIS	RO	0x0000.0000	Analog Comparator Raw Interrupt Status	443
80x0	ACINTEN	R/W	0x0000.0000	Analog Comparator Interrupt Enable	444
0x10	ACREFCTL	R/W	0x0000.0000	Analog Comparator Reference Voltage Control	445
0x20	ACSTAT0	RO	0x0000.0000	Analog Comparator Status 0	446
0x24	ACCTL0	R/W	0x0000.0000	Analog Comparator Control 0	447

17.5 Register Descriptions

The remainder of this section lists and describes the Analog Comparator registers, in numerical order by address offset.

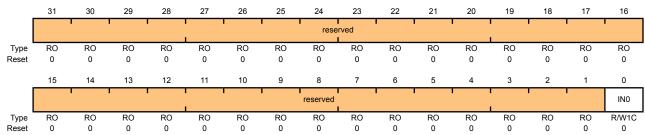
Register 1: Analog Comparator Masked Interrupt Status (ACMIS), offset 0x00

This register provides a summary of the interrupt status (masked) of the comparator.

Analog Comparator Masked Interrupt Status (ACMIS)

Base 0x4003.C000 Offset 0x00

Offset 0x00 Type R/W1C, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	IN0	R/W1C	0	Comparator 0 Masked Interrupt Status

Gives the masked interrupt state of this interrupt. Write 1 to this bit to clear the pending interrupt.

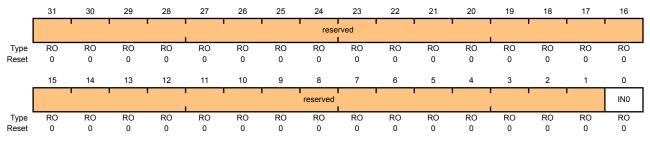
Register 2: Analog Comparator Raw Interrupt Status (ACRIS), offset 0x04

This register provides a summary of the interrupt status (raw) of the comparator.

Analog Comparator Raw Interrupt Status (ACRIS)

Base 0x4003.C000

Offset 0x04
Type RO, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	IN0	RO	0	When set, indicates that an interrupt has been generated by comparator 0.

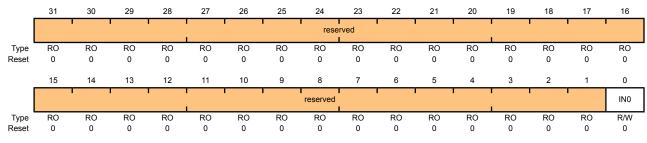
Register 3: Analog Comparator Interrupt Enable (ACINTEN), offset 0x08

This register provides the interrupt enable for the comparator.

Analog Comparator Interrupt Enable (ACINTEN)

Base 0x4003.C000

Offset 0x08
Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	IN0	R/W	0	When set, enables the controller interrupt from the comparator 0 output.

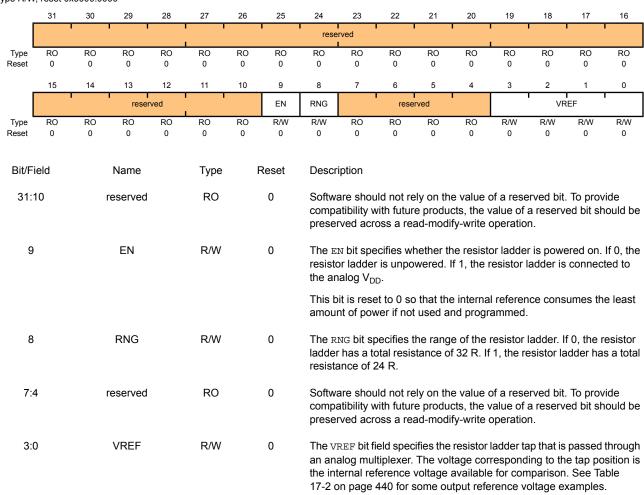
Register 4: Analog Comparator Reference Voltage Control (ACREFCTL), offset 0x10

This register specifies whether the resistor ladder is powered on as well as the range and tap.

Analog Comparator Reference Voltage Control (ACREFCTL)

Base 0x4003.C000

Offset 0x10
Type R/W, reset 0x0000.0000



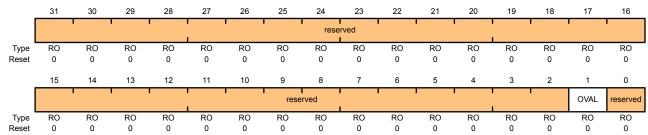
Register 5: Analog Comparator Status 0 (ACSTAT0), offset 0x20

This register specifies the current output value of the comparator.

Analog Comparator Status 0 (ACSTAT0)

Base 0x4003.C000

Offset 0x20 Type RO, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	OVAL	RO	0	The ${\tt OVAL}$ bit specifies the current output value of the comparator.
0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

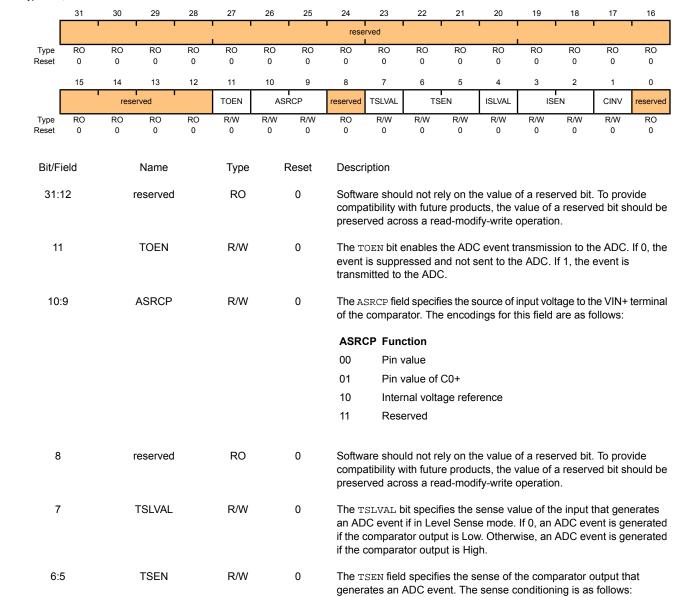
Register 6: Analog Comparator Control 0 (ACCTL0), offset 0x24

This register configures the comparator's input and output.

Analog Comparator Control 0 (ACCTL0)

Base 0x4003.C000 Offset 0x24

Type R/W, reset 0x0000.0000



TSEN Function

00 Level sense, see TSLVAL

01 Falling edge

10 Rising edge

11 Either edge

Bit/Field	Name	Type	Reset	Description
4	ISLVAL	R/W	0	The ISLVAL bit specifies the sense value of the input that generates an interrupt if in Level Sense mode. If 0, an interrupt is generated if the comparator output is Low. Otherwise, an interrupt is generated if the comparator output is High.
3:2	ISEN	R/W	0	The ISEN field specifies the sense of the comparator output that generates an interrupt. The sense conditioning is as follows:
				ISEN Function
				00 Level sense, see ISLVAL
				01 Falling edge
				10 Rising edge
				11 Either edge
1	CINV	R/W	0	The CINV bit conditionally inverts the output of the comparator. If 0, the output of the comparator is unchanged. If 1, the output of the comparator is inverted prior to being processed by hardware.
0	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.

18 Pulse Width Modulator (PWM)

Pulse width modulation (PWM) is a powerful technique for digitally encoding analog signal levels. High-resolution counters are used to generate a square wave, and the duty cycle of the square wave is modulated to encode an analog signal. Typical applications include switching power supplies and motor control.

The Stellaris[®] PWM module consists of three PWM generator blocks and a control block. Each PWM generator block contains one timer (16-bit down or up/down counter), two PWM comparators, a PWM signal generator, a dead-band generator, and an interrupt/ADC-trigger selector. The control block determines the polarity of the PWM signals, and which signals are passed through to the pins.

Each PWM generator block produces two PWM signals that can either be independent signals (other than being based on the same timer and therefore having the same frequency) or a single pair of complementary signals with dead-band delays inserted. The output of the PWM generation blocks are managed by the output control block before being passed to the device pins.

The Stellaris[®] PWM module provides a great deal of flexibility. It can generate simple PWM signals, such as those required by a simple charge pump. It can also generate paired PWM signals with dead-band delays, such as those required by a half-H bridge driver. It can also generate the full six channels of gate controls required by a 3-Phase inverter bridge.

18.1 Block Diagram

Figure 18-1 on page 449 provides a block diagram of a Stellaris[®] PWM module. The LM3S2739 controller contains three generator blocks (PWM0, PWM1, and PWM2) and generates six independent PWM signals or three paired PWM signals with dead-band delays inserted.

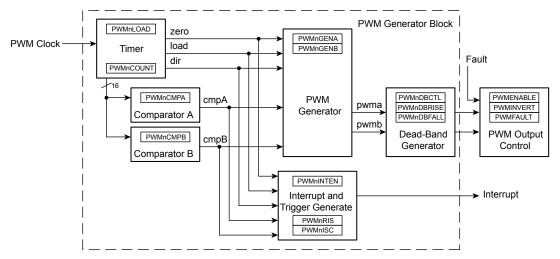


Figure 18-1. PWM Module Block Diagram

18.2 Functional Description

18.2.1 **PWM Timer**

The timer in each PWM generator runs in one of two modes: Count-Down mode or Count-Up/Down mode. In Count-Down mode, the timer counts from the load value to zero, goes back to the load value, and continues counting down. In Count-Up/Down mode, the timer counts from zero up to the

load value, back down to zero, back up to the load value, and so on. Generally, Count-Down mode is used for generating left- or right-aligned PWM signals, while the Count-Up/Down mode is used for generating center-aligned PWM signals.

The timers output three signals that are used in the PWM generation process: the direction signal (this is always Low in Count-Down mode, but alternates between Low and High in Count-Up/Down mode), a single-clock-cycle-width High pulse when the counter is zero, and a single-clock-cycle-width High pulse when the counter is equal to the load value. Note that in Count-Down mode, the zero pulse is immediately followed by the load pulse.

18.2.2 PWM Comparators

There are two comparators in each PWM generator that monitor the value of the counter; when either match the counter, they output a single-clock-cycle-width High pulse. When in Count-Up/Down mode, these comparators match both when counting up and when counting down; they are therefore qualified by the counter direction signal. These qualified pulses are used in the PWM generation process. If either comparator match value is greater than the counter load value, then that comparator never outputs a High pulse.

Figure 18-2 on page 450 shows the behavior of the counter and the relationship of these pulses when the counter is in Count-Down mode. Figure 18-3 on page 451 shows the behavior of the counter and the relationship of these pulses when the counter is in Count-Up/Down mode.

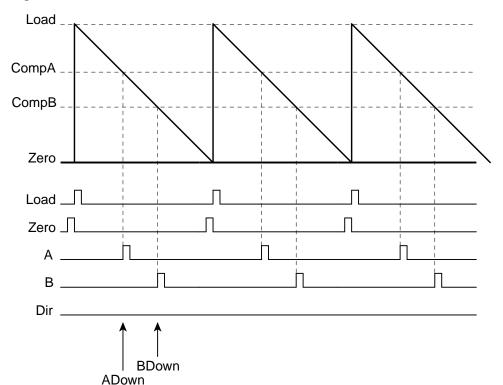


Figure 18-2. PWM Count-Down Mode

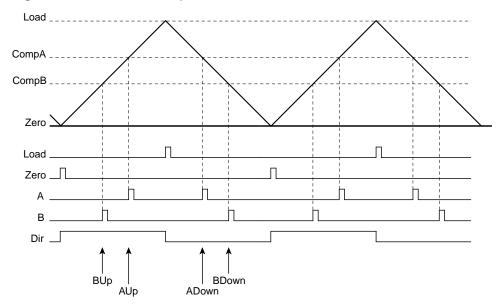


Figure 18-3. PWM Count-Up/Down Mode

18.2.3 PWM Signal Generator

The PWM generator takes these pulses (qualified by the direction signal), and generates two PWM signals. In Count-Down mode, there are four events that can affect the PWM signal: zero, load, match A down, and match B down. In Count-Up/Down mode, there are six events that can affect the PWM signal: zero, load, match A down, match A up, match B down, and match B up. The match A or match B events are ignored when they coincide with the zero or load events. If the match A and match B events coincide, the first signal, PWMA, is generated based only on the match A event, and the second signal, PWMB, is generated based only on the match B event.

For each event, the effect on each output PWM signal is programmable: it can be left alone (ignoring the event), it can be toggled, it can be driven Low, or it can be driven High. These actions can be used to generate a pair of PWM signals of various positions and duty cycles, which do or do not overlap. Figure 18-4 on page 451 shows the use of Count-Up/Down mode to generate a pair of center-aligned, overlapped PWM signals that have different duty cycles.

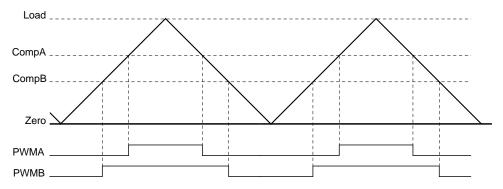


Figure 18-4. PWM Generation Example In Count-Up/Down Mode

In this example, the first generator is set to drive High on match A up, drive Low on match A down, and ignore the other four events. The second generator is set to drive High on match B up, drive Low on match B down, and ignore the other four events. Changing the value of comparator A

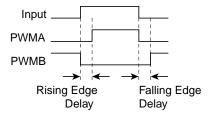
changes the duty cycle of the PWMA signal, and changing the value of comparator B changes the duty cycle of the PWMB signal.

18.2.4 Dead-Band Generator

The two PWM signals produced by the PWM generator are passed to the dead-band generator. If disabled, the PWM signals simply pass through unmodified. If enabled, the second PWM signal is lost and two PWM signals are generated based on the first PWM signal. The first output PWM signal is the input signal with the rising edge delayed by a programmable amount. The second output PWM signal is the inversion of the input signal with a programmable delay added between the falling edge of the input signal and the rising edge of this new signal.

This is therefore a pair of active High signals where one is always High, except for a programmable amount of time at transitions where both are Low. These signals are therefore suitable for driving a half-H bridge, with the dead-band delays preventing shoot-through current from damaging the power electronics. Figure 18-5 on page 452 shows the effect of the dead-band generator on an input PWM signal.

Figure 18-5. PWM Dead-Band Generator



18.2.5 Interrupt/ADC-Trigger Selector

The PWM generator also takes the same four (or six) counter events and uses them to generate an interrupt or an ADC trigger. Any of these events or a set of these events can be selected as a source for an interrupt; when any of the selected events occur, an interrupt is generated. Additionally, the same event, a different event, the same set of events, or a different set of events can be selected as a source for an ADC trigger; when any of these selected events occur, an ADC trigger pulse is generated. The selection of events allows the interrupt or ADC trigger to occur at a specific position within the PWM signal. Note that interrupts and ADC triggers are based on the raw events; delays in the PWM signal edges caused by the dead-band generator are not taken into account.

18.2.6 Synchronization Methods

There is a global reset capability that can synchronously reset any or all of the counters in the PWM generators. If multiple PWM generators are configured with the same counter load value, this can be used to guarantee that they also have the same count value (this does imply that the PWM generators must be configured before they are synchronized). With this, more than two PWM signals can be produced with a known relationship between the edges of those signals since the counters always have the same values.

The counter load values and comparator match values of the PWM generator can be updated in two ways. The first is immediate update mode, where a new value is used as soon as the counter reaches zero. By waiting for the counter to reach zero, a guaranteed behavior is defined, and overly short or overly long output PWM pulses are prevented.

The other update method is synchronous, where the new value is not used until a global synchronized update signal is asserted, at which point the new value is used as soon as the counter reaches zero. This second mode allows multiple items in multiple PWM generators to be updated

simultaneously without odd effects during the update; everything runs from the old values until a point at which they all run from the new values. The Update mode of the load and comparator match values can be individually configured in each PWM generator block. It typically makes sense to use the synchronous update mechanism across PWM generator blocks when the timers in those blocks are synchronized, though this is not required in order for this mechanism to function properly.

18.2.7 Fault Conditions

There are two external conditions that affect the PWM block; the signal input on the Fault pin and the stalling of the controller by a debugger. There are two mechanisms available to handle such conditions: the output signals can be forced into an inactive state and/or the PWM timers can be stopped.

Each output signal has a fault bit. If set, a fault input signal causes the corresponding output signal to go into the inactive state. If the inactive state is a safe condition for the signal to be in for an extended period of time, this keeps the output signal from driving the outside world in a dangerous manner during the fault condition. A fault condition can also generate a controller interrupt.

Each PWM generator can also be configured to stop counting during a stall condition. The user can select for the counters to run until they reach zero then stop, or to continue counting and reloading. A stall condition does not generate a controller interrupt.

18.2.8 Output Control Block

With each PWM generator block producing two raw PWM signals, the output control block takes care of the final conditioning of the PWM signals before they go to the pins. Via a single register, the set of PWM signals that are actually enabled to the pins can be modified; this can be used, for example, to perform commutation of a brushless DC motor with a single register write (and without modifying the individual PWM generators, which are modified by the feedback control loop). Similarly, fault control can disable any of the PWM signals as well. A final inversion can be applied to any of the PWM signals, making them active Low instead of the default active High.

18.3 Initialization and Configuration

The following example shows how to initialize the PWM Generator 0 with a 25-KHz frequency, and with a 25% duty cycle on the PWM0 pin and a 75% duty cycle on the PWM1 pin. This example assumes the system clock is 20 MHz.

- 1. Enable the PWM clock by writing a value of 0x00100000 to the **RCGC0** register in the System Control module.
- Enable the clock to the appropriate GPIO module via the RCGC2 register in the System Control module.
- In the GPIO module, enable the appropriate pins for their alternate function using the GPIOAFSEL register.
- 4. Configure the Run-Mode Clock Configuration (RCC) register in the System Control module to use the PWM divide (USEPWMDIV) and set the divider (PWMDIV) to divide by 2 (000).
- Configure the PWM generator for countdown mode with immediate updates to the parameters.
 - Write the PWM0CTL register with a value of 0x0000.0000.
 - Write the PWM0GENA register with a value of 0x0000.008C.

- Write the **PWM0GENB** register with a value of 0x0000.080C.
- 6. Set the period. For a 25-KHz frequency, the period = 1/25,000, or 40 microseconds. The PWM clock source is 10 MHz; the system clock divided by 2. This translates to 400 clock ticks per period. Use this value to set the **PWM0LOAD** register. In Count-Down mode, set the Load field in the **PWM0LOAD** register to the requested period minus one.
 - Write the PWM0LOAD register with a value of 0x0000.018F.
- 7. Set the pulse width of the PWM0 pin for a 25% duty cycle.
 - Write the PWM0CMPA register with a value of 0x0000.012B.
- 8. Set the pulse width of the PWM1 pin for a 75% duty cycle.
 - Write the PWM0CMPB register with a value of 0x0000.0063.
- 9. Start the timers in PWM generator 0.
 - Write the PWM0CTL register with a value of 0x0000.0001.
- 10. Enable PWM outputs.
 - Write the PWMENABLE register with a value of 0x0000.0003.

18.4 Register Map

"Register Map" on page 454 lists the PWM registers. The offset listed is a hexadecimal increment to the register's address, relative to the PWM base address of 0x4002.8000.

Table 18-1. PWM Register Map

Offset	Name	Type	Reset	Description	See page
		R/W	0x0000.0000		466
0x000	PWMCTL	R/W	0x0000.0000	PWM Master Control	456
0x004	PWMSYNC	R/W	0x0000.0000	PWM Time Base Sync	457
0x008	PWMENABLE	R/W	0x0000.0000	PWM Output Enable	458
0x00C	PWMINVERT	R/W	0x0000.0000	PWM Output Inversion	459
0x010	PWMFAULT	R/W	0x0000.0000	PWM Output Fault	460
0x014	PWMINTEN	R/W	0x0000.0000	PWM Interrupt Enable	461
0x018	PWMRIS	RO	0x0000.0000	PWM Raw Interrupt Status	462
0x01C	PWMISC	R/W1C	0x0000.0000	PWM Interrupt Status and Clear	463
0x020	PWMSTATUS	RO	0x0000.0000	PWM Status	464
0x040	PWM0CTL	R/W	0x0000.0000	PWM0 Control	465
0x048	PWM0RIS	RO	0x0000.0000	PWM0 Raw Interrupt Status	468
0x04C	PWM0ISC	R/W1C	0x0000.0000	PWM0 Interrupt Status and Clear	469

Offset	Name	Туре	Reset	Description	See page
0x050	PWM0LOAD	R/W	0x0000.0000	PWM0 Load	470
0x054	PWM0COUNT	RO	0x0000.0000	PWM0 Counter	471
0x058	PWM0CMPA	R/W	0x0000.0000	PWM0 Compare A	472
0x05C	PWM0CMPB	R/W	0x0000.0000	PWM0 Compare B	473
0x060	PWM0GENA	R/W	0x0000.0000	PWM0 Generator A Control	474
0x064	PWM0GENB	R/W	0x0000.0000	PWM0 Generator B Control	476
0x068	PWM0DBCTL	R/W	0x0000.0000	PWM0 Dead-Band Control	477
0x06C	PWM0DBRISE	R/W	0x0000.0000	PWM0 Dead-Band Rising-Edge Delay	478
0x070	PWM0DBFALL	R/W	0x0000.0000	PWM0 Dead-Band Falling-Edge-Delay	479
0x080	PWM1CTL	R/W	0x0000.0000	PWM1 Control	465
0x084	PWM1INTEN	R/W	0x0000.0000	PWM1 Interrupt and Trigger Enable	466
0x088	PWM1RIS	RO	0x0000.0000	PWM1 Raw Interrupt Status	468
0x08C	PWM1ISC	R/W1C	0x0000.0000	PWM1 Interrupt Status and Clear	469
0x090	PWM1LOAD	R/W	0x0000.0000	PWM1 Load	470
0x094	PWM1COUNT	RO	0x0000.0000	PWM1 Counter	471
0x098	PWM1CMPA	R/W	0x0000.0000	PWM1 Compare A	472
0x09C	PWM1CMPB	R/W	0x0000.0000	PWM1 Compare B	473
0x0A0	PWM1GENA	R/W	0x0000.0000	PWM1 Generator A Control	474
0x0A4	PWM1GENB	R/W	0x0000.0000	PWM1 Generator B Control	476
0x0A8	PWM1DBCTL	R/W	0x0000.0000	PWM1 Dead-Band Control	477
0x0AC	PWM1DBRISE	R/W	0x0000.0000	PWM1 Dead-Band Rising-Edge Delay	478
0x0B0	PWM1DBFALL	R/W	0x0000.0000	PWM1 Dead-Band Falling-Edge-Delay	479

18.5 Register Descriptions

The remainder of this section lists and describes the PWM registers, in numerical order by address offset.

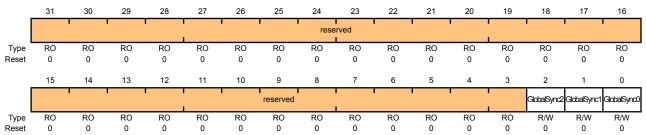
Register 1: PWM Master Control (PWMCTL), offset 0x000

This register provides master control over the PWM generation blocks.

PWM Master Control (PWMCTL)

Base 0x4002.8000

Offset 0x000 Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:3	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
2	GlobalSync2	R/W	0	Same as GlobalSync0 but for PWM generator 2.
1	GlobalSync1	R/W	0	Same as GlobalSync0 but for PWM generator 1.
0	GlobalSync0	R/W	0	Setting this bit causes any queued update to a load or comparator register in PWM generator 0 to be applied the next time the corresponding counter becomes zero. This bit automatically clears when the updates have completed; it cannot be cleared by software.

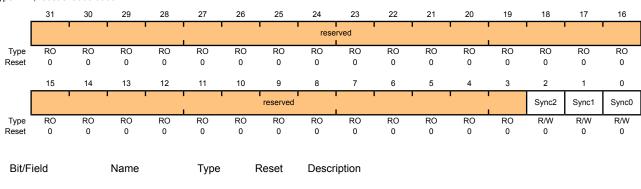
Register 2: PWM Time Base Sync (PWMSYNC), offset 0x004

This register provides a method to perform synchronization of the counters in the PWM generation blocks. Writing a bit in this register to 1 causes the specified counter to reset back to 0; writing multiple bits resets multiple counters simultaneously. The bits auto-clear after the reset has occurred; reading them back as zero indicates that the synchronization has completed.

PWM Time Base Sync (PWMSYNC)

Base 0x4002.8000

Offset 0x004 Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:3	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
2	Sync2	R/W	0	Performs a reset of the PWM generator 2 counter.
1	Sync1	R/W	0	Performs a reset of the PWM generator 1 counter.
0	Sync0	R/W	0	Performs a reset of the PWM generator 0 counter.

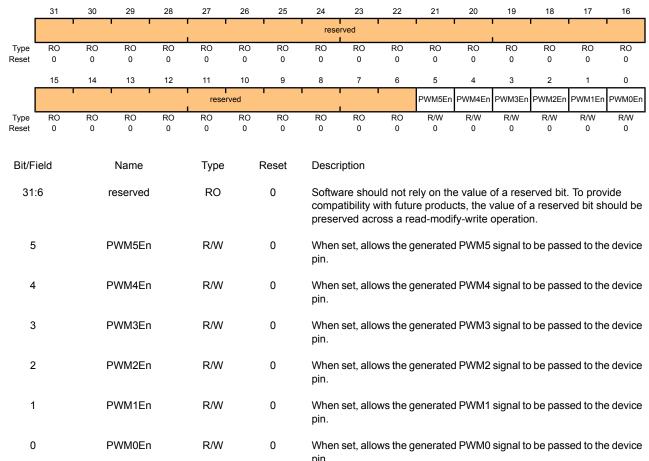
Register 3: PWM Output Enable (PWMENABLE), offset 0x008

This register provides a master control of which generated PWM signals are output to device pins. By disabling a PWM output, the generation process can continue (for example, when the time bases are synchronized) without driving PWM signals to the pins. When bits in this register are set, the corresponding PWM signal is passed through to the output stage, which is controlled by the **PWMINVERT** register. When bits are not set, the PWM signal is replaced by a zero value which is also passed to the output stage.

PWM Output Enable (PWMENABLE)

Base 0x4002.8000 Offset 0x008

Type R/W, reset 0x0000.0000



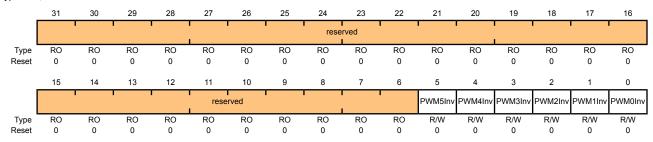
Register 4: PWM Output Inversion (PWMINVERT), offset 0x00C

This register provides a master control of the polarity of the PWM signals on the device pins. The PWM signals generated by the PWM generator are active High; they can optionally be made active Low via this register. Disabled PWM channels are also passed through the output inverter (if so configured) so that inactive channels maintain the correct polarity.

PWM Output Inversion (PWMINVERT)

Base 0x4002.8000

Offset 0x00C Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:6	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
5	PWM5Inv	R/W	0	When set, the generated PWM5 signal is inverted.
4	PWM4Inv	R/W	0	When set, the generated PWM4 signal is inverted.
3	PWM3Inv	R/W	0	When set, the generated PWM3 signal is inverted.
2	PWM2Inv	R/W	0	When set, the generated PWM2 signal is inverted.
1	PWM1Inv	R/W	0	When set, the generated PWM1 signal is inverted.
0	PWM0Inv	R/W	0	When set, the generated PWM0 signal is inverted.

Register 5: PWM Output Fault (PWMFAULT), offset 0x010

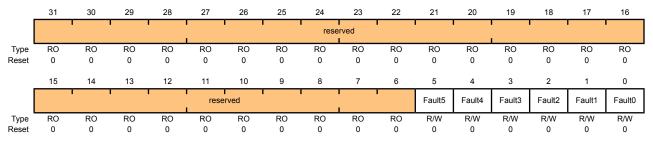
This register controls the behavior of the PWM outputs in the presence of fault conditions. Both the fault input and debug events are considered fault conditions. On a fault condition, each PWM signal can either be passed through unmodified or driven Low. For outputs that are configured for pass-through, the debug event handling on the corresponding PWM generator also determines if the PWM signal continues to be generated.

Fault condition control happens before the output inverter, so PWM signals driven Low on fault are inverted if the channel is configured for inversion (therefore, the pin is driven High on a fault condition).

PWM Output Fault (PWMFAULT)

Base 0x4002.8000

Offset 0x010 Type R/W, reset 0x0000.0000



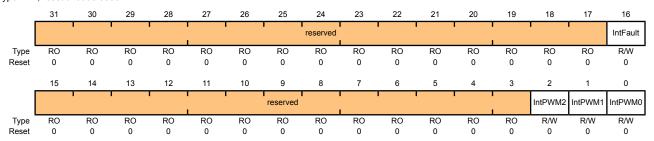
Bit/Field	Name	Туре	Reset	Description
31:6	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
5	Fault5	R/W	0	When set, the PWM5 output signal is driven Low on a fault condition.
4	Fault4	R/W	0	When set, the PWM4 output signal is driven Low on a fault condition.
3	Fault3	R/W	0	When set, the PWM3 output signal is driven Low on a fault condition.
2	Fault2	R/W	0	When set, the PWM2 output signal is driven Low on a fault condition.
1	Fault1	R/W	0	When set, the PWM1 output signal is driven Low on a fault condition.
0	Fault0	R/W	0	When set, the PWM0 output signal is driven Low on a fault condition.

Register 6: PWM Interrupt Enable (PWMINTEN), offset 0x014

This register controls the global interrupt generation capabilities of the PWM module. The events that can cause an interrupt are the fault input and the individual interrupts from the PWM generators.

PWM Interrupt Enable (PWMINTEN)

Base 0x4002.8000 Offset 0x014 Type R/W, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:17	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
16	IntFault	R/W	0	When 1, an interrupt occurs when the fault input is asserted.
15:3	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
2	IntPWM2	R/W	0	When 1, an interrupt occurs when the PWM generator 2 block asserts an interrupt.
1	IntPWM1	R/W	0	When 1, an interrupt occurs when the PWM generator 1 block asserts an interrupt.
0	IntPWM0	R/W	0	When 1, an interrupt occurs when the PWM generator 0 block asserts an interrupt.

Register 7: PWM Raw Interrupt Status (PWMRIS), offset 0x018

This register provides the current set of interrupt sources that are asserted, regardless of whether they cause an interrupt to be asserted to the controller. The fault interrupt is latched on detection; it must be cleared through the **PWM Interrupt Status and Clear (PWMISC)** register (see page 463). The PWM generator interrupts simply reflect the status of the PWM generators; they are cleared via the interrupt status register in the PWM generator blocks. Bits set to 1 indicate the events that are active; a zero bit indicates that the event in question is not active.

PWM Raw Interrupt Status (PWMRIS)

reserved

IntPWM2

IntPWM1

RO

RO

RO

0

0

0

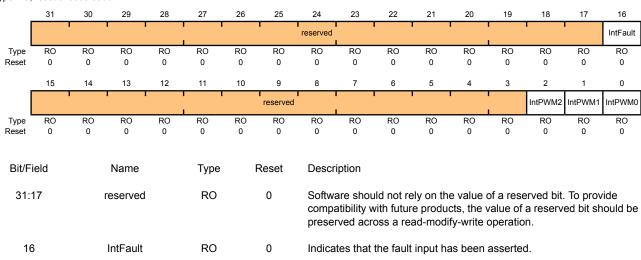
Base 0x4002.8000 Offset 0x018

15:3

2

1

Type RO, reset 0x0000.0000



Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be

Indicates that the PWM generator 2 block is asserting its interrupt.

Indicates that the PWM generator 1 block is asserting its interrupt.

preserved across a read-modify-write operation.

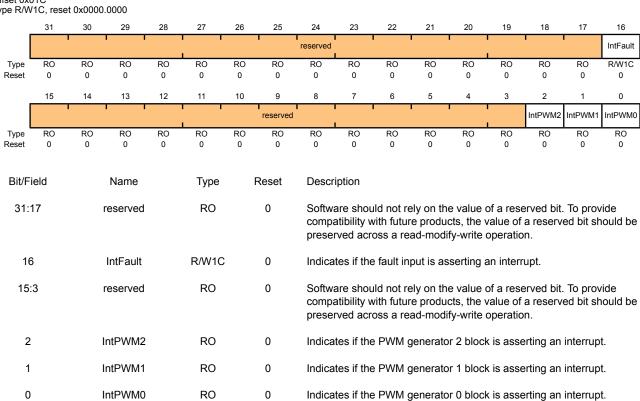
Register 8: PWM Interrupt Status and Clear (PWMISC), offset 0x01C

This register provides a summary of the interrupt status of the individual PWM generator blocks. A bit set to 1 indicates that the corresponding generator block is asserting an interrupt. The individual interrupt status registers in each block must be consulted to determine the reason for the interrupt, and used to clear the interrupt. For the fault interrupt, a write of 1 to that bit position clears the latched interrupt status.

PWM Interrupt Status and Clear (PWMISC)

Base 0x4002.8000 Offset 0x01C

Type R/W1C, reset 0x0000.0000

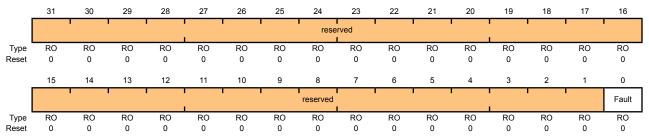


Register 9: PWM Status (PWMSTATUS), offset 0x020

This register provides the status of the Fault input signal.

PWM Status (PWMSTATUS)

Base 0x4002.8000 Offset 0x020 Type RO, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	Fault	RO	0	When set to 1, indicates the fault input is asserted.

Register 10: PWM0 Control (PWM0CTL), offset 0x040

Register 11: PWM1 Control (PWM1CTL), offset 0x080

Register 12: PWM2 Control (PWM2CTL), offset 0x0C0

The PWM0 block produces the PWM0 and PWM1 outputs, the PWM1 block produces the PWM2 and PWM3 outputs, and the PWM2 block produces the PWM4 and PWM5 outputs.

PWM0 Control (PWM0CTL)

Base 0x4002.8000 Offset 0x040 Type R/W, reset 0x0000.0000

,,	,															
	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
		1	1	'	· · · · ·		1	rese	rved I	1	1	1	·	1		1
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		1	ı	•	reser	ved	1	•			CmpBUpd	CmpAUpd	LoadUpd	Debug	Mode	Enable
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Bit/F	ield		Name		Туре	F	Reset	Descr	iption							
31:	:6		reserved	I	RO		0	compa	atibility v	vith futu	ely on the re product ad-modi	cts, the v	alue of	a reserve	•	
5		,	CmnDI In	٨	D/M/		0	Samo	00 C	بط المستتم	ıt for the	compar	otor P ro	giotor		

31:6	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
5	CmpBUpd	R/W	0	Same as CmpAUpd but for the comparator B register.
4	CmpAUpd	R/W	0	The Update mode for the comparator A register. If 0, updates to the register are reflected to the comparator the next time the counter is 0. If 1, updates to the register are delayed until the next time the counter is 0 after a synchronous update has been requested through the PWM Master Control (PWMCTL) register (see page 456).
3	LoadUpd	R/W	0	The Update mode for the load register. If 0, updates to the register are reflected to the counter the next time the counter is 0. If 1, updates to the register are delayed until the next time the counter is 0 after a synchronous update has been requested through the PWM Master Control (PWMCTL) register.
2	Debug	R/W	0	The behavior of the counter in Debug mode. If 0, the counter stops running when it next reaches 0, and continues running again when no longer in Debug mode. If 1, the counter always runs.
1	Mode	R/W	0	The mode for the counter. If 0, the counter counts down from the load value to 0 and then wraps back to the load value (Count-Down mode). If 1, the counter counts up from 0 to the load value, back down to 0, and then repeats (Count-Up/Down mode).
0	Enable	R/W	0	Master enable for the PWM generation block. If 0, the entire block is disabled and not clocked. If 1, the block is enabled and produces PWM signals.

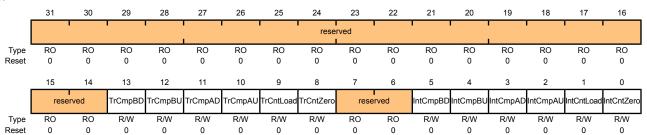
Register 13: PWM0 Interrupt and Trigger Enable (PWM0INTEN), offset 0x044 Register 14: PWM1 Interrupt and Trigger Enable (PWM1INTEN), offset 0x084 Register 15: PWM2 Interrupt and Trigger Enable (PWM2INTEN), offset 0x0C4

These registers control the interrupt and ADC trigger generation capabilities of the PWM generators (**PWM0INTEN** controls the PWM generator 0 block, and so on). The events that can cause an interrupt or an ADC trigger are:

- The counter being equal to the load register
- The counter being equal to zero
- The counter being equal to the comparator A register while counting up
- The counter being equal to the comparator A register while counting down
- The counter being equal to the comparator B register while counting up
- The counter being equal to the comparator B register while counting down

Any combination of these events can generate either an interrupt or an ADC trigger, though no determination can be made as to the actual event that caused an ADC trigger if more than one is specified.

()
Base 0x4002.8000
Offset
Type R/W, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:14	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
13	TrCmpBD	R/W	0	When 1, a trigger pulse is output when the counter matches the comparator B value and the counter is counting down.
12	TrCmpBU	R/W	0	When 1, a trigger pulse is output when the counter matches the comparator B value and the counter is counting up.
11	TrCmpAD	R/W	0	When 1, a trigger pulse is output when the counter matches the comparator A value and the counter is counting down.
10	TrCmpAU	R/W	0	When 1, a trigger pulse is output when the counter matches the comparator A value and the counter is counting up.

Bit/Field	Name	Туре	Reset	Description
9	TrCntLoad	R/W	0	When 1, a trigger pulse is output when the counter matches the PWMnLOAD register.
8	TrCntZero	R/W	0	When 1, a trigger pulse is output when the counter is 0.
7:6	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
5	IntCmpBD	R/W	0	When 1, an interrupt occurs when the counter matches the comparator B value and the counter is counting down.
4	IntCmpBU	R/W	0	When 1, an interrupt occurs when the counter matches the comparator B value and the counter is counting up.
3	IntCmpAD	R/W	0	When 1, an interrupt occurs when the counter matches the comparator A value and the counter is counting down.
2	IntCmpAU	R/W	0	When 1, an interrupt occurs when the counter matches the comparator A value and the counter is counting up.
1	IntCntLoad	R/W	0	When 1, an interrupt occurs when the counter matches the PWMnLOAD register.
0	IntCntZero	R/W	0	When 1, an interrupt occurs when the counter is 0.

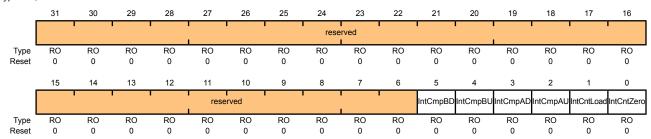
Register 16: PWM0 Raw Interrupt Status (PWM0RIS), offset 0x048 Register 17: PWM1 Raw Interrupt Status (PWM1RIS), offset 0x088 Register 18: PWM2 Raw Interrupt Status (PWM2RIS), offset 0x0C8

These registers provide the current set of interrupt sources that are asserted, regardless of whether they cause an interrupt to be asserted to the controller (**PWM0RIS** controls the PWM generator 0 block, and so on). Bits set to 1 indicate the latched events that have occurred; a 0 bit indicates that the event in question has not occurred.

PWM0 Raw Interrupt Status (PWM0RIS)

Base 0x4002.8000 Offset 0x048

Type RO, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:6	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
5	IntCmpBD	RO	0	Indicates that the counter has matched the comparator B value while counting down.
4	IntCmpBU	RO	0	Indicates that the counter has matched the comparator B value while counting up.
3	IntCmpAD	RO	0	Indicates that the counter has matched the comparator A value while counting down.
2	IntCmpAU	RO	0	Indicates that the counter has matched the comparator A value while counting up.
1	IntCntLoad	RO	0	Indicates that the counter has matched the PWMnLOAD register.
0	IntCntZero	RO	0	Indicates that the counter has matched 0.

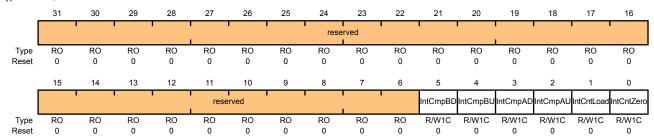
Register 19: PWM0 Interrupt Status and Clear (PWM0ISC), offset 0x04C Register 20: PWM1 Interrupt Status and Clear (PWM1ISC), offset 0x08C Register 21: PWM2 Interrupt Status and Clear (PWM2ISC), offset 0x0CC

These registers provide the current set of interrupt sources that are asserted to the controller (**PWM0ISC** controls the PWM generator 0 block, and so on). Bits set to 1 indicate the latched events that have occurred; a 0 bit indicates that the event in question has not occurred. These are R/W1C registers; writing a 1 to a bit position clears the corresponding interrupt reason.

PWM0 Interrupt Status and Clear (PWM0ISC)

Base 0x4002.8000

Offset 0x04C Type R/W1C, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:6	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
5	IntCmpBD	R/W1C	0	Indicates that the counter has matched the comparator B value while counting down.
4	IntCmpBU	R/W1C	0	Indicates that the counter has matched the comparator B value while counting up.
3	IntCmpAD	R/W1C	0	Indicates that the counter has matched the comparator A value while counting down.
2	IntCmpAU	R/W1C	0	Indicates that the counter has matched the comparator A value while counting up.
1	IntCntLoad	R/W1C	0	Indicates that the counter has matched the PWMnLOAD register.
0	IntCntZero	R/W1C	0	Indicates that the counter has matched 0.

Register 22: PWM0 Load (PWM0LOAD), offset 0x050

Register 23: PWM1 Load (PWM1LOAD), offset 0x090

Register 24: PWM2 Load (PWM2LOAD), offset 0x0D0

These registers contain the load value for the PWM counter (**PWM0LOAD** controls the PWM generator 0 block, and so on). Based on the counter mode, either this value is loaded into the counter after it reaches zero, or it is the limit of up-counting after which the counter decrements back to zero. If the Load Value Update mode is immediate, this value is used the next time the counter reaches zero; if the mode is synchronous, it is used the next time the counter reaches zero after a synchronous update has been requested through the **PWM Master Control (PWMCTL)** register (see page 456). If this register is re-written before the actual update occurs, the previous value is never used and is lost.

PWM0 Load (PWM0LOAD)

Base 0x4002.8000 Offset 0x050

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
		1	1	'			1	rese	rved	1				'	'	'
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO							
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		i	i	i			ı	Lo	l ad	î				i	1	
Туре	R/W	R/W	R/W	R/W	I R/W	R/W	R/W	Lo R/W	ad R/W	R/W						
Type Reset	R/W 0			R/W 0												
								R/W	R/W							

Ditt icia	Hamo	Турс	110001	Becomplien
31:16	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
15:0	Load	R/W	0	The counter load value.

Register 25: PWM0 Counter (PWM0COUNT), offset 0x054

Register 26: PWM1 Counter (PWM1COUNT), offset 0x094

Register 27: PWM2 Counter (PWM2COUNT), offset 0x0D4

These registers contain the current value of the PWM counter (PWM0COUNT is the value of the PWM generator 0 block, and so on). When this value matches the load register, a pulse is output; this can drive the generation of a PWM signal (via the PWMnGENA/PWMnGENB registers, see page 474 and page 476) or drive an interrupt or ADC trigger (via the **PWMnINTEN** register, see page 466). A pulse with the same capabilities is generated when this value is zero.

PWM0 Counter (PWM0COUNT)

Base 0x4002.8000 Offset 0x054

Offset 0x0 Type RO,		0000.000	00													
_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
					'		'	rese	rved				·			•
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
			1				I	Co	unt I	1	1		I			'
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0
Bit/F	ield		Name		Туре	F	Reset	Descr	iption							
31:	31:16 reserved RO 0					0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.									
15:	:0		Count		RO		0	The c	urrent va	lue of th	e count	er.				

Register 28: PWM0 Compare A (PWM0CMPA), offset 0x058

Register 29: PWM1 Compare A (PWM1CMPA), offset 0x098

Register 30: PWM2 Compare A (PWM2CMPA), offset 0x0D8

These registers contain a value to be compared against the counter (**PWM0CMPA** controls the PWM generator 0 block, and so on). When this value matches the counter, a pulse is output; this can drive the generation of a PWM signal (via the **PWMnGENA/PWMnGENB** registers) or drive an interrupt or ADC trigger (via the **PWMnINTEN** register). If the value of this register is greater than the **PWMnLOAD** register (see page 470), then no pulse is ever output.

If the comparator A update mode is immediate (based on the CmpAUpd bit in the **PWMnCTL** register), then this 16-bit CompA value is used the next time the counter reaches zero. If the update mode is synchronous, it is used the next time the counter reaches zero after a synchronous update has been requested through the **PWM Master Control (PWMCTL)** register (see page 456). If this register is rewritten before the actual update occurs, the previous value is never used and is lost.

PWM0 Compare A (PWM0CMPA)

Base 0x4002.8000 Offset 0x058

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
		'	'	'	' '		'	rese	rved	•		'		•	'	'
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		1	1	•	! ! !		ı	Con	I npA I	ı	ı	ı	! !	I	1	'
Туре	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Bit/F	ield		Name		Туре	I	Reset	Descr	iption							
31:	16 reserved			C				Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.								
15	:0		CompA		R/W		0	The va	alue to b	e compa	ared aga	ainst the	counter	Ē		

Register 31: PWM0 Compare B (PWM0CMPB), offset 0x05C

Register 32: PWM1 Compare B (PWM1CMPB), offset 0x09C

Register 33: PWM2 Compare B (PWM2CMPB), offset 0x0DC

These registers contain a value to be compared against the counter (**PWM0CMPB** controls the PWM generator 0 block, and so on). When this value matches the counter, a pulse is output; this can drive the generation of a PWM signal (via the **PWMnGENA/PWMnGENB** registers) or drive an interrupt or ADC trigger (via the **PWMnINTEN** register). If the value of this register is greater than the **PWMnLOAD** register, then no pulse is ever output.

IF the comparator B update mode is immediate (based on the <code>CmpBUpd</code> bit in the **PWMnCTL** register), then this 16-bit <code>CompB</code> value is used the next time the counter reaches zero. If the update mode is synchronous, it is used the next time the counter reaches zero after a synchronous update has been requested through the **PWM Master Control (PWMCTL)** register (see page 456). If this register is rewritten before the actual update occurs, the previous value is never used and is lost.

PWM0 Compare B (PWM0CMPB)

Base 0x4002.8000 Offset 0x05C

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
		•	•				'	rese	rved	•	•	•		•	•	•
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		1	1				ı	Cor	I npB I	1	ı	ı		ı	1	'
Туре	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Dive	: - 1 - 1		Mana		T		D 4	D								
Bit/F	ieia		Name		Type		Reset	Descr	iption							
31:	16	7,1						Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.								
15:	:0		CompB		R/W		0	The va	alue to b	e comp	ared aga	ainst the	counter	:		

Register 34: PWM0 Generator A Control (PWM0GENA), offset 0x060

Register 35: PWM1 Generator A Control (PWM1GENA), offset 0x0A0

Register 36: PWM2 Generator A Control (PWM2GENA), offset 0x0E0

These registers control the generation of the PWMnA signal based on the load and zero output pulses from the counter, as well as the compare A and compare B pulses from the comparators (**PWM0GENA** controls the PWM generator 0 block, and so on). When the counter is running in Count-Down mode, only four of these events occur; when running in Count-Up/Down mode, all six occur. These events provide great flexibility in the positioning and duty cycle of the PWM signal that is produced.

The **PWM0GENA** register controls generation of the PWM0A signal; **PWM1GENA**, the PWM1A signal; and **PWM2GENA**, the PWM2A signal.

Each field in these registers can take on one of the values defined in Table 18-2 on page 475, which defines the effect of the event on the output signal.

If a zero or load event coincides with a compare A or compare B event, the zero or load action is taken and the compare A or compare B action is ignored. If a compare A event coincides with a compare B event, the compare A action is taken and the compare B action is ignored.

PWM0 Generator A Control (PWM0GENA)

29

28

26

30

Base 0x4002.8000 Offset 0x060

Type	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO		
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
_	15	14	13	12	11	10	9	. 8	7	6	5	4	3	2	1	0		
		rese	erved		ActCm	npBD	ActC	mpBU	ActCr	npAD	ActCr	npAU	ActL	oad	Actz	Zero		
Type	RO	RO	RO	RO	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W		
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
					_	_		_										
Bit/Fi	eld		Name		Type	F	Reset	Descr	iption									
													_	f a reserved bit. To provide				
31:1	12	I	reserved		RO		0				•							
					compatibility with						e produ	cts, the ι	alue of	a reserv	ed bit sh	ould be		
								prese	rved acre	oss a rea	ad-modi	fy-write	operatio	٦.				
11:1	10	Α	ctCmpBl	D	R/W		0	The a	The action to be taken when the counter matches comparator B while									
								counting down.										
								Coo Table 19 2 on page 475, which defines the effect of the event on										
								See Table 18-2 on page 475, which defines the effect of the event on										
								the output signal.										
9:8	3	Α	ctCmpBl	U	R/W		0						er match		•			
								counti	ng up. C	occurs o	nly wher	n the Mo	de bit in	the PW	MnCTL	register		
								(see p	age 465	i) is set t	o 1.							
								Coo T	abla 10	2 on n	17E :	- ا- طمنطب	finas the	offoot -	of the co	ant an		
											je 4/5, \	wnich de	fines the	e enect o	or trie ev	ent on		
								trie ot	ıtput sigr	ıaı.								
			10 41	_	D 44/		•											
7:6	Ó	А	ctCmpAl	ט	R/W		0				wnen tr	ne count	er match	nes com	parator i	4 while		
								counti	ng dowr	١.								
								See T	able 18-	2 on nac	ne 475 v	which de	fines the	effect o	of the ev	ent on		
									tput sigr		,	······································		2 311001). IIIO OV	J. 10 J. 1		
								uie Ou	itput sigi	iai.								

Bit/Field	Name	Туре	Reset	Description
5:4	ActCmpAU	R/W	0	The action to be taken when the counter matches comparator A while counting up. Occurs only when the Mode bit in the PWMnCTL register is set to 1.
				See Table 18-2 on page 475, which defines the effect of the event on the output signal.
3:2	ActLoad	R/W	0	The action to be taken when the counter matches the load value.
				See Table 18-2 on page 475, which defines the effect of the event on the output signal.
1:0	ActZero	R/W	0	The action to be taken when the counter is zero.
				See Table 18-2 on page 475, which defines the effect of the event on the output signal.

Table 18-2. PWM Generator Action Encodings

Value	Description
00	Do nothing.
01	Invert the output signal.
10	Set the output signal to 0.
11	Set the output signal to 1.

Register 37: PWM0 Generator B Control (PWM0GENB), offset 0x064 Register 38: PWM1 Generator B Control (PWM1GENB), offset 0x0A4 Register 39: PWM2 Generator B Control (PWM2GENB), offset 0x0E4

These registers control the generation of the PWMnB signal based on the load and zero output pulses from the counter, as well as the compare A and compare B pulses from the comparators (**PWM0GENB** controls the PWM generator 0 block, and so on). When the counter is running in Down mode, only four of these events occur; when running in Up/Down mode, all six occur. These events provide great flexibility in the positioning and duty cycle of the PWM signal that is produced.

The **PWM0GENB** register controls generation of the PWM0B signal; **PWM1GENB**, the PWM1B signal; and **PWM2GENB**, the PWM2B signal.

Each field in these registers can take on one of the values defined in Table 18-2 on page 475, which defines the effect of the event on the output signal.

If a zero or load event coincides with a compare A or compare B event, the zero or load action is taken and the compare A or compare B action is ignored. If a compare A event coincides with a compare B event, the compare B action is taken and the compare A action is ignored.

PWM0 Generator B Control (PWM0GENB)

Base 0x4002.8000 Offset 0x064

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
				•				rese	rved							
Type Reset	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0	RO 0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		rese	rved		ActCr	npBD	ActCr	mpBU	ActCr	npAD	ActCr	npAU	ActL	oad_	Act	Zero
Type Reset	RO 0	RO 0	RO 0	RO 0	R/W 0											

Bit/Field	Name	Туре	Reset	Description
31:12	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
11:10	ActCmpBD	R/W	0	The action to be taken when the counter matches comparator B while counting down.
9:8	ActCmpBU	R/W	0	The action to be taken when the counter matches comparator B while counting up. Occurs only when the Mode bit in the PWMnCTL register (see page 465) is set to 1.
7:6	ActCmpAD	R/W	0	The action to be taken when the counter matches comparator A while counting down.
5:4	ActCmpAU	R/W	0	The action to be taken when the counter matches comparator A while counting up. Occurs only when the <code>Mode</code> bit in the <code>PWMnCTL</code> register is set to 1.
3:2	ActLoad	R/W	0	The action to be taken when the counter matches the load value.
1:0	ActZero	R/W	0	The action to be taken when the counter is 0.

Register 40: PWM0 Dead-Band Control (PWM0DBCTL), offset 0x068 Register 41: PWM1 Dead-Band Control (PWM1DBCTL), offset 0x0A8 Register 42: PWM2 Dead-Band Control (PWM2DBCTL), offset 0x0E8

The **PWM0DBCTL** register controls the dead-band generator, which produces the PWM0 and PWM1 signals based on the PWM0A and PWM0B signals. When disabled, the PWM0A signal passes through to the PWM0 signal and the PWM0B signal passes through to the PWM1 signal. When enabled and inverting the resulting waveform, the PWM0B signal is ignored; the PWM0 signal is generated by delaying the rising edge(s) of the PWM0A signal by the value in the **PWM0DBRISE** register (see page 478), and the PWM1 signal is generated by delaying the falling edge(s) of the PWM0A signal by the value in the **PWM0DBFALL** register (see page 479). In a similar manner, PWM2 and PWM3 are produced from the PWM1A and PWM1B signals, and PWM4 and PWM5 are produced from the PWM2A and PWM2B signals.

PWM0 Dead-Band Control (PWM0DBCTL)

Base 0x4002.8000 Offset 0x068

_	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
			'	'				rese	rved					•		'
Туре	RO	RO	RO	RO	RO	RO	RO	RO	RO							
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		Î	î	i			ì	reserved						î i		Enable
Туре	RO	RO	RO	RO	RO	RO	RO	RO	R/W							
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Bit/Field	Name	Type	Reset	Description
31:1	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
0	Enable	R/W	0	When set, the dead-band generator inserts dead bands into the output signals; when clear, it simply passes the PWM signals through.

Register 43: PWM0 Dead-Band Rising-Edge Delay (PWM0DBRISE), offset 0x06C

Register 44: PWM1 Dead-Band Rising-Edge Delay (PWM1DBRISE), offset 0x0AC

Register 45: PWM2 Dead-Band Rising-Edge Delay (PWM2DBRISE), offset 0x0EC

The **PWM0DBRISE** register contains the number of clock ticks to delay the rising edge of the PWM0A signal when generating the PWM0 signal. If the dead-band generator is disabled through the **PWMnDBCTL** register, the **PWM0DBRISE** register is ignored. If the value of this register is larger than the width of a High pulse on the input PWM signal, the rising-edge delay consumes the entire High time of the signal, resulting in no High time on the output. Care must be taken to ensure that the input High time always exceeds the rising-edge delay. In a similar manner, PWM2 is generated from PWM1A with its rising edge delayed and PWM4 is produced from PWM2A with its rising edge delayed.

PWM0 Dead-Band Rising-Edge Delay (PWM0DBRISE)

Base 0x4002.8000 Offset 0x06C

	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
							•	rese	rved			'		'	•	•
Type	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO	RO
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
		rese	rved	'		•	•	•	!	Risel) Delay	•	!	1	•	'
Type	RO	RO	RO	RO	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Bit/Field	Name	Type	Reset	Description
31:12	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
11:0	RiseDelay	R/W	0	The number of clock ticks to delay the rising edge.

Register 46: PWM0 Dead-Band Falling-Edge-Delay (PWM0DBFALL), offset 0x070

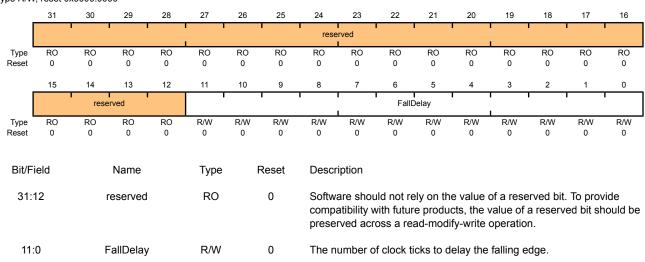
Register 47: PWM1 Dead-Band Falling-Edge-Delay (PWM1DBFALL), offset 0x0B0

Register 48: PWM2 Dead-Band Falling-Edge-Delay (PWM2DBFALL), offset 0x0F0

The **PWM0DBFALL** register contains the number of clock ticks to delay the falling edge of the PWM0A signal when generating the PWM1 signal. If the dead-band generator is disabled, this register is ignored. If the value of this register is larger than the width of a Low pulse on the input PWM signal, the falling-edge delay consumes the entire Low time of the signal, resulting in no Low time on the output. Care must be taken to ensure that the input Low time always exceeds the falling-edge delay. In a similar manner, PWM3 is generated from PWM1A with its falling edge delayed and PWM5 is produced from PWM2A with its falling edge delayed.

PWM0 Dead-Band Falling-Edge-Delay (PWM0DBFALL)

Base 0x4002.8000 Offset 0x070 Type R/W, reset 0x0000.0000



19 Quadrature Encoder Interface (QEI)

A quadrature encoder, also known as a 2-channel incremental encoder, converts linear displacement into a pulse signal. By monitoring both the number of pulses and the relative phase of the two signals, you can track the position, direction of rotation, and speed. In addition, a third channel, or index signal, can be used to reset the position counter.

The Stellaris[®] quadrature encoder interface (QEI) module interprets the code produced by a quadrature encoder wheel to integrate position over time and determine direction of rotation. In addition, it can capture a running estimate of the velocity of the encoder wheel.

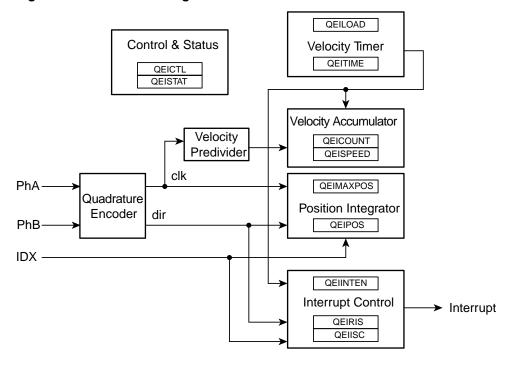
The Stellaris[®] quadrature encoder has the following features:

- Position integrator that tracks the encoder position
- Velocity capture using built-in timer
- Interrupt generation on:
 - Index pulse
 - Velocity-timer expiration
 - Direction change
 - Quadrature error detection

19.1 Block Diagram

Figure 19-1 on page 480 provides a block diagram of a Stellaris[®] QEI module.

Figure 19-1. QEI Block Diagram



19.2 Functional Description

The QEI module interprets the two-bit gray code produced by a quadrature encoder wheel to integrate position over time and determine direction of rotation. In addition, it can capture a running estimate of the velocity of the encoder wheel.

The position integrator and velocity capture can be independently enabled, though the position integrator must be enabled before the velocity capture can be enabled. The two phase signals, PhA and PhB, can be swapped before being interpreted by the QEI module to change the meaning of forward and backward, and to correct for miswiring of the system. Alternatively, the phase signals can be interpreted as a clock and direction signal as output by some encoders.

The QEI module supports two modes of signal operation: quadrature phase mode and clock/direction mode. In quadrature phase mode, the encoder produces two clocks that are 90 degrees out of phase; the edge relationship is used to determine the direction of rotation. In clock/direction mode, the encoder produces a clock signal to indicate steps and a direction signal to indicate the direction of rotation. This mode is determined by the SigMode bit of the **QEI Control (QEICTL)** register (see page 485).

When the QEI module is set to use the quadrature phase mode (SigMode bit equals zero), the capture mode for the position integrator can be set to update the position counter on every edge of the PhA signal or to update on every edge of both PhA and PhB. Updating the position counter on every PhA and PhB provides more positional resolution at the cost of less range in the positional counter.

When edges on PhA lead edges on PhB, the position counter is incremented. When edges on PhB lead edges on PhA, the position counter is decremented. When a rising and falling edge pair is seen on one of the phases without any edges on the other, the direction of rotation has changed.

The positional counter is automatically reset on one of two conditions: sensing the index pulse or reaching the maximum position value. Which mode is determined by the ResMode bit of the **QEI Control (QEICTL)** register.

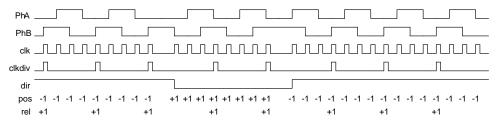
When ResMode is 0, the positional counter is reset when the index pulse is sensed. This limits the positional counter to the values [0:N-1], where N is the number of phase edges in a full revolution of the encoder wheel. The **QEIMAXPOS** register must be programmed with N-1 so that the reverse direction from position 0 can move the position counter to N-1. In this mode, the position register contains the absolute position of the encoder relative to the index (or home) position once an index pulse has been seen.

When ResMode is 1, the positional counter is constrained to the range [0:M], where M is the programmable maximum value. The index pulse is ignored by the positional counter in this mode.

The velocity capture has a configurable timer and a count register. It counts the number of phase edges (using the same configuration as for the position integrator) in a given time period. The edge count from the previous time period is available to the controller via the **QEISPEED** register, while the edge count for the current time period is being accumulated in the **QEICOUNT** register. As soon as the current time period is complete, the total number of edges counted in that time period is made available in the **QEISPEED** register (losing the previous value), the **QEICOUNT** is reset to 0, and counting commences on a new time period. The number of edges counted in a given time period is directly proportional to the velocity of the encoder.

Figure 19-2 on page 482 shows how the Stellaris[®] quadrature encoder converts the phase input signals into clock pulses, the direction signal, and how the velocity predivider operates (in Divide by 4 mode).

Figure 19-2. Quadrature Encoder and Velocity Predivider Operation



The period of the timer is configurable by specifying the load value for the timer in the **QEILOAD** register. When the timer reaches zero, an interrupt can be triggered, and the hardware reloads the timer with the **QEILOAD** value and continues to count down. At lower encoder speeds, a longer timer period is needed to be able to capture enough edges to have a meaningful result. At higher encoder speeds, both a shorter timer period and/or the velocity predivider can be used.

The following equation converts the velocity counter value into an rpm value:

```
rpm = (clock * (2 ^ VelDiv) * Speed * 60) ÷ (Load * ppr * edges)
```

where:

clock is the controller clock rate

ppr is the number of pulses per revolution of the physical encoder

edges is 2 or 4, based on the capture mode set in the **QEICTL** register (2 for CapMode set to 0 and 4 for CapMode set to 1)

For example, consider a motor running at 600 rpm. A 2048 pulse per revolution quadrature encoder is attached to the motor, producing 8192 phase edges per revolution. With a velocity predivider of ÷1 (VelDiv set to 0) and clocking on both PhA and PhB edges, this results in 81,920 pulses per second (the motor turns 10 times per second). If the timer were clocked at 10,000 Hz, and the load value was 2,500 (¼ of a second), it would count 20,480 pulses per update. Using the above equation:

```
rpm = (10000 * 1 * 20480 * 60) ÷ (2500 * 2048 * 4) = 600 rpm
```

Now, consider that the motor is sped up to 3000 rpm. This results in 409,600 pulses per second, or 102,400 every $\frac{1}{4}$ of a second. Again, the above equation gives:

```
rpm = (10000 * 1 * 102400 * 60) \div (2500 * 2048 * 4) = 3000 rpm
```

Care must be taken when evaluating this equation since intermediate values may exceed the capacity of a 32-bit integer. In the above examples, the clock is 10,000 and the divider is 2,500; both could be predivided by 100 (at compile time if they are constants) and therefore be 100 and 25. In fact, if they were compile-time constants, they could also be reduced to a simple multiply by 4, cancelled by the ÷4 for the edge-count factor.

Important: Reducing constant factors at compile time is the best way to control the intermediate values of this equation, as well as reducing the processing requirement of computing this equation.

The division can be avoided by selecting a timer load value such that the divisor is a power of 2; a simple shift can therefore be done in place of the division. For encoders with a power of 2 pulses per revolution, this is a simple matter of selecting a power of 2 load value. For other encoders, a load value must be selected such that the product is very close to a power of two. For example, a 100 pulse per revolution encoder could use a load value of 82, resulting in 32,800 as the divisor,

which is 0.09% above 2¹⁴; in this case a shift by 15 would be an adequate approximation of the divide in most cases. If absolute accuracy were required, the controller's divide instruction could be used.

The QEI module can produce a controller interrupt on several events: phase error, direction change, reception of the index pulse, and expiration of the velocity timer. Standard masking, raw interrupt status, interrupt status, and interrupt clear capabilities are provided.

19.3 Initialization and Configuration

The following example shows how to configure the Quadrature Encoder module to read back an absolute position:

- 1. Enable the QEI clock by writing a value of 0x0000.0100 to the **RCGC1** register in the System Control module.
- Enable the clock to the appropriate GPIO module via the RCGC2 register in the System Control module.
- In the GPIO module, enable the appropriate pins for their alternate function using the GPIOAFSEL register.
- 4. Configure the quadrature encoder to capture edges on both signals and maintain an absolute position by resetting on index pulses. Using a 1000-line encoder at four edges per line, there are 4000 pulses per revolution; therefore, set the maximum position to 3999 (0xF9F) since the count is zero-based.
 - Write the QEICTL register with the value of 0x0000.0018.
 - Write the QEIMAXPOS register with the value of 0x0000.0F9F.
- 5. Enable the quadrature encoder by setting bit 0 of the **QEICTL** register.
- Delay for some time.
- 7. Read the encoder position by reading the **QEIPOS** register value.

19.4 Register Map

"Register Map" on page 483 lists the QEI registers. The offset listed is a hexadecimal increment to the register's address, relative to the module's base address:

QEI0: 0x4002.C000

Table 19-1. QEI Register Map

Offset	Name	Туре	Reset	Description	See page
0x000	QEICTL	R/W	0x0000.0000	QEI Control	485
0x004	QEISTAT	RO	0x0000.0000	QEI Status	487
800x0	QEIPOS	R/W	0x0000.0000	QEI Position	488
0x00C	QEIMAXPOS	R/W	0x0000.0000	QEI Maximum Position	489
0x010	QEILOAD	R/W	0x0000.0000	QEI Timer Load	490

Offset	Name	Туре	Reset	Description	See page
0x014	QEITIME	RO	0x0000.0000	QEI Timer	491
0x018	QEICOUNT	RO	0x0000.0000	QEI Velocity Counter	492
0x01C	QEISPEED	RO	0x0000.0000	QEI Velocity	493
0x020	QEIINTEN	R/W	0x0000.0000	QEI Interrupt Enable	494
0x024	QEIRIS	RO	0x0000.0000	QEI Raw Interrupt Status	495
0x028	QEIISC	R/W1C	0x0000.0000	QEI Interrupt Status and Clear	496

19.5 Register Descriptions

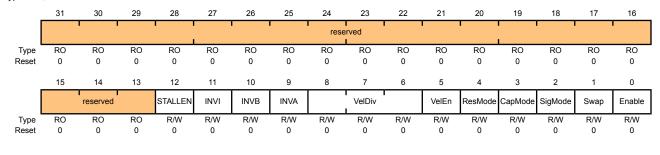
The remainder of this section lists and describes the QEI registers, in numerical order by address offset.

Register 1: QEI Control (QEICTL), offset 0x000

This register contains the configuration of the QEI module. Separate enables are provided for the quadrature encoder and the velocity capture blocks; the quadrature encoder must be enabled in order to capture the velocity, but the velocity does not need to be captured in applications that do not need it. The phase signal interpretation, phase swap, Position Update mode, Position Reset mode, and velocity predivider are all set via this register.

QEI Control (QEICTL)

QEI0 base: 0x4002.C000 Offset 0x000 Type R/W, reset 0x0000.0000



Bit/Field	Name	Type	Reset	Description
31:13	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
12	STALLEN	R/W	0	When set, the QEI stalls when the microcontroller asserts Halt.
11	INVI	R/W	0	When set , the input Index Pulse is inverted.
10	INVB	R/W	0	When set, the PhB input is inverted.
9	INVA	R/W	0	When set, the PhA input is inverted.
8:6	VelDiv	R/W	0	A predivider of the input quadrature pulses before being applied to the QEICOUNT accumulator. This field can be set to the following values:

Binary Value	Predivide
000	÷1
001	÷2
010	÷4
011	÷8
100	÷16
101	÷32
110	÷64
111	÷128

5	VelEn	R/W	0	When set, enables capture of the velocity of the quadrature encoder.
4	ResMode	R/W	0	The Reset mode for the position counter. When 0, the position counter is reset when it reaches the maximum; when 1, the position counter is reset when the index pulse is captured.

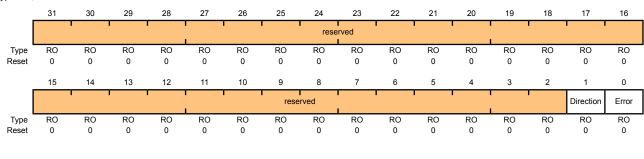
Bit/Field	Name	Type	Reset	Description
3	CapMode	R/W	0	The Capture mode defines the phase edges that are counted in the position. When 0, only the PhA edges are counted; when 1, the PhA and PhB edges are counted, providing twice the positional resolution but half the range.
2	SigMode	R/W	0	When 1, the PhA and PhB signals are clock and direction; when 0, they are quadrature phase signals.
1	Swap	R/W	0	Swaps the PhA and PhB signals.
0	Enable	R/W	0	Enables the quadrature encoder module.

Register 2: QEI Status (QEISTAT), offset 0x004

This register provides status about the operation of the QEI module.

QEI Status (QEISTAT)

QEI0 base: 0x4002.C000 Offset 0x004 Type RO, reset 0x0000.0000



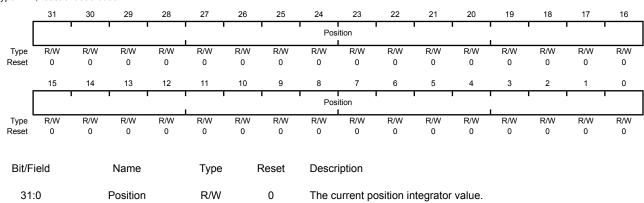
Bit/Field	Name	Туре	Reset	Description
31:2	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
1	Direction	RO	0	Indicates the direction the encoder is rotating. 0: Forward rotation 1: Reverse rotation
0	Error	RO	0	Indicates that an error was detected in the gray code sequence (that is, both signals changing at the same time).

Register 3: QEI Position (QEIPOS), offset 0x008

This register contains the current value of the position integrator. Its value is updated by inputs on the QEI phase inputs, and can be set to a specific value by writing to it.

QEI Position (QEIPOS)

QEI0 base: 0x4002.C000 Offset 0x008 Type R/W, reset 0x0000.0000



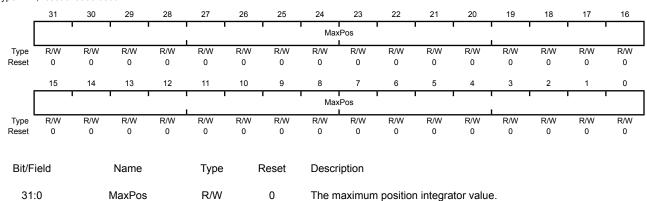
Register 4: QEI Maximum Position (QEIMAXPOS), offset 0x00C

This register contains the maximum value of the position integrator. When moving forward, the position register resets to zero when it increments past this value. When moving backward, the position register resets to this value when it decrements from zero.

QEI Maximum Position (QEIMAXPOS)

QEI0 base: 0x4002.C000

Offset 0x00C Type R/W, reset 0x0000.0000



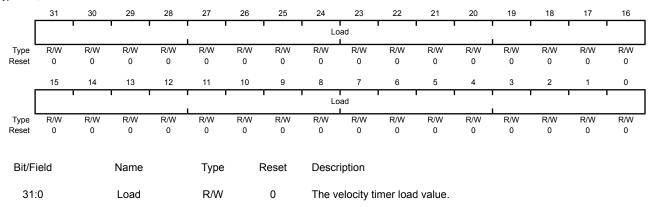
Register 5: QEI Timer Load (QEILOAD), offset 0x010

This register contains the load value for the velocity timer. Since this value is loaded into the timer the clock cycle after the timer is zero, this value should be one less than the number of clocks in the desired period. So, for example, to have 2000 clocks per timer period, this register should contain 1999.

QEI Timer Load (QEILOAD)

QEI0 base: 0x4002.C000

Offset 0x010 Type R/W, reset 0x0000.0000

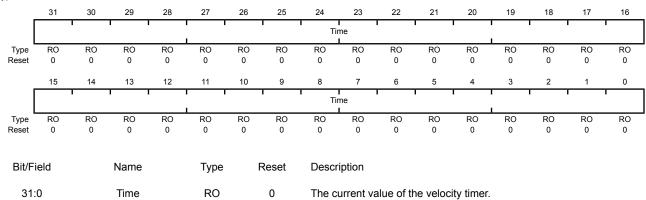


Register 6: QEI Timer (QEITIME), offset 0x014

This register contains the current value of the velocity timer. This counter does not increment when VelEn in QEICTL is 0.

QEI Timer (QEITIME)

QEI0 base: 0x4002.C000 Offset 0x014 Type RO, reset 0x0000.0000

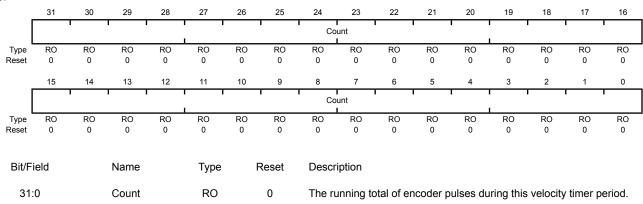


Register 7: QEI Velocity Counter (QEICOUNT), offset 0x018

This register contains the running count of velocity pulses for the current time period. Since this is a running total, the time period to which it applies cannot be known with precision (that is, a read of this register does not necessarily correspond to the time returned by the **QEITIME** register since there is a small window of time between the two reads, during which time either value may have changed). The **QEISPEED** register should be used to determine the actual encoder velocity; this register is provided for information purposes only. This counter does not increment when Velen in **QEICTL** is 0.

QEI Velocity Counter (QEICOUNT)

QEI0 base: 0x4002.C000 Offset 0x018

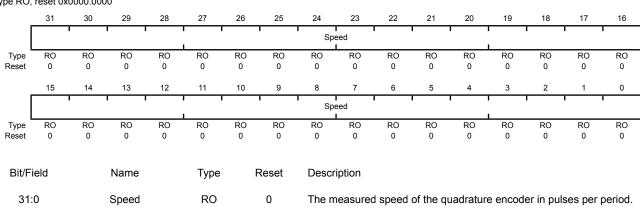


Register 8: QEI Velocity (QEISPEED), offset 0x01C

This register contains the most recently measured velocity of the quadrature encoder. This corresponds to the number of velocity pulses counted in the previous velocity timer period. This register does not update when VelEn in **QEICTL** is 0.

QEI Velocity (QEISPEED)

QEI0 base: 0x4002.C000 Offset 0x01C Type RO, reset 0x0000.0000

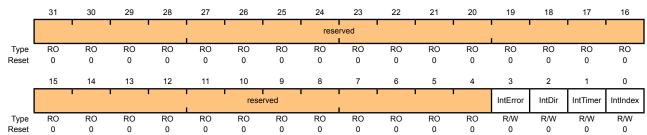


Register 9: QEI Interrupt Enable (QEIINTEN), offset 0x020

This register contains enables for each of the QEI module's interrupts. An interrupt is asserted to the controller if its corresponding bit in this register is set to 1.

QEI Interrupt Enable (QEIINTEN)

QEI0 base: 0x4002.C000 Offset 0x020 Type R/W, reset 0x0000.0000



Bit/Field	Name	Туре	Reset	Description
31:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	IntError	R/W	0	When 1, an interrupt occurs when a phase error is detected.
2	IntDir	R/W	0	When 1, an interrupt occurs when the direction changes.
1	IntTimer	R/W	0	When 1, an interrupt occurs when the velocity timer expires.
0	IntIndex	R/W	0	When 1, an interrupt occurs when the index pulse is detected.

Register 10: QEI Raw Interrupt Status (QEIRIS), offset 0x024

This register provides the current set of interrupt sources that are asserted, regardless of whether they cause an interrupt to be asserted to the controller (this is set through the QEIINTEN register). Bits set to 1 indicate the latched events that have occurred; a zero bit indicates that the event in question has not occurred.

QEI Raw Interrupt Status (QEIRIS)

IntIndex

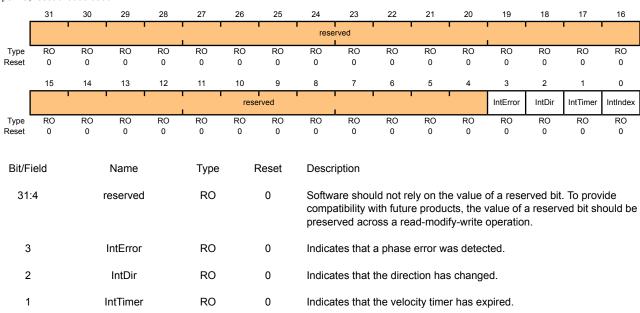
RO

0

QEI0 base: 0x4002.C000

0

Offset 0x024 Type RO, reset 0x0000.0000



Indicates that the index pulse has occurred.

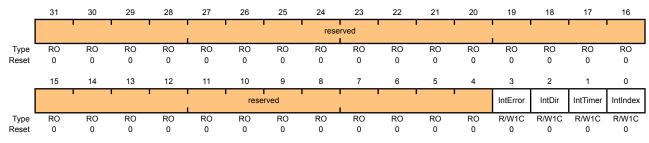
Register 11: QEI Interrupt Status and Clear (QEIISC), offset 0x028

This register provides the current set of interrupt sources that are asserted to the controller. Bits set to 1 indicate the latched events that have occurred; a zero bit indicates that the event in question has not occurred. This is a R/W1C register; writing a 1 to a bit position clears the corresponding interrupt reason.

QEI Interrupt Status and Clear (QEIISC)

QEI0 base: 0x4002.C000

Offset 0x028
Type R/W1C, reset 0x0000.0000

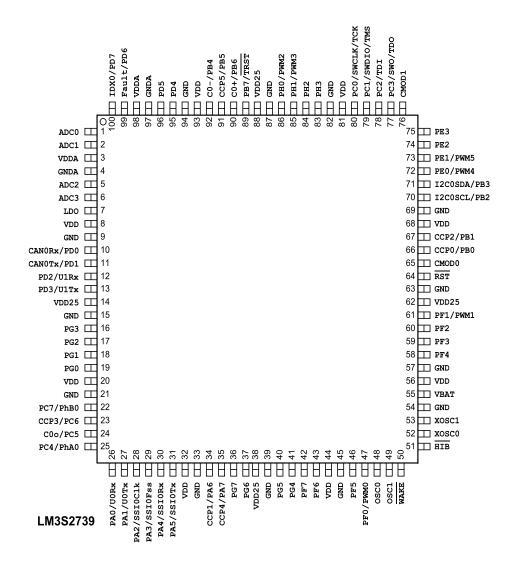


Bit/Field	Name	Type	Reset	Description
31:4	reserved	RO	0	Software should not rely on the value of a reserved bit. To provide compatibility with future products, the value of a reserved bit should be preserved across a read-modify-write operation.
3	IntError	R/W1C	0	Indicates that a phase error was detected.
2	IntDir	R/W1C	0	Indicates that the direction has changed.
1	IntTimer	R/W1C	0	Indicates that the velocity timer has expired.
0	IntIndex	R/W1C	0	Indicates that the index pulse has occurred.

20 Pin Diagram

Figure 20-1 on page 497 shows the pin diagram and pin-to-signal-name mapping.

Figure 20-1. Pin Connection Diagram



21 Signal Tables

The following tables list the signals available for each pin. Functionality is enabled by software with the GPIOAFSEL register.

Important: All multiplexed pins are GPIOs by default, with the exception of the five JTAG pins (PB7 and PC[3:0]) which default to the JTAG functionality.

Table 21-1 on page 498 shows the pin-to-signal-name mapping, including functional characteristics of the signals. Table 21-2 on page 502 lists the signals in alphabetical order by signal name.

Table 21-3 on page 506 groups the signals by functionality, except for GPIOs. Table 21-4 on page 509 lists the GPIO pins and their alternate functionality.

Table 21-1. Signals by Pin Number

Pin Number	Pin Name	Pin Type	Buffer Type	Description
1	ADC0	I	Analog	Analog-to-digital converter input 0.
2	ADC1	I	Analog	Analog-to-digital converter input 1.
3	VDDA	-	Power	The positive supply (3.3 V) for the analog circuits (ADC, Analog Comparators, etc.). These are separated from VDD to minimize the electrical noise contained on VDD from affecting the analog functions.
4	GNDA	-	Power	The ground reference for the analog circuits (ADC, Analog Comparators, etc.). These are separated from GND to minimize the electrical noise contained on VDD from affecting the analog functions.
5	ADC2	I	Analog	Analog-to-digital converter input 2.
6	ADC3	I	Analog	Analog-to-digital converter input 3.
7	LDO	-	Power	Low drop-out regulator output voltage. This pin requires an external capacitor between the pin and GND of 1 µF or greater. When the on-chip LDO is used to provide power to the logic, the LDO pin must also be connected to the VDD25 pins at the board level in addition to the decoupling capacitor(s).
8	VDD	-	Power	Positive supply for I/O and some logic.
9	GND	-	Power	Ground reference for logic and I/O pins.
10	CAN0Rx	I	TTL	CAN module 0 receive
	PD0	I/O	TTL	GPIO port D bit 0
11	CAN0Tx	0	TTL	CAN module 0 transmit
	PD1	I/O	TTL	GPIO port D bit 1
12	PD2	I/O	TTL	GPIO port D bit 2
	U1Rx	I	TTL	UART module 1 receive. When in IrDA mode, this signal has IrDA modulation.
13	PD3	I/O	TTL	GPIO port D bit 3
	U1Tx	0	TTL	UART module 1 transmit. When in IrDA mode, this signal has IrDA modulation.

Pin Number	Pin Name	Pin Type	Buffer Type	Description
14	VDD25	-	Power	Positive supply for most of the logic function, including the processor core and most peripherals.
15	GND	-	Power	Ground reference for logic and I/O pins.
16	PG3	I/O	TTL	GPIO port G bit 3
17	PG2	I/O	TTL	GPIO port G bit 2
18	PG1	I/O	TTL	GPIO port G bit 1
19	PG0	I/O	TTL	GPIO port G bit 0
20	VDD	-	Power	Positive supply for I/O and some logic.
21	GND	-	Power	Ground reference for logic and I/O pins.
22	PC7	I/O	TTL	GPIO port C bit 7
	PhB0	1	TTL	QEI module 0 Phase B
23	CCP3	I/O	TTL	Capture/Compare/PWM 3
	PC6	I/O	TTL	GPIO port C bit 6
24	C0o	0	TTL	Analog comparator 0 output
	PC5	I/O	TTL	GPIO port C bit 5
25	PC4	I/O	TTL	GPIO port C bit 4
	PhA0	I	TTL	QEI module 0 Phase A
26	PA0	I/O	TTL	GPIO port A bit 0
	U0Rx	I	TTL	UART module 0 receive. When in IrDA mode, this signal has IrDA modulation.
27	PA1	I/O	TTL	GPIO port A bit 1
	UOTx	0	TTL	UART module 0 transmit. When in IrDA mode, this signal has IrDA modulation.
28	PA2	I/O	TTL	GPIO port A bit 2
	SSIOClk	I/O	TTL	SSI module 0 clock
29	PA3	I/O	TTL	GPIO port A bit 3
	SSI0Fss	I/O	TTL	SSI module 0 frame
30	PA4	I/O	TTL	GPIO port A bit 4
	SSI0Rx	I	TTL	SSI module 0 receive
31	PA5	I/O	TTL	GPIO port A bit 5
	SSIOTx	0	TTL	SSI module 0 transmit
32	VDD	-	Power	Positive supply for I/O and some logic.
33	GND	-	Power	Ground reference for logic and I/O pins.
34	CCP1	I/O	TTL	Capture/Compare/PWM 1
	PA6	I/O	TTL	GPIO port A bit 6
35	CCP4	I/O	TTL	Capture/Compare/PWM 1
	PA7	I/O	TTL	GPIO port A bit 7
36	PG7	I/O	TTL	GPIO port G bit 7
37	PG6	I/O	TTL	GPIO port G bit 6
38	VDD25	-	Power	Positive supply for most of the logic function, including the processor core and most peripherals.
39	GND	-	Power	Ground reference for logic and I/O pins.

Pin Number	Pin Name	Pin Type	Buffer Type	Description
40	PG5	I/O	TTL	GPIO port G bit 5
41	PG4	I/O	TTL	GPIO port G bit 4
42	PF7	I/O	TTL	GPIO port F bit 7
43	PF6	I/O	TTL	GPIO port F bit 6
44	VDD	-	Power	Positive supply for I/O and some logic.
45	GND	-	Power	Ground reference for logic and I/O pins.
46	PF5	I/O	TTL	GPIO port F bit 5
47	PF0	I/O	TTL	GPIO port F bit 0
	PWM0	0	TTL	PWM 0
48	osc0	I	Analog	Main oscillator crystal input or an external clock reference input.
49	OSC1	0	Analog	Main oscillator crystal output.
50	WAKE	I	OD	An external input that brings the processor out of hibernate mode when asserted.
51	ĦĪВ	0	TTL	An output that indicates the processor is in hibernate mode.
52	XOSCO	I	Analog	Hibernation Module oscillator crystal input or an external clock reference input. Note that this is either a 4.19-MHz crystal or a 32.768-kHz oscillator for the Hibernation Module RTC. See the CLKSEL bit in the HIBCTL register.
53	XOSC1	0	Analog	Hibernation Module oscillator crystal output.
54	GND	-	Power	Ground reference for logic and I/O pins.
55	VBAT	-	Power	Power source for the Hibernation Module. It is normally connected to the positive terminal of a battery and serves as the battery backup/Hibernation Module power-source supply.
56	VDD	-	Power	Positive supply for I/O and some logic.
57	GND	-	Power	Ground reference for logic and I/O pins.
58	PF4	I/O	TTL	GPIO port F bit 4
59	PF3	I/O	TTL	GPIO port F bit 3
60	PF2	I/O	TTL	GPIO port F bit 2
61	PF1	I/O	TTL	GPIO port F bit 1
	PWM1	0	TTL	PWM 1
62	VDD25	-	Power	Positive supply for most of the logic function, including the processor core and most peripherals.
63	GND	-	Power	Ground reference for logic and I/O pins.
64	RST	ı	TTL	System reset input.
65	CMOD0	I/O	TTL	CPU Mode bit 0. Input must be set to logic 0 (grounded); other encodings reserved.
66	CCP0	I/O	TTL	Capture/Compare/PWM 0
	PB0	I/O	TTL	GPIO port B bit 0
67	CCP2	I/O	TTL	Capture/Compare/PWM 2
	PB1	I/O	TTL	GPIO port B bit 1

Pin Number	Pin Name	Pin Type	Buffer Type	Description
68	VDD	-	Power	Positive supply for I/O and some logic.
69	GND	-	Power	Ground reference for logic and I/O pins.
70	I2C0SCL	I/O	OD	I2C module 0 clock
	PB2	I/O	TTL	GPIO port B bit 2
71	I2C0SDA	I/O	OD	I2C module 0 data
	PB3	I/O	TTL	GPIO port B bit 3
72	PE0	I/O	TTL	GPIO port E bit 0
	PWM4	0	TTL	PWM 4
73	PE1	I/O	TTL	GPIO port E bit 1
	PWM5	0	TTL	PWM 5
74	PE2	I/O	TTL	GPIO port E bit 2
75	PE3	I/O	TTL	GPIO port E bit 3
76	CMOD1	I/O	TTL	CPU Mode bit 1. Input must be set to logic 0 (grounded); other encodings reserved.
77	PC3	I/O	TTL	GPIO port C bit 3
	SWO	0	TTL	JTAG TDO and SWO
	TDO	0	TTL	JTAG TDO and SWO
78	PC2	I/O	TTL	GPIO port C bit 2
	TDI	I	TTL	JTAG TDI
79	PC1	I/O	TTL	GPIO port C bit 1
	SWDIO	I/O	TTL	JTAG TMS and SWDIO
	TMS	I/O	TTL	JTAG TMS and SWDIO
80	PC0	I/O	TTL	GPIO port C bit 0
	SWCLK	I	TTL	JTAG/SWD CLK
	TCK	1	TTL	JTAG/SWD CLK
81	VDD	-	Power	Positive supply for I/O and some logic.
82	GND	-	Power	Ground reference for logic and I/O pins.
83	PH3	I/O	TTL	GPIO port H bit 3
84	PH2	I/O	TTL	GPIO port H bit 2
85	PH1	I/O	TTL	GPIO port H bit 1
	PWM3	0	TTL	PWM 3
86	PH0	I/O	TTL	GPIO port H bit 0
	PWM2	0	TTL	PWM 2
87	GND	-	Power	Ground reference for logic and I/O pins.
88	VDD25	-	Power	Positive supply for most of the logic function, including the processor core and most peripherals.
89	PB7	I/O	TTL	GPIO port B bit 7
	TRST	I	TTL	JTAG TRSTn
90	C0+	I	Analog	Analog comparator 0 positive input
	PB6	I/O	TTL	GPIO port B bit 6
91	CCP5	I/O	TTL	Capture/Compare/PWM 5
	PB5	I/O	TTL	GPIO port B bit 5
		-		

Pin Number	Pin Name	Pin Type	Buffer Type	Description
92	C0-	I	Analog	Analog comparator 0 negative input
	PB4	I/O	TTL	GPIO port B bit 4
93	VDD	-	Power	Positive supply for I/O and some logic.
94	GND	-	Power	Ground reference for logic and I/O pins.
95	PD4	I/O	TTL	GPIO port D bit 4
96	PD5	I/O	TTL	GPIO port D bit 5
97	GNDA	-	Power	The ground reference for the analog circuits (ADC, Analog Comparators, etc.). These are separated from GND to minimize the electrical noise contained on VDD from affecting the analog functions.
98	VDDA	-	Power	The positive supply (3.3 V) for the analog circuits (ADC, Analog Comparators, etc.). These are separated from VDD to minimize the electrical noise contained on VDD from affecting the analog functions.
99	Fault	I	TTL	PWM Fault
	PD6	I/O	TTL	GPIO port D bit 6
100	IDX0	I	TTL	QEI module 0 index
	PD7	I/O	TTL	GPIO port D bit 7

Table 21-2. Signals by Signal Name

Pin Name	Pin Number	Pin Type	Buffer Type	Description
ADC0	1	I	Analog	Analog-to-digital converter input 0.
ADC1	2	I	Analog	Analog-to-digital converter input 1.
ADC2	5	I	Analog	Analog-to-digital converter input 2.
ADC3	6	I	Analog	Analog-to-digital converter input 3.
C0+	90	I	Analog	Analog comparator 0 positive input
C0-	92	I	Analog	Analog comparator 0 negative input
COo	24	0	TTL	Analog comparator 0 output
CAN0Rx	10	I	TTL	CAN module 0 receive
CAN0Tx	11	0	TTL	CAN module 0 transmit
CCP0	66	I/O	TTL	Capture/Compare/PWM 0
CCP1	34	I/O	TTL	Capture/Compare/PWM 1
CCP2	67	I/O	TTL	Capture/Compare/PWM 2
CCP3	23	I/O	TTL	Capture/Compare/PWM 3
CCP4	35	I/O	TTL	Capture/Compare/PWM 1
CCP5	91	I/O	TTL	Capture/Compare/PWM 5
CMOD0	65	I/O	TTL	CPU Mode bit 0. Input must be set to logic 0 (grounded); other encodings reserved.
CMOD1	76	I/O	TTL	CPU Mode bit 1. Input must be set to logic 0 (grounded); other encodings reserved.
Fault	99	I	TTL	PWM Fault
GND	9	-	Power	Ground reference for logic and I/O pins.
GND	15	-	Power	Ground reference for logic and I/O pins.

Pin Name	Pin Number	Pin Type	Buffer Type	Description
GND	21	-	Power	Ground reference for logic and I/O pins.
GND	33	-	Power	Ground reference for logic and I/O pins.
GND	39	-	Power	Ground reference for logic and I/O pins.
GND	45	-	Power	Ground reference for logic and I/O pins.
GND	54	-	Power	Ground reference for logic and I/O pins.
GND	57	-	Power	Ground reference for logic and I/O pins.
GND	63	-	Power	Ground reference for logic and I/O pins.
GND	69	-	Power	Ground reference for logic and I/O pins.
GND	82	-	Power	Ground reference for logic and I/O pins.
GND	87	-	Power	Ground reference for logic and I/O pins.
GND	94	-	Power	Ground reference for logic and I/O pins.
GNDA	4	-	Power	The ground reference for the analog circuits (ADC, Analog Comparators, etc.). These are separated from GND to minimize the electrical noise contained on VDD from affecting the analog functions.
GNDA	97	-	Power	The ground reference for the analog circuits (ADC, Analog Comparators, etc.). These are separated from GND to minimize the electrical noise contained on VDD from affecting the analog functions.
HIB	51	0	TTL	An output that indicates the processor is in hibernate mode.
I2C0SCL	70	I/O	OD	I2C module 0 clock
I2C0SDA	71	I/O	OD	I2C module 0 data
IDX0	100	I	TTL	QEI module 0 index
LDO	7	-	Power	Low drop-out regulator output voltage. This pin requires an external capacitor between the pin and GND of 1 μ F or greater. When the on-chip LDO is used to provide power to the logic, the LDO pin must also be connected to the VDD25 pins at the board level in addition to the decoupling capacitor(s).
osc0	48	I	Analog	Main oscillator crystal input or an external clock reference input.
OSC1	49	0	Analog	Main oscillator crystal output.
PA0	26	I/O	TTL	GPIO port A bit 0
PA1	27	I/O	TTL	GPIO port A bit 1
PA2	28	I/O	TTL	GPIO port A bit 2
PA3	29	I/O	TTL	GPIO port A bit 3
PA4	30	I/O	TTL	GPIO port A bit 4
PA5	31	I/O	TTL	GPIO port A bit 5
PA6	34	I/O	TTL	GPIO port A bit 6
PA7	35	I/O	TTL	GPIO port A bit 7
PB0	66	I/O	TTL	GPIO port B bit 0
PB1	67	I/O	TTL	GPIO port B bit 1
PB2	70	I/O	TTL	GPIO port B bit 2

Pin Name	Pin Number	Pin Type	Buffer Type	Description
PB3	71	I/O	TTL	GPIO port B bit 3
PB4	92	I/O	TTL	GPIO port B bit 4
PB5	91	I/O	TTL	GPIO port B bit 5
PB6	90	I/O	TTL	GPIO port B bit 6
PB7	89	I/O	TTL	GPIO port B bit 7
PC0	80	I/O	TTL	GPIO port C bit 0
PC1	79	I/O	TTL	GPIO port C bit 1
PC2	78	I/O	TTL	GPIO port C bit 2
PC3	77	I/O	TTL	GPIO port C bit 3
PC4	25	I/O	TTL	GPIO port C bit 4
PC5	24	I/O	TTL	GPIO port C bit 5
PC6	23	I/O	TTL	GPIO port C bit 6
PC7	22	I/O	TTL	GPIO port C bit 7
PD0	10	I/O	TTL	GPIO port D bit 0
PD1	11	I/O	TTL	GPIO port D bit 1
PD2	12	I/O	TTL	GPIO port D bit 2
PD3	13	I/O	TTL	GPIO port D bit 3
PD4	95	I/O	TTL	GPIO port D bit 4
PD5	96	I/O	TTL	GPIO port D bit 5
PD6	99	I/O	TTL	GPIO port D bit 6
PD7	100	I/O	TTL	GPIO port D bit 7
PE0	72	I/O	TTL	GPIO port E bit 0
PE1	73	I/O	TTL	GPIO port E bit 1
PE2	74	I/O	TTL	GPIO port E bit 2
PE3	75	I/O	TTL	GPIO port E bit 3
PF0	47	I/O	TTL	GPIO port F bit 0
PF1	61	I/O	TTL	GPIO port F bit 1
PF2	60	I/O	TTL	GPIO port F bit 2
PF3	59	I/O	TTL	GPIO port F bit 3
PF4	58	I/O	TTL	GPIO port F bit 4
PF5	46	I/O	TTL	GPIO port F bit 5
PF6	43	I/O	TTL	GPIO port F bit 6
PF7	42	I/O	TTL	GPIO port F bit 7
PG0	19	I/O	TTL	GPIO port G bit 0
PG1	18	I/O	TTL	GPIO port G bit 1
PG2	17	I/O	TTL	GPIO port G bit 2
PG3	16	I/O	TTL	GPIO port G bit 3
PG4	41	I/O	TTL	GPIO port G bit 4
PG5	40	I/O	TTL	GPIO port G bit 5
PG6	37	I/O	TTL	GPIO port G bit 6
PG7	36	I/O	TTL	GPIO port G bit 7
PH0	86	I/O	TTL	GPIO port H bit 0

Pin Name	Pin Number	Pin Type	Buffer Type	Description	
PH1	85	I/O	TTL	GPIO port H bit 1	
PH2	84	I/O	TTL	GPIO port H bit 2	
PH3	83	I/O	TTL	GPIO port H bit 3	
PWM0	47	0	TTL	PWM 0	
PWM1	61	0	TTL	PWM 1	
PWM2	86	0	TTL	PWM 2	
PWM3	85	0	TTL	PWM 3	
PWM4	72	0	TTL	PWM 4	
PWM5	73	0	TTL	PWM 5	
PhA0	25	I	TTL	QEI module 0 Phase A	
PhB0	22	I	TTL	QEI module 0 Phase B	
RST	64	I	TTL	System reset input.	
SSIOClk	28	I/O	TTL	SSI module 0 clock	
SSIOFss	29	I/O	TTL	SSI module 0 frame	
SSI0Rx	30	I	TTL	SSI module 0 receive	
SSIOTx	31	0	TTL	SSI module 0 transmit	
SWCLK	80	I	TTL	JTAG/SWD CLK	
SWDIO	79	I/O	TTL	JTAG TMS and SWDIO	
SWO	77	0	TTL	JTAG TDO and SWO	
TCK	80	I	TTL	JTAG/SWD CLK	
TDI	78	I	TTL	JTAG TDI	
TDO	77	0	TTL	JTAG TDO and SWO	
TMS	79	I/O	TTL	JTAG TMS and SWDIO	
TRST	89	I	TTL	JTAG TRSTn	
UORx	26	I	TTL	UART module 0 receive. When in IrDA mode, this signal has IrDA modulation.	
UOTx	27	0	TTL	UART module 0 transmit. When in IrDA mode, this signal has IrDA modulation.	
UlRx	12	l	TTL	UART module 1 receive. When in IrDA mode, this signal has IrDA modulation.	
UlTx	13	0	TTL	UART module 1 transmit. When in IrDA mode, this signal has IrDA modulation.	
VBAT	55	-	Power	Power source for the Hibernation Module. It is normally connected to the positive terminal of a battery and serves as the battery backup/Hibernation Module power-source supply.	
VDD	8	-	Power	Positive supply for I/O and some logic.	
VDD	20	-	Power	Positive supply for I/O and some logic.	
VDD	32	-	Power	Positive supply for I/O and some logic.	
VDD	44	-	Power	Positive supply for I/O and some logic.	
VDD	56	-	Power	Positive supply for I/O and some logic.	
VDD	68	-	Power	Positive supply for I/O and some logic.	
VDD	81	-	Power	Positive supply for I/O and some logic.	
VDD	93	-	Power	Positive supply for I/O and some logic.	

Pin Name	Pin Number	Pin Type	Buffer Type	Description
VDD25	14	-	Power	Positive supply for most of the logic function, including the processor core and most peripherals.
VDD25	38	-	Power	Positive supply for most of the logic function, including the processor core and most peripherals.
VDD25	62	-	Power	Positive supply for most of the logic function, including the processor core and most peripherals.
VDD25	88	-	Power	Positive supply for most of the logic function, including the processor core and most peripherals.
VDDA	3	-	Power	The positive supply (3.3 V) for the analog circuits (ADC, Analog Comparators, etc.). These are separated from VDD to minimize the electrical noise contained on VDD from affecting the analog functions.
VDDA	98	-	Power	The positive supply (3.3 V) for the analog circuits (ADC, Analog Comparators, etc.). These are separated from VDD to minimize the electrical noise contained on VDD from affecting the analog functions.
WAKE	50	I	OD	An external input that brings the processor out of hibernate mode when asserted.
xosc0	52	I	Analog	Hibernation Module oscillator crystal input or an external clock reference input. Note that this is either a 4.19-MHz crystal or a 32.768-kHz oscillator for the Hibernation Module RTC. See the CLKSEL bit in the HIBCTL register.
XOSC1	53	0	Analog	Hibernation Module oscillator crystal output.

Table 21-3. Signals by Function, Except for GPIO

Function	Pin Name	Pin Number	Pin Type	Buffer Type	Description
ADC	ADC0	1	I	Analog	Analog-to-digital converter input 0.
	ADC1	2	I	Analog	Analog-to-digital converter input 1.
	ADC2	5	I	Analog	Analog-to-digital converter input 2.
	ADC3	6	I	Analog	Analog-to-digital converter input 3.
Analog	C0+	90	I	Analog	Analog comparator 0 positive input
Comparators	C0-	92	I	Analog	Analog comparator 0 negative input
	C0o	24	0	TTL	Analog comparator 0 output
Controller Area	CAN0Rx	10	I	TTL	CAN module 0 receive
Network	CAN0Tx	11	0	TTL	CAN module 0 transmit
General-Purpose	CCP0	66	I/O	TTL	Capture/Compare/PWM 0
Timers	CCP1	34	I/O	TTL	Capture/Compare/PWM 1
	CCP2	67	I/O	TTL	Capture/Compare/PWM 2
	CCP3	23	I/O	TTL	Capture/Compare/PWM 3
	CCP4	35	I/O	TTL	Capture/Compare/PWM 1
	CCP5	91	I/O	TTL	Capture/Compare/PWM 5

Function	Pin Name	Pin Number	Pin Type	Buffer Type	Description
I2C	I2C0SCL	70	I/O	OD	I2C module 0 clock
	I2C0SDA	71	I/O	OD	I2C module 0 data
JTAG/SWD/SWO	SWCLK	80	I	TTL	JTAG/SWD CLK
	SWDIO	79	I/O	TTL	JTAG TMS and SWDIO
	SWO	77	0	TTL	JTAG TDO and SWO
	TCK	80	I	TTL	JTAG/SWD CLK
	TDI	78	I	TTL	JTAG TDI
	TDO	77	0	TTL	JTAG TDO and SWO
	TMS	79	I/O	TTL	JTAG TMS and SWDIO
PWM	Fault	99	I	TTL	PWM Fault
	PWM0	47	0	TTL	PWM 0
	PWM1	61	0	TTL	PWM 1
	PWM2	86	0	TTL	PWM 2
	PWM3	85	0	TTL	PWM 3
	PWM4	72	0	TTL	PWM 4
	PWM5	73	0	TTL	PWM 5

Function	Pin Name	Pin Number	Pin Type	Buffer Type	Description
Power	GND	9	-	Power	Ground reference for logic and I/O pins.
	GND	15	-	Power	Ground reference for logic and I/O pins.
	GND	21	-	Power	Ground reference for logic and I/O pins.
	GND	33	-	Power	Ground reference for logic and I/O pins.
	GND	39	-	Power	Ground reference for logic and I/O pins.
	GND	45	-	Power	Ground reference for logic and I/O pins.
	GND	54	-	Power	Ground reference for logic and I/O pins.
	GND	57	-	Power	Ground reference for logic and I/O pins.
	GND	63	-	Power	Ground reference for logic and I/O pins.
	GND	69	-	Power	Ground reference for logic and I/O pins.
	GND	82	-	Power	Ground reference for logic and I/O pins.
	GND	87	-	Power	Ground reference for logic and I/O pins.
	GND	94	-	Power	Ground reference for logic and I/O pins.
	GNDA	4	-	Power	The ground reference for the analog circuits (ADC Analog Comparators, etc.). These are separated from GND to minimize the electrical noise containe on VDD from affecting the analog functions.
	GNDA	97	-	Power	The ground reference for the analog circuits (ADC Analog Comparators, etc.). These are separated from GND to minimize the electrical noise containe on VDD from affecting the analog functions.
	HIB	51	0	TTL	An output that indicates the processor is in hibernate mode.
	LDO	7	-	Power	Low drop-out regulator output voltage. This pin requires an external capacitor between the pin an GND of 1 μ F or greater. When the on-chip LDO i used to provide power to the logic, the LDO pin must also be connected to the VDD25 pins at the board level in addition to the decoupling capacitor(s).
	VBAT	55	-	Power	Power source for the Hibernation Module. It is normally connected to the positive terminal of a battery and serves as the battery backup/Hibernation Module power-source supply
	VDD	8	-	Power	Positive supply for I/O and some logic.
	VDD	20	-	Power	Positive supply for I/O and some logic.
	VDD	32	-	Power	Positive supply for I/O and some logic.
	VDD	44	-	Power	Positive supply for I/O and some logic.
	VDD	56	-	Power	Positive supply for I/O and some logic.
	VDD	68	-	Power	Positive supply for I/O and some logic.
	VDD	81	-	Power	Positive supply for I/O and some logic.
	VDD	93	-	Power	Positive supply for I/O and some logic.
	VDD25	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		Positive supply for most of the logic function, including the processor core and most peripherals	
	VDD25	38	-	Power	Positive supply for most of the logic function, including the processor core and most peripheral
	VDD25	62	-	Power	Positive supply for most of the logic function, including the processor core and most peripherals

Function	Pin Name	Pin Number	Pin Type	Buffer Type	Description
	VDD25	88	-	Power	Positive supply for most of the logic function, including the processor core and most peripherals.
	VDDA	3	-	Power	The positive supply (3.3 V) for the analog circuits (ADC, Analog Comparators, etc.). These are separated from VDD to minimize the electrical noise contained on VDD from affecting the analog functions.
	VDDA	98	-	Power	The positive supply (3.3 V) for the analog circuits (ADC, Analog Comparators, etc.). These are separated from VDD to minimize the electrical noise contained on VDD from affecting the analog functions.
	WAKE	50	I	OD	An external input that brings the processor out of hibernate mode when asserted.
QEI	IDX0	100	I	TTL	QEI module 0 index
	PhA0	25	I	TTL	QEI module 0 Phase A
	PhB0	22	I	TTL	QEI module 0 Phase B
SSI	SSI0Clk	28	I/O	TTL	SSI module 0 clock
	SSI0Fss	29	I/O	TTL	SSI module 0 frame
	SSIORx	30	I	TTL	SSI module 0 receive
	SSIOTx	31	0	TTL	SSI module 0 transmit
System Control & Clocks	CMOD0	65	I/O	TTL	CPU Mode bit 0. Input must be set to logic 0 (grounded); other encodings reserved.
	CMOD1	76	I/O	TTL	CPU Mode bit 1. Input must be set to logic 0 (grounded); other encodings reserved.
	OSC0	48	I	Analog	Main oscillator crystal input or an external clock reference input.
	OSC1	49	0	Analog	Main oscillator crystal output.
	RST	64	I	TTL	System reset input.
	TRST	89	I	TTL	JTAG TRSTn
	xosc0	52	I	Analog	Hibernation Module oscillator crystal input or an external clock reference input. Note that this is either a 4.19-MHz crystal or a 32.768-kHz oscillator for the Hibernation Module RTC. See the CLKSEL bit in the HIBCTL register.
	XOSC1	53	0	Analog	Hibernation Module oscillator crystal output.
UART	U0Rx	26	I	TTL	UART module 0 receive. When in IrDA mode, this signal has IrDA modulation.
	UOTx	27	0	TTL	UART module 0 transmit. When in IrDA mode, this signal has IrDA modulation.
	U1Rx	12	I	TTL	UART module 1 receive. When in IrDA mode, this signal has IrDA modulation.
	UlTx	13	0	TTL	UART module 1 transmit. When in IrDA mode, this signal has IrDA modulation.
					-

Table 21-4. GPIO Pins and Alternate Functions

GPIO Pin	Pin Number	Multiplexed Function	Multiplexed Function
PA0	26	U0Rx	

GPIO Pin	Pin Number	Multiplexed Function	Multiplexed Function
PA1	27	UOTx	
PA2	28	SSI0Clk	
PA3	29	SSI0Fss	
PA4	30	SSIORx	
PA5	31	SSIOTx	
PA6	34	CCP1	
PA7	35	CCP4	
PB0	66	CCP0	
PB1	67	CCP2	
PB2	70	I2C0SCL	
PB3	71	I2C0SDA	
PB4	92	C0-	
PB5	91	CCP5	
PB6	90	C0+	
PB7	89	TRST	
PC0	80	TCK	SWCLK
PC1	79	TMS	SWDIO
PC2	78	TDI	
PC3	77	TDO	SWO
PC4	25	PhA0	
PC5	24	C0o	
PC6	23	CCP3	
PC7	22	PhB0	
PD0	10	CAN0Rx	
PD1	11	CAN0Tx	
PD2	12	U1Rx	
PD3	13	UlTx	
PD4	95		
PD5	96		
PD6	99	Fault	
PD7	100	IDX0	
PE0	72	PWM4	
PE1	73	PWM5	
PE2	74		
PE3	75		
PF0	47	PWM0	
PF1	61	PWM1	
PF2	60		
PF3	59		
PF4	58		
PF5	46		
PF6	43		

GPIO Pin	Pin Number	Multiplexed Function	Multiplexed Function
PF7	42		
PG0	19		
PG1	18		
PG2	17		
PG3	16		
PG4	41		
PG5	40		
PG6	37		
PG7	36		
PH0	86	PWM2	
PH1	85	PWM3	
PH2	84		
PH3	83		

22 Operating Characteristics

Table 22-1. Temperature Characteristics

Characteristic	Symbol	Value	Unit
Operating temperature range ^a	T _A	-40 to +85	°C

a. Maximum storage temperature is 150°C.

Table 22-2. Thermal Characteristics

Characteristic	Symbol	Value	Unit
Thermal resistance (junction to ambient) ^a	Θ_{JA}	55.3	°C/W
Average junction temperature ^b	T _J	$T_A + (P_{AVG} \cdot \Theta_{JA})$	°C

a. Junction to ambient thermal resistance $\boldsymbol{\theta}_{JA}$ numbers are determined by a package simulator.

b. Power dissipation is a function of temperature.

23 Electrical Characteristics

23.1 DC Characteristics

23.1.1 Maximum Ratings

The maximum ratings are the limits to which the device can be subjected without permanently damaging the device.

Note: The device is not guaranteed to operate properly at the maximum ratings.

Table 23-1. Maximum Ratings

Characteristic	Symbol	Va	lue	Unit
u .		Min	Max	
I/O supply voltage (V _{DD})	V _{DD}	0	4	٧
Core supply voltage (V _{DD25})	V _{DD25}	0	4	٧
Analog supply voltage (V _{DDA})	V_{DDA}	0	4	٧
Battery supply voltage (V _{BAT})	V_{BAT}	0	4	V
Input voltage	V _{IN}	-0.3	5.5	٧
Maximum current per output pins	I	-	25	mA

a. Voltages are measured with respect to GND.

Important: This device contains circuitry to protect the inputs against damage due to high-static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are connected to an appropriate logic voltage level (for example, either GND or VDD).

23.1.2 Recommended DC Operating Conditions

Table 23-2. Recommended DC Operating Conditions

Parameter	Parameter Name	Min	Nom	Max	Unit
V _{DD}	I/O supply voltage	3.0	3.3	3.6	V
V _{DD25}	Core supply voltage	2.25	2.5	2.75	V
V_{DDA}	Analog supply voltage	3.0	3.3	3.6	V
V_{BAT}	Battery supply voltage	2.3	3.0	3.6	V
V _{IH}	High-level input voltage	2.0	-	5.0	V
V _{IL}	Low-level input voltage	-0.3	-	1.3	V
V _{SIH}	High-level input voltage for Schmitt trigger inputs	0.8 * V _{DD}	-	V _{DD}	V
V _{SIL}	Low-level input voltage for Schmitt trigger inputs	0	-	0.2 * V _{DD}	V
V _{OH}	High-level output voltage	2.4	-	-	V
V _{OL}	Low-level output voltage	-	-	0.4	V
I _{OH}	High-level source current, V _{OH} =2.4 V				
	2-mA Drive	2.0	-	-	mA
	4-mA Drive	4.0	-	-	mA
	8-mA Drive	8.0	-	-	mA

Parameter	Parameter Name		Min	Nom	Max	Unit
I _{OL}	Low-level sink current, V _{OL} =0.4 V					
		2-mA Drive	2.0	-	-	mA
		4-mA Drive	4.0	-	-	mA
		8-mA Drive	8.0	-	-	mA

23.1.3 On-Chip Low Drop-Out (LDO) Regulator Characteristics

Table 23-3. LDO Regulator Characteristics

Parameter	Parameter Name	Min	Nom	Max	Unit
V _{LDOOUT}	Programmable internal (logic) power supply output value	2.25	2.5	2.75	٧
	Output voltage accuracy	-	2%	-	%
t _{PON}	Power-on time	-	-	100	μs
t _{ON}	Time on	-	-	200	μs
t _{OFF}	Time off	-	-	100	μs
V _{STEP}	Step programming incremental voltage	-	50	-	mV
C _{LDO}	External filter capacitor size for internal power supply	-	1	-	μF

23.1.4 Power Specifications

The power measurements specified in the tables that follow are run on the core processor using SRAM with the following specifications (except as noted):

- $V_{DD} = 3.3 \text{ V}$
- V_{DD25} = 2.50 V
- V_{BAT} = 3.0 V
- V_{DDA} = 3.3 V
- Temperature = 25°C
- Clock Source (MOSC) =3.579545 MHz Crystal Oscillator
- Main oscillator (MOSC) = enabled
- Internal oscillator (IOSC) = disabled

Table 23-4. Detailed Power Specifications

Parameter	Parameter Name	Conditions		V _{DD} , V _{DDA} , 'DDPHY	2.5	V V _{DD25}	3.0	V V _{BAT}	Unit
			Nom	Max	Nom	Max	Nom	Max	
I _{DD_RUN}	Run mode 1	V _{DD25} = 2.50 V	3	pending ^a	108	pending ^a	0	pending ^a	mA
	(Flash loop)	Code= while(1){} executed in Flash							
		Peripherals = All ON							
		System Clock = 50 MHz (with PLL)							
	Run mode 2	V _{DD25} = 2.50 V	0	pending ^a	53	pending ^a	0	pending ^a	mA
	(Flash loop)	Code= while(1){} executed in Flash							
		Peripherals = All OFF							
		System Clock = 50 MHz (with PLL)							
	Run mode 1	V _{DD25} = 2.50 V	3	pending ^a	102	pending ^a	0	pending ^a	mA
	(SRAM loop)	Code= while(1){} executed in SRAM							
		Peripherals = All ON							
		System Clock = 50 MHz (with PLL)							
	Run mode 2	V _{DD25} = 2.50 V	0	pending ^a	47	pending ^a	0	pending ^a	mA
	(SRAM loop)	Code= while(1){} executed in SRAM							
		Peripherals = All OFF							
		System Clock = 50 MHz (with PLL)							
I _{DD_SLEEP}	Sleep mode	V _{DD25} = 2.50 V	0	pending ^a	17	pending ^a	0	pendinga	mA
		Peripherals = All OFF							
		System Clock = 50 MHz (with PLL)							
I _{DD_DEEPSLEEP}		LDO = 2.25 V	0.14	pending ^a	0.18	pending ^a	0	pending ^a	mA
	mode	Peripherals = All OFF							
		System Clock = IOSC30KHZ/64							
I _{DD_HIBERNATE}	Hibernate mode	$V_{BAT} = 3.0 \text{ V}$	0	pending ^a	0	pending ^a	16	pending ^a	μA
	mode	$V_{DD} = 0 V$							
		V _{DD25} = 0 V							
		V _{DDA} = 0 V							
		V _{DDPHY} = 0 V							
		Peripherals = All OFF							
		System Clock = OFF							
		Hibernate Module = 32 kHz							

a. Pending characterization completion.

23.1.5 Flash Memory Characteristics

Table 23-5. Flash Memory Characteristics

Parameter	Parameter Name	Min	Nom	Max	Unit
PE _{CYC}	Number of guaranteed program/erase cycles before failure ^a	10,000	100,000	-	cycles
T _{RET}	Data retention at average operating temperature of 85°C	10	-	-	years
T _{PROG}	Word program time	20	-	-	μs
T _{ERASE}	Page erase time	20	-	-	ms
T _{ME}	Mass erase time	200	-	-	ms

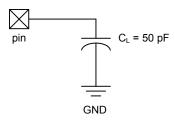
a. A program/erase cycle is defined as switching the bits from 1-> 0 -> 1.

23.2 AC Characteristics

23.2.1 Load Conditions

Unless otherwise specified, the following conditions are true for all timing measurements. Timing measurements are for 4-mA drive strength.

Figure 23-1. Load Conditions



23.2.2 Clocks

Table 23-6. Phase Locked Loop (PLL) Characteristics

Parameter	Parameter Name	Min	Nom	Max	Unit
f _{ref_crystal}	Crystal reference ^a	3.579545	-	8.192	MHz
f _{ref_ext}	External clock reference ^a	3.579545	-	8.192	MHz
f _{pll}	PLL frequency ^b	-	400	-	MHz
T _{READY}	PLL lock time	-	-	0.5	ms

a. The exact value is determined by the crystal value programmed into the XTAL field of the Run-Mode Clock Configuration (RCC) register.

Table 23-7. Clock Characteristics

Parameter	Parameter Name	Min	Nom	Max	Unit
f _{IOSC}	Internal 12 MHz oscillator frequency	8.4	12	15.6	MHz
f _{IOSC30KHZ}	Internal 30 KHz oscillator frequency	21	30	39	KHz
f _{XOSC}	Hibernation module oscillator frequency	-	4.194304	-	MHz
f _{XOSC_XTAL}	Crystal reference for hibernation oscillator	-	4.194304	-	MHz
f _{XOSC_EXT}	External clock reference for hibernation module	-	32.768	-	KHz

b. PLL frequency is automatically calculated by the hardware based on the XTAL field of the RCC register.

Parameter	Parameter Name	Min	Nom	Max	Unit
f _{MOSC}	Main oscillator frequency	1	-	8	MHz
t _{MOSC_per}	Main oscillator period	125	-	1000	ns
f _{ref_crystal_bypass}	Crystal reference using the main oscillator (PLL in BYPASS mode) a	1	-	8	MHz
f _{ref_ext_bypass}	External clock reference (PLL in BYPASS mode) ^a	0	-	50	MHz
f _{system_clock}	System clock	0	-	50	MHz

a. The ADC must be clocked from the PLL or directly from a 14-MHz to 18-MHz clock source to operate properly.

Table 23-8. Crystal Characteristics

Parameter Name		Units			
Frequency	8	6	4	3.5	MHz
Frequency tolerance	±50	±50	±50	±50	ppm
Aging	±5	±5	±5	±5	ppm/yr
Oscillation mode	Parallel	Parallel	Parallel	Parallel	
Temperature stability (0 - 85 °C)	±25	±25	±25	±25	ppm
Motional capacitance (typ)	27.8	37.0	55.6	63.5	pF
Motional inductance (typ)	14.3	19.1	28.6	32.7	mH
Equivalent series resistance (max)	120	160	200	220	Ω
Shunt capacitance (max)	10	10	10	10	pF
Load capacitance (typ)	16	16	16	16	pF
Drive level (typ)	100	100	100	100	μW

23.2.3 Temperature Sensor

Table 23-9. Temperature Sensor Characteristics

Parameter	Parameter Name	Min	Nom	Max	Unit
V _{TSO}	Output voltage	0.3	-	2.7	V
t _{TSERR}	Output voltage temperature accuracy	-	-	±3.5	°C
t _{TSNL}	Output temperature nonlinearity	-	-	±1	°C

23.2.4 Analog-to-Digital Converter

Table 23-10. ADC Characteristics

Parameter	Parameter Name	Min	Nom	Max	Unit
V _{ADCIN}	Maximum single-ended, full-scale analog input voltage	-	-	3.0	V
	Minimum single-ended, full-scale analog input voltage	-	-	0	V
	Maximum differential, full-scale analog input voltage	-	-	1.5	V
	Minimum differential, full-scale analog input voltage	-	-	-1.5	V
C _{ADCIN}	Equivalent input capacitance	-	1	-	pF
N	Resolution	-	10	-	bits
f _{ADC}	ADC internal clock frequency	7	8	9	MHz
t _{ADCCONV}	Conversion time	-	-	16	t _{ADC} cycles ^a
f ADCCONV	Conversion rate	438	500	563	k samples/s

Parameter	Parameter Name	Min	Nom	Max	Unit
INL	Integral nonlinearity	-	-	±1	LSB
DNL	Differential nonlinearity	-	-	±1	LSB
OFF	Offset	-	-	±1	LSB
GAIN	Gain	-	-	±1	LSB

a. t_{ADC}= 1/f_{ADC clock}

23.2.5 Analog Comparator

Table 23-11. Analog Comparator Characteristics

Parameter	Parameter Name	Min	Nom	Max	Unit
V _{os}	Input offset voltage	-	±10	±25	mV
V _{CM}	Input common mode voltage range	0	-	V _{DD} -1.5	٧
C _{MRR}	Common mode rejection ratio	50	-	-	dB
T _{RT}	Response time	-	-	1	μs
T _{MC}	Comparator mode change to Output Valid	-	-	10	μs

Table 23-12. Analog Comparator Voltage Reference Characteristics

Parameter	Parameter Name	Min	Nom	Max	Unit
R _{HR}	Resolution high range	-	V _{DD} /32	-	LSB
R _{LR}	Resolution low range	-	V _{DD} /24	-	LSB
A _{HR}	Absolute accuracy high range	-	-	±1/2	LSB
A _{LR}	Absolute accuracy low range	-	-	±1/4	LSB

23.2.6 I²C

Table 23-13. I²C Characteristics

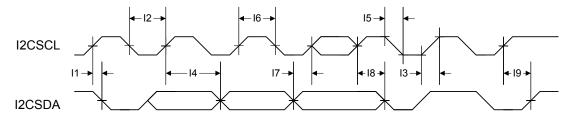
Parameter No.	Parameter	Parameter Name	Min	Nom	Max	Unit
I1 ^a	t _{SCH}	Start condition hold time	36	-	-	system clocks
I2 ^a	t _{LP}	Clock Low period	36	-	-	system clocks
I3 ^b	t _{SRT}	<code>I2CSCL/I2CSDA</code> rise time (V $_{\rm IL}$ =0.5 V to V $_{\rm IH}$ =2.4 V)	-	-	(see note b)	ns
I4 ^a	t _{DH}	Data hold time	2	-	-	system clocks
I5 ^c	t _{SFT}	<code>I2CSCL/I2CSDA</code> fall time (V $_{IH}$ =2.4 V to V $_{IL}$ =0.5 V)	-	9	10	ns
I6 ^a	t _{HT}	Clock High time	24	-	-	system clocks
I7 ^a	t _{DS}	Data setup time	18	-	-	system clocks
I8 ^a	t _{SCSR}	Start condition setup time (for repeated start condition only)	36	-	-	system clocks
19 ^a	t _{SCS}	Stop condition setup time	24	-	-	system clocks

a. Values depend on the value programmed into the TPR bit in the I²C Master Timer Period (I2CMTPR) register; a TPR programmed for the maximum I2CSCL frequency (TPR=0x2) results in a minimum output timing as shown in the table above. The I²C interface is designed to scale the actual data transition time to move it to the middle of the I2CSCL Low period. The actual position is affected by the value programmed into the TPR; however, the numbers given in the above values are minimum values.

b. Because I2CSCL and I2CSDA are open-drain-type outputs, which the controller can only actively drive Low, the time I2CSCL or I2CSDA takes to reach a high level depends on external signal capacitance and pull-up resistor values.

c. Specified at a nominal 50 pF load.

Figure 23-2. I²C Timing



23.2.7 Hibernation Module

The Hibernation Module requires special system implementation considerations since it is intended to power-down all other sections of its host device. The system power-supply distribution and interfaces of the system must be driven to 0 V_{DC} or powered down with the same regulator controlled by $\overline{\rm HIB}$.

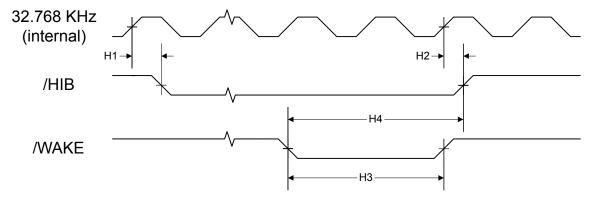
The regulators controlled by $\overline{\mbox{HIB}}$ are expected to have a settling time of 250 μs or less.

Table 23-14. Hibernation Module Characteristics

Parameter No	Parameter	Parameter Name	Min	Nom	Max	Unit
H1	t _{HIB_LOW}	Internal 32.768 KHz clock reference rising edge to /HIB asserted	-	200	-	μs
H2	t _{HIB_HIGH}	Internal 32.768 KHz clock reference rising edge to /HIB deasserted	-	30	-	μs
H3	t _{WAKE_ASSERT}	/WAKE assertion time	62	-	-	μs
H4	t _{WAKETOHIB}	/WAKE assert to /HIB desassert	62	-	124	μs
H5	t _{XOSC_SETTLE}	XOSC settling time ^a	20	-	-	ms
H6	t _{HIB_REG_WRITE}	Time for a write to non-volatile registers in HIB module to complete	92	-	-	μs

a. This parameter is highly sensitive to PCB layout and trace lengths, which may make this parameter time longer. Care must be taken in PCB design to minimize trace lengths and RLC (resistance, inductance, capacitance).

Figure 23-3. Hibernation Module Timing



23.2.8 Synchronous Serial Interface (SSI)

Table 23-15, SSI Characteristics

Parameter No.	Parameter	Parameter Name	Min	Nom	Max	Unit
S1	t _{clk_per}	SSIC1k cycle time	2	-	65024	system clocks
S2	t _{clk_high}	SSIC1k high time	-	1/2	-	t clk_per

Parameter No.	Parameter	Parameter Name	Min	Nom	Max	Unit
S3	t _{clk_low}	SSIC1k low time	-	1/2	-	t clk_per
S4	t _{clkrf}	SSIC1k rise/fall time	-	7.4	26	ns
S5	t _{DMd}	Data from master valid delay time	0	-	20	ns
S6	t _{DMs}	Data from master setup time	20	-	-	ns
S7	t _{DMh}	Data from master hold time	40	-	-	ns
S8	t _{DSs}	Data from slave setup time	20	-	-	ns
S9	t _{DSh}	Data from slave hold time	40	-	-	ns

Figure 23-4. SSI Timing for TI Frame Format (FRF=01), Single Transfer Timing Measurement

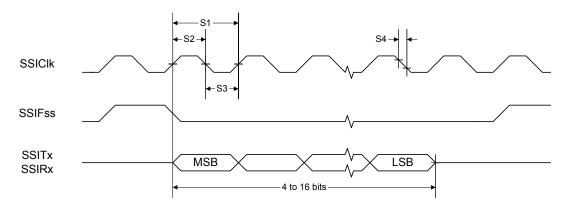
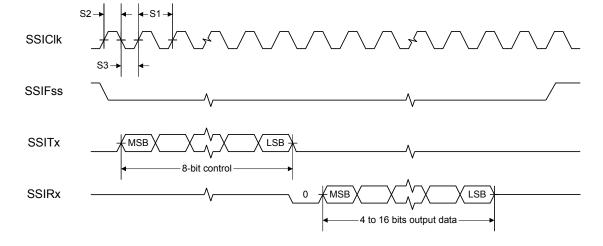


Figure 23-5. SSI Timing for MICROWIRE Frame Format (FRF=10), Single Transfer



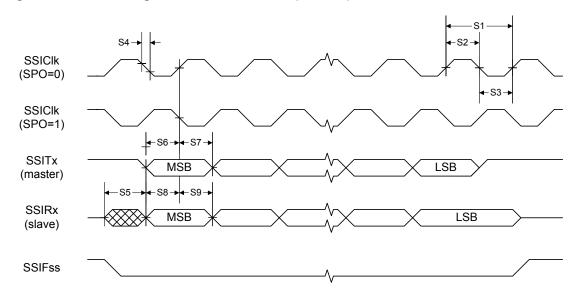


Figure 23-6. SSI Timing for SPI Frame Format (FRF=00), with SPH=1

23.2.9 JTAG and Boundary Scan

Table 23-16. JTAG Characteristics

Parameter No.	Parameter	Parameter Name	Min	Nom	Max	Unit
J1	f _{TCK}	тск operational clock frequency	0	-	10	MHz
J2	t _{TCK}	TCK operational clock period	100	-	-	ns
J3	t _{TCK_LOW}	TCK clock Low time	-	t _{TCK}	-	ns
J4	t _{TCK_HIGH}	TCK clock High time	-	t _{TCK}	-	ns
J5	t _{TCK_R}	TCK rise time	0	-	10	ns
J6	t _{TCK_F}	TCK fall time	0	-	10	ns
J7	t _{TMS_SU}	TMS setup time to TCK rise	20	-	-	ns
J8	t _{TMS_HLD}	TMS hold time from TCK rise	20	-	-	ns
J9	t _{TDI_SU}	TDI setup time to TCK rise	25	-	-	ns
J10	t _{TDI_HLD}	TDI hold time from TCK rise	25	-	-	ns
J11	TCK fall to Data Valid from High-Z	2-mA drive	-	23	35	ns
t _{TDO_ZDV}		4-mA drive		15	26	ns
_		8-mA drive		14	25	ns
		8-mA drive with slew rate control		18	29	ns
J12	TCK fall to Data Valid from Data Valid	2-mA drive	-	21	35	ns
t _{TDO_DV}		4-mA drive		14	25	ns
		8-mA drive		13	24	ns
		8-mA drive with slew rate control		18	28	ns

Parameter No.	Parameter	Parameter Name	Min	Nom	Max	Unit
J13	TCK fall to High-Z from Data Valid	2-mA drive	-	9	11	ns
t TDO DVZ		4-mA drive		7	9	ns
_		8-mA drive		6	8	ns
		8-mA drive with slew rate control		7	9	ns
J14	t _{TRST}	TRST assertion time	100	-	-	ns
J15	t _{TRST_SU}	TRST setup time to TCK rise	10	-	-	ns

Figure 23-7. JTAG Test Clock Input Timing

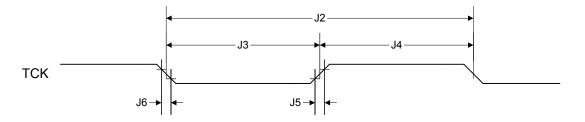


Figure 23-8. JTAG Test Access Port (TAP) Timing

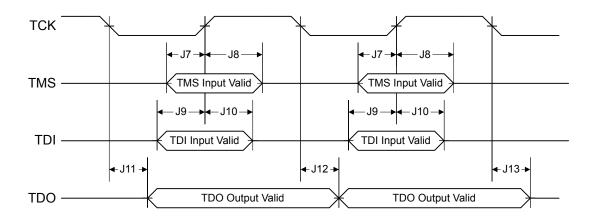
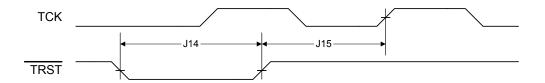


Figure 23-9. JTAG TRST Timing



23.2.10 General-Purpose I/O

Note: All GPIOs are 5 V-tolerant.

Table 23-17. GPIO Characteristics

Parameter	Parameter Name	Condition	Min	Nom	Max	Unit
t _{GPIOR}	GPIO Rise Time (from 20% to 80% of V_{DD})	2-mA drive	-	17	26	ns
		4-mA drive		9	13	ns
		8-mA drive		6	9	ns
		8-mA drive with slew rate control		10	12	ns
t _{GPIOF}	GPIO Fall Time (from 80% to 20% of V _{DD})	2-mA drive	-	17	25	ns
		4-mA drive		8	12	ns
		8-mA drive		6	10	ns
		8-mA drive with slew rate control		11	13	ns

23.2.11 Reset

Table 23-18. Reset Characteristics

Parameter No.	Parameter	Parameter Name	Min	Nom	Max	Unit
R1	V _{TH}	Reset threshold	-	2.0	-	٧
R2	V _{BTH}	Brown-Out threshold	2.85	2.9	2.95	V
R3	T _{POR}	Power-On Reset timeout	-	10	-	ms
R4	T _{BOR}	Brown-Out timeout	-	500	-	μs
R5	T _{IRPOR}	Internal reset timeout after POR	6	-	11	ms
R6	T _{IRBOR}	Internal reset timeout after BOR	0	-	1	μs
R7	T _{IRHWR}	Internal reset timeout after hardware reset (RST pin)	0	-	1	ms
R8	T _{IRSWR}	Internal reset timeout after software-initiated system reset a	2.5	-	20	μs
R9	T _{IRWDR}	Internal reset timeout after watchdog reset ^a	2.5	-	20	μs
R10	T _{VDDRISE}	Supply voltage (V _{DD}) rise time (0V-3.3V)	-	-	100	ms
R11	T _{MIN}	Minimum RST pulse width	2	-	-	μs

a. 20 * t _{MOSC_per}

Figure 23-10. External Reset Timing (RST)

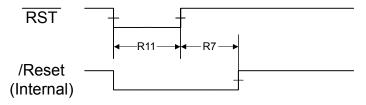


Figure 23-11. Power-On Reset Timing

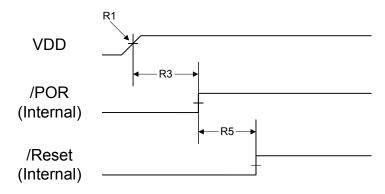


Figure 23-12. Brown-Out Reset Timing

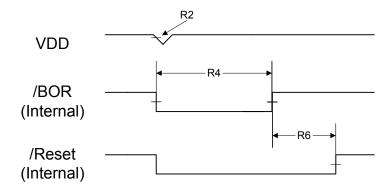


Figure 23-13. Software Reset Timing

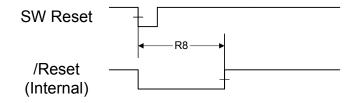
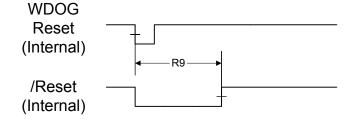
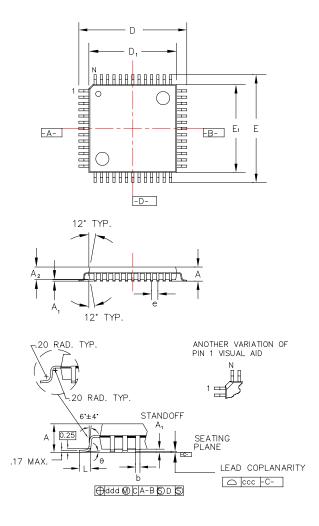


Figure 23-14. Watchdog Reset Timing



24 Package Information

Figure 24-1. 100-Pin LQFP Package



Notes

- 1. All dimensions shown in mm.
- 2. Dimensions shown are nominal with tolerances indicated.
- 3. Foot length 'L' is measured at gage plane 0.25 mm above seating plane.
- 4. L/F: Eftec 64T Cu or equivalent, 0.127 mm (0.005") or 0.152 mm (0.006") thick.
- 5. Use variation BED for body dimensions.

Body +2.00 mm Footprint, 1.4 mm package thickness						
Symbols	Symbols Leads 100L					
Α	A Max.					
A ₁		0.05 Min./0.15 Max.				

A ₂	±0.05	1.40
D	±0.20	16.00
D ₁	±0.05	14.00
E	±0.20	16.00
E ₁	±0.05	14.00
L	±0.15/-0.10	0.60
е	BASIC	0.50
b	±0.05	0.22
θ		0°~7°
ddd	Max.	0.08
ccc	Max.	0.08
JEDEC Refer	MS-026	
Variation [BED	

25 Ordering and Contact Information

25.1 Ordering Information

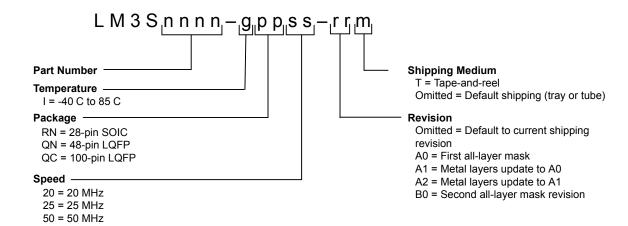


Table 25-1. Part Ordering Information

Orderable Part Number	
LM3S2739-IQC50	Stellaris® LM3S2739 Microcontroller

25.2 Company Information

Luminary Micro, Inc. designs, markets, and sells ARM Cortex-M3-based microcontrollers (MCUs). Austin, Texas-based Luminary Micro is the lead partner for the Cortex-M3 processor, delivering the world's first silicon implementation of the Cortex-M3 processor. Luminary Micro's introduction of the Stellaris® family of products provides 32-bit performance for the same price as current 8- and 16-bit microcontroller designs. With entry-level pricing at \$1.00 for an ARM technology-based MCU, Luminary Micro's Stellaris product line allows for standardization that eliminates future architectural upgrades or software tool changes.

Luminary Micro, Inc. 108 Wild Basin, Suite 350 Austin, TX 78746 Main: +1-512-279-8800

Fax: +1-512-279-8879

http://www.luminarymicro.com sales@luminarymicro.com

25.3 Support Information

For support on Luminary Micro products, contact: support@luminarymicro.com +1-512-279-8800, ext. 3

A Serial Flash Loader

A.1 Serial Flash Loader

The Stellaris[®] serial flash loader is a preprogrammed flash-resident utility used to download code to the flash memory of a device without the use of a debug interface. The serial flash loader uses a simple packet interface to provide synchronous communication with the device. The flash loader runs off the crystal and does not enable the PLL, so its speed is determined by the crystal used. The two serial interfaces that can be used are the UART0 and SSI interfaces. For simplicity, both the data format and communication protocol are identical for both serial interfaces.

A.2 Interfaces

Once communication with the flash loader is established via one of the serial interfaces, that interface is used until the flash loader is reset or new code takes over. For example, once you start communicating using the SSI port, communications with the flash loader via the UART are disabled until the device is reset.

A.2.1 UART

The Universal Asynchronous Receivers/Transmitters (UART) communication uses a fixed serial format of 8 bits of data, no parity, and 1 stop bit. The baud rate used for communication is automatically detected by the flash loader and can be any valid baud rate supported by the host and the device. The auto detection sequence requires that the baud rate should be no more than 1/32 the crystal frequency of the board that is running the serial flash loader. This is actually the same as the hardware limitation for the maximum baud rate for any UART on a Stellaris[®] device.

In order to determine the baud rate, the serial flash loader needs to determine the relationship between its own crystal frequency and the baud rate. This is enough information for the flash loader to configure its UART to the same baud rate as the host. This automatic baud-rate detection allows the host to use any valid baud rate that it wants to communicate with the device.

The method used to perform this automatic synchronization relies on the host sending the flash loader two bytes that are both 0x55. This generates a series of pulses to the flash loader that it can use to calculate the ratios needed to program the UART to match the host's baud rate. After the host sends the pattern, it attempts to read back one byte of data from the UART. The flash loader returns the value of 0xCC to indicate successful detection of the baud rate. If this byte is not received after at least twice the time required to transfer the two bytes, the host can resend another pattern of 0x55, 0x55, and wait for the 0xCC byte again until the flash loader acknowledges that it has received a synchronization pattern correctly. For example, the time to wait for data back from the flash loader should be calculated as at least 2*(20(bits/sync)/baud rate (bits/sec)). For a baud rate of 115200, this time is 2*(20/115200) or 0.35 ms.

A.2.2 SSI

The Synchronous Serial Interface (SSI) port also uses a fixed serial format for communications, with the framing defined as Motorola format with SPH set to 1 and SPO set to 1. See the section on SSI formats for more details on this transfer protocol. Like the UART, this interface has hardware requirements that limit the maximum speed that the SSI clock can run. This allows the SSI clock to be at most 1/12 the crystal frequency of the board running the flash loader. Since the host device is the master, the SSI on the flash loader device does not need to determine the clock as it is provided directly by the host.

A.3 Packet Handling

All communications, with the exception of the UART auto-baud, are done via defined packets that are acknowledged (ACK) or not acknowledged (NAK) by the devices. The packets use the same format for receiving and sending packets, including the method used to acknowledge successful or unsuccessful reception of a packet.

A.3.1 Packet Format

All packets sent and received from the device use the following byte-packed format.

```
struct
{
  unsigned char ucSize;
  unsigned char ucCheckSum;
  unsigned char Data[];
};
```

ucSize The first byte received holds the total size of the transfer including

the size and checksum bytes.

ucChecksum This holds a simple checksum of the bytes in the data buffer only.

The algorithm is Data[0]+Data[1]+...+ Data[ucSize-3].

Data This is the raw data intended for the device, which is formatted in

some form of command interface. There should be ucSize-2 bytes of data provided in this buffer to or from the device.

A.3.2 Sending Packets

The actual bytes of the packet can be sent individually or all at once; the only limitation is that commands that cause flash memory access should limit the download sizes to prevent losing bytes during flash programming. This limitation is discussed further in the commands that interact with the flash.

Once the packet has been formatted correctly by the host, it should be sent out over the UART or SSI interface. Then the host should poll the UART or SSI interface for the first non-zero data returned from the device. The first non-zero byte will either be an ACK (0xCC) or a NAK (0x33) byte from the device indicating the packet was received successfully (ACK) or unsuccessfully (NAK). This does not indicate that the actual contents of the command issued in the data portion of the packet were valid, just that the packet was received correctly.

A.3.3 Receiving Packets

The flash loader sends a packet of data in the same format that it receives a packet. The flash loader may transfer leading zero data before the first actual byte of data is sent out. The first non-zero byte is the size of the packet followed by a checksum byte, and finally followed by the data itself. There is no break in the data after the first non-zero byte is sent from the flash loader. Once the device communicating with the flash loader receives all the bytes, it must either ACK or NAK the packet to indicate that the transmission was successful. The appropriate response after sending a NAK to the flash loader is to resend the command that failed and request the data again. If needed, the host may send leading zeros before sending down the ACK/NAK signal to the flash loader, as the flash loader only accepts the first non-zero data as a valid response. This zero padding is needed by the SSI interface in order to receive data to or from the flash loader.

A.4 Commands

The next section defines the list of commands that can be sent to the flash loader. The first byte of the data should always be one of the defined commands, followed by data or parameters as determined by the command that is sent.

A.4.1 COMMAND_PING (0X20)

This command simply accepts the command and sets the global status to success. The format of the packet is as follows:

```
Byte[0] = 0x03;
Byte[1] = checksum(Byte[2]);
Byte[2] = COMMAND PING;
```

The ping command has 3 bytes and the value for COMMAND_PING is 0x20 and the checksum of one byte is that same byte, making Byte[1] also 0x20. Since the ping command has no real return status, the receipt of an ACK can be interpreted as a successful ping to the flash loader.

A.4.2 COMMAND_GET_STATUS (0x23)

This command returns the status of the last command that was issued. Typically, this command should be sent after every command to ensure that the previous command was successful or to properly respond to a failure. The command requires one byte in the data of the packet and should be followed by reading a packet with one byte of data that contains a status code. The last step is to ACK or NAK the received data so the flash loader knows that the data has been read.

```
Byte[0] = 0x03
Byte[1] = checksum(Byte[2])
Byte[2] = COMMAND GET STATUS
```

A.4.3 COMMAND_DOWNLOAD (0x21)

This command is sent to the flash loader to indicate where to store data and how many bytes will be sent by the COMMAND_SEND_DATA commands that follow. The command consists of two 32-bit values that are both transferred MSB first. The first 32-bit value is the address to start programming data into, while the second is the 32-bit size of the data that will be sent. This command also triggers an erase of the full area to be programmed so this command takes longer than other commands. This results in a longer time to receive the ACK/NAK back from the board. This command should be followed by a COMMAND_GET_STATUS to ensure that the Program Address and Program size are valid for the device running the flash loader.

The format of the packet to send this command is a follows:

```
Byte[0] = 11
Byte[1] = checksum(Bytes[2:10])
Byte[2] = COMMAND_DOWNLOAD
Byte[3] = Program Address [31:24]
Byte[4] = Program Address [23:16]
Byte[5] = Program Address [7:0]
Byte[6] = Program Address [7:0]
Byte[7] = Program Size [31:24]
Byte[8] = Program Size [23:16]
Byte[9] = Program Size [15:8]
Byte[10] = Program Size [7:0]
```

A.4.4 COMMAND SEND DATA (0x24)

This command should only follow a COMMAND_DOWNLOAD command or another COMMAND_SEND_DATA command if more data is needed. Consecutive send data commands automatically increment address and continue programming from the previous location. The caller should limit transfers of data to a maximum 8 bytes of packet data to allow the flash to program successfully and not overflow input buffers of the serial interfaces. The command terminates programming once the number of bytes indicated by the COMMAND_DOWNLOAD command has been received. Each time this function is called it should be followed by a COMMAND_GET_STATUS to ensure that the data was successfully programmed into the flash. If the flash loader sends a NAK to this command, the flash loader does not increment the current address to allow retransmission of the previous data.

```
Byte[0] = 11
Byte[1] = checksum(Bytes[2:10])
Byte[2] = COMMAND_SEND_DATA
Byte[3] = Data[0]
Byte[4] = Data[1]
Byte[5] = Data[2]
Byte[6] = Data[3]
Byte[7] = Data[4]
Byte[8] = Data[5]
Byte[9] = Data[6]
Byte[10] = Data[7]
```

A.4.5 COMMAND_RUN (0x22)

This command is used to tell the flash loader to execute from the address passed as the parameter in this command. This command consists of a single 32-bit value that is interpreted as the address to execute. The 32-bit value is transmitted MSB first and the flash loader responds with an ACK signal back to the host device before actually executing the code at the given address. This allows the host to know that the command was received successfully and the code is now running.

```
Byte[0] = 7
Byte[1] = checksum(Bytes[2:6])
Byte[2] = COMMAND_RUN
Byte[3] = Execute Address[31:24]
Byte[4] = Execute Address[23:16]
Byte[5] = Execute Address[15:8]
Byte[6] = Execute Address[7:0]
```

A.4.6 COMMAND_RESET (0x25)

This command is used to tell the flash loader device to reset. This is useful when downloading a new image that overwrote the flash loader and wants to start from a full reset. Unlike the COMMAND_RUN command, this allows the initial stack pointer to be read by the hardware and set up for the new code. It can also be used to reset the flash loader if a critical error occurs and the host device wants to restart communication with the flash loader.

```
Byte[0] = 3
Byte[1] = checksum(Byte[2])
Byte[2] = COMMAND_RESET
```

The flash loader responds with an ACK signal back to the host device before actually executing the software reset to the device running the flash loader. This allows the host to know that the command was received successfully and the part will be reset.